

# **Sicherheitstechnik - Safety Technology**



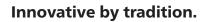
Produktkatalog · Product Catalogue



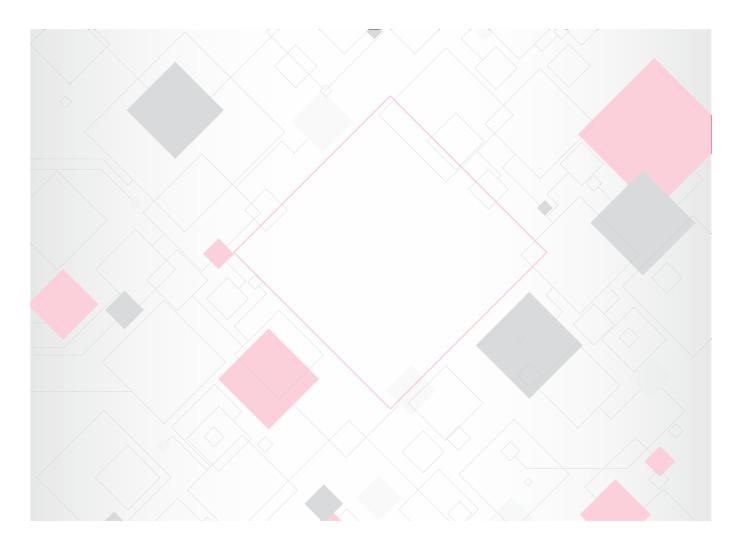
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# **General**



#### Mayser GmbH & Co. KG

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#### Copyright

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### **Quality management**

In addition to the important role played by our employees, another key ingredient of our success is the quality of our products. We want our customers to be excited about our products and solutions. To achieve this, we offer intensive support, critically examine the requirements of our customers and generate new ideas.

In addition, Mayser strives for continuous improvement of quality – both in production and in development. In this way, we can ensure that all products, systems and solutions fulfil the relevant quality standards and comply with the applicable standards and directives. This is also backed up by our certifications.

We are certified by **TÜV SÜD Management Service GmbH** for the areas of

- the development, construction and sale of safety technology products and electronic monitoring devices in accordance with ISO 9001 and ISO 14001
- the development and construction of anti-pinch protection systems and seat occupancy detectors – and their components – for the automotive industry in accordance with IATF 16949









Tip:

### **Certificates**

### Quality management

# Quality management systemCertificate No.According to ISO 9001:201512 100 22318 TMSAccording to IATF 16949:201612 111 22318 TMS

#### tificates can be found in the Downloads area of our website at www.mayser.com.

Detailed versions of all the cer-

Further details can be found in the certificates: Please click on the desired certificate.

### **Environmental management**

Environmental management system	Certificate No.
According to ISO 14001:2015	12 104 22318 TMS

### Safety edges

Safety edges	Certificate No.
SK SP 37	44 205 13043610 *
SK SP 57	44 205 13043611 *
SK SP 67	44 205 13043612 *
SK SP 87	44 205 13043614 *
SK SP according to CSA C22.2 No. 247	UL-CA-L496132-21-41508102-1
SK SP according to UL 325	UL-US-L496132-11-41508102-1
SL NC II	IFA 2001029 *

### Miniature safety edges

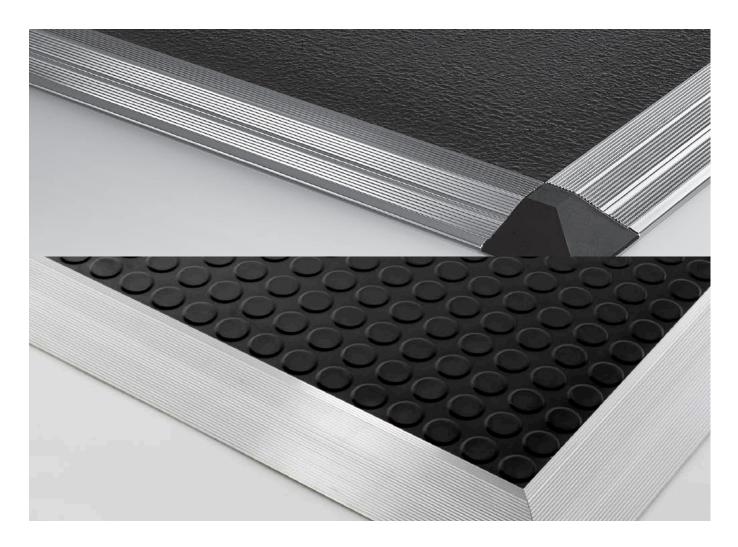
Miniature safety edge	Certificate No.
EKS and SE 1 TPE according to UL 325	20180912-E496132

### Control units

Control unit	Certificate No.
SG-EFS 104/4L	44 205 15176904
SG-EFS 104/4L according to UL 508	20150327-E471221
SG-EFS 104/2W	44 205 13127902
SG-RS 309-2	44 205 13043613
RB3 system: T868 + R868	44 207 13749706

\* EC type examination certificates apply exclusively to the combinations of sensor and control unit specified therein.





# **Safety mats SM and SM11**



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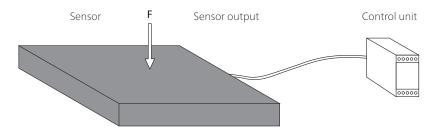
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#### **Definitions**

### Pressure-sensitive protection device

A pressure-sensitive protection device consists of one or more pressure-sensitive sensors, a signal processing unit, and one or more output signal switching devices. The control unit is made up of the signal processing unit and output signal switching device(s). The pressure-sensitive protection device is triggered when the sensor is activated.

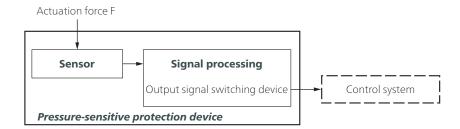


#### Sensor

The sensor is the part of the pressure-sensitive protection device that generates a signal when the actuation force F is applied. Mayser safety systems feature a sensor whose actuation area is deformed locally.

#### **Signal processing**

The signal processing unit is the part of the pressure-sensitive protection device that converts the output signal of the sensor and controls the status of the output signal switching device. The output signal switching device is the part of the signal processing unit which is connected to the forwarding control system and which transmits safety output signals such as STOP.



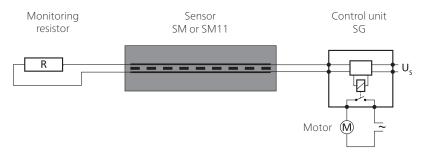
Tip: Terms are defined in ISO 13856-1 Section 3.



#### Criteria for selecting the sensor type

- Category according to ISO 13849-1
- Performance level of the pressure-sensitive protection device = at least PL,
- Temperature range
- Degree of protection in accordance with IEC 60529:
   IP65 is the standard for safety mats.
   Higher degrees of protection must be checked individually.
- Environmental influences such as swarf, oil, coolant, outdoor use...
- Is it necessary to detect people who weigh < 35 kg?

### Operation principle of 2-wire technology



The monitoring resistor must be compatible with the control unit. The standard type is 8k2.

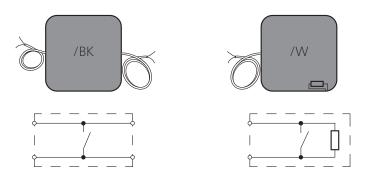
#### For your safety:

The sensor and connection cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on controlled bridging of the contact surfaces with a monitoring resistor (closed-circuit principle).

#### **Types**

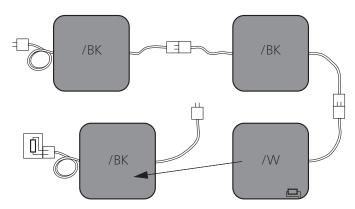
/BK With cables on both sides for use as a through sensor or with an external monitoring resistor for use as an end sensor

/W With an integrated monitoring resistor for use as an end sensor





#### **Sensor combination**



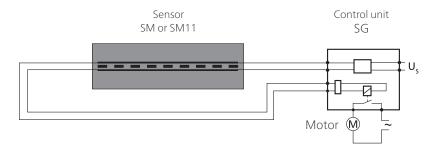
Version with external resistor, therefore no variety of models

#### Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety mats can be combined to create an overall surface of any size and shape



### Operation principle of 4-wire technology



The 4-wire technology can only be used together with control unit SG-EFS 104/4L.

#### For your safety:

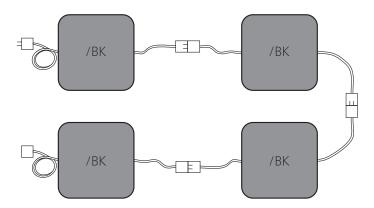
The sensor and connecting cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on signal transmission feedback – without a monitoring resistor.

#### **Types**

/BK With cables on both sides for use as a through sensor



#### **Sensor combination**



#### Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety mats can be combined to create an overall surface of any size and shape



### **Safety**

#### Intended use

A safety mat detects a person standing on it or who steps onto it. It is a flat protection device that is capable of monitoring when somebody is present. Its task is to prevent possible hazardous situations that could affect someone within a danger zone.

Typical areas of application are moving parts on machines and systems. Safe operation of a safety mat depends entirely on

- the surface condition of the mounting surface,
- the correct selection of the size and resistance rating as well as
- correct installation.

Tip: This is illustrated clearly by Figures B.1 and B.2 in ISO 13856-1.

Due to the design, the actuation area is actually smaller than it looks because of the non-sensitive edges. Once these have been allowed for, what remains is the effective actuation area (see chapter *Effective actuation area*).

#### Limits

- No more than 10 /BK-type sensors can be connected to one control unit.
- No more than 9 /BK-type sensors and 1 /W-type sensor can be connected to one control unit.
- Max. system size: 15 m<sup>2</sup>
  - = max. quantity  $\times$  max. sensor size

#### **Exclusions**

Sensors are not suitable for:

- Detecting people who weigh less than 20 kg
- Driving on with industrial trucks

Sensor combinations are not suitable for:

• Detecting people who weigh less than 35 kg



### Selecting the appropriate product line

The size and shape of safety mats can be customised to create a bespoke solution. SM safety mats are highly resistant to environmental influences and normal chemical influences.

If your sensor requirements are lower, our SM11 or SM8 safety mat products may be right for you.

### Other safety aspects

The following safety aspects relate to pressure-sensitive protection devices consisting of a sensor and a control unit.

#### **Performance Level (PL)**

The PL has been determined using the procedure defined by ISO 13849-1. Fault exclusion according to ISO 13849-2 Table D.8: Non-closing of contacts in the case of pressure-sensitive protection devices according to ISO 13856. In this case, no characteristic values of the sensor whatsoever are included when determining the PL. Assuming a high MTTF $_{\rm D}$  value for the control unit, a performance level of up to PL d can be achieved by the safety mat system (pressure-sensitive protection device) as a whole.

#### Is the protection device suitable?

First, the integrator must decide what  $PL_r$  is required for the hazard. After that, they must select the protection device.

Finally, the integrator needs to check whether the category and PL of the selected protection device are appropriate.

#### Risk and safety assessment

For the risk and safety assessment of your machine, we recommend ISO 12100 "Safety of machinery — General principles for design".

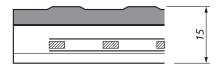
#### Without reset function

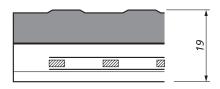
When a protection device without reset function is used (automatic reset), the reset function must be provided in some other way.



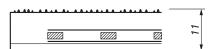
### **Design**

### Design of the SM





### Design of the SM11



#### SM with GM1

Moulded onto a plastic plate. The rubber studded covering provides the necessary non-slip properties and ensures mechanical protection.

#### SM with GM5

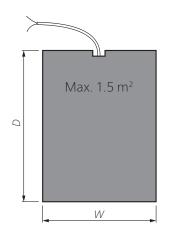
Moulded onto a plastic plate. The high-strength rubber studded covering provides the necessary non-slip properties and ensures a high level of mechanical protection.

#### **SM11**

Moulded onto a plastic plate. The surface texture provides the necessary non-slip properties and ensures mechanical protection.

#### Available sizes

Sensors are available up to a max. size of 1.5 m<sup>2</sup>. The side lengths must be within a range of 200 to 3000 mm.



W: Width (broad side)
D: Depth (long side)

 $W \times D \le 1.5 \text{ m}^2$ 

The cable exit can be on the broad or long side.

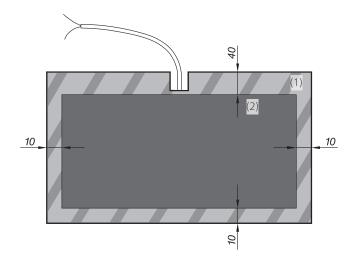
According to ISO 13855, the minimum depth to the danger zone must be taken into account (see chapter *Calculation of the necessary actuation area*). The non-sensitive edges must be taken into account (see chapter *Effective actuation area*).



### Effective actuation area

A non-sensitive edge (1) surrounds the effective actuation area (2):

- 40 mm = on the cable exit side
- 10 mm = on the remaining sides



#### **Sensor combinations**

When sensor combinations are used, only the sides with 10 mm edges should be placed next to one another.



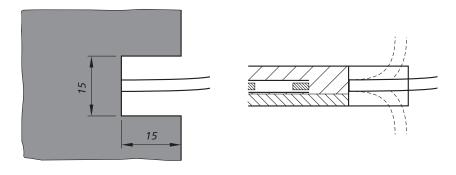
### **Connection**

### Cable exit

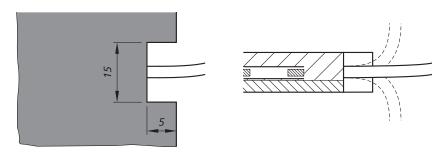
The multifunction cut-out also allows the cable to be laid so that it exits upwards or downwards.

The cable exit is located in the middle of the side.

#### **SM** cable exit



#### SM11 cable exit

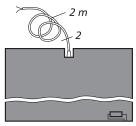


### Cable connection

- Standard cable lengths L = 2.0 m
- Maximum total cable length to the control unit  $L_{max} = 100 \text{ m}$



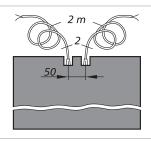
Without plug (standard)	With plug (M8)
<ul><li>Suitable for universal use</li><li>Variable cable length</li></ul>	<ul><li>Service-friendly</li><li>Easy assembly</li><li>Secure connection</li><li>Watertight plug connection</li></ul>
/W-type sensor with 1 line	
2 m	0.25 m

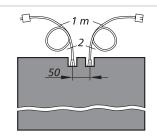




- As an individual /W-type sensor or a /W-type end sensor
- Integrated resistor
- 1 two-wire cable

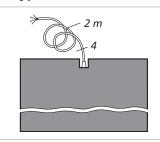
#### /BK-type sensor with 2 lines

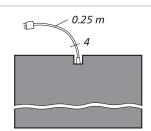




- As a /BK-type through sensor
- Without resistor
- 2 two-wire cables

#### /BK-type sensor with 1 line





- As a /BK-type through sensor
- Without resistor
- 1 four-wire cable



### Wire colours

Without plug (standard)	With plug (M8)
	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$
/W-type sensor with 1 line	
BK I RD	3
/BK-type sensor with 2 lines	5
BK	3
/BK-type sensor with 1 line	
BU T BK	3

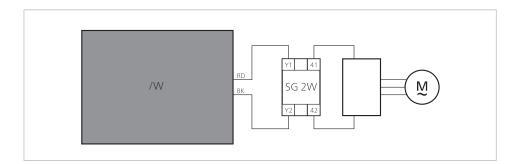
### Colour coding

BK Black
BN Brown
BU Blue
RD Red
WH White

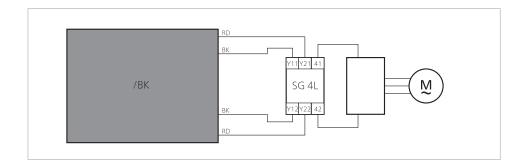
### Connection examples

Key:

SG 2W Evaluation with 2-wire technology SG 4L Evaluation with 4-wire technology







### **Sensor surface**

### Sensor surface of the SM

The rubber studded covering is glued in place at the factory. It provides the necessary non-slip properties and ensures mechanical protection.

#### GM1

Black covering with circular studs Yellow covering with circular studs

Material: NBR

Thickness: 4.5 mm ±0.5

Max. size:  $1.0 \text{ m} \times 10 \text{ m}$ 

 $1.2 \text{ m} \times 10 \text{ m}$ 

#### GM5

Green covering with circular studs With high mechanical strength

Material: NBR Thickness: 9 mm ±0.5

Max. size:  $1.2 \text{ m} \times 10 \text{ m}$ 







### Sensor surface of the SM11

The rough surface texture is applied at the factory. It provides the necessary non-slip properties and ensures mechanical protection.

#### **Surface texture**

Grey

Material: PUR Thickness: 1.0 mm



### Resistance

The resistance ratings listed below (at a room temperature of 23 °C) depend on the sensor having:

- A rubber studded covering that is bonded face to face with the sensor (SM only)
- An undamaged surface (SM and SM11)

#### **Physical resistance**

NBR	PUR
(SM)	(SM11)
120 mg	< 150 mg
B2	B2
+ +	+ +
	<b>(SM)</b> 120 mg

Explanation of symbols:

+ = resistant



#### **Chemical resistance**

The sensor is broadly resistant to normal chemical influences such as diluted acids and alkalis, as well as alcohol, over an exposure period of 24 hrs.

The values in the table are the results of tests carried out in our laboratory. You must always conduct your own practical tests to verify that our products are suitable for your specific area of application.

# Explanation of symbols:

- + = resistant
- ± = resistant to a certain extent
- = not resistant

Material	NBR (SM)	PUR (SM11)
Acetone	+	_
Ammonia	+	+
Brake fluid	±	
Cutting emulsion	±	+
Acetic acid	±	
Greases	+	_
Caustic potash solution	+	
Cooling lubricant	+	±
Metal working oil	+	+
Methyl alcohol	±	_
Sodium hydroxide	+	
Cellulose thinner	±	_
Hydrochloric acid 10%	+	±
Suds	+	
Spirit (ethyl alcohol)	+	_
Water	+	+
Petroleum ether / petrol	+	_
Citric acid	+	
Drawing compound	±	_



### **Mounting**

The sensors must be mounted immediately in front of the danger zone. They must be fixed in place using ramp edges, Z-profiles or cable conduits (optional), which must be screwed to the floor. Ramp edges are required on the access sides to minimise the risk of tripping.

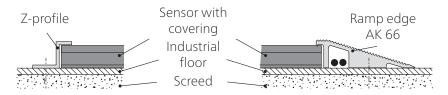
### Overview of fixing materials

SM with GM1	SM with GM1 SM with GM5 SM11	
Overall height 15 mm	Overall height 19 mm	Overall height 11 mm
Z-profile (machine side)	Z/1-profile (machine side)	Z/2-profile or AP 45 cable conduit (machine side)
Sensor with rubber studded covering	Sensor with rubber studded covering	Sensor with surface texture
Ramp edge AK 66 or AK 105 (access side)	Ramp edge AK 105/1 (access side)	Ramp edge AK 56 (access side)
	Other fixing materials	
		Outer corner connector E1 AK 56
Sealing plug	_	Connecting wedge Vk AK 56
		Inner corner connector E2 AK 56



### Fixing the SM with GM1

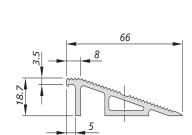
#### Ramp edge AK 66 with Z-profile



- Not suitable for plug-in cable connections
- Cable conduit for max. 2 cables

#### Aluminium ramp edge AK 66

- 1-piece with cable conduit
- For sensor combinations with up to 2 sensors
- Sensor without plug
- Aluminium ramp edge for sensors with GM1
- Rod 3 m (7500053), rod 6 m (1000008) or fixed length

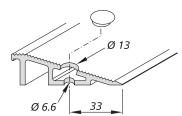


#### **Stepped hole for AK 66**

• For fixing aluminium ramp edge AK 66

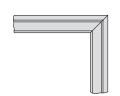
#### **Sealing plug**

• Seals the stepped hole (1000615)



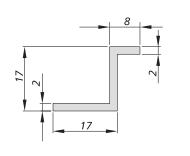
#### Mitre cut

For corner connections



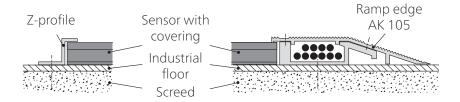
#### **Aluminium Z-profile**

- Edging at the machine or wall side
- Aluminium Z-profile for sensors with GM1
- Aluminium Z-profile: Rod 3 m (7500054), rod 6 m (1000011) or fixed length





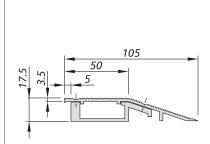
#### Ramp edge AK 105 with Z-profile



- Suitable for plug-in cable connections
- Cable conduit for max. 10 cables

#### Aluminium ramp edge AK 105

- 2-piece with cable conduit
- For sensor combinations
- Sensors with or without plugs
- Aluminium ramp edge AK 105 for sensors with GM1
- Aluminium ramp edge AK 105: Rod 3 m upper and lower sections (7500052), rod 6 m upper section (1000009), rod 6 m lower section (1000010), or fixed length



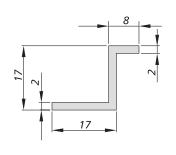
#### Mitre cut

• For corner connections



#### **Aluminium Z-profile**

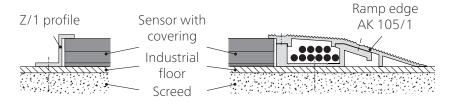
- Edging at the machine or wall side
- Aluminium Z-profile for sensors with GM1
- Aluminium Z-profile: Rod 3 m (7500054), rod 6 m (1000011) or fixed length





### Fixing the SM with GM5

#### Ramp edge AK 105/1 with Z/1-profile

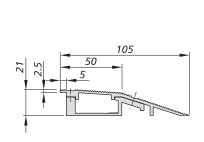


- Suitable for plug-in cable connections
- Cable conduit for max. 10 cables

Ramp edge AK 105/1 and Z/1-profile only suitable for sensors with GM5.

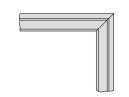
#### Aluminium ramp edge AK 105/1

- 2-piece with cable conduit
- For sensor combinations
- Sensors with or without plugs
- Aluminium ramp edge AK 105/1 for sensors with GM5
- Aluminium ramp edge AK 105/1: Rod 3 m upper and lower sections (7500224),
  - rod 6 m upper section (1000992), rod 6 m lower section (1000010), or fixed length



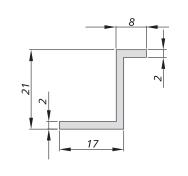
#### Mitre cut

• For corner connections



#### **Aluminium Z/1-profile**

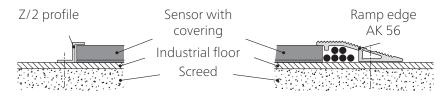
- Edging at the machine or wall side
- Aluminium Z/1-profile for sensors with GM5
- Aluminium Z/1-profile: Rod 3 m (7500738), rod 6 m (1001478) or fixed length





### Fixing the SM11

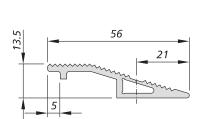
#### Ramp edge AK 56 with Z/2-profile



- Not suitable for plug-in cable connections
- Cable conduit for max. 6 cables

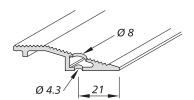
#### Aluminium ramp edge AK 56

- 1-piece with cable conduit
- For sensor combinations
- Sensors with or without plugs
- Rod 3 m (7501014), rod 6 m (1002684) or fixed length



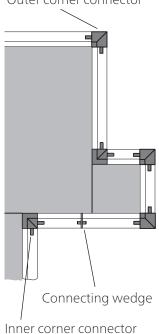
#### **Stepped hole for AK 56**

• For fixing ramp edge AK 56



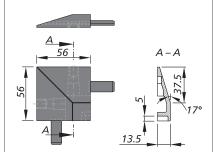
#### **Example:**

Outer corner connector



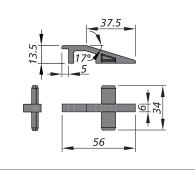
#### **Outer corner connector E1 AK 56**

- For connecting the corners of ramp edge AK 56
- Material: Black plastic (1002751)



#### **Connecting wedge Vk AK 56**

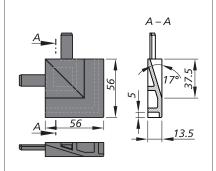
- For connecting several ramp edges AK 56 lengthwise
- Material: Black plastic (1002996)





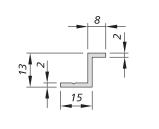
#### Inner corner connector E2 AK 56

- For connecting the corners of ramp edge AK 56
- Material: Black plastic (1002752)



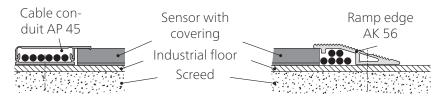
#### **Aluminium Z/2-profile**

- Edging at the machine or wall side
- Rod 3 m (7500385), rod 6 m (1001666) or fixed length



#### Optional: Ramp edge AK 56 with cable conduit AP 45

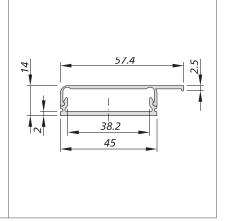
Instead of using a Z/2 profile, you can also use cable conduit AP 45 to fix the sensor in place.



- Cable conduit AP 45 instead of Z/2-profile
- Suitable for plug-in cable connections
- Cable conduit for max. 6 cables

#### **Aluminium cable conduit AP 45**

- 2-piece cable conduit
- For sensor combinations
- Sensors with or without plugs
- Upper section is clipped into lower section
- Rod 3 m upper section (1002546), rod 3 m lower section (1002547) or fixed length upper and lower sections





S = Minimum distance

between the dan-

parameter [ mm/s ]

the complete system

ger zone and the furthest edge of the

sensor [ mm ]

T = Follow-through of

t<sub>1</sub> = Response time of the protection

 $t_2$  = Stopping time of the

C = Safety margin [ mm ]

H = Step height [ mm ]

K = Approximation

[s]

device

machine

### **Calculation of the necessary actuation area**

According to ISO 13855, the effective actuation area that is required with reference to the danger zone is calculated using the following formula:

 $S = (K \times T) + C$ 

where:

K = 1600 mm/s

 $T = t_1 + t_2$ 

C = 1200 mm - 0.4 H

#### With installation at floor level

H = 0; thus:

 $S = (1600 \text{ mm/s} \times \text{T}) + 1200 \text{ mm}$ 

### With installation on a step

 $H \neq 0$ ; thus:

 $S = (1600 \text{ mm/s} \times \text{T}) + (1200 \text{ mm} - 0.4\text{H})$ 

### Calculation examples

#### **Calculation example 1**

A safety mat detects when someone inadvertently accesses the danger zone of an automated movement. The mat is installed at floor level, i.e. H=0.

The follow-through time of the movement is 300 ms, the response time of the protection device is 18 ms.

 $S = (1600 \text{ mm/s} \times (300 \text{ ms} + 18 \text{ ms})) + 1200 \text{ mm}$ 

 $S = (1600 \text{ mm/s} \times 0.318 \text{ s}) + 1200 \text{ mm}$ 

S = 509 mm + 1200 mm

S = 1709 mm

#### **Calculation example 2**

The same conditions as Example 1, except that there is a step with a height of 150 mm leading up to the danger zone that has to be dealt with.

 $S = (1600 \text{ mm/s} \times (300 \text{ ms} + 18 \text{ ms})) + (1200 - (0.4 \times 150)) \text{ mm}$ 

 $S = (1600 \text{ mm/s} \times 0.318 \text{ s}) + (1200 - 60) \text{ mm}$ 

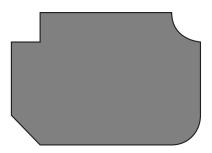
S = 509 mm + 1140 mm

S = 1649 mm



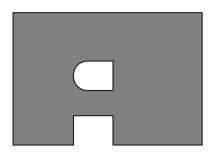
### **Customised designs**

### Special shapes



e.g. different corner shapes

Different shapes such as circles, circle segments, trapeziums etc. are possible.



e.g. cut-outs

Mats can be ready-manufactured with cut-outs, e.g. for machine feet, switch cabinets, and so on.

### Special versions

Special versions are available for particular ambient conditions, e.g. aggressive substances (fuels, solvents etc.).

### **Maintenance and cleaning**

The sensors are virtually maintenance-free.

The control unit also monitors the sensor at the same time.

#### **Regular inspection**

Depending on the operational demands, the sensors must be inspected at regular intervals (at least monthly)

- for proper functioning,
- for damage and
- for correct mounting.

#### Cleaning

If the sensors become dirty, they can be cleaned with a mild cleaning product.



### **Technical data**

	Safety mat SM/W or SM11/W with control unit SG-EFS 104/2W	Safety mat SM/BK or SM11/BK with control unit SG-EFS 104/4L	Sensor* SM/W, SM/BK or SM11/W, SM11/BK (without control unit)
Testing basis	ISO 13856-1		
Switching characteristics at v <sub>test</sub>	= 250 mm/s		
Switching operations at 0.1 A Actuation forces Test piece (cylinder) Ø 11 mm Test piece (cylinder) Ø 80 mm Test piece (cylinder) Ø 200 mm Response time	> 4× 10 <sup>6</sup> < 300 N < 300 N < 600 N 23 ms	38 ms	8 ms
Safety classifications	I.		
ISO 13856: reset function ISO 13849-1:2015  MTTF <sub>D</sub> (pressure-sensitive protection device)  B <sub>10D</sub> (sensor) n <sub>op</sub> (assumption)	With/without Category 3 PL d 210 a  6× 10 <sup>6</sup> 52560/a	With/without Category 3 PL d 65 a  6× 10 <sup>6</sup> 52560/a	Category 1  6× 10 <sup>6</sup>
Mechanical operating condition	าร		
Sensor size Side length (min./max.) Cable length (min./max.) Static load (up to 8 h) SM with GM1 SM with GM5 SM11 Driving on with industrial trucks Weight SM with GM1 SM with GM5 SM11 IEC 60529: degree of protection Sensor Max. humidity (23 °C)	Max. 1.5 m <sup>2</sup> 200 mm / 3000 mm 10 cm / 100 m  Max. 800 N/cm <sup>2</sup> Max. 1200 N/cm <sup>2</sup> Max. 800 N/cm <sup>2</sup> Not suitable  17.3 kg/m <sup>2</sup> 23.9 kg/m <sup>2</sup> 12.0 kg/m <sup>2</sup> IP65 95% (non-condensing)		
Operating temperature Individual sensor Sensor combination Storage temperature	-20 to +55 °C +5 to +55 °C -20 to +55 °C		



	Safety mat SM/W or SM11/W with control unit SG-EFS 104/2W	Safety mat SM/BK or SM11/BK with control unit SG-EFS 104/4L	Sensor* SM/W, SM/BK or SM11/W, SM11/BK (without control unit)		
Electrical operating conditions					
Connection cable	Ø 5.0 mm PVC				
	2× 0.5 mm <sup>2</sup>	2× 0.5 mm <sup>2</sup> or 4× 0.34 mm <sup>2</sup>	$2 \times 0.5 \text{ mm}^2 \text{ or}$ $4 \times 0.34 \text{ mm}^2$		
Sensor	24 V DC / max. 100 mA		"		
Number of /BK-type sensors	Max. 10 in series				
Dimensional tolerances					
Length dimension	ISO 2768 – c				
Perpendicularity	ISO 2768 – c				

<sup>\*</sup> If you combine sensors with control units and thereby place pressure-sensitive protection devices on the market, you should observe the basic requirements according to ISO 13856.

As well as meeting technical requirements, this also means – in particular – observing any that relate to marking and information for use.

Declarations of Conformity only apply to pressure-sensitive protection devices. In the case of sensors that are going to be used to make pressure-sensitive protection devices, Declarations of Incorporation are issued instead.

### **Conformity**



The CE symbol indicates that this Mayser product complies with the relevant EC directives and that the stipulated conformity assessments have been carried out.

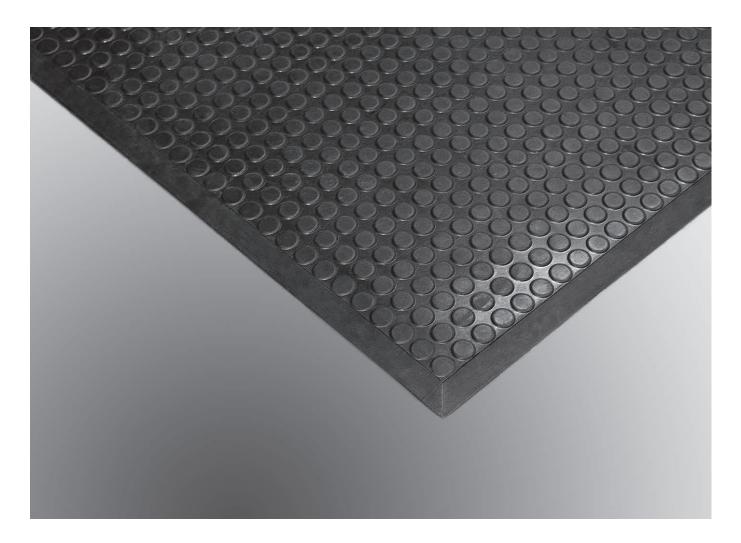
The design type of the pressure-sensitive protection device complies with the basic requirements of the following directives:

- 2006/42/EC (Safety of Machinery)
- 2011/65/EU (RoHS)
- 2014/30/EU (EMC)

The Declaration of Conformity is available in the Downloads section of our website:

www.mayser.com/de/download.





# **Safety mats SM8**



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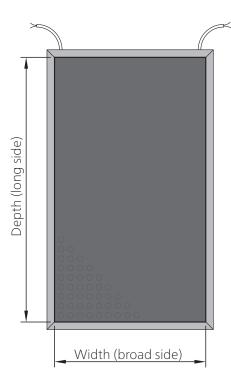


### **Available sizes**

SM8 sensors are only available in fixed sizes:

Part number	SM8/BK	Width ×	Depth
5006626	SM8/BK	750 ×	1000 mm
5006627	SM8/BK	750 ×	1250 mm
5006628	SM8/BK	750 ×	1500 mm
5006623	SM8/BK	1000 ×	1000 mm
5006624	SM8/BK	1000 ×	1250 mm
5006625	SM8/BK	1000 ×	1500 mm

The dimensions refer solely to the contact surface. An extra 25 mm must be added on each side that has a moulded ramp.



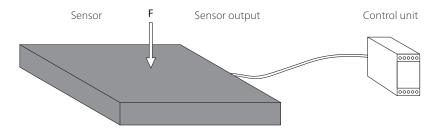
According to ISO 13855, the minimum depth to the danger zone must be taken into account (see chapter *Calculation of the necessary actuation area*). The non-sensitive edges must be taken into account (see chapter *Effective actuation area*).



#### **Definitions**

### Pressure-sensitive protection device

A pressure-sensitive protection device consists of one or more pressure-sensitive sensors, a signal processing unit, and one or more output signal switching devices. The control unit is made up of the signal processing unit and output signal switching device(s). The pressure-sensitive protection device is triggered when the sensor is activated.

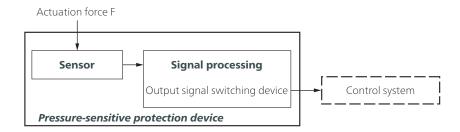


#### Sensor

The sensor is the part of the pressure-sensitive protection device that generates a signal when the actuation force F is applied. Mayser safety systems feature a sensor whose actuation area is deformed locally.

#### **Signal processing**

The signal processing unit is the part of the pressure-sensitive protection device that converts the output signal of the sensor and controls the status of the output signal switching device. The output signal switching device is the part of the signal processing unit which is connected to the forwarding control system and which transmits safety output signals such as STOP.



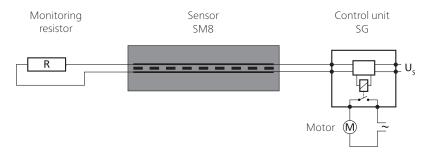
Tip: Terms are defined in ISO 13856-1 Section 3.



#### Criteria for selecting the sensor type

- Category according to ISO 13849-1
- Performance level of the pressure-sensitive protection device
   at least PL,
- Temperature range
- Degree of protection in accordance with IEC 60529:
   IP65 is the standard for safety mats.
   Higher degrees of protection must be checked individually.
- Environmental influences such as swarf, oil, coolant, outdoor use...
- Is it necessary to detect people who weigh < 35 kg?</li>

# Operation principle of 2-wire technology



The monitoring resistor must be compatible with the control unit. The standard type is 8k2.

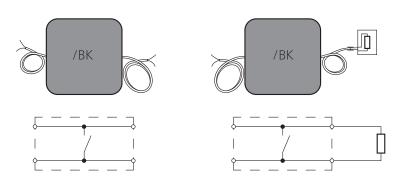
#### For your safety:

The sensor and connecting cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on controlled bridging of the contact surfaces with a monitoring resistor (closed-circuit principle).

### **Types**

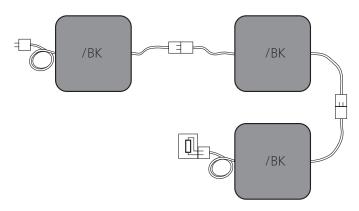
/BK

With cables on both sides for use as a through sensor or with an external monitoring resistor for use as an end sensor





#### **Sensor combination**

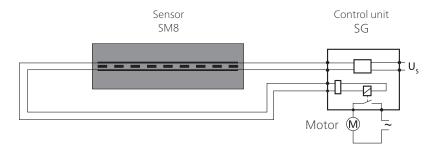


#### Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety mats can be combined to create an overall surface of any size and shape



# Operation principle of 4-wire technology



The 4-wire technology can only be used together with control unit SG-EFS 104/4L.

#### For your safety:

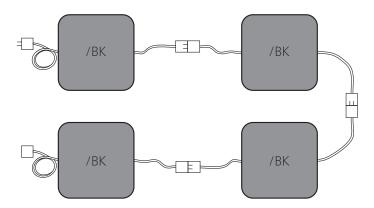
The sensor and connecting cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on signal transmission feedback – without a monitoring resistor.

#### **Types**

/BK With cables on both sides for use as a through sensor



#### **Sensor combination**



#### Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety mats can be combined to create an overall surface of any size and shape



### **Safety**

### Intended use

A safety mat detects a person standing on it or who steps onto it. It is a flat protection device that is capable of monitoring when somebody is present. Its purpose is to prevent possible hazardous situations for personnel within a danger zone.

Typical areas of application are moving parts on machines and systems.

- Safe operation of a safety mat depends entirely onthe surface condition of the mounting surface,
- the correct selection of the size and resistance rating as well as
- correct installation.

Tip: This is illustrated clearly by Figures B.1 and B.2 in ISO 13856-1.

Due to the design, the actuation area is actually smaller than it looks because of the non-sensitive edges. Once these have been allowed for, what remains is the effective actuation area (see chapter *Effective actuation area*).

#### Limits

- No more than 10 /BK-type sensors can be connected to one control unit.
- Max. system size: 15 m<sup>2</sup>
  - = max. quantity  $\times$  max. sensor size

### **Exclusions**

Sensors are not suitable for:

- Detecting walking aids
- Detecting people who weigh less than 20 kg
- Driving on with industrial trucks

Sensor combinations are not suitable for:

• Detecting people who weigh less than 35 kg

# Selecting the appropriate product line

Sensors from our SM8 line of safety mat products are only available in a rectangular shape. The surface is resistant to external influences and normal chemical influences to a degree.

If your sensor requirements are higher, only our SM safety mat products will be able to meet them



### Other safety aspects

The following safety aspects relate to pressure-sensitive protection devices consisting of a sensor and a control unit.

#### **Performance Level (PL)**

The PL has been determined using the procedure defined by ISO 13849-1. Fault exclusion according to ISO 13849-2 Table D.8: Non-closing of contacts in the case of pressure-sensitive protection devices according to ISO 13856. In this case, no characteristic values of the sensor whatsoever are included when determining the PL. Assuming a high MTTF $_{\rm D}$  value for the control unit, a performance level of up to PL d can be achieved by the safety mat system (pressure-sensitive protection device) as a whole.

#### Is the protection device suitable?

First, the integrator must decide what PL<sub>r</sub> is required for the hazard. After that, they must select the protection device.

Finally, the integrator needs to check whether the category and PL of the selected protection device are appropriate.

#### Risk and safety assessment

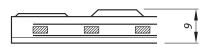
For the risk and safety assessment of your machine, we recommend ISO 12100 "Safety of machinery — General principles for design".

#### Without reset function

When a protection device without reset function is used (automatic reset), the reset function must be provided in some other way.



# **Design**



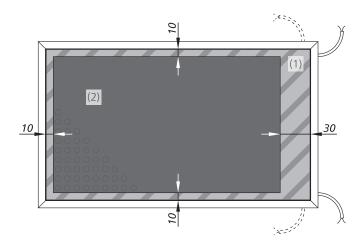
#### SM8

Moulded onto a plastic plate. The surface texture provides the necessary non-slip properties and ensures mechanical protection.

### Effective actuation area

A non-sensitive edge (1) surrounds the effective actuation area (2):

- 30 mm = on the cable exit side
- 10 mm = on the remaining sides



The ramps running around the sides are discounted when considering the effective actuation area.

#### **Sensor combinations**

When sensor combinations are used, only the sides with 10 mm edges should be placed next to one another.

The integrated ramps must be removed from these sides before combining the sensors.

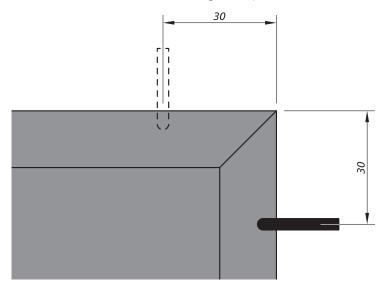


### **Connection**

### Cable exits

The cables are located at two corners.

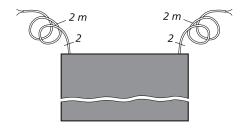
Two cable exits are available at each corner and you can either use the one on the broad side (width) or the one on the long side (depth). The required cable exit must be cut out on site at the designated point on the mat.



### Cable connection

- Standard cable lengths
   L = 2.0 m
- Maximum total cable length to the control unit  $L_{max} = 100 \text{ m}$

#### /BK-type sensor with 2 lines



- As a /BK-type through sensor
- Without resistor
- 2 two-wire cables

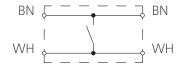


### Wire colours

### /BK-type sensor with 2 lines

#### **Colour coding**

BN Brown WH White

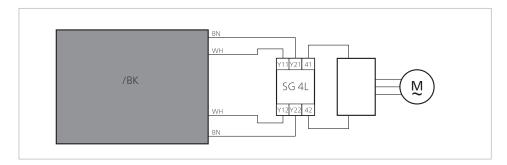




# Connection example

Key:

SG 4L Evaluation with 4-wire technology





### **Sensor surface**

The rubber surface structure is created at the factory during moulding. It provides the necessary non-slip properties and ensures mechanical protection. No further sensor cover is required.



### Resistance

The resistance ratings listed below (at a room temperature of 23  $^{\circ}$ C) depend on the sensor having an undamaged surface.

### **Physical resistance**

	PUR
DIN 53516: Abrasion DIN 4102: Fire behaviour Alternating climate stress conditions UV resistance	120 mg B2 + +

# Explanation of symbols:

+ = resistant



#### **Chemical resistance**

The sensor is broadly resistant to normal chemical influences such as diluted acids and alkalis, as well as alcohol, over an exposure period of 24 hrs.

The values in the table are the results of tests carried out in our laboratory. You must always conduct your own practical tests to verify that our products are suitable for your specific area of application.

# Explanation of symbols:

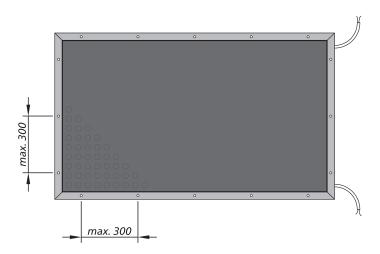
- + = resistant
- ± = resistant to a certain extent
- = not resistant

Material	PUR
Acetone	_
Formic acid 5%	+
Ammonia	+
ATF (automatic transmission fluid)	+
DOT 4 brake fluid	_
Cutting emulsion	+
Demineralised water	+
Diesel	±
Acetic acid 10%	+
Ethanol	_
Greases	_
Hydraulic oil	+
Caustic potash solution 10%	+
Saline solution 5%	+
Cooling lubricant	±
Metal working oil	+
Methanol	_
Mineral oil	+
Caustic soda 10%	±
Cellulose thinner	_
Hydrochloric acid 10%	±
Brine 10%	+
Suds 5%	+
Spirit (ethyl alcohol)	_
Universal thinner	_
Water	+
Petroleum ether / petrol	_
Citric acid 10%	+
Drawing compound	_



### **Mounting**

To minimise the risk of tripping, the sensor has integrated ramps all the way round the edges. No separate ramp edges are required.



The sensor must be fixed to the floor using flat-head screws with a diameter of at least 5 mm (recommended: 6 x 50 mm flat-head screws). These parts are not supplied as standard. The screws must be spaced no further than 300 mm apart.

# **Calculation of the necessary actuation area**

S = Minimum distance between the danger zone and the furthest edge of the sensor [ mm ]

K = Approximation parameter [ mm/s ]

T = Follow-through of the complete system [s]

t<sub>1</sub> = Response time of the protection device

t<sub>2</sub> = Stopping time of the machine

C = Safety margin [ mm ]
H = Step height [ mm ]

According to ISO 13855, the effective actuation area that is required with reference to the danger zone is calculated using the following formula:

$$S = (K \times T) + C$$
 where:  $K = 1600 \text{ mm/s}$ 

 $T = t_1 + t_2$ 

C = 1200 mm - 0.4 H

#### With installation at floor level

H = 0; thus:

 $S = (1600 \text{ mm/s} \times \text{T}) + 1200 \text{ mm}$ 

#### With installation on a step

 $H \neq 0$ : thus:

 $S = (1600 \text{ mm/s} \times \text{T}) + (1200 \text{ mm} - 0.4\text{H})$ 



### Calculation examples

#### **Calculation example 1**

A safety mat detects when someone inadvertently accesses the danger zone of an automated movement. The mat is installed at floor level, i.e. H = 0.

The follow-through time of the movement is 140 ms, the response time of the protection device is 38 ms.

```
S = (1600 \text{ mm/s} \times (140 \text{ ms} + 38 \text{ ms})) + 1200 \text{ mm}
```

 $S = (1600 \text{ mm/s} \times 0.178 \text{ s}) + 1200 \text{ mm}$ 

S = 285 mm + 1200 mm

S = 1485 mm

#### **Calculation example 2**

The same conditions as Example 1, except that there is a step with a height of 150 mm leading up to the danger zone that has to be dealt with.

```
S = (1600 \text{ mm/s} \times (140 \text{ ms} + 38 \text{ ms})) + (1200 - (0.4 \times 150)) \text{ mm}
```

 $S = (1600 \text{ mm/s} \times 0.178 \text{ s}) + (1200 - 60) \text{ mm}$ 

S = 285 mm + 1140 mm

S = 1425 mm

### **Maintenance and cleaning**

The sensors are virtually maintenance-free.

The control unit also monitors the sensor at the same time.

#### **Regular inspection**

Depending on the operational demands, the sensors must be inspected at regular intervals (at least monthly)

- for proper functioning,
- for damage and
- for correct mounting.

#### Cleaning

If the sensors become dirty, they can be cleaned with a mild cleaning product.



### **Technical data**

	Safety mat SM8/BK with control unit SG-EFS 104/4L	Sensor* SM8/BK (without control unit)		
Testing basis	ISO 13856-1			
Switching characteristics at v <sub>test</sub>	= 250 mm/s			
Switching operations at 0.1 A Actuation forces Test piece (cylinder) Ø 80 mm Test piece (cylinder) Ø 200 mm Response time				
Safety classifications				
ISO 13856: reset function ISO 13849-1:2015  MTTF <sub>D</sub> (pressure-sensitive protection device)  B <sub>10D</sub> (sensor) n <sub>op</sub> (assumption)	With/without Category 3 PL d  65 a 6 × 10 <sup>6</sup> 52560/a   - Category 1  - 6 × 10 <sup>6</sup>			
Mechanical operating condition	ns			
Sensor size Cable length (min./max.) Static load (up to 8 h) Driving on with industrial trucks Weight IEC 60529: degree of protection Sensor Max. humidity (23 °C) Operating temperature Individual sensor Sensor combination Storage temperature	13.0 kg/m <sup>2</sup>			
Electrical operating conditions	T			
Connection cable Sensor Number of /BK-type sensors	Ø 3.8 mm PVC 2 × 0.25 mm <sup>2</sup> 24 V DC / max. 100 mA Max. 10 in series			
Dimensional tolerances				
Length dimension Perpendicularity	ISO 2768 – c ISO 2768 – c			

<sup>\*</sup> If you combine sensors with control units and thereby place pressure-sensitive protection devices on the market, you should observe the basic requirements according to ISO 13856.

Declarations of Conformity only apply to pressure-sensitive protection devices. In the case of sensors that are going to be used to make pressure-sensitive protection devices, Declarations of Incorporation are issued instead.

As well as meeting technical requirements, this also means – in particular – observing any that relate to marking and information for use.



# **Conformity**



The CE symbol indicates that this Mayser product complies with the relevant EC directives and that the stipulated conformity assessments have been carried out.

The design type of the pressure-sensitive protection device complies with the basic requirements of the following directives:

- 2006/42/EC (Safety of Machinery)
- 2011/65/EU (RoHS)
- 2014/30/EU (EMC)

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# **SP DIY sensor profiles**



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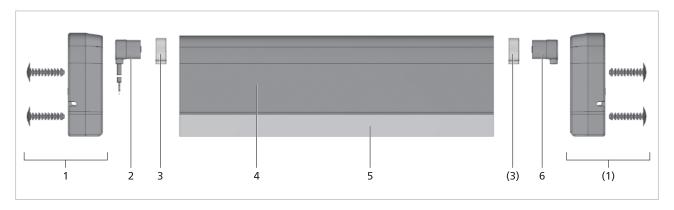


SK SP 67-2 TPE	39
SK SP 87-2 TPE	
Marking	
Conformity	
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UL certification	

### **Overview**

#### **Contact profile - Sensor profile**

The semi-finished contact profile (No. 4) is cut to length and assembled with the other components. This results in a functioning product called a sensor profile.



Nos. 2, 3 and 6 are identical for all sensor profiles.

No. 2Closing plug with 2.5 m cable7502873No. 3Ear clamp1005684No. 6Closing plug with resistor7502875

Alternatives for No. 2:

Closing plug with 5.0 m cable 7503774 Closing plug with 10 m cable 7503775

Sensor profile	No. 1 Set of end caps		No. 4 Contact profile		o. 5 um profile
SP 17-3 without end caps	1005786	SP 17-3	7503461	C 15	1000016
SP 37-1 without end caps	1000606	SP 37-1	7502853	C 25	1000004
SP 37-1 with end caps	7503008	SP 37-1	7502853	C 25	1000004
SP 37-2 with end caps	7503988	SP 37-2	7503318	C 26	1004330
SP 37L-2 with end caps	7503988	SP 37L-2	7504192	C 26	1004330
SP 37-3 with end caps	7503505 (7503654)	SP 37-3	7503343	C 25	1000004
SP 57-2 with end caps	7503603	SP 57-2	7503055	C 30	1005844
SP 57L-2 with end caps	7503603	SP 57L-2	7503412	C 30	1005844

### **Materials list**

Part No.	Designation	PU
7503461	Contact profile SP 17-3 TPE	80 m
7502853	Contact profile SP 37-1 TPE	30 m
7503318	Contact profile SP 37-2 TPE	30 m
7504192	Contact profile SP 37L-2 TPE	30 m
7503343	Contact profile SP 37-3 TPE "black"	30 m
7503534	Contact profile SP 37-3 TPE "red"	30 m
7503055	Contact profile SP 57-2 TPE	30 m
7503412	Contact profile SP 57L-2 TPE	30 m
7503521	Contact profile SP 57-3 TPE	25 m
7503633	Contact profile SP 57-4 TPE	25 m
7503711	Contact profile SP 57L-4 TPE	25 m
7503285	Contact profile SP 67-2 TPE	30 m
7503722	Contact profile SP 87-2 TPE	25 m
7502875	Closing plug with 8k2 resistor	10 pcs.
7502873	Closing plug with 2.5 m PUR cable, angled 90°	10 pcs.
7503774	Closing plug with 5.0 m PUR cable, angled 90°	10 pcs.
7503775	Closing plug with 10 m PUR cable, angled 90°	10 pcs.
7503708	Closing plug without resistor	10 pcs.
1005684	Ear clamp for closing plug	20 pcs.
1005786	Countersunk tapping screw 3.5 x 25 for SP 17-3	20 pcs.
7503008	Set of end caps for SP 37-1: 2 end caps, 2 fixing stoppers and 2 screws 3.9 × 25	10 pcs.
7503988	Set of end caps for SP 37(L)-2: 2 end caps and 4 pine tree clips	10 pcs.

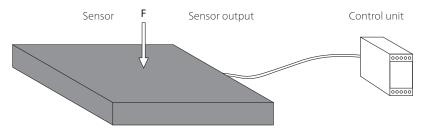
Part No.	Designation	PU
7503505	Set of end caps for SP 37-3 "black":	
	2 end caps and 2 pine tree clips	10 pcs.
7503654	Set of end caps for SP 37-3 "red":	10 pcs
7503603	2 end caps and 2 pine tree clips  Set of end caps for SP 57(L)-2 with clips:	10 pcs.
7303003	2 end caps and 4 pine tree clips	10 pcs.
7503618	Set of end caps for SP 57-3 and SP 57(L)-4: 2 end caps and 6 pine tree clips	10 pcs.
7503655	Set of end caps for SP 67-2: 2 end caps and 4 pine tree clips	10 pcs.
7504118	Set of end caps for SP 87-2: 2 end caps and 8 pine tree clips	10 pcs.
1000016	Aluminium profile C 15	6 m
1000854	Aluminium profile C 25M, upper section	6 m
1000855	Aluminium profile C 25M, lower section	6 m
1000829	Aluminium profile C 25L	6 m
1000012	Aluminium profile C 25S	6 m
1000004	Aluminium profile C 25	6 m
1004626	Aluminium profile C 26M, upper section	6 m
1004627	Aluminium profile C 26M, lower section	6 m
1004330	Aluminium profile C 26, perforated	6 m
1005844	Aluminium profile C 30	6 m
1001398	Aluminium profile C 35M, upper section	6 m
1001399	Aluminium profile C 35M, lower section	6 m
1000013	Aluminium profile C 35S	6 m
1000006	Aluminium profile C 35	6 m
1004629	Aluminium profile C 36M, upper section	6 m
1004630	Aluminium profile C 36M, lower section	6 m
1003849	Aluminium profile C 36L, perforated	6 m
1003850	Aluminium profile C 36S, perforated	6 m
1003848	Aluminium profile C 36, perforated	6 m
1001223	End stopper for C 25M, for SP without end caps	1 pc.
1000606	End stopper for C 25 or C 25S, for SP without end caps	1 pc.
1005906	Section cutter, cutting length 87 mm	1 pc.
7502868	Assembly aid SH3	1 pc.
1005741	Notching pliers Knipex 7742115	1 pc.
1005729	Vice-grip pliers, Knipex System Oetiker 1099	1 pc.



### **Definitions**

# Pressure-sensitive protection device

A pressure-sensitive protection device consists of one or more pressure-sensitive sensors, a signal processing unit, and one or more output signal switching devices. The control unit is made up of the signal processing unit and output signal switching device(s). The pressure-sensitive protection device is triggered when the sensor is activated.

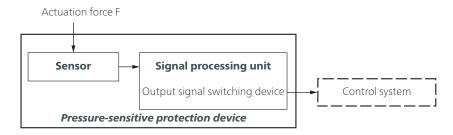


#### Sensor

The sensor is the part of the pressure-sensitive protection device that generates a signal when the actuation force F is applied. Mayser safety systems feature a sensor whose actuating surface is deformed locally.

#### Signal processing unit

The signal processing unit is the part of the pressure-sensitive protection device that converts the output signal of the sensor and controls the status of the output signal switching device. The output signal switching device is the part of the signal processing unit which is connected to the forwarding control system and which transmits safety output signals such as STOP.

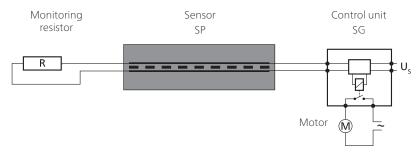


Tip: Terms are defined in ISO 13856-2 Section 3.

#### Criteria for selecting the sensor type

- Category according to ISO 13849-1
- Performance level of the pressure-sensitive protection device
   at least PL<sub>2</sub>
- Temperature range
- Degree of protection in accordance with IEC 60529:
   IP67 is the standard for safety edges.
   Higher degrees of protection must be checked individually.
- Environmental influences such as swarf, oil, coolant, outdoor use...
- Finger detection necessary?

# Operation principle of 2-wire technology



The monitoring resistor must be compatible with the control unit. The standard type is 8k2.

#### For your safety:

The sensor and connecting cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on controlled bridging of the contact surfaces with a monitoring resistor (closed-circuit principle).

#### **Types**

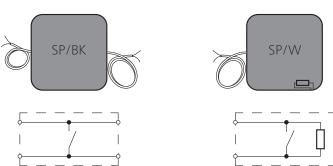
SP/BK With cables on both sides for use as a through sensor or

with an external monitoring resistor for use as an end

sensor

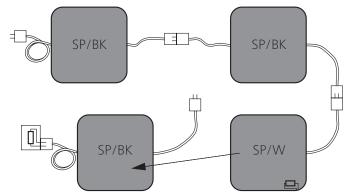
SP/W With an integrated monitoring resistor for use as an end

sensor





#### **Sensor combination**

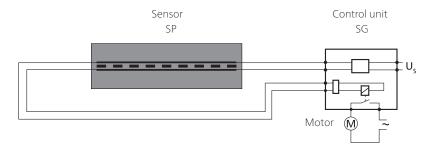


Version with external resistor, therefore no variety of models

#### Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety edge design with custom lengths and angles

# Operation principle of 4-wire technology



The 4-wire technology can only be used together with control unit SG-EFS 104/4L.

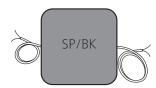
#### For your safety:

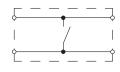
The sensor and connecting cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on signal transmission feedback – without a monitoring resistor.

#### **Types**

SP/BK

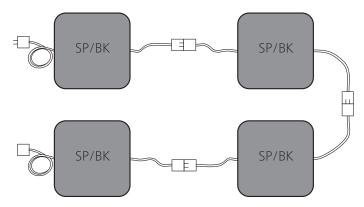
With cables on both sides for use as a through sensor







#### **Sensor combination**



#### Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety edge design with custom lengths and angles

### **Safety**

### Intended use

A safety edge detects a person or part of the body when pressure is applied to the effective actuation area. It is a linear tripping device. Its task is to prevent possible hazardous situations that could affect someone within a danger zone, such as shearing and pinching edges.

Typical areas of application are door and gate systems, moving parts on machines, platforms and lifting devices.

Safe operation of a safety edge depends entirely on

- the surface condition of the mounting surface,
- the correct selection of the size and resistance rating as well as
- correct installation.

For additional application guidelines, please refer to ISO 13856-2 Annex E.

Due to the design, the actuation area is actually smaller than it looks because of the non-sensitive edges. Once these have been allowed for, what remains is the effective actuation area (see chapter *Effective actuation area*).

### Limits

- No more than 5 /BK-type sensors can be connected to one control unit.
- No more than 4 /BK-type sensors and 1 /W-type sensor can be connected to one control unit.

### **Exclusions**

The sensors are not suitable for:

• performing a sealing function. Constant actuation of sensors can result in permanent damage.

**Exception:** The L version with an attached lip seal.

The lip seal can be in full contact with the closing edge, which allows it to repel wind and water.

# Selecting the appropriate product line

If you opt for our line of SP DIY sensor profiles that have to be assembled with tools, the maximum class of protection that can be achieved is IP68 and IPX8 (20 weeks). If a class of protection of IP67 or IPX8 (13 days) is sufficient for your application, we recommend using our line of SP DIY sensor profiles for **toolless** self-assembly instead.

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### Other safety aspects

The following safety aspects relate to pressure-sensitive protection devices consisting of a sensor and a control unit.

#### **Performance Level (PL)**

The PL has been determined using the procedure defined by ISO 13849-1.

Fault exclusion according to ISO 13849-2 Table D.8: Non-closing of contacts by pressure-sensitive equipment according to ISO 13856. In this case, the diagnostic coverage (DC) is not calculated or taken into account when determining the PL. Assuming a high MTTF<sub>D</sub> value for the control unit, a performance level of up to PL d can be achieved by the safety edge system (pressure-sensitive protection device) as a whole.

#### Is the protection device suitable?

First, the integrator must decide what PL<sub>r</sub> is required for the hazard. After that, they must select the protection device.

Finally, the integrator needs to check whether the category and PL of the selected protection device are appropriate.

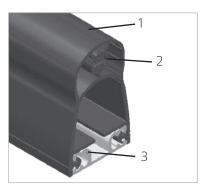
#### Risk and safety assessment

For the risk and safety assessment of your machine, we recommend ISO 12100 "Safety of machinery — General principles for design".

#### Without reset function

When a protection device without reset function is used (automatic reset), the reset function must be provided in some other way.

### **Design**



one sensor (1 to 3)
(1) SP contact profile with
(2) integrated normally open
switching element,
(3) aluminium profile and an
evaluating control unit SG.

The SP sensor profile consists of

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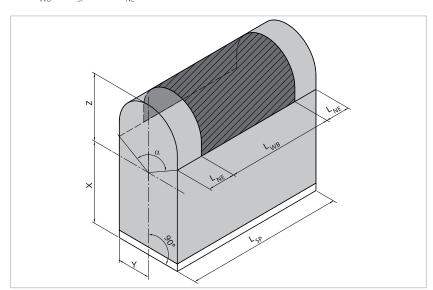


### Effective actuation area

The parameters X, Y, Z,  $L_{WB}$  and the angle  $\,\alpha\,$  describe the effective actuation area.

For the effective actuation area, the following applies:

$$L_{WB} = L_{SP} - 2 \times L_{NE}$$



#### Parameters:

 $L_{WB}$ = effective actuation length

 $L_{SP}$  = total length of sensor profile

 $L_{NE}$  = non-sensitive length at end of sensor profile

 $\alpha$  = effective actuation angle

	SP 17-3 <sup>1)</sup>	SP 37-1	SP 37(L)-2	SP 37-3	SP 57(L)-2	SP 57-3	SP 57(L)-4	SP 67-2	SP 87-2
	<b>8</b>								
Incl.	C 15	C 25	C 26	C 25	C 30	C 35	C 35	C 30	C 36
α	90°	100°	100°	100°	90°	90°	90°	90°	90°
L <sub>NE</sub>	60 mm	20 mm	20 mm	20 mm	10 mm <sup>2)</sup>	10 mm <sup>2)</sup>	10 mm <sup>2)</sup>	20 mm <sup>2)</sup>	10 mm <sup>2)</sup>
Υ	6.7 mm	12.5 mm	13 mm	12.5 mm	17 mm	17.5 mm	17.5 mm	17 mm	18.1 mm
X	15.3 mm	28.5 mm	30 mm	29 mm	44 mm	52 mm	52 mm	57.3 mm	72 mm
Z	5 mm	9 mm	9 mm <sup>3)</sup>	9 mm	12 mm <sup>3)</sup>	12 mm	12 mm <sup>3)</sup>	10 mm	15 mm
X + Z	20.3 mm	37.5 mm	39 mm <sup>3)</sup>	38 mm	56 mm <sup>3)</sup>	64 mm	64 mm <sup>3)</sup>	67.3 mm	87 mm

<sup>1)</sup> without end cap

## Installation position

The installation position can be selected as required, i.e. all installation positions from A to D as per ISO 13856-2 are possible.

<sup>&</sup>lt;sup>2)</sup> with finger protection

<sup>3)</sup> without lip

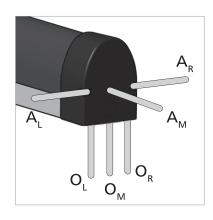
# **Connection**

# Cable exits

Depending on the end cap, the following cable exits are available.

 $\begin{array}{lll} \textbf{A}_{L} &=& \text{axial left} \\ \textbf{A}_{M} &=& \text{axial middle} \\ \textbf{A}_{R} &=& \text{axial right} \\ \textbf{O}_{L} &=& \text{orthogonal left} \\ \textbf{O}_{M} &=& \text{orthogonal middle} \end{array}$ 

 $O_R$  = orthogonal right



			Cable	e exit			
Lateral exit				$A_R$			
	Axial exit		A <sub>M</sub>				
	90° exit				O <sub>L</sub>	O <sub>M</sub>	O <sub>R</sub>
Combi	nation						
Contact profile	Set of end caps						
SP 17-3	_					•	
SP 37-1	7503008	•		•	•		•
SP 37(L)-2	7503988	•	•	•		•	
SP 37-3 black	7503505	•		•	•		•
SP 37-3 red	7503654	•		•	•		•
CD [7/1] 2	7503062	•	•	•		•	
SP 57(L)-2	7503603	•	•	•		•	
SP 57-3	7503618	•	•	•		•	
SP 57(L)-4	7503796	•	•	•	•		•
SP 67-2	7503655	•	•	•		•	
SP 87-2	7504118	•	•	•		•	

• = possible



### Cable connection

- Standard cable lengthsL = 2.5 m / 5.0 m / 10 m
- Maximum total cable length to the control unit  $L_{max} = 100 \text{ m}$

/W-type sensor with 1 line	/BK-type sensor with 2 lines
<ul> <li>As an individual /W-type sensor or a /W-type end sensor</li> <li>Integrated resistor</li> <li>1 two-wire cable</li> </ul>	<ul> <li>As a /BK-type through sensor</li> <li>Without resistor</li> <li>2 two-wire cables</li> </ul>

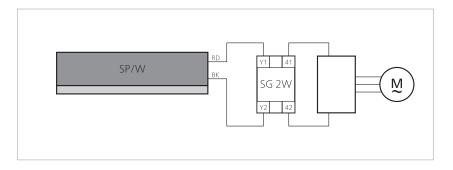
### Wire colours

/W-type sensor with 1 line	/BK-type sensor with 2 lines
RD I BK	RD ← ← → RD   BK ← → BK

# Connection examples

Key:

SG 2W evaluation with 2-wire technology SG 4L evaluation with 4-wire technology



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Subject to technical modifications.

**Colour coding** 

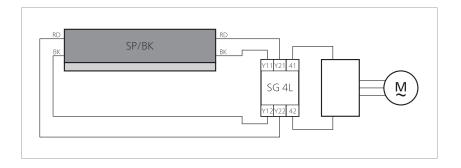
Black

Red

ВК

RD





### **Sensor surface**

### Resistance

The resistance ratings listed below (at a room temperature of 23 °C) depend on the sensor having an undamaged surface.

#### **Physical resistance**

	TPE
UV resistance	Yes

#### **Chemical resistance**

The sensor is broadly resistant to normal chemical influences such as diluted acids and alkalis, as well as alcohol, over an exposure period of 24 hrs.

The values in the table are the results of tests carried out in our laboratory. You must always conduct your own practical tests to verify that our products are suitable for your specific area of application.



### **Explanation of symbols:**

+ = resistant

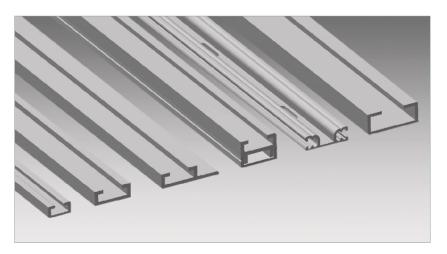
 $\pm$  = resistant to a certain extent

- = not resistant

Material	TPE
Acetone	-
Formic acid	-
Armor All	+
Car shampoo	+
Petrol	_
Brake fluid	+
Buraton	+
Butanol	-
Sodium hypochlorite	_
Disinfectant 1%	+
Diesel	-
Acetic acid 10%	-
Ethanol	+
Ethyl acetate	_
Ethylene glycol	+
Greases	±
Anti-frost agent	+
Skin cream	+
Incidin	+
Incidin Plus	+
Cooling lubricant	_
Plastic cleaner	+
Lyso FD 10	+
Metal working oil	_
Microbac	+
Microbac forte	+
Minutil	+
Saline solution 5%	+
Spirit (ethyl alcohol)	+
Terralin	+
Centring oil	-

# **Mounting**

The sensors are mounted directly onto the main and secondary closing edges that present a danger. They are fixed using special aluminium profiles. The profiles are fastened with screws or rivets.



#### **Material properties**

- AlMgSi0.5 F22
- Wall thickness at least
   2.0 mm
   C 15: at least 1.7 mm
  - C 30: at least 1.5 mm
- Extruded
- Hot hardened
- Tolerances as per EN 755-9

# Aluminium profiles: Overview of combinations

Sensor pr	ofile foot	C 15	C 25 C 25M C 25S C 25L	C 26 C 26M	C 30	C 35 C 35M C 35S	C 36 C 36M C 36S C 36L
Snap-in foot (middle)	1	-	SP 37-1	_	_	_	_
Clip bars (outside)	2	_	_	SP 37(L)-2	SP 57(L)-2 SP 67-2	_	SP 87-2
T-foot (middle)	3	SP 17-3	SP 37-3	_	_	SP 57-3	_
T-foot narrow (middle)	4	-	_	_	_	SP 57(L)-4	_



### Aluminium profiles: Mounting types

#### **Standard profile**

First the aluminium profile must be mounted onto the closing edge and then the sensor profile clipped into the aluminium profile.

C 15	C 25	C 26	C 30	C 35	C 36
		<u> </u>			

#### Two-part profile, type M

For convenient assembly and disassembly. The sensor profile is clipped into the upper section and the upper section inserted into the installed lower section and fastened.

-	C 25M	C 26M	C 35M	C 36M

#### Flange profile, type S

Final assembly is also possible when the sensor profile is already clipped into the aluminium profile.

-	C 25S	-	C 35S	C 36S

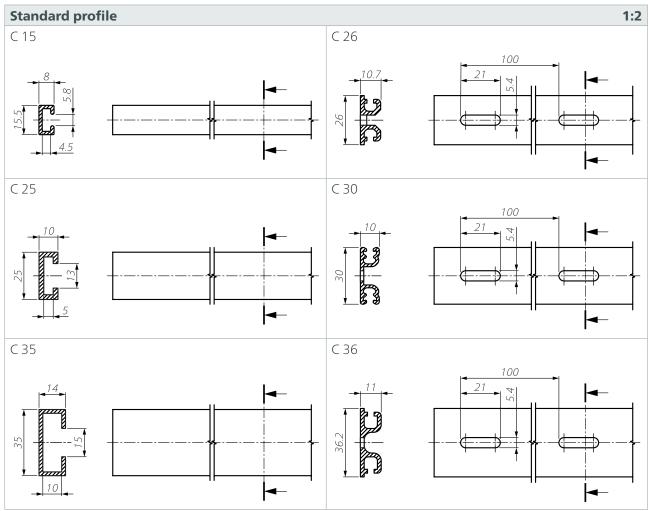
#### Angle profile, type L

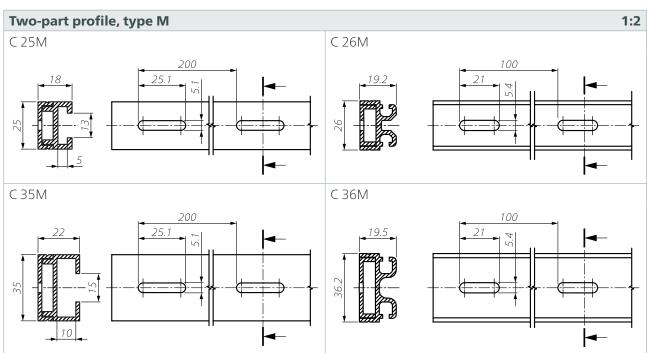
If the closing edge should or must not have assembly holes, this "round-the-corner" solution is suitable. Final assembly is also possible when the sensor profile is already clipped into the aluminium profile.

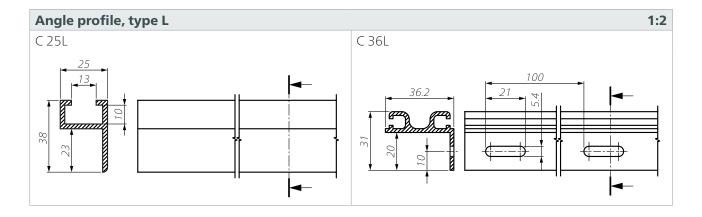


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# Aluminium profiles: Dimensions









- s<sub>1</sub> = Stopping distance of the dangerous movement [ mm ]
- v = Velocity of the dangerous movement [ mm/s ]
- T = Follow-through time of the complete system [s]
- $t_1$  = Safety edge response time
- t<sub>2</sub> = Stopping time of the machine
- s = Minimum overtravel distance of the safety edge to ensure that the stipulated limit forces are not exceeded [ mm ]
- C = Safety factor; if components susceptible to failures (braking system) exist in the system, a higher factor must be selected.

### **SP: Making the right selection**

# Calculation for selection of the safety edge height

The stopping distance of the dangerous movement is calculated using the following formula:

$$s_1 = 1/2 \times v \times T$$
 where:  $T = t_1 + t_2$ 

In accordance with ISO 13856-2, the minimum overtravel distance of the safety edge is calculated using the following formula:

$$s = s_1 \times C$$
 where:  $C = 1.2$ 

A suitable safety edge profile can now be selected based on the result. For details of the overtravel distances for safety edge profiles, see chapter *Technical data*.

## Calculation examples

#### **Calculation example 1**

The dangerous movement on your machine has a velocity of v=10 mm/s and can be brought to a standstill within  $t_2=200$  ms. The relatively low velocity suggests that a short overtravel distance is to be expected. Therefore, the sensor profile SP 37-1 TPE could be sufficient. The response time of the safety edge (SP 37-1 TPE + control unit\*) is  $t_1=600$  ms.

$$s_1 = 1/2 \times v \times T$$
 where:  $T = t_1 + t_2$   
 $s_1 = 1/2 \times 10 \text{ mm/s} \times (0.6 \text{ s} + 0.2 \text{ s})$   
 $s_1 = 1/2 \times 10 \text{ mm/s} \times 0.8 \text{ s} = 4.0 \text{ mm}$ 

$$s = s_1 \times C$$
 where:  $C = 1.2$   
 $s = 4.0 \text{ mm} \times 1.2 = 4.8 \text{ mm}$ 

The safety edge must have a minimum overtravel distance of s = 4.8 mm. The selected SP 37-1 TPE has an overtravel distance of at least 9.2 mm. This is more than the required 4.8 mm.

**Result:** The SP 37-1 TPE is **suitable** for this case.

Subject to technical modifications.

<sup>\*</sup> Assumption: Typical reaction time of a control unit = 20 ms



#### **Calculation example 2**

The same conditions apply as in calculation example 1 with the exception of the velocity of the dangerous movement. This is now v = 200 mm/s. The response time of the safety edge (SP 37-1 TPE + control unit\*) is  $t_1 = 55 \text{ ms}$ .

$$s_1 = 1/2 \times v \times T$$
 where:  $T = t_1 + t_2$   
 $s_1 = 1/2 \times 200 \text{ mm/s} \times (0.055 \text{ s} + 0.2 \text{ s})$   
 $s_1 = 1/2 \times 200 \text{ mm/s} \times 0.255 \text{ s} = 25.5 \text{ mm}$ 

$$s = s_1 \times C$$
 where:  $C = 1.2$   
 $s = 25.5 \text{ mm} \times 1.2 = 30.6 \text{ mm}$ 

The safety edge must have a minimum overtravel distance of s = 30.6 mm. The selected SP 37-1 TPE has an overtravel distance of at least 3.8 mm. This is less than the required 30.6 mm.

**Result:** The SP 37-1 TPE is **not suitable** for this case.

#### **Calculation example 3**

The same conditions apply as in calculation example 2. Instead of SP 37-1 EPDM, the SP 67-1 TPE is selected. The response time of the safety edge (SP 67-2 TPE + control unit\*) is  $t_1 = 72$  ms.

$$s_1 = 1/2 \times v \times T$$
 where:  $T = t_1 + t_2$   
 $s_1 = 1/2 \times 200 \text{ mm/s} \times (0.072 \text{ s} + 0.2 \text{ s})$   
 $s_1 = 1/2 \times 200 \text{ mm/s} \times 0.272 \text{ s} = 27.2 \text{ mm}$ 

$$s = s_1 \times C$$
 where:  $C = 1.2$   
 $s = 27.2 \text{ mm} \times 1.2 = 32.6 \text{ mm}$ 

The safety edge must have a minimum overtravel distance of s = 32.6 mm. The selected SP 67-2 TPE has an overtravel distance of at least 36.5 mm. This is more than the required 32.6 mm.

**Result:** The SP 67-2 TPE is **suitable** for this case.

131221 V3.12-1

<sup>\*</sup> Assumption: Typical reaction time of a control unit = 20 ms



# **Maintenance and cleaning**

The sensors are virtually maintenance-free.

The control unit also monitors the sensor at the same time.

#### **Regular inspection**

Depending on the operational demands, the sensors must be inspected at regular intervals (at least monthly)

- for proper functioning,
- for damage and
- for correct mounting

#### Cleaning

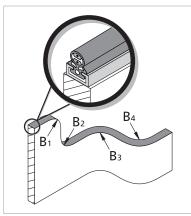
If the sensors become dirty, they can be cleaned with a mild cleaning product.

31221 v3 12



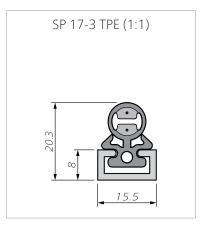
# SK SP 17-3 TPE

Sensor profile (without control unit)	SK SP/W 17-3 TPE or SK SP/BK 17-3 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at $v_{test} = 10 \text{ mm/s}$	
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	1.5 mm
Test piece (cylinder) Ø 80 mm	±45°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 80 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum $B_1 / B_2 / B_3 / B_4$	200 / 200 / 50 / 50 mm
Operating velocity (min. / max.)	10 mm/s / 10 mm/s
Max. load capacity (impulse)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: Degree of protection	IP68
SP in water: 9 cm bottom edge	IPX8: 20 weeks
Operating temperature	−25 to +55 °C
short-term (15 min)	-40 to +80 °C
Storage temperature	−40 to +80 °C
Weight	SP 17-3
without aluminium profile	0.12 kg/m
with aluminium profile C 15	0.28 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>





# Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

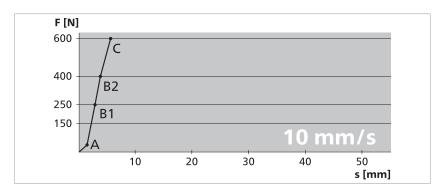
# **Test conditions** according to ISO 13856-2

- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø
   80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.

#### **Force-distance ratios**

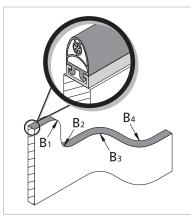
Test velocity	10 mm/s
Actuation force	38 N
Response time	140 ms
Actuation distance (A)	1.4 mm
Overtravel distance	
up to 250 N (B1)	1.4 mm
up to 400 N (B2)	2.3 mm
up to 600 N (C)	4.1 mm
Total deformation	5.5 mm





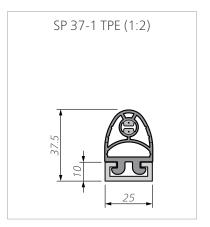
# **SK SP 37-1 TPE**

Sensor profile (without control unit)	SK SP/W 37-1 TPE or SK SP/BK 37-1 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v <sub>test</sub> =	100 mm/s
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	6 mm
Test piece (cylinder) Ø 80 mm	±50°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 30 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	500 / 500 / 200 / 200 mm
Operating velocity	10 / 200
(min. / max.)	10 mm/s / 200 mm/s
Max. load capacity (impulse) Tensile load, cable (max.)	600 N 20 N
IEC 60529: Degree of protection	IP68
SP in water: 9 cm bottom edge	IPX8: 20 weeks
Operating temperature	-25 to +55 °C
short-term (15 min)	-40 to +80 °C
Storage temperature	-40 to +80 °C
Weight	SP 37-1
without aluminium profile	0.33 kg/m
with aluminium profile C 25	0.64 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>





# Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

**Test conditions** according to ISO 13856-2

- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø
   80 mm

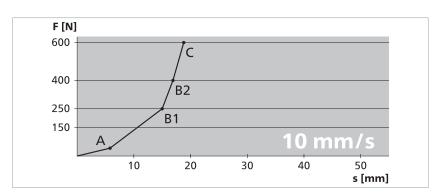
All datal soute connered is raio cumented in EC type examination certificates.

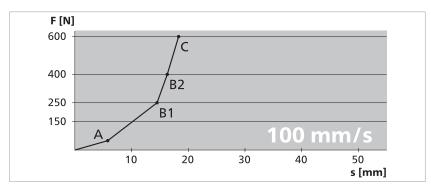
#### **Force-distance ratios**

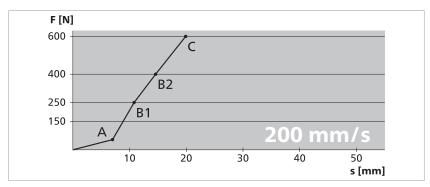
Test velocity	10 mm/s
Actuation force	42 N
Response time	580 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	9.2 mm
up to 400 N (B2)	11.1 mm
up to 600 N (C)	13.0 mm
Total deformation	18.8 mm

Test velocity 1	00 mm/s
Actuation force	50 N
Response time	58 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	8.7 mm
up to 400 N (B2)	10.5 mm
up to 600 N (C)	12.5 mm
Total deformation	18.3 mm

Test velocity <b>2</b> 0	00 mm/s
Actuation force	54 N
Response time	35 ms
Actuation distance (A)	7.0 mm
Overtravel distance	
up to 250 N (B1)	3.8 mm
up to 400 N (B2)	7.6 mm
up to 600 N (C)	12.9 mm
Total deformation	19.9 mm



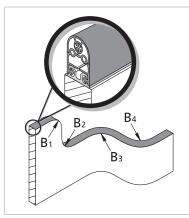






# SK SP 37(L)-2 TPE

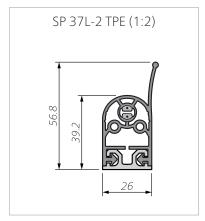
Sensor profile (without control unit)	SK SP/W 37(L)-2 TPE or SK SP/BK 37(L)-2 TPE	
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2	
Switching characteristics at v <sub>test</sub> =	100 mm/s	
Switching operations Actuation force	10,000	
Test piece (rod) Ø 20 mm	< 50 N	
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N	
Test piece (cylinder) Ø 80 mm Actuation angle	6 mm	
Test piece (cylinder) Ø 80 mm Finger detection	±50° Yes	
Safety classifications		
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>	
Mechanical operating conditions		
Sensor length (min./max.)	10 cm / 30 m	
Cable length (min./max.)	10 cm / 100 m	
Bend radii, minimum		
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	500 / 500 / 200 / 200 mm	
Operating velocity		
(min. / max.)	10 mm/s / 200 mm/s	
Max. load capacity (impulse)	600 N	
Tensile load, cable (max.)	20 N	
IEC 60529: Degree of protection	IP68	
SP in water: 9 cm bottom edge	IPX8: 20 weeks	
Operating temperature	−25 to +55 °C	
short-term (15 min)	−40 to +80 °C	
Storage temperature	-40 to +80 °C	
Weight	SP 37-2 SP 37L-2	
without aluminium profile	0.36 kg/m 0.41 kg/m	
with aluminium profile C 26	0.69 kg/m 0.74 kg/m	
<b>Electrical operating conditions</b>		
Terminal resistance	8k2 ±1%	
Nominal output (max.)	250 mW	
Contact transition resistance	< 400 ohms (per sensor)	
Number of BK-type sensors	Max. 5 in series	
Switching voltage (max.)	DC 24 V	
Switching current (min./max.)	1 mA / 10 mA	
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>	



# SP 37-2 TPE (1:2)

Dimensional tolerances according to ISO 3302 E2/L2

# Dimensions and distances



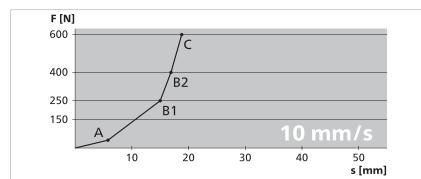
Dimensional tolerances according to ISO 3302 E2/L2

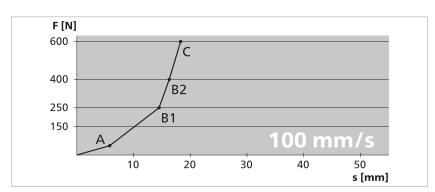
# **Test conditions** according to ISO 13856-2

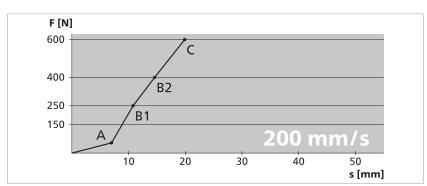
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit
- Lip not taken into account

All data stated here is documented in EC type examination certificates.

#### **Force-distance ratios**







# 10 mm/s

Actuation force 42 N 580 ms Response time Actuation distance (A) 5.8 mm Overtravel distance

Test velocity

up to 250 N (B1) 9.2 mm up to 400 N (B2) 11.1 mm up to 600 N (C) 13.0 mm Total deformation 18.8 mm

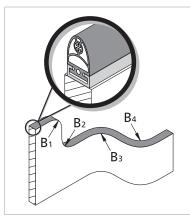
Test velocity 1	00 mm/s
Actuation force	50 N
Response time	58 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	8.7 mm
up to 400 N (B2)	10.5 mm
up to 600 N (C)	12.5 mm
Total deformation	18.3 mm

Test velocity 20	00 mm/s
Actuation force	54 N
Response time	35 ms
Actuation distance (A)	7.0 mm
Overtravel distance	
up to 250 N (B1)	3.8 mm
up to 400 N (B2)	7.6 mm
up to 600 N (C)	12.9 mm
Total deformation	19.9 mm



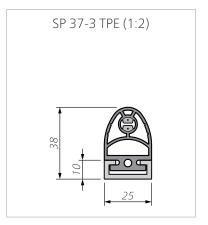
# **SK SP 37-3 TPE**

Sensor profile (without control unit)	SK SP/W 37-3 TPE or SK SP/BK 37-3 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v <sub>test</sub> = 100 mm/s	
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	6 mm
Test piece (cylinder) Ø 80 mm	±50°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 30 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	F00 / F00 / 200 / 200
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub> Operating velocity	500 / 500 / 200 / 200 mm
(min. / max.)	10 mm/s / 200 mm/s
Max. load capacity (impulse)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: Degree of protection	IP68
SP in water: 9 cm bottom edge	IPX8: 20 weeks
Operating temperature	−25 to +55 °C
short-term (15 min)	−40 to +80 °C
Storage temperature	−40 to +80 °C
Weight	SP 37-3
without aluminium profile	0.34 kg/m
with aluminium profile C 25	0.66 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>





# Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

# **Test conditions** according to ISO 13856-2

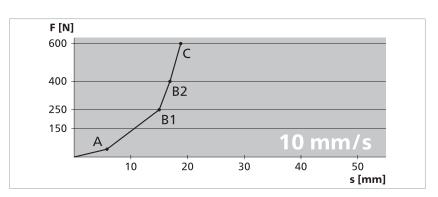
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

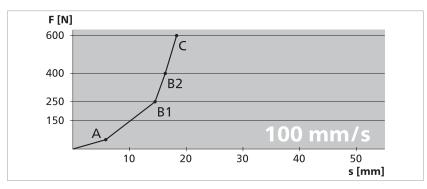
#### **Force-distance ratios**

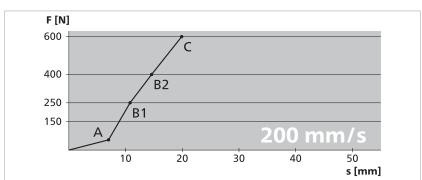
Test velocity	10 mm/s
Actuation force	42 N
Response time	580 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	9.2 mm
up to 400 N (B2)	11.1 mm
up to 600 N (C)	13.0 mm
Total deformation	18.8 mm

Test velocity 1	00 mm/s
Actuation force	50 N
Response time	58 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	8.7 mm
up to 400 N (B2)	10.5 mm
up to 600 N (C)	12.5 mm
Total deformation	18.3 mm

Test velocity 2	00 mm/s
Actuation force	54 N
Response time	35 ms
Actuation distance (A)	7.0 mm
Overtravel distance	
up to 250 N (B1)	3.8 mm
up to 400 N (B2)	7.6 mm
up to 600 N (C)	12.9 mm
Total deformation	19.9 mm



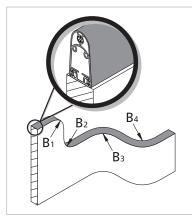






# SK SP 57(L)-2 TPE

Sensor profile (without control unit)	SK SP/W 57(L)-2 TPE or SK SP/BK 57(L)-2 TPE	
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2	
Switching characteristics at v <sub>test</sub> =	100 mm/s	
Switching operations Actuation force	10,000	
Test piece (rod) Ø 20 mm	< 50 N	
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N	
Test piece (cylinder) Ø 80 mm Actuation angle	8 mm	
Test piece (cylinder) Ø 80 mm	±45°	
Finger detection	Yes	
Safety classifications		
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>	
Mechanical operating conditions		
Sensor length (min./max.)	10 cm / 30 m	
Cable length (min./max.)	10 cm / 100 m	
Bend radii, minimum		
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	1000 / 1000 / 200 / 200 mm	
Operating velocity		
(min. / max.)	10 mm/s / 200 mm/s	
Max. load capacity (impulse)	600 N	
Tensile load, cable (max.)	20 N	
IEC 60529: Degree of protection	IP68	
SP in water: 9 cm bottom edge	IPX8: 20 weeks	
Operating temperature	-25 to +55 °C	
short-term (15 min)	-40 to +80 °C	
Storage temperature	-40 to +80 °C	
Weight	SP 57-2 SP 57L-2	
without aluminium profile	0.44 kg/m 0.47 kg/m	
with aluminium profile C 30	0.74 kg/m 0.77 kg/m	
Electrical operating conditions		
Terminal resistance	8k2 ±1%	
Nominal output (max.)	250 mW	
Contact transition resistance	< 400 ohms (per sensor)	
Number of BK-type sensors	Max. 5 in series	
Switching voltage (max.)	DC 24 V	
Switching current (min./max.)	1 mA / 10 mA	
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>	



# SP 57-2 TPE (1:2)

Dimensional tolerances according to ISO 3302 E2/L2

10 mm/s

48 N

910 ms

9.1 mm

24.5 mm

29.3 mm

31.0 mm

40.1 mm

39.5 mm

40.1 mm

Test velocity

Actuation force

Response time

Actuation distance (A)

up to 250 N (B1)

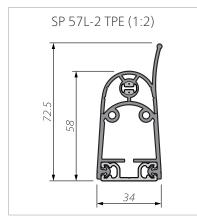
up to 400 N (B2)

up to 600 N (C)

Overtravel distance

Total deformation

# Dimensions and distances



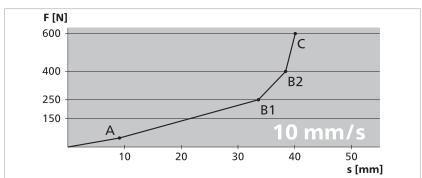
Dimensional tolerances according to ISO 3302 E2/L2

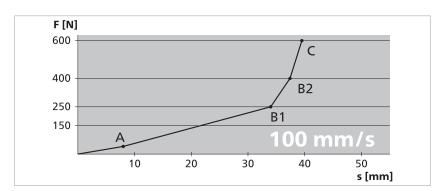
# **Test conditions** according to ISO 13856-2

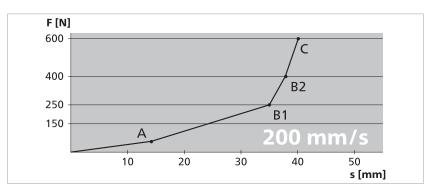
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit
- Lip not taken into account

All data stated here is documented in EC type examination certificates.

#### **Force-distance ratios**







Total deformation Test velocity 100 mm/s Actuation force 41 N Response time 80 ms Actuation distance (A) 8.0 mm Overtravel distance up to 250 N (B1) 26.0 mm up to 400 N (B2) 29.4 mm up to 600 N (C) 31.5 mm

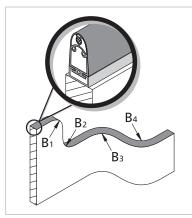
Test velocity 2	00 mm/s
Actuation force	58 N
Response time	71 ms
Actuation distance (A)	14.2 mm
Overtravel distance	
up to 250 N (B1)	20.8 mm
up to 400 N (B2)	23.7 mm
up to 600 N (C)	25.9 mm

Total deformation



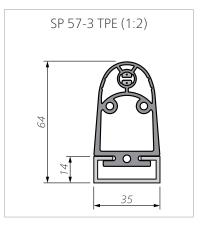
# **SK SP 57-3 TPE**

Sensor profile (without control unit)	SK SP/W 57-3 TPE or SK SP/BK 57-3 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v <sub>test</sub> =	100 mm/s
Switching operations	10,000
Actuation force	
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm	< 150 N
Actuation distance	0, 100, 100
Test piece (cylinder) Ø 80 mm	8 mm
Actuation angle Test piece (cylinder) Ø 80 mm	±45°
Finger detection	Yes
Safety classifications	103
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 25 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	10 (1117 100 111
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	1000 / 1000 / 200 / 200 mm
Operating velocity	
(min. / max.)	10 mm/s / 200 mm/s
Max. load capacity (impulse)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: Degree of protection	IP68
SP in water: 9 cm bottom edge	IPX8: 20 weeks
Operating temperature	−25 to +55 °C
short-term (15 min)	-40 to +80 °C
Storage temperature	-40 to +80 °C
Weight	SP 57-3
without aluminium profile	0.60 kg/m
with aluminium profile C 35	1.00 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching current (min./max.)	DC 24 V
Switching current (min./max.) Connection cable	1 mA / 10 mA Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>
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# Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

# **Test conditions** according to ISO 13856-2

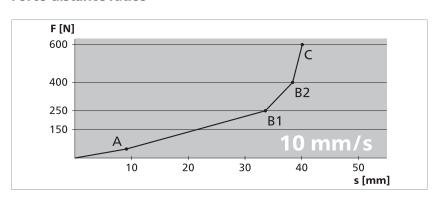
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø
   80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

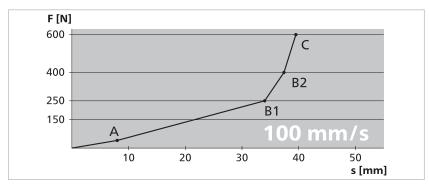
#### **Force-distance ratios**

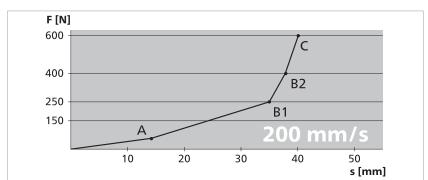
Test velocity	10 mm/s
Actuation force	48 N
Response time	910 ms
Actuation distance (A)	9.1 mm
Overtravel distance	
up to 250 N (B1)	24.5 mm
up to 400 N (B2)	29.3 mm
up to 600 N (C)	31.0 mm
Total deformation	40.1 mm

Test velocity 1	00 mm/s
Actuation force	41 N
Response time	80 ms
Actuation distance (A)	8.0 mm
Overtravel distance	
up to 250 N (B1)	26.0 mm
up to 400 N (B2)	29.4 mm
up to 600 N (C)	31.5 mm
Total deformation	39.5 mm

Test velocity 2	00 mm/s
Actuation force	58 N
Response time	71 ms
Actuation distance (A)	14.2 mm
Overtravel distance	
up to 250 N (B1)	20.8 mm
up to 400 N (B2)	23.7 mm
up to 600 N (C)	25.9 mm
Total deformation	40.1 mm



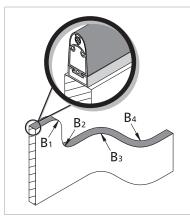






# SK SP 57(L)-4 TPE

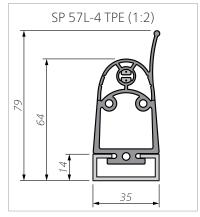
Sensor profile (without control unit)	SK SP/W 57(L)-4 TPE or SK SP/BK 57(L)-4 TPE	
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2	
Switching characteristics at v <sub>test</sub> = 100 mm/s		
Switching operations Actuation force	10,000	
Test piece (rod) Ø 20 mm	< 50 N	
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N	
Test piece (cylinder) Ø 80 mm Actuation angle	8 mm	
Test piece (cylinder) Ø 80 mm	±45°	
Finger detection	Yes	
Safety classifications		
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>	
Mechanical operating conditions		
Sensor length (min./max.)	10 cm / 25 m	
Cable length (min./max.)	10 cm / 100 m	
Bend radii, minimum	4000 / 4000 / 200 / 200	
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	1000 / 1000 / 200 / 200 mm	
Operating velocity (min. / max.)	10 mm/s / 200 mm/s	
Max. load capacity (impulse)	600 N	
Tensile load, cable (max.)	20 N	
IEC 60529: Degree of protection	IP68	
SP in water: 9 cm bottom edge	IPX8: 20 weeks	
Operating temperature	−25 to +55 °C	
short-term (15 min)	−40 to +80 °C	
Storage temperature	-40 to +80 °C	
Weight	SP 57-4 SP 57L-4	
without aluminium profile with aluminium profile C 35	0.58 kg/m 0.62 kg/m 0.99 kg/m 1.03 kg/m	
	0.99 kg/111 1.03 kg/111	
Electrical operating conditions	01.2 . 10/	
Terminal resistance Nominal output (max.)	8k2 ±1% 250 mW	
Contact transition resistance	< 400 ohms (per sensor)	
Number of BK-type sensors	Max. 5 in series	
Switching voltage (max.)	DC 24 V	
Switching current (min./max.)	1 mA / 10 mA	
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>	



# SP 57-4 TPE (1:2)

Dimensional tolerances according to ISO 3302 E2/L2

# Dimensions and distances



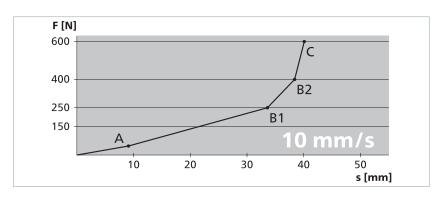
Dimensional tolerances according to ISO 3302 E2/L2

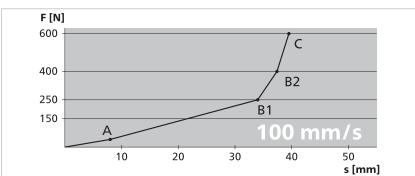
# **Test conditions** according to ISO 13856-2

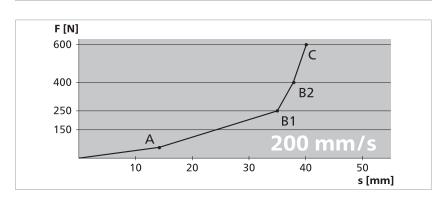
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit
- Lip not taken into account

All data stated here is documented in EC type examination certificates.

#### **Force-distance ratios**







**10 mm/s** 48 N

Actuation force 48 N Response time 910 ms Actuation distance (A) 9.1 mm

Overtravel distance

Test velocity

up to 250 N (B1) 24.5 mm up to 400 N (B2) 29.3 mm up to 600 N (C) 31.0 mm Total deformation 40.1 mm

Test velocity 100 mm/s
Actuation force 41 N
Response time 80 ms
Actuation distance (A) 8.0 mm
Overtravel distance

up to 250 N (B1) 26.0 mm up to 400 N (B2) 29.4 mm up to 600 N (C) 31.5 mm Total deformation 39.5 mm

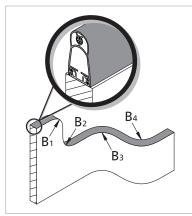
Test velocity 200 mm/s
Actuation force 58 N
Response time 71 ms
Actuation distance (A) 14.2 mm
Overtravel distance

up to 250 N (B1) 20.8 mm up to 400 N (B2) 23.7 mm up to 600 N (C) 25.9 mm Total deformation 40.1 mm

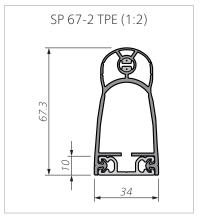


# **SK SP 67-2 TPE**

Sensor profile (without control unit)	SK SP/W 67-2 TPE or SK SP/BK 67-2 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v <sub>test</sub> =	100 mm/s
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm Test piece (cylinder) Ø 80 mm Actuation distance	< 50 N < 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	11 mm
Test piece (cylinder) Ø 80 mm Finger detection	± 45° Yes
Safety classifications	
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>
Mechanical operating conditions	
Sensor length (min./max.) Cable length (min./max.) Bend radii, minimum B1 / B2 / B3 / B4 Operating velocity (min. / max.) Max. load capacity (impulse) Tensile load, cable (max.) IEC 60529: Degree of protection SP in water: 9 cm bottom edge Operating temperature short-term (15 min) Storage temperature Weight without aluminium profile C 30	10 cm / 30 m 10 cm / 100 m 1000 / 1000 / 200 / 200 mm 10 mm/s / 200 mm/s 600 N 20 N IP68 IPX8: 20 weeks -25 to +55 °C -40 to +80 °C -40 to +80 °C SP 67-2 0.49 kg/m 0.79 kg/m
Electrical operating conditions	
Terminal resistance Nominal output (max.) Contact transition resistance Number of BK-type sensors Switching voltage (max.) Switching current (min./max.) Connection cable	8k2 ±1% 250 mW < 400 ohms (per sensor) Max. 5 in series DC 24 V 1 mA / 10 mA Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>



# Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

# **Test conditions** according to ISO 13856-2

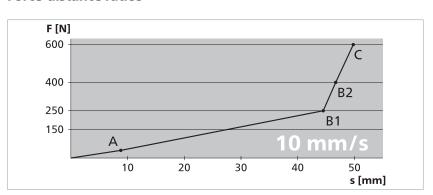
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

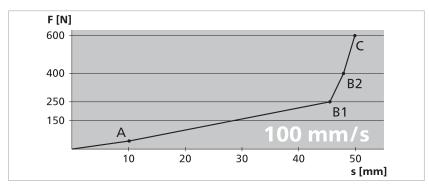
#### **Force-distance ratios**

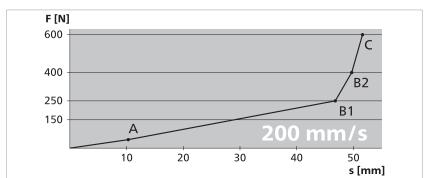
Test velocity	10 mm/s
Actuation force	41 N
Response time	880 ms
Actuation distance (A)	8.8 mm
Overtravel distance	
up to 250 N (B1)	35.7 mm
up to 400 N (B2)	37.9 mm
up to 600 N (C)	41 mm
Total deformation	49.8 mm

Test velocity <b>1</b>	00 mm/s
Actuation force	43 N
Response time	101 ms
Actuation distance (A)	10.1 mm
Overtravel distance	
up to 250 N (B1)	35.4 mm
up to 400 N (B2)	37.8 mm
up to 600 N (C)	39.8 mm
Total deformation	49.9 mm

Test velocity 20	00 mm/s
Actuation force	45 N
Response time	51.5 ms
Actuation distance (A)	10.3 mm
Overtravel distance	
up to 250 N (B1)	36.5 mm
up to 400 N (B2)	39.4 mm
up to 600 N (C)	41.3 mm
Total deformation	51.6 mm



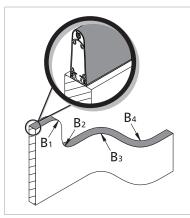




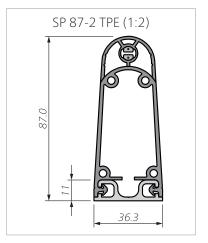


# **SK SP 87-2 TPE**

Sensor profile (without control unit)	SK SP/W 87-2 TPE or SK SP/BK 87-2 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v <sub>test</sub> =	100 mm/s
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	9 mm
Test piece (cylinder) Ø 80 mm	± 45°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 25 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	1000 / 1000 / 200 / 200 mm
Operating velocity	10 / 200
(min. / max.)	10 mm/s / 200 mm/s
Max. load capacity (impulse) Tensile load, cable (max.)	600 N 20 N
IEC 60529: Degree of protection	IP68
SP in water: 9 cm bottom edge	IPX8: 20 weeks
Operating temperature	-25 to +55 °C
short-term (15 min)	-40 to +80 °C
Storage temperature	-40 to +80 °C
Weight	SP 87-2
without aluminium profile	0.64 kg/m
with aluminium profile C 36	1.06 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>



# Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

# **Test conditions** according to ISO 13856-2

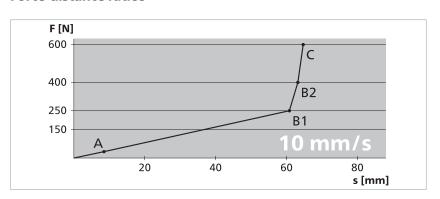
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø
   80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

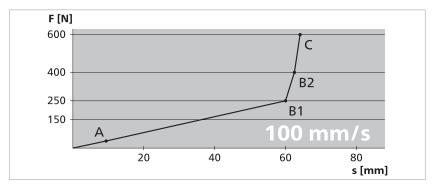
#### **Force-distance ratios**

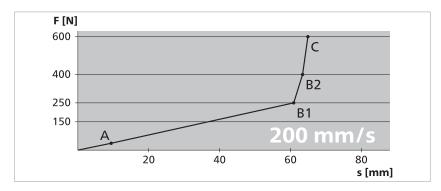
10 mm/s
34 N
850 ms
8.5 mm
52.3 mm
54.7 mm
56.2 mm
64.7 mm

Test velocity <b>1</b>	00 mm/s
Actuation force	38 N
Response time	81 ms
Actuation distance (A)	8.1 mm
Overtravel distance	
up to 250 N (B1)	51.9 mm
up to 400 N (B2)	54.4 mm
up to 600 N (C)	56.0 mm
Total deformation	64.1 mm

Test velocity 20	00 mm/s
Actuation force	37 N
Response time	47 ms
Actuation distance (A)	9.4 mm
Overtravel distance	
up to 250 N (B1)	51.5 mm
up to 400 N (B2)	54.0 mm
up to 600 N (C)	55.5 mm
Total deformation	64.9 mm









# **Marking**

If you combine sensors with control units and thereby place pressure-sensitive protection devices on the market, you should observe the basic requirements according to ISO 13856.

As well as meeting technical requirements, this also means – in particular – observing any that relate to marking and information for use.

# **Conformity**

# EC type examination

The product was tested by an independent institute.

There is an EC type examination certificate to confirm conformity.

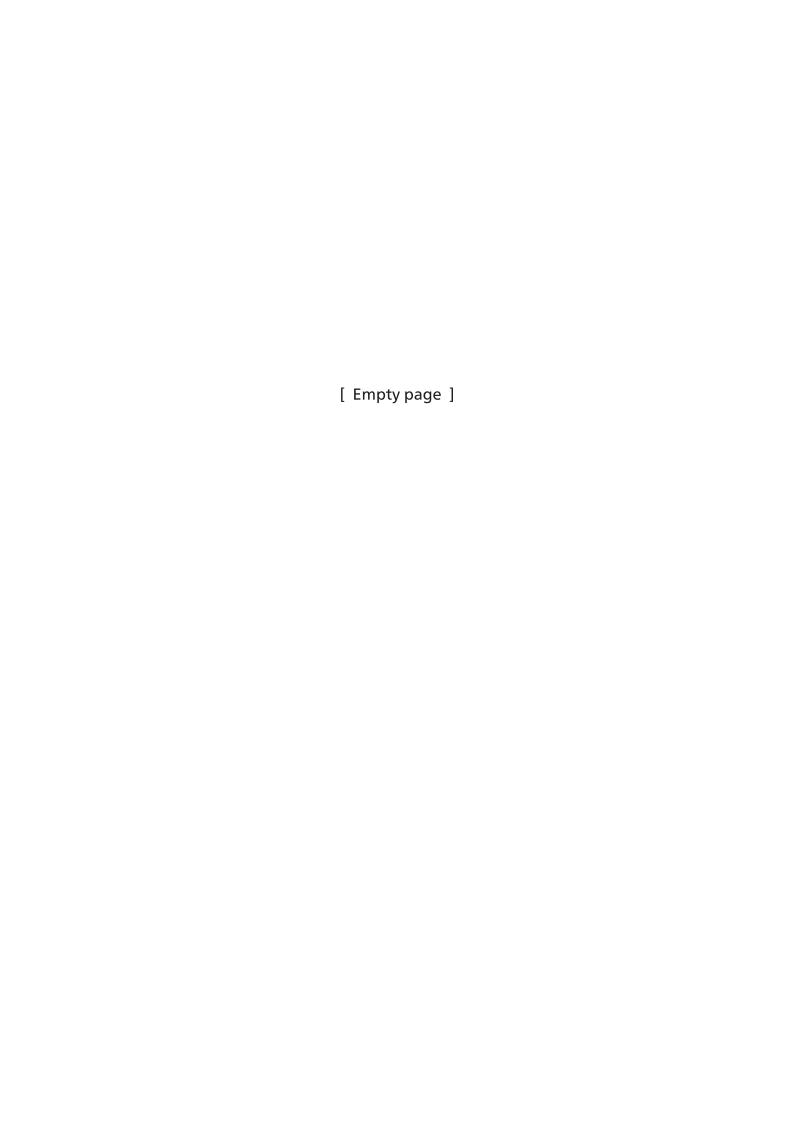
The EC type examination certificate is stored in the Downloads section of our website: www.mayser.com.

# **UL** certification



The design type of the product conforms to the basic requirements of UL certification:

• UL 325







# SP DIY sensor profiles for toolless self-assembly



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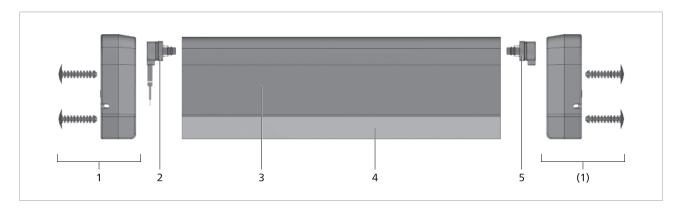


SK SP 67-2 TPE	39
SK SP 87-2 TPE	
Marking	
Conformity	
EC type examination	
UL certification	

# **Overview**

### **Contact profile - Sensor profile**

The semi-finished contact profile (No. 3) is cut to length and assembled with the other components. This results in a functioning product called a sensor profile.



Nos. 2 and 5 are identical for all sensor profiles.

No. 2 Closing plug with 2.5 m cable 7504038No. 5 Closing plug with resistor 7504039

Alternatives for No. 2:

Closing plug with 5.0 m cable 7504103 Closing plug with 10 m cable 7504102

Sensor profile	or profile No. 1 No. 3 Set of end caps Contact profile				No. 4 Aluminium profile		
SP 17-3 without end caps	1005786	SP 17-3	7503461	C 15	1000016		
SP 37-1 without end caps	1000606	SP 37-1	7502853	C 25	1000004		
SP 37-1 with end caps	7503008	SP 37-1	7502853	C 25	1000004		
SP 37-2 with end caps	7503988	SP 37-2	7503318	C 26	1004330		
SP 37L-2 with end caps	7503988	SP 37L-2	7504192	C 26	1004330		
SP 37-3 with end caps	7503505 (7503654)	SP 37-3	7503343	C 25	1000004		
SP 57-2 with end caps	7503603	SP 57-2	7503055	C 30	1005844		
SP 57L-2 with end caps	7503603	SP 57L-2	7503412	C 30	1005844		
SP 57-3 with end caps	7503618	SP 57-3	7503521	C 35	1000006		



Sensor profile	No. 1 Set of end caps		o. 3 t profile		o. 4 um profile
SP 57-4 with end caps	7503618	SP 57-4	7503633	C 35	1000006
SP 57L-4 with end caps	7503618	SP 57L-4	7503711	C 35	1000006
SP 67-2 with end caps	7503655	SP 67-2	7503285	C 30	1005844
SP 87-2 with end caps	7504118	SP 87-2	7503722	C 36	1003848

# **Materials list**

Part No.	Designation	Pack- ing unit
7503461	Contact profile SP 17-3 TPE	80 m
7502853	Contact profile SP 37-1 TPE	30 m
7503318	Contact profile SP 37-2 TPE	30 m
7504192	Contact profile SP 37L-2 TPE	30 m
7503343	Contact profile SP 37-3 TPE "black"	30 m
7503534	Contact profile SP 37-3 TPE "red"	30 m
7503055	Contact profile SP 57-2 TPE	30 m
7503412	Contact profile SP 57L-2 TPE	30 m
7503521	Contact profile SP 57-3 TPE	25 m
7503633	Contact profile SP 57-4 TPE	25 m
7503711	Contact profile SP 57L-4 TPE	25 m
7503285	Contact profile SP 67-2 TPE	30 m
7503722	Contact profile SP 87-2 TPE	25 m
7504039	Closing plug with resistor 8k2	10 pcs.
7504038	Closing plug with 2.5 m PUR cable, angled 90°	10 pcs.
7504103	Closing plug with 5.0 m PUR cable, angled 90°	10 pcs.
7504102	Closing plug with 10 m PUR cable, angled 90°	10 pcs.
7504101	Closing plug without resistor	10 pcs.
1005786	Countersunk tapping screw 3.5 x 25 for SP 17-3	20 pcs.
7503008	Set of end caps for SP 37-1: 2 end caps, 2 fixing stoppers and 2 screws 3.9 × 25	10 pcs.
7503988	Set of end caps for SP 37(L)-2: 2 end caps and 4 pine tree clips	10 pcs.



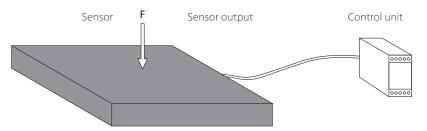
Part No.	Designation	Pack- ing unit
7503505	Set of end caps for SP 37-3 "black":	
	2 end caps and 2 pine tree clips	10 pcs.
7503654	Set of end caps for SP 37-3 "red": 2 end caps and 2 pine tree clips	10 pcs.
7503603	Set of end caps for SP 57(L)-2 with clips: 2 end caps and 4 pine tree clips	10 pcs.
7503618	Set of end caps for SP 57-3 and SP 57(L)-4: 2 end caps and 6 pine tree clips	10 pcs.
7503655	Set of end caps for SP 67-2: 2 end caps and 4 pine tree clips	10 pcs.
7504118	Set of end caps for SP 87-2: 2 end caps and 8 pine tree clips	10 pcs.
1000016	Aluminium profile C 15	6 m
1000854	Aluminium profile C 25M, upper section	6 m
1000855	Aluminium profile C 25M, lower section	6 m
1000829	Aluminium profile C 25L	6 m
1000012	Aluminium profile C 25S	6 m
1000004	Aluminium profile C 25	6 m
1004626	Aluminium profile C 26M, upper section	6 m
1004627	Aluminium profile C 26M, lower section	6 m
1004330	Aluminium profile C 26, perforated	6 m
1005844	Aluminium profile C 30	6 m
1001398	Aluminium profile C 35M, upper section	6 m
1001399	Aluminium profile C 35M, lower section	6 m
1000013	Aluminium profile C 35S	6 m
1000006	Aluminium profile C 35	6 m
1004629	Aluminium profile C 36M, upper section	6 m
1004630	Aluminium profile C 36M, lower section	6 m
1003849	Aluminium profile C 36L, perforated	6 m
1003850	Aluminium profile C 36S, perforated	6 m
1003848	Aluminium profile C 36, perforated	6 m
1001223	End stopper for C 25M, for SP without end caps	1 pc.
1000606	End stopper for C 25 or C 25S, for SP without end caps	1 pc.
1005906	Section cutter, cutting length 87 mm	1 pc.



# **Definitions**

# Pressure-sensitive protection device

A pressure-sensitive protection device consists of one or more pressure-sensitive sensors, a signal processing unit, and one or more output signal switching devices. The control unit is made up of the signal processing unit and output signal switching device(s). The pressure-sensitive protection device is triggered when the sensor is activated.

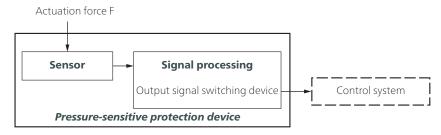


#### Sensor

The sensor is the part of the pressure-sensitive protection device that generates a signal when the actuation force F is applied. Mayser safety systems feature a sensor whose actuating surface is deformed locally.

#### **Signal processing**

The signal processing unit is the part of the pressure-sensitive protection device that converts the output signal of the sensor and controls the status of the output signal switching device. The output signal switching device is the part of the signal processing unit which is connected to the forwarding control system and which transmits safety output signals such as STOP.

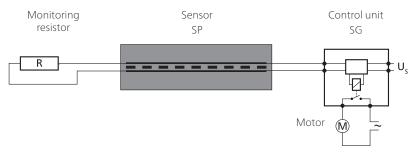


Tip: Terms are defined in ISO 13856-2 Section 3.

#### Criteria for selecting the sensor type

- Category according to ISO 13849-1
- Performance level of the pressure-sensitive protection device
   at least PL<sub>2</sub>
- Temperature range
- Degree of Protection in accordance with IEC 60529:
   IP67 is the standard for safety edges.
   Higher degrees of protection must be checked individually.
- Environmental influences such as swarf, oil, coolant, outdoor use...
- Finger detection necessary?

# Operation principle of 2-wire technology



The monitoring resistor must be compatible with the control unit. The standard type is 8k2.

### For your safety:

The sensor and connecting cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on controlled bridging of the contact surfaces with a monitoring resistor (closed-circuit principle).

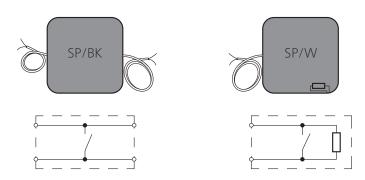
### **Types**

SP/BK With cables on both sides for use as a through sensor or

with an external monitoring resistor for use as an end sen-

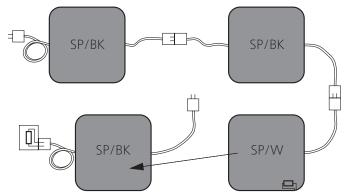
sor

SP/W With an integrated monitoring resistor for use as an end





#### Sensor combination

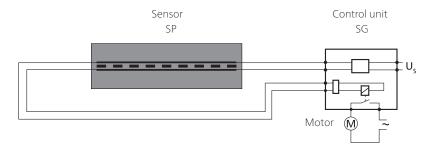


Version with external resistor, therefore no variety of models

#### Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety edge design with custom lengths and angles

# Operation principle of 4-wire technology



The 4-wire technology can only be used together with control unit SG-EFS 104/4L.

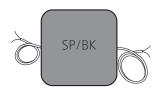
#### For your safety:

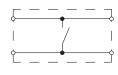
The sensor and connecting cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on signal transmission feedback – without a monitoring resistor.

#### **Types**

SP/BK

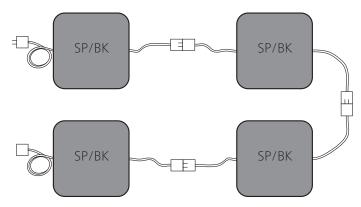
With cables on both sides for use as a through sensor





131221 v1.03-RiA

### **Sensor combination**



#### Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety edge design with custom lengths and angles

# Safety

# Intended use

A safety edge detects a person or part of the body when pressure is applied to the effective actuation area. It is a linear tripping device. Its task is to prevent possible hazardous situations that could affect someone within a danger zone, such as shearing and pinching edges.

Typical areas of application are door and gate systems, moving parts on machines, platforms and lifting devices.

Safe operation of a safety edge depends entirely on

- the surface condition of the mounting surface,
- the correct selection of the size and resistance rating as well as
- correct installation.

For additional application guidelines, please refer to ISO 13856-2 Annex E.

Due to the design, the actuation area is actually smaller than it looks because of the non-sensitive edges. Once these have been allowed for, what remains is the effective actuation area (see chapter *Effective actuation area*).

# Limits

- No more than 5 /BK-type sensors can be connected to one control unit.
- No more than 4 /BK-type sensors and 1 /W-type sensor can be connected to one control unit.

# **Exclusions**

The sensors are not suitable for:

• performing a sealing function. Constant actuation of sensors can result in permanent damage.

**Exception:** The L version with an attached lip seal.

The lip seal can be in full contact with the closing edge, which allows it to repel wind and water.

# Selecting the appropriate product line

If you opt for our line of SP DIY sensor profiles for toolless self-assembly, the maximum class of protection that can be achieved is IP67 and IPX8 (13 days). If a higher protection class of IP68 or IPX8 (20 weeks) is required for your application, we recommend using our line of SP DIY sensor profiles for **assembly with tools** instead.



# Other safety aspects

The following safety aspects relate to pressure-sensitive protection devices consisting of a sensor and a control unit.

#### **Performance Level (PL)**

The PL has been determined using the procedure defined by ISO 13849-1.

Fault exclusion according to ISO 13849-2 Table D.8: Non-closing of contacts by pressure-sensitive equipment according to ISO 13856. In this case, the diagnostic coverage (DC) is not calculated or taken into account when determining the PL. Assuming a high MTTF<sub>D</sub> value for the control unit, a performance level of up to PL d can be achieved by the safety edge system (pressure-sensitive protection device) as a whole.

#### Is the protection device suitable?

First, the integrator must decide what  $PL_r$  is required for the hazard. After that, they must select the protection device.

Finally, the integrator needs to check whether the category and PL of the selected protection device are appropriate.

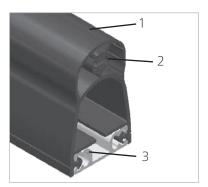
#### Risk and safety assessment

For the risk and safety assessment of your machine, we recommend ISO 12100 "Safety of machinery — General principles for design".

#### Without reset function

When a protection device without reset function is used (automatic reset), the reset function must be provided in some other way.

# Design



The SP sensor profile consists of one sensor (1 to 3)

- (1) SP contact profile with
- (2) integrated normally open switching element,
- (3) aluminium profile and an evaluating control unit SG.

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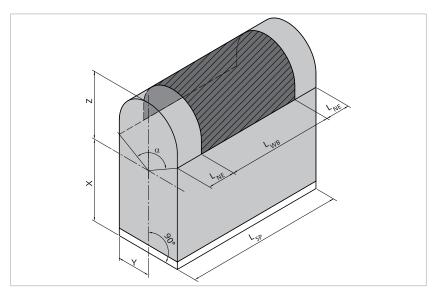


# Effective actuation area

The parameters X, Y, Z,  $L_{WB}$  and the angle  $\,\alpha\,$  describe the effective actuation area.

For the effective actuation area, the following applies:

$$L_{WB} = L_{SP} - 2 \times L_{NE}$$



#### Parameters:

 $L_{WB} = effective actuation$ length

 $L_{SP}$  = total length of sensor profile

 $L_{NE} = non-sensitive length at end of sensor profile$ 

 $\alpha$  = effective actuation angle

	SP 17-3 <sup>1)</sup>	SP 37-1	SP 37(L)-2	SP 37-3	SP 57(L)-2	SP 57-3	SP 57(L)-4	SP 67-2	SP 87-2
Incl.	C 15	C 25	C 26	C 25	C 30	C 35	C 35	C 30	C 36
α	90°	100°	100°	100°	90°	90°	90°	90°	90°
L <sub>NE</sub>	60 mm	20 mm	20 mm	20 mm	10 mm <sup>2)</sup>	10 mm <sup>2)</sup>	10 mm <sup>2)</sup>	20 mm <sup>2)</sup>	10 mm <sup>2)</sup>
Υ	6.7 mm	12.5 mm	13 mm	12.5 mm	17 mm	17.5 mm	17.5 mm	17 mm	18.1 mm
X	15.3 mm	28.5 mm	30 mm	29 mm	44 mm	52 mm	52 mm	57.3 mm	72 mm
Z	5 mm	9 mm	9 mm <sup>3)</sup>	9 mm	12 mm <sup>3)</sup>	12 mm	12 mm <sup>3)</sup>	10 mm	15 mm
X + Z	20.3 mm	37.5 mm	39 mm <sup>3)</sup>	38 mm	56 mm <sup>3)</sup>	64 mm	64 mm <sup>3)</sup>	67.3 mm	87 mm

<sup>1)</sup> without end cap

# Installation position

The installation position can be selected as required, i.e. all installation positions from A to D as per ISO 13856-2 are possible.

<sup>&</sup>lt;sup>2)</sup> with finger protection

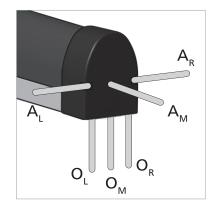
<sup>3)</sup> without lip

# **Connection**

# Cable exits

Depending on the end cap, the following cable exits are available.

 $A_L$  = axial left  $A_M$  = axial middle  $A_R$  = axial right  $O_L$  = orthogonal left  $O_M$  = orthogonal middle  $O_R$  = orthogonal right



			Cable	e exit			
	$A_L$		$A_R$				
	Axial exit		A <sub>M</sub>				
	90° exit				O <sub>L</sub>	O <sub>M</sub>	O <sub>R</sub>
Combi	nation						
Contact profile	Set of end caps						
SP 17-3	_					•	
SP 37-1	7503008	•		•	•		•
SP 37(L)-2	7503988	•	•	•		•	
SP 37-3 black	7503505	•		•	•		•
SP 37-3 red	7503654	•		•	•		•
CD [7/1] 2	7503062	•	•	•		•	
SP 57(L)-2	7503603	•	•	•		•	
SP 57-3	7503618	•	•	•		•	
SP 57(L)-4	7503796	•	•	•	•		•
SP 67-2	7503655	•	•	•		•	
SP 87-2	7504118	•	•	•		•	

• = possible

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### Cable connection

- Standard cable lengths
   L = 2.5 m / 5.0 m / 10 m
- Maximum total cable length to the control unit  $L_{max} = 100 \text{ m}$

/W-type sensor with 1 line	/BK-type sensor with 2 lines
<ul> <li>As an individual /W-type sensor or a /W-type end sensor</li> <li>Integrated resistor</li> <li>1 two-wire cable</li> </ul>	<ul> <li>As a /BK-type through sensor</li> <li>Without resistor</li> <li>2 two-wire cables</li> </ul>

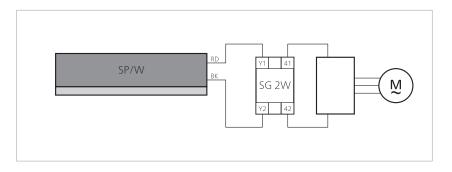
### Wire colours

/W-type sensor with 1 line	/BK-type sensor with 2 lines
RD I BK	RD ← ← ← → RD   BK ← → BK

# Connection examples

Key:

SG 2W evaluation with 2-wire technology SG 4L evaluation with 4-wire technology

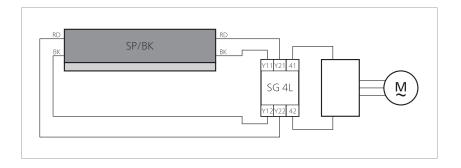


### **Colour coding**

BK Black RD Red

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### **Sensor surface**

### Resistance

The resistance ratings listed below (at a room temperature of 23 °C) depend on the sensor having an undamaged surface.

### **Physical resistance**

	TPE
UV resistance	Yes

### **Chemical resistance**

The sensor is broadly resistant to normal chemical influences such as diluted acids and alkalis, as well as alcohol, over an exposure period of 24 hrs.

The values in the table are the results of tests carried out in our laboratory. You must always conduct your own practical tests to verify that our products are suitable for your specific area of application.



### **Explanation of symbols:**

+ = resistant

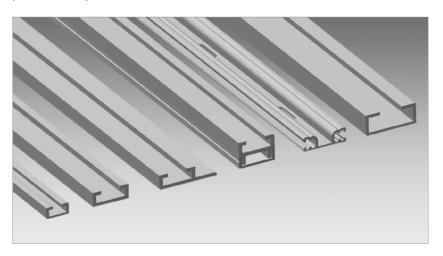
 $\pm$  = resistant to a certain extent

- = not resistant

Material	TPE
Acetone	-
Formic acid	-
Armor All	+
Car shampoo	+
Petrol	-
Brake fluid	+
Buraton	+
Butanol	-
Sodium hypochlorite	-
Disinfectant 1%	+
Diesel	-
Acetic acid 10%	-
Ethanol	+
Ethyl acetate	-
Ethylene glycol	+
Greases	±
Anti-frost agent	+
Skin cream	+
Incidin	+
Incidin Plus	+
Cooling lubricant	-
Plastic cleaner	+
Lyso FD 10	+
Metal working oil	-
Microbac	+
Microbac forte	+
Minutil	+
Saline solution 5%	+
Spirit (ethyl alcohol)	+
Terralin	+
Centring oil	-

# **Mounting**

The sensors are mounted directly onto the main and secondary closing edges that present a danger. They are fixed using special aluminium profiles. The profiles are fastened with screws or rivets.



### **Material properties**

- AlMgSi0.5 F22
- Wall thickness at least
   2.0 mm
   C 15: at least 1.7 mm

C 30: at least 1.5 mm

- Extruded
- Hot hardened
- Tolerances as per EN 755-9

# Aluminium profiles: Overview of combinations

Sensor pr	ofile foot	C 15	C 25 C 25M C 25S C 25L	C 26 C 26M	C 30	C 35 C 35M C 35S	C 36 C 36M C 36S C 36L
Snap-in foot (middle)	1	-	SP 37-1	_	_	_	-
Clip bars (outside)	2	_	_	SP 37(L)-2	SP 57(L)-2 SP 67-2	_	SP 87-2
T-foot (middle)	3	SP 17-3	SP 37-3	_	_	SP 57-3	_
T-foot narrow (middle)	4	-	-	_	_	SP 57(L)-4	_



### Aluminium profiles: Mounting types

### **Standard profile**

First the aluminium profile must be mounted onto the closing edge and then the sensor profile clipped into the aluminium profile.

C 15	C 25	C 26	C 30	C 35	C 36
		<u> DC</u>			

### Two-part profile, type M

For convenient assembly and disassembly. The sensor profile is clipped into the upper section and the upper section inserted into the installed lower section and fastened.

-	C 25M	C 26M	C 35M	C 36M

### Flange profile, type S

Final assembly is also possible when the sensor profile is already clipped into the aluminium profile.

-	C 25S	-	C 35S	C 36S

### Angle profile, type L

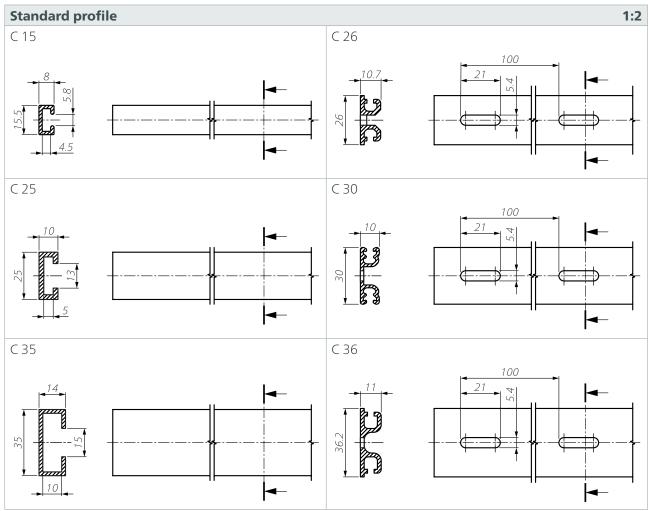
If the closing edge should or must not have assembly holes, this "round-the-corner" solution is suitable. Final assembly is also possible when the sensor profile is already clipped into the aluminium profile.

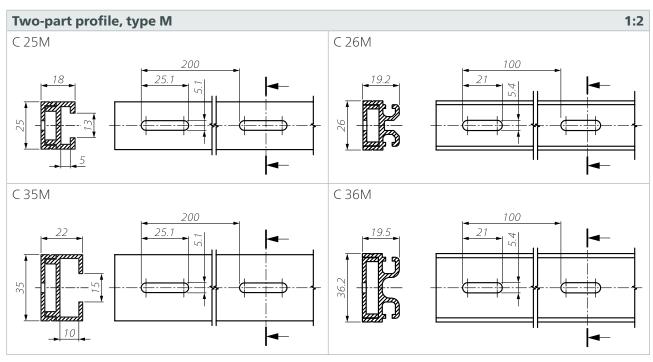


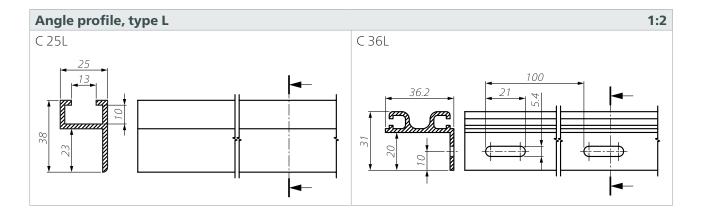
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## **MAYSER®**

# Aluminium profiles: Dimensions









- s<sub>1</sub> = Stopping distance of the dangerous movement [ mm ]
- v = Velocity of the dangerous movement [ mm/s ]
- T = Follow-through time of the complete system [s]
- $t_1$  = Safety edge response time
- t<sub>2</sub> = Stopping time of the machine
- s = Minimum overtravel distance of the safety edge to ensure that the stipulated limit forces are not exceeded [ mm ]
- C = Safety factor; if components susceptible to failures (braking system) exist in the system, a higher factor must be selected.

### **SP: Making the right selection**

# Calculation for selection of the safety edge height

The stopping distance of the dangerous movement is calculated using the following formula:

$$s_1 = 1/2 \times v \times T$$
 where:  $T = t_1 + t_2$ 

In accordance with ISO 13856-2, the minimum overtravel distance of the safety edge is calculated using the following formula:

$$s = s_1 \times C$$
 where:  $C = 1.2$ 

A suitable safety edge profile can now be selected based on the result. For details of the overtravel distances for safety edge profiles, see chapter *Technical data*.

## Calculation examples

### **Calculation example 1**

The dangerous movement on your machine has a velocity of v=10 mm/s and can be brought to a standstill within  $t_2=200$  ms. The relatively low velocity suggests that a short overtravel distance is to be expected. Therefore, the sensor profile SP 37-1 TPE could be sufficient. The response time of the safety edge (SP 37-1 TPE + control unit\*) is  $t_1=600$  ms.

$$s_1 = 1/2 \times v \times T$$
 where:  $T = t_1 + t_2$   
 $s_1 = 1/2 \times 10 \text{ mm/s} \times (0.6 \text{ s} + 0.2 \text{ s})$   
 $s_1 = 1/2 \times 10 \text{ mm/s} \times 0.8 \text{ s} = 4.0 \text{ mm}$ 

$$s = s_1 \times C$$
 where:  $C = 1.2$   
 $s = 4.0 \text{ mm} \times 1.2 = 4.8 \text{ mm}$ 

The safety edge must have a minimum overtravel distance of s = 4.8 mm. The selected SP 37-1 TPE has an overtravel distance of at least 9.2 mm. This is more than the required 4.8 mm.

**Result:** The SP 37-1 TPE is **suitable** for this case.

Subject to technical modifications.

<sup>\*</sup> Assumption: Typical reaction time of a control unit = 20 ms



### **Calculation example 2**

The same conditions apply as in calculation example 1 with the exception of the velocity of the dangerous movement. This is now v = 200 mm/s. The response time of the safety edge (SP 37-1 TPE + control unit\*) is  $t_1 = 55 \text{ ms}$ .

$$s_1 = 1/2 \times v \times T$$
 where:  $T = t_1 + t_2$   
 $s_1 = 1/2 \times 200 \text{ mm/s} \times (0.055 \text{ s} + 0.2 \text{ s})$   
 $s_1 = 1/2 \times 200 \text{ mm/s} \times 0.255 \text{ s} = 25.5 \text{ mm}$ 

$$s = s_1 \times C$$
 where:  $C = 1.2$ 

 $s = 25.5 \text{ mm} \times 1.2 = 30.6 \text{ mm}$ 

The safety edge must have a minimum overtravel distance of s = 30.6 mm. The selected SP 37-1 TPE has an overtravel distance of at least 3.8 mm. This is less than the required 30.6 mm.

**Result:** The SP 37-1 TPE is **not suitable** for this case.

### **Calculation example 3**

The same conditions apply as in calculation example 2. Instead of SP 37-1 EPDM, the SP 67-1 TPE is selected. The response time of the safety edge (SP 67-2 TPE + control unit\*) is  $t_1 = 72$  ms.

$$s_1 = 1/2 \times v \times T$$
 where:  $T = t_1 + t_2$   
 $s_1 = 1/2 \times 200 \text{ mm/s} \times (0.072 \text{ s} + 0.2 \text{ s})$   
 $s_1 = 1/2 \times 200 \text{ mm/s} \times 0.272 \text{ s} = 27.2 \text{ mm}$ 

$$s = s_1 \times C$$
 where:  $C = 1.2$   
 $s = 27.2 \text{ mm} \times 1.2 = 32.6 \text{ mm}$ 

The safety edge must have a minimum overtravel distance of s = 32.6 mm. The selected SP 67-2 TPE has an overtravel distance of at least 36.5 mm. This is more than the required 32.6 mm.

**Result:** The SP 67-2 TPE is **suitable** for this case.

<sup>\*</sup> Assumption: Typical reaction time of a control unit = 20 ms



# **Maintenance and cleaning**

The sensors are virtually maintenance-free.

The control unit also monitors the sensor at the same time.

### **Regular inspection**

Depending on the operational demands, the sensors must be inspected at regular intervals (at least monthly)

- for proper functioning,
- for damage and
- for correct mounting.

### Cleaning

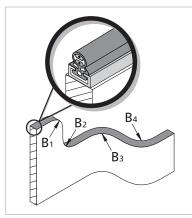
If the sensors become dirty, they can be cleaned with a mild cleaning product.

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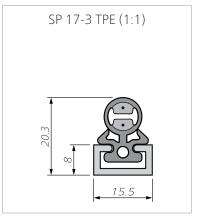
# SK SP 17-3 TPE

Sensor profile (without control unit)	SK SP/W 17-3 TPE or SK SP/BK 17-3 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v <sub>test</sub> =	10 mm/s
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	1.5 mm
Test piece (cylinder) Ø 80 mm	±45°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 80 m
Cable length (min./max.) Bend radii, minimum	10 cm / 100 m
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	200 / 200 / 50 / 50 mm
Operating velocity	
(min. / max.)	10 mm/s / 10 mm/s
Max. load capacity (impulse) Tensile load, cable (max.)	600 N 20 N
IEC 60529: Degree of protection	IP67
SP in water: 9 cm bottom edge	IPX8: 13 days
Operating temperature	−25 to +55 °C
short-term (15 min)	−40 to +80 °C
Storage temperature	−40 to +80 °C
Weight	SP 17-3
without aluminium profile	0.12 kg/m
with aluminium profile C 15	0.28 kg/m
<b>Electrical operating conditions</b>	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR $2 \times 0.25$ mm <sup>2</sup>





### Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

# **Test conditions** according to ISO 13856-2

- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø
   80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.

### **Force-distance ratios**

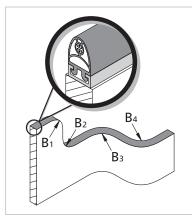
Test velocity	10 mm/s
Actuation force	38 N
Response time	140 ms
Actuation distance (A)	1.4 mm
Overtravel distance	
up to 250 N (B1)	1.4 mm
up to 400 N (B2)	2.3 mm
up to 600 N (C)	4.1 mm
Total deformation	5.5 mm

F [N]					
600	С				
400 B	2				
250 B1					
A				10 m	m/s
<u> </u>	10	20	30	40	50 s [mm]



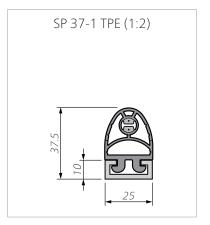
### **SK SP 37-1 TPE**

Sensor profile (without control unit)	SK SP/W 37-1 TPE or SK SP/BK 37-1 TPE					
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2					
Switching characteristics at v <sub>test</sub> = 1	Switching characteristics at v <sub>test</sub> = 100 mm/s					
Switching operations	10,000					
Actuation force						
Test piece (rod) Ø 20 mm	< 50 N					
Test piece (cylinder) Ø 80 mm	< 150 N					
Actuation distance						
Test piece (cylinder) Ø 80 mm	6 mm					
Actuation angle	. 500					
Test piece (cylinder) Ø 80 mm	±50°					
Finger detection	Yes					
Safety classifications						
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>					
Mechanical operating conditions						
Sensor length (min./max.)	10 cm / 30 m					
Cable length (min./max.)	10 cm / 100 m					
Bend radii, minimum						
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	500 / 500 / 200 / 200 mm					
Operating velocity						
(min. / max.)	10 mm/s / 200 mm/s					
Max. load capacity (impulse)	600 N					
Tensile load, cable (max.)	20 N					
IEC 60529: Degree of protection	IP67					
SP in water: 9 cm bottom edge	IPX8: 13 days					
Operating temperature	−25 to +55 °C					
short-term (15 min)	-40 to +80 °C					
Storage temperature	-40 to +80 °C					
Weight	SP 37-1					
without aluminium profile	0.33 kg/m					
with aluminium profile C 25	0.64 kg/m					
Electrical operating conditions						
Terminal resistance	8k2 ±1%					
Nominal output (max.)	250 mW					
Contact transition resistance	< 400 ohms (per sensor)					
Number of BK-type sensors	Max. 5 in series					
Switching voltage (max.)	DC 24 V					
Switching current (min./max.)	1 mA / 10 mA					
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>					





### Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

# **Test conditions** according to ISO 13856-2

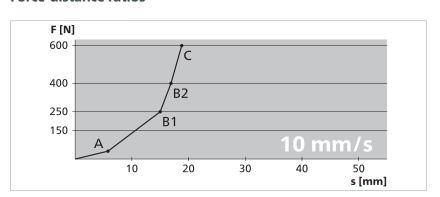
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

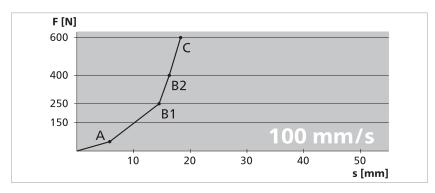
### **Force-distance ratios**

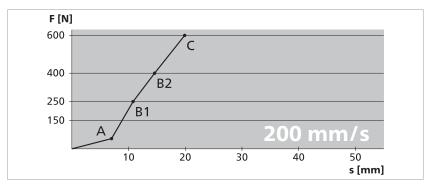
Test velocity	10 mm/s
Actuation force	42 N
Response time	580 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	9.2 mm
up to 400 N (B2)	11.1 mm
up to 600 N (C)	13.0 mm
Total deformation	18.8 mm

Test velocity 10	00 mm/s
Actuation force	50 N
Response time	58 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	8.7 mm
up to 400 N (B2)	10.5 mm
up to 600 N (C)	12.5 mm
Total deformation	18.3 mm

Test velocity <b>2</b>	00 mm/s
Actuation force	54 N
Response time	35 ms
Actuation distance (A)	7.0 mm
Overtravel distance	
up to 250 N (B1)	3.8 mm
up to 400 N (B2)	7.6 mm
up to 600 N (C)	12.9 mm
Total deformation	19.9 mm



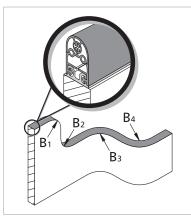






# SK SP 37(L)-2 TPE

Sensor profile (without control unit)	SK SP/W 37(L)-2 TPE or SK SP/BK 37(L)-2 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v <sub>test</sub> =	100 mm/s
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	6 mm
Test piece (cylinder) Ø 80 mm Finger detection	±50° Yes
Safety classifications	
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 30 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	500 / 500 / 200 / 200 mm
Operating velocity	
(min. / max.)	10 mm/s / 200 mm/s
Max. load capacity (impulse)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: Degree of protection	IP67
SP in water: 9 cm bottom edge Operating temperature	IPX8: 13 days –25 to +55 °C
short-term (15 min)	-40 to +80 °C
Storage temperature	-40 to +80 °C
Weight	SP 37-2 SP 37L-2
without aluminium profile	0.36 kg/m 0.41 kg/m
with aluminium profile C 26	0.69 kg/m 0.74 kg/m
<b>Electrical operating conditions</b>	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>



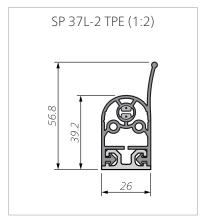
# SP 37-2 TPE (1:2)

Dimensional tolerances according to ISO 3302 E2/L2

Test velocity

Actuation force

### Dimensions and distances



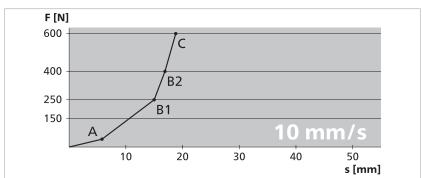
Dimensional tolerances according to ISO 3302 E2/L2

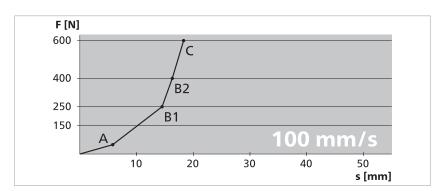
# **Test conditions** according to ISO 13856-2

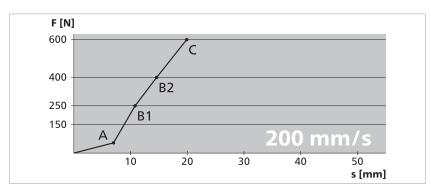
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit
- Lip not taken into account

All data stated here is documented in EC type examination certificates.

### **Force-distance ratios**







10 mm/s

42 N

Response time 580 ms
Actuation distance (A) 5.8 mm
Overtravel distance
up to 250 N (B1) 9.2 mm
up to 400 N (B2) 11.1 mm
up to 600 N (C) 13.0 mm
Total deformation 18.8 mm

Test velocity 100 mm/s

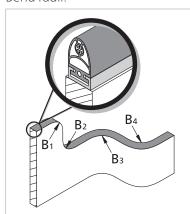
Test velocity 10	00 mm/s
Actuation force	50 N
Response time	58 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	8.7 mm
up to 400 N (B2)	10.5 mm
up to 600 N (C)	12.5 mm
Total deformation	18.3 mm

Test velocity <b>2</b>	00 mm/s
Actuation force	54 N
Response time	35 ms
Actuation distance (A)	7.0 mm
Overtravel distance	
up to 250 N (B1)	3.8 mm
up to 400 N (B2)	7.6 mm
up to 600 N (C)	12.9 mm
Total deformation	19.9 mm



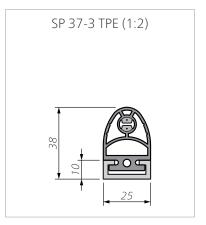
### **SK SP 37-3 TPE**

Sensor profile (without control unit)	SK SP/W 37-3 TPE or SK SP/BK 37-3 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v <sub>test</sub> = '	100 mm/s
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	6 mm
Test piece (cylinder) Ø 80 mm	±50°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 30 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	F00 / F00 / 300 / 300 maga
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub> Operating velocity	500 / 500 / 200 / 200 mm
(min. / max.)	10 mm/s / 200 mm/s
Max. load capacity (impulse)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: Degree of protection	IP67
SP in water: 9 cm bottom edge	IPX8: 13 days
Operating temperature	−25 to +55 °C
short-term (15 min)	-40 to +80 °C
Storage temperature	−40 to +80 °C SP 37-3
Weight without aluminium profile	0.34 kg/m
with aluminium profile C 25	0.66 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>





### Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

# **Test conditions** according to ISO 13856-2

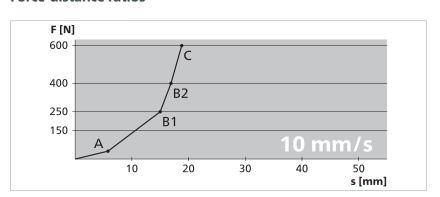
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

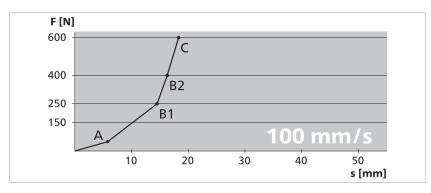
### **Force-distance ratios**

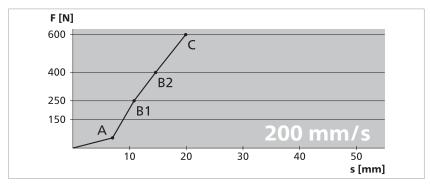
Test velocity	10 mm/s
Actuation force	42 N
Response time	580 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	9.2 mm
up to 400 N (B2)	11.1 mm
up to 600 N (C)	13.0 mm
Total deformation	18.8 mm

Test velocity 1	00 mm/s
Actuation force	50 N
Response time	58 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	8.7 mm
up to 400 N (B2)	10.5 mm
up to 600 N (C)	12.5 mm
Total deformation	18.3 mm

Test velocity <b>2</b>	00 mm/s
Actuation force	54 N
Response time	35 ms
Actuation distance (A)	7.0 mm
Overtravel distance	
up to 250 N (B1)	3.8 mm
up to 400 N (B2)	7.6 mm
up to 600 N (C)	12.9 mm
Total deformation	19.9 mm



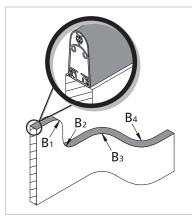






# SK SP 57(L)-2 TPE

Sensor profile (without control unit)	SK SP/W 57(L)-2 TPE or SK SP/BK 57(L)-2 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v <sub>test</sub> =	100 mm/s
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	8 mm
Test piece (cylinder) Ø 80 mm	±45°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 30 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	1000 / 1000 / 200 / 200 mm
Operating velocity	10 mm/s / 200 mm/s
(min. / max.) Max. load capacity (impulse)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: Degree of protection	IP67
SP in water: 9 cm bottom edge	IPX8: 13 days
Operating temperature	−25 to +55 °C
short-term (15 min)	−40 to +80 °C
Storage temperature	−40 to +80 °C
Weight	SP 57-2 SP 57L-2
without aluminium profile	0.44 kg/m 0.47 kg/m
with aluminium profile C 30	0.74 kg/m 0.77 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.) Switching current (min./max.)	DC 24 V 1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>
CONTRCUOTECADIE	₩ Z.J IIIIII UN ZA U.ZJ IIIIII

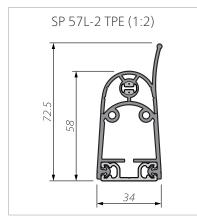


# SP 57-2 TPE (1:2)

Dimensional tolerances according to ISO 3302 E2/L2

Test velocity

### Dimensions and distances



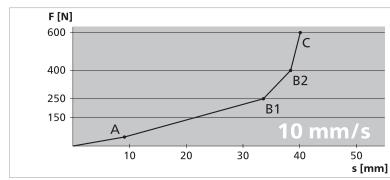
Dimensional tolerances according to ISO 3302 E2/L2

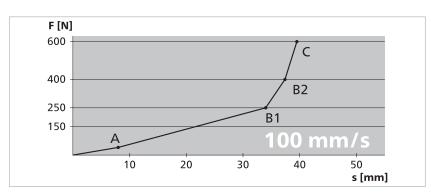
# **Test conditions** according to ISO 13856-2

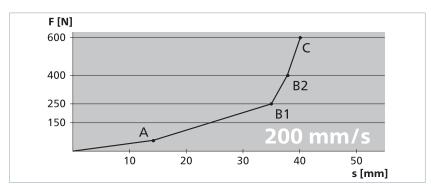
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit
- Lip not taken into account

All data stated here is documented in EC type examination certificates.

### **Force-distance ratios**







### 10 mm/s

Actuation force 48 N
Response time 910 ms
Actuation distance (A) 9.1 mm
Overtravel distance
up to 250 N (B1) 24.5 mm
up to 400 N (B2) 29.3 mm
up to 600 N (C) 31.0 mm
Total deformation 40.1 mm

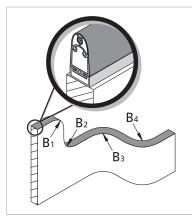
Test velocity 1	00 mm/s
Actuation force	41 N
Response time	80 ms
Actuation distance (A)	8.0 mm
Overtravel distance	
up to 250 N (B1)	26.0 mm
up to 400 N (B2)	29.4 mm
up to 600 N (C)	31.5 mm
Total deformation	39.5 mm

lest velocity 2	00 mm/s
Actuation force	58 N
Response time	71 ms
Actuation distance (A)	14.2 mm
Overtravel distance	
up to 250 N (B1)	20.8 mm
up to 400 N (B2)	23.7 mm
up to 600 N (C)	25.9 mm
Total deformation	40.1 mm



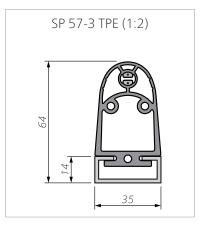
### **SK SP 57-3 TPE**

Sensor profile (without control unit)	SK SP/W 57-3 TPE or SK SP/BK 57-3 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v <sub>test</sub> =	100 mm/s
Switching operations	10,000
Actuation force	
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm	< 150 N
Actuation distance	
Test piece (cylinder) Ø 80 mm	8 mm
Actuation angle	1.450
Test piece (cylinder) Ø 80 mm	±45°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 25 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	1000 / 1000 / 200 / 200 mm
Operating velocity	
(min. / max.)	10 mm/s / 200 mm/s
Max. load capacity (impulse)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: Degree of protection	IP67
SP in water: 9 cm bottom edge	IPX8: 13 days
Operating temperature	-25 to +55 °C
short-term (15 min)	-40 to +80 °C
Storage temperature	-40 to +80 °C
Weight	SP 57-3
without aluminium profile	0.60 kg/m
with aluminium profile C 35	1.00 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>





### Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

# **Test conditions** according to ISO 13856-2

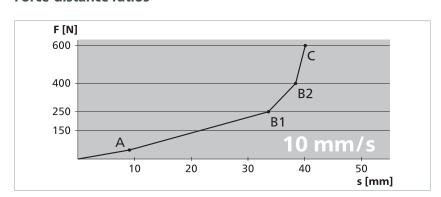
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø
   80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

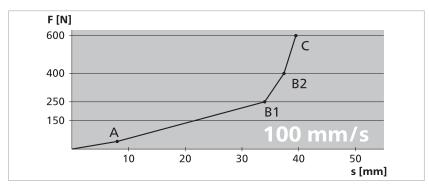
### **Force-distance ratios**

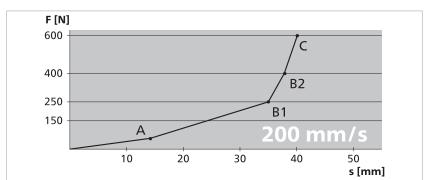
Test velocity	10 mm/s
Actuation force	48 N
Response time	910 ms
Actuation distance (A)	9.1 mm
Overtravel distance	
up to 250 N (B1)	24.5 mm
up to 400 N (B2)	29.3 mm
up to 600 N (C)	31.0 mm
Total deformation	40.1 mm

Test velocity 1	00 mm/s
Actuation force	41 N
Response time	80 ms
Actuation distance (A)	8.0 mm
Overtravel distance	
up to 250 N (B1)	26.0 mm
up to 400 N (B2)	29.4 mm
up to 600 N (C)	31.5 mm
Total deformation	39.5 mm

Test velocity 2	00 mm/s
Actuation force	58 N
Response time	71 ms
Actuation distance (A)	14.2 mm
Overtravel distance	
up to 250 N (B1)	20.8 mm
up to 400 N (B2)	23.7 mm
up to 600 N (C)	25.9 mm
Total deformation	40.1 mm



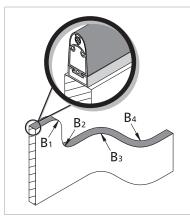






# SK SP 57(L)-4 TPE

Sensor profile (without control unit)	SK SP/W 57(L)-4 TPE or SK SP/BK 57(L)-4 TPE	
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2	
Switching characteristics at v <sub>test</sub> =	100 mm/s	
Switching operations Actuation force	10,000	
Test piece (rod) Ø 20 mm	< 50 N	
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N	
Test piece (cylinder) Ø 80 mm Actuation angle	8 mm	
Test piece (cylinder) Ø 80 mm	±45°	
Finger detection	Yes	
Safety classifications		
ISO 13849-1: B <sub>10D</sub>	2×10 <sup>6</sup>	
Mechanical operating conditions		
Sensor length (min./max.)	10 cm / 25 m	
Cable length (min./max.)	10 cm / 100 m	
Bend radii, minimum	1000 / 1000 / 200 / 200	
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub> Operating velocity	1000 / 1000 / 200 / 200 mm	
(min. / max.)	10 mm/s / 200 mm/s	
Max. load capacity (impulse)	600 N	
Tensile load, cable (max.)	20 N	
IEC 60529: Degree of protection	IP67	
SP in water: 9 cm bottom edge	IPX8: 13 days	
Operating temperature	−25 to +55 °C	
short-term (15 min)	-40 to +80 °C	
Storage temperature	-40 to +80 °C	
Weight without aluminium profile	SP 57-4 SP 57L-4	
with aluminium profile C 35	0.58 kg/m 0.62 kg/m 0.99 kg/m 1.03 kg/m	
	0.99 kg/111 1.05 kg/111	
Electrical operating conditions	01.2 - 4.0/	
Terminal resistance	8k2 ±1%	
Nominal output (max.) Contact transition resistance	250 mW < 400 ohms (per sensor)	
Number of BK-type sensors	Max. 5 in series	
Switching voltage (max.)	DC 24 V	
Switching current (min./max.)	1 mA / 10 mA	
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>	



# SP 57-4 TPE (1:2)

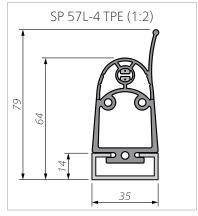
Dimensional tolerances according to ISO 3302 E2/L2

Test velocity

Actuation force

Response time

### Dimensions and distances



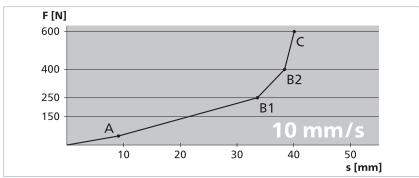
Dimensional tolerances according to ISO 3302 E2/L2

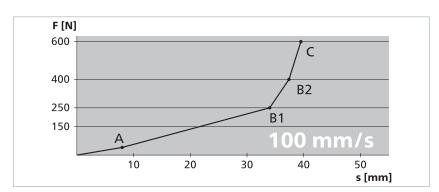
# **Test conditions** according to ISO 13856-2

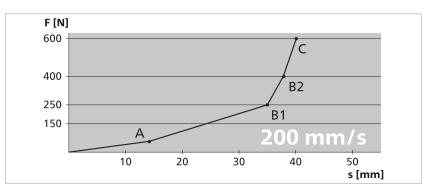
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø
   80 mm
- Without control unit
- Lip not taken into account

All data stated here is documented in EC type examination certificates.

### **Force-distance ratios**







10 mm/s

48 N

910 ms

Actuation distance (A	4) 9.1 mm
Overtravel distance	
up to 250 N (B1)	24.5 mm
up to 400 N (B2)	29.3 mm
up to 600 N (C)	31.0 mm
Total deformation	40.1 mm
Test velocity	100 mm/s
Actuation force	41 N
Response time	20 ms

rest velocity	00 1111111/3
Actuation force	41 N
Response time	80 ms
Actuation distance (A)	8.0 mm
Overtravel distance	
up to 250 N (B1)	26.0 mm
up to 400 N (B2)	29.4 mm
up to 600 N (C)	31.5 mm
Total deformation	39 5 mm

Actuation force	58 N
Response time	71 ms
Actuation distance (A	A) 14.2 mm
Overtravel distance	
up to 250 N (B1)	20.8 mm
up to 400 N (B2)	23.7 mm
up to 600 N (C)	25.9 mm
Total deformation	40.1 mm

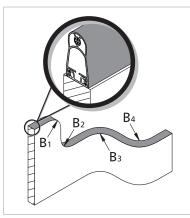
Test velocity

200 mm/s



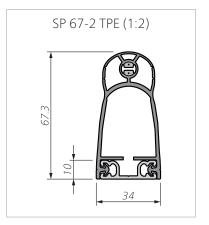
# **SK SP 67-2 TPE**

Sensor profile (without control unit)	SK SP/W 67-2 TPE or SK SP/BK 67-2 TPE	
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2	
Switching characteristics at v <sub>test</sub> =	100 mm/s	
Switching operations Actuation force	10,000	
Test piece (rod) Ø 20 mm	< 50 N	
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N	
Test piece (cylinder) Ø 80 mm Actuation angle	11 mm	
Test piece (cylinder) Ø 80 mm	± 45°	
Finger detection	Yes	
Safety classifications		
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>	
<b>Mechanical operating conditions</b>		
Sensor length (min./max.)	10 cm / 30 m	
Cable length (min./max.)	10 cm / 100 m	
Bend radii, minimum	1000 / 1000 / 200 / 200	
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	1000 / 1000 / 200 / 200 mm	
Operating velocity (min. / max.)	10 mm/s / 200 mm/s	
Max. load capacity (impulse)	600 N	
Tensile load, cable (max.)	20 N	
IEC 60529: Degree of protection	IP67	
SP in water: 9 cm bottom edge	IPX8: 13 days	
Operating temperature	−25 to +55 °C	
short-term (15 min)	−40 to +80 °C	
Storage temperature	−40 to +80 °C	
Weight	SP 67-2	
without aluminium profile	0.49 kg/m	
with aluminium profile C 30	0.79 kg/m	
Electrical operating conditions		
Terminal resistance	8k2 ±1%	
Nominal output (max.)	250 mW	
Contact transition resistance	< 400 ohms (per sensor)	
Number of BK-type sensors	Max. 5 in series	
Switching voltage (max.)	DC 24 V	
Switching current (min./max.)	1 mA / 10 mA	
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>	





### Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

# **Test conditions** according to ISO 13856-2

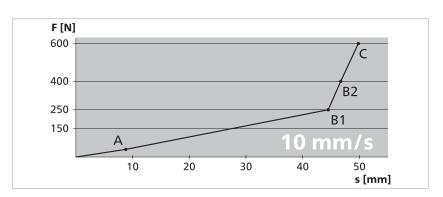
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø
   80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

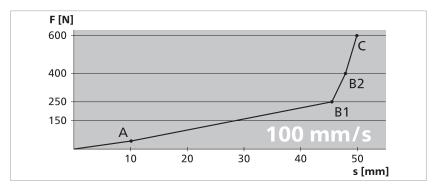
### **Force-distance ratios**

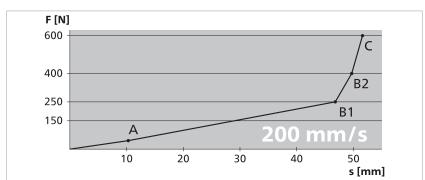
Test velocity	10 mm/s
Actuation force	41 N
Response time	880 ms
Actuation distance (A)	8.8 mm
Overtravel distance	
up to 250 N (B1)	35.7 mm
up to 400 N (B2)	37.9 mm
up to 600 N (C)	41 mm
Total deformation	49.8 mm

Test velocity 1	00 mm/s
Actuation force	43 N
Response time	101 ms
Actuation distance (A)	10.1 mm
Overtravel distance	
up to 250 N (B1)	35.4 mm
up to 400 N (B2)	37.8 mm
up to 600 N (C)	39.8 mm
Total deformation	49.9 mm

Test velocity 2	00 mm/s
Actuation force	45 N
Response time	51.5 ms
Actuation distance (A)	10.3 mm
Overtravel distance	
up to 250 N (B1)	36.5 mm
up to 400 N (B2)	39.4 mm
up to 600 N (C)	41.3 mm
Total deformation	51.6 mm



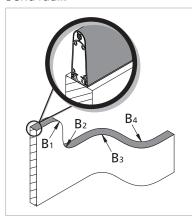






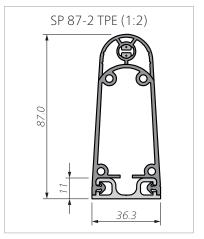
# SK SP 87-2 TPE

Sensor profile (without control unit)	SK SP/W 87-2 TPE or SK SP/BK 87-2 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v <sub>test</sub> =	100 mm/s
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	9 mm
Test piece (cylinder) Ø 80 mm	± 45°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 25 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	1000 / 1000 / 200 / 200 mm
Operating velocity	10 / 100
(min. / max.)	10 mm/s / 200 mm/s
Max. load capacity (impulse)	600 N
Tensile load, cable (max.)	20 N IP67
IEC 60529: Degree of protection SP in water: 9 cm bottom edge	IPX8: 13 days
Operating temperature	-25 to +55 °C
short-term (15 min)	-40 to +80 °C
Storage temperature	-40 to +80 °C
Weight	SP 87-2
without aluminium profile	0.64 kg/m
with aluminium profile C 36	1.06 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>





### Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

# **Test conditions** according to ISO 13856-2

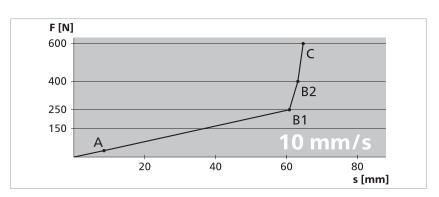
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

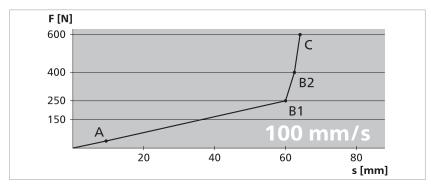
### **Force-distance ratios**

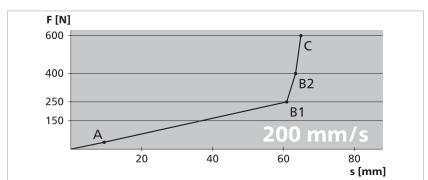
Test velocity	10 mm/s
Actuation force	34 N
Response time	850 ms
Actuation distance (A)	8.5 mm
Overtravel distance	
up to 250 N (B1)	52.3 mm
up to 400 N (B2)	54.7 mm
up to 600 N (C)	56.2 mm
Total deformation	64.7 mm

Test velocity <b>1</b>	00 mm/s
Actuation force	38 N
Response time	81 ms
Actuation distance (A)	8.1 mm
Overtravel distance	
up to 250 N (B1)	51.9 mm
up to 400 N (B2)	54.4 mm
up to 600 N (C)	56.0 mm
Total deformation	64.1 mm

Test velocity 20	00 mm/s
Actuation force	37 N
Response time	47 ms
Actuation distance (A)	9.4 mm
Overtravel distance	
up to 250 N (B1)	51.5 mm
up to 400 N (B2)	54.0 mm
up to 600 N (C)	55.5 mm
Total deformation	64.9 mm









# **Marking**

If you combine sensors with control units and thereby place pressure-sensitive protection devices on the market, you should observe the basic requirements according to ISO 13856.

As well as meeting technical requirements, this also means – in particular – observing any that relate to marking and information for use.

### **Conformity**

# EC type examination

The product has been tested by an independent institute.

There is an EC type examination certificate to confirm conformity.

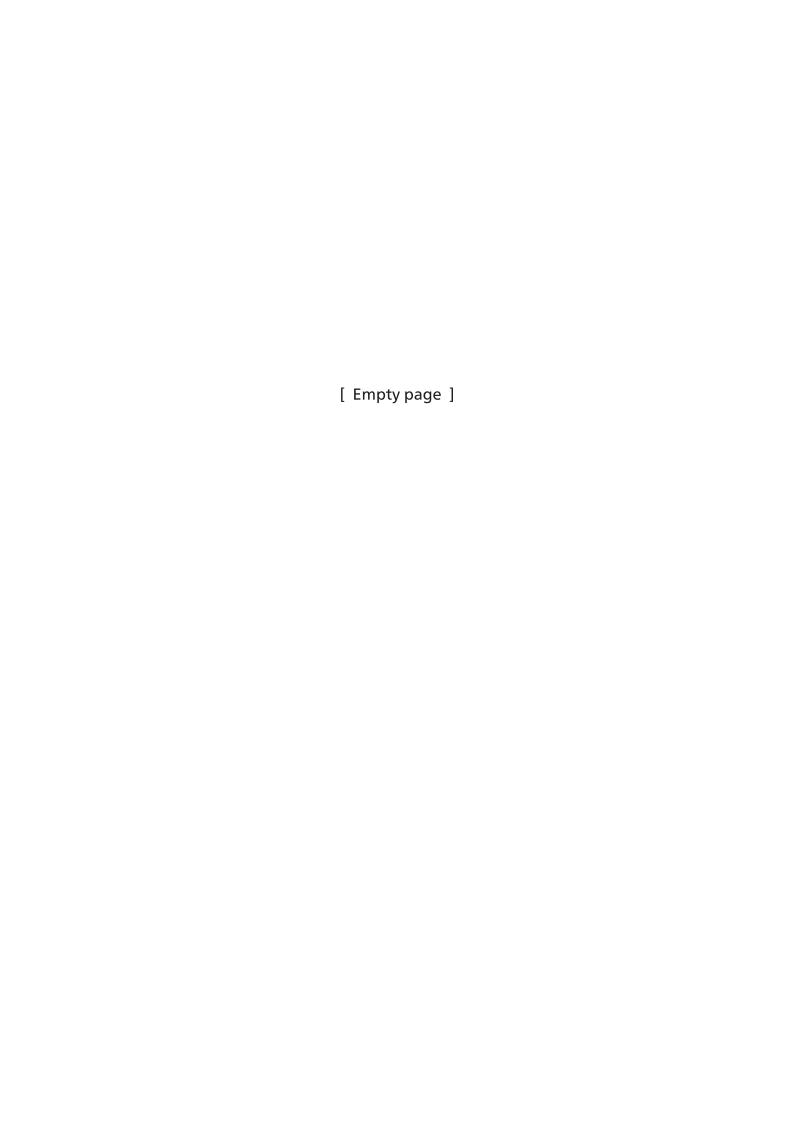
The EC type examination certificate is stored in the Downloads section of our website: www.mayser.com.

### **UL** certification



The design type of the product conforms to the basic requirements of UL certification:

• UL 325







# Safety edges SL



### Mayser GmbH & Co. KG

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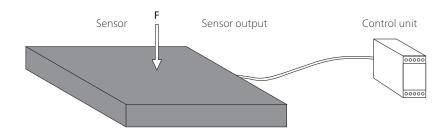
nical data21
GP 15-1 NBR21
GP 22-1 NBR
GP 39-1 NBR25
GP 39-1 EPDM27
GP 39L-1 EPDM
GP 50(L)-1 EPDM31
GP 50-1 CR
GP 60-1 EPDM35
GP 120-1 EPDM
formity39



### **Definitions**

# Pressure-sensitive protection device

A pressure-sensitive protection device consists of one or more pressure-sensitive sensors, a signal processing unit, and one or more output signal switching devices. The control unit is made up of the signal processing unit and output signal switching device(s). The pressure-sensitive protection device is triggered when the sensor is activated.

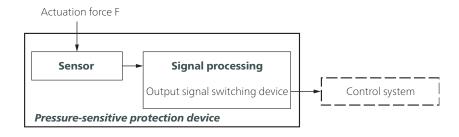


### Sensor

The sensor is the part of the pressure-sensitive protection device that generates a signal when the actuation force F is applied. Mayser safety systems feature a sensor whose actuation area is deformed locally.

### Signal processing

The signal processing unit is the part of the pressure-sensitive protection device that converts the output signal of the sensor and controls the status of the output signal switching device. The output signal switching device is the part of the signal processing unit which is connected to the forwarding control system and which transmits safety output signals such as STOP.



Tip: Terms are defined in ISO 13856-2 Section 3.

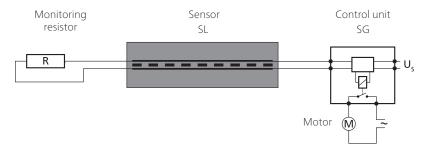
290421 v2.01-RiA

### Criteria for selecting the sensor type

- Category according to ISO 13849-1
- Performance level of the pressure-sensitive protection device
   at least PL<sub>e</sub>
- Temperature range
- Degree of protection in accordance with IEC 60529:
   IP67 is standard for safety edges.
   Higher degrees of protection must be checked individually.
- Environmental influences such as swarf, oil, coolant, outdoor use...
- Finger detection necessary?

Tip: For further sensor selection criteria, see ISO 13856-2 Annex C and Annex E.

# Operation principle of 2-wire technology



The monitoring resistor must be compatible with the control unit. The standard type is 8k2.

### For your safety:

The sensor and connection cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on controlled bridging of the contact surfaces with a monitoring resistor (closed-circuit principle).

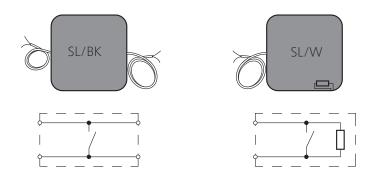


### **Types**

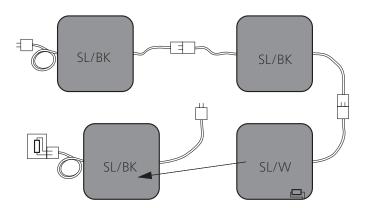
SL/BK With cables on both sides for use as a through sensor or with an external monitoring resistor for use as an end sen-

sor

SL/W With an integrated monitoring resistor for use as an end sensor



### **Sensor combination**

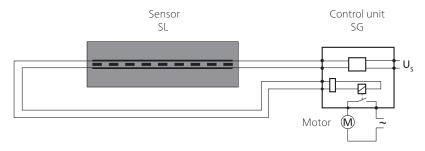


Version with external resistor, therefore no variety of models

### Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety edges can be combined to achieve custom lengths and angles

## Operation principle of 4-wire technology



The 4-wire technology can only be used together with control unit SG-EFS 104/4L.

#### For your safety:

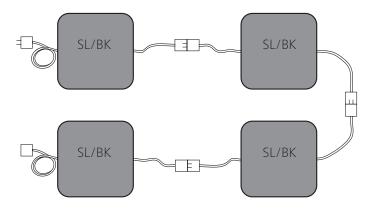
The sensor and connection cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on signal transmission feedback – without a monitoring resistor.

#### **Types**

SL/BK With cables on both sides for use as a through sensor



#### **Sensor combination**



#### Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety edges can be combined to achieve custom lengths and angles

Subject to technical modifications.



## **Safety**

#### Intended use

A safety edge detects a person or part of the body when pressure is applied to the effective actuation area. It is a linear tripping device. Its purpose is to prevent possible hazardous situations that could affect someone within a danger zone, such as shearing and pinching edges. Typical areas of application are door and gate systems, and moving parts on machines, platforms and lifting devices.

Safe operation of a safety edge depends entirely on

- the surface condition of the mounting surface,
- the correct selection of the size and resistance rating as well as
- correct installation.

For additional application guidance, please refer to ISO 13856-2 Annex E.

Due to the design, the actuation area is actually smaller than it looks because of the non-sensitive edges. Once these have been allowed for, what remains is the effective actuation area (see chapter *Effective actuation area*).

#### Limits

- No more than 10 /BK-type sensors can be connected to one control unit.
- No more than 9 /BK-type sensors and 1 /W-type sensor can be connected to one control unit.

## **Exclusions**

The sensors are not suitable for:

- Detecting fingers.
- Performing a sealing function. Constant actuation of sensors can result in permanent damage.

**Exception:** The L version with an attached lip seal.

The lip seal can be in full contact with the closing edge, which allows it to repel wind and water.

## Other safety aspects

The following safety aspects relate to pressure-sensitive protection devices consisting of a sensor and a control unit.

#### **Performance Level (PL)**

The PL has been determined using the procedure defined by ISO 13849-1.

Fault exclusion according to ISO 13849-2 Table D.8: Non-closing of contacts in the case of pressure-sensitive protection devices according to ISO 13856. In this case, the diagnostic coverage (DC) is not calculated or taken into account when determining the PL. Assuming a high MTTF $_{\rm D}$  value for the control unit, a performance level of up to PL d can be achieved by the safety edge system (pressure-sensitive protection device) as a whole.

#### Is the protection device suitable?

First, the integrator must decide what  ${\rm PL_r}$  is required for the hazard. After that, they must select the protection device.

Finally, the integrator needs to check whether the category and PL of the selected protection device are appropriate.

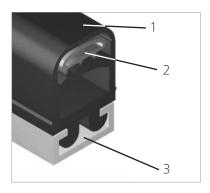
#### Risk and safety assessment

For the risk and safety assessment of your machine, we recommend ISO 12100 "Safety of machinery — General principles for design".

#### Without reset function

When a protection device without reset function is used (automatic reset), the reset function must be provided in some other way.

## Design



The safety edge SL consists of a sensor (1 to 3) –

- (1) rubber profile GP,
- (2) switch element,
- (3) aluminium profile and an evaluating control unit SG.

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Subject to technical modifications.

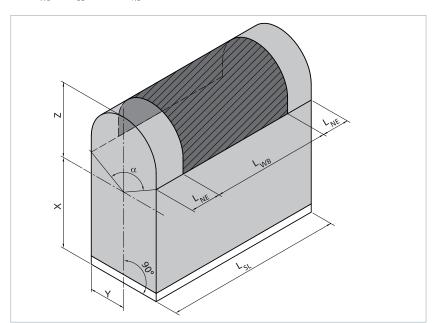


#### Effective actuation area

The parameters X, Y, Z,  $L_{WB}$  and the angle  $\alpha$  describe the effective actuation area.

For the effective actuation area, the following applies:

$$L_{WB} = L_{SL} - 2 \times L_{NE}$$



#### Parameters:

 $L_{WB}$ = effective actuation length

 $L_{SL}$  = overall length of safety edge

 $L_{NE} = non-sensitive length at the end of the safety edge$ 

 $\alpha$  = effective actuation angle

	GP 15-1	GP 22-1	GP 39-1	GP 39L-1	GP 50(L)-1	GP 60-1	GP 120-1
Aluminium profile	C 15	C 25	C 25	C 25	C 35	C 35	C 35
α	70°	70°	110°	120°	90°	110°	120°
L <sub>NE</sub>	35 mm	35 mm	35 mm	35 mm	35 mm	35 mm	35 mm
Υ	9.5 mm	12.5 mm	13 mm	14.5 mm	17.5 mm	18 mm	18 mm
X	14 mm	15 mm	33 mm	33 mm	40.5 mm	54.5 mm	110 mm
Z	7 mm	9 mm	7 mm	7 mm	21.5 mm	21.5 mm	19 mm
X + Z	21 mm	24 mm	40 mm	40 mm	62 mm	76 mm	129 mm

At 70°, the effective actuation angle  $\,\alpha\,$  of GP 15-1 and GP 22-1 falls below the requirements of ISO 13856-2 and EN 12978.

## Installation position

The installation position can be selected as required, i.e. all installation positions from A to D as per ISO 13856-2 are possible.

Subject to technical modifications.

tallation

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## **Connection**

## Cable exits

- With cable sleeves in some cases
- L-type (L) rubber profiles: the rubber lip is always located on the lefthand side when the product is viewed from the end
- Other designs (e.g. shorter non-sensitive ends) available on request

Cable exit (	CE)			SL	GP		
		15-1	22-1	39 (L)-1	50 (L)-1	60-1	120-1
Distance betw. CE & en	At the bottom Distance betw. CE & end = 25 mm in each case; versions with cable sleeves						
Version 11: SL/W				•	•	•	•
Version 5: SL/BK				•	•	•	•
At the side Distance betw. CE & en each case; versions withou	d = 25 mm in		1	1			
Version 12: SL/W				•	•	•	
Version 13: SL/W				•	•	•	
Version 14: SL/BK				•	•	•	
<b>Axial exit at</b> Versions without cal							
Version 9: SL/W		•	•	•	•	•	•
Version 10: SL/W				•	•	•	•
Version 1: SL/BK		•	•	•	•	•	•
Version 3: SL/BK				•	•	•	•
Version 4: SL/BK				•	•	•	•

• = available

Subject to technical modifications.



#### Cable connection

Standard cable lengths
 L = 2.0 m / 5.0 m / 10 m

• Maximum total cable length to the control unit  $L_{max} = 100 \text{ m}$ 

• Cable ends: stripped wires
Option: Cable ends available with plug and coupling

/W-type sensor with 1 line	/BK-type sensor with 2 lines
<ul> <li>As an individual /W-type sensor or a /W-type end sensor</li> <li>Integrated resistor</li> <li>Two-wire cables</li> </ul>	<ul> <li>As a /BK-type through sensor</li> <li>Without resistor</li> <li>2 two-wire cables</li> </ul>

## Wire colours

/W-type sensor with 1 line	/BK-type sensor with 2 lines
RD I BK	RD ← — — → RD

## Connection examples

Key:

SG 2W Evaluation with 2-wire technology SG 4L Evaluation with 4-wire technology

Subject to technical modifications.

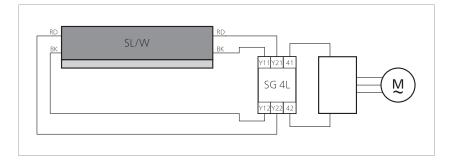
**Colour coding** 

Black

Red

ВК

RD



### **Sensor surface**

#### Resistance

The resistance ratings listed below (at a room temperature of 23  $^{\circ}$ C) depend on the sensor having an undamaged surface.

#### **Physical resistance**

Rubber profile GP	EPDM	NBR	CR
UV resistance	Yes	Yes	Yes

#### **Chemical resistance**

The sensor is broadly resistant to normal chemical influences such as diluted acids and alkalis, as well as alcohol, over an exposure period of 24 hrs.

The values in the table are the results of tests carried out in our laboratory. You must always conduct your own practical tests to verify that our products are suitable for your specific area of application.

#### **Explanation of symbols:**

+ = resistant

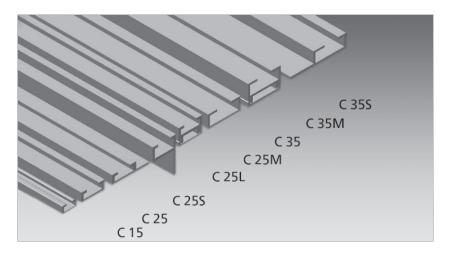
 $\pm$  = resistant to a certain extent

– = not resistant

Chemical resistance	EPDM	NBR	CR
Acetone	+	±	+
Formic acid	+	+	+
Ammonia	+	+	+
Petrol	_	+	+
Brake fluid	<u>±</u>	±	<u>±</u>
Chloride solutions	+	+	+
Diesel oil	_	+	+
Greases	_	+	+
Household/sanitary cleaners	+	+	+
Isopropanol	+	+	+
Cooling lubricant	_	+	+
Metal working oil	_	+	+
Methanol	+	+	±
Oils	_	+	+
Ozone and weather conditions	+	_	+
Hydrochloric acid 10%	+	+	+
Ethyl alcohol (ethanol)	+	+	+
Carbon tetrachloride	_	+	+
Water and frost	+	_	+
Hydrogen peroxide 10%	+	+	_

## **Mounting**

The sensors are mounted directly onto the main and secondary closing edges that present a danger. They are fixed using special aluminium profiles. The profiles are fastened with screws or rivets.



#### **Material properties**

- AlMgSi0.5 F22
- Wall thickness: at least 2.0 mm
   C 15: at least 1.7 mm
- Extruded
- Hot hardened
- Tolerances as per EN 755-9

Subject to technical modifications.

## Aluminium profiles:

## Overview of combinations

Sensor pr	ofile foot	C 15	C 25 C 25M C 25S C 25L	C 25 C 25M C 25S C 25L	C 35 C 35M C 35S	C 35 C 35M C 35S	C 35 C 35M C 35S
Snap-in foot (middle)	1	GP 15-1	GP 22-1	GP 39(L)-1	GP 50(L)-1	GP 60-1	GP 120-1

## Aluminium profiles: Mounting types

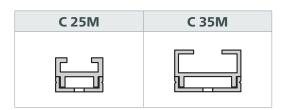
#### **Standard profile**

First the aluminium profile must be mounted onto the closing edge and then the sensor profile clipped into the aluminium profile.

C 15	C 25	C 35

#### Two-part profile, type M

For convenient assembly and disassembly. The sensor profile is clipped into the upper section and the upper section inserted into the installed lower section and fastened.



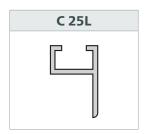
#### Flange profile, type S

Final assembly is also possible when the sensor profile is already clipped into the aluminium profile.

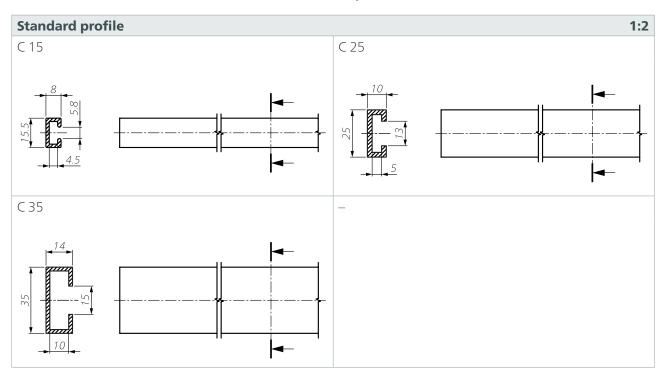
C 25S	C 35S

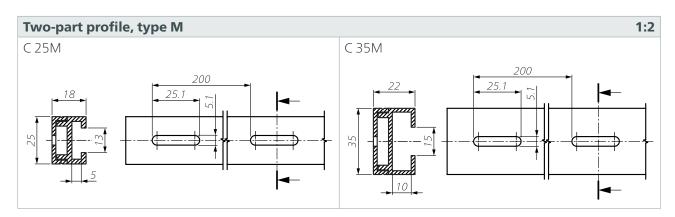
#### Angle profile, type L

If the closing edge should not or must not have assembly holes, this "round-the-corner" solution is suitable. Final assembly is also possible when the sensor profile is already clipped into the aluminium profile.

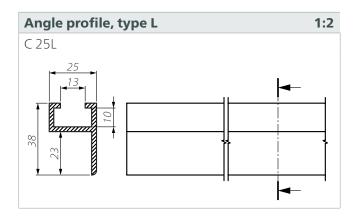


## Aluminium profiles: Dimensions





Subject to technical modifications.





## $s_1$ = Stopping distance of the dangerous movement

v = Velocity of the dangerous movement [ mm/s ]

[ mm ]

- T = Follow-through time of the complete system [s]
- $t_1$  = Safety edge response time
- t<sub>2</sub> = Stopping time of the machine
- s = Minimum overtravel distance of the safety edge to ensure that the stipulated limit forces are not exceeded [ mm ]
- C = Safety factor; if components susceptible to failures (braking system) exist in the system, a higher factor must be selected.

## **SL: Making the right selection**

# Calculation for selection of the safety edge height

The stopping distance of the dangerous movement is calculated using the following formula:

$$s_1 = 1/2 \times v \times T$$
 where:  $T = t_1 + t_2$ 

In accordance with ISO 13856-2, the minimum overtravel distance of the safety edge is calculated using the following formula:

$$s = s_1 \times C$$
 where:  $C = 1.2$ 

A suitable safety edge profile can now be selected based on the result. For details of the overtravel distances for safety edge profiles, see chapter *Technical data*.

## Calculation examples

#### **Calculation example 1**

The dangerous movement on your machine has a velocity of v=10 mm/s and can be brought to a standstill within  $t_2=190 \text{ ms}$ . The relatively low velocity suggests that a short overtravel distance is to be expected. Therefore, the normally closed safety edge SL GP 39-1 EPDM might be sufficient. The response time of the safety edge is  $t_1=435 \text{ ms}$ .

$$s_1 = 1/2 \times v \times T$$
 where:  $T = t_1 + t_2$   
 $s_1 = 1/2 \times 10 \text{ mm/s} \times (435 \text{ ms} + 190 \text{ ms})$   
 $s_1 = 1/2 \times 10 \text{ mm/s} \times 0.625 \text{ s} = 3.1 \text{ mm}$ 

$$s = s_1 \times C$$
 where:  $C = 1.2$ 

$$s = 3.1 \text{ mm} \times 1.2 = 3.8 \text{ mm}$$

The safety edge must have a minimum overtravel distance of s = 3.8 mm. The selected SL GP 39-1 EPDM has an overtravel distance of at least 10.9 mm. This is more than the required 3.8 mm.

**Result:** The SL GP 39-1 EPDM is **suitable** for this case.

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Subject to technical modifications.

#### **Calculation example 2**

The same conditions apply as in calculation example 1 with the exception of the velocity of the dangerous movement. This is now v = 100 mm/s. As a result, the response time of the safety edge is reduced to  $t_1 = 59$  ms.

$$s_1 = 1/2 \times v \times T$$
 where:  $T = t_1 + t_2$   
 $s_1 = 1/2 \times 100 \text{ mm/s} \times (59 \text{ ms} + 190 \text{ ms})$   
 $s_1 = 1/2 \times 100 \text{ mm/s} \times 0.249 \text{ s} = 12.5 \text{ mm}$ 

$$s = s_1 \times C$$
 where:  $C = 1.2$ 

$$s = 12.5 \text{ mm} \times 1.2 = 15.0 \text{ mm}$$

The safety edge must have a minimum overtravel distance of s = 15.0 mm. The selected SL GP 39-1 EPDM has an overtravel distance of at least 7.7 mm. This is less than the required 15.0 mm.

**Result:** The SL GP 39-1 EPDM is **not suitable** for this case.

#### **Calculation example 3**

The same conditions as in calculation example 2. Instead of the SL GP 39-1 EPDM, the SL GP 120-1 EPDM is selected. The response time of the safety edge is  $t_1 = 95$  ms.

$$s_1 = 1/2 \times v \times T$$
 where:  $T = t_1 + t_2$   
 $s_1 = 1/2 \times 100 \text{ mm/s} \times (95 \text{ ms} + 190 \text{ ms})$   
 $s_1 = 1/2 \times 100 \text{ mm/s} \times 0.285 \text{ s} = 14.3 \text{ mm}$   
 $s = s_1 \times C$  where:  $C = 1.2$ 

$$s = 14.3 \text{ mm} \times 1.2 = 17.2 \text{ mm}$$

The safety edge must have a minimum overtravel distance of s=17.2 mm. With a velocity of 100 mm/s, the selected SL GP 120-1 EPDM has an overtravel distance of at least 17.7 mm. This is more than the required 17.2 mm.

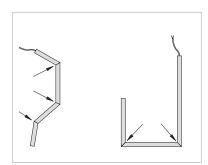
**Result:** The SL GP 120-1 EPDM is **suitable** for this case.



## **Customised designs**

In addition to the standard range, special solutions are also possible, such as:

- Safety edges with sensitive ends
- Resistance to high temperatures:
  - short-term (< 15 min) up to +80 °C
  - long-term up to +55 °C
  - with degree of protection: IP50
- Resistance to low temperatures:
  - long-term down to −20 °C
- Angled safety edges with sensitive zones in the corner areas
- Safety edges GP 39-1, GP 50-1, GP 60-1 and GP 120-1 can be supplied with sensitive ends



## **Maintenance and cleaning**

The sensors are virtually maintenance-free.

The control unit also monitors the sensor at the same time.

#### **Regular inspection**

Depending on the operational demands, the sensors must be inspected at regular intervals (at least monthly)

- for proper functioning,
- for damage and
- for correct mounting.

#### **Cleaning**

If the sensors become dirty, they can be cleaned with a mild cleaning product.

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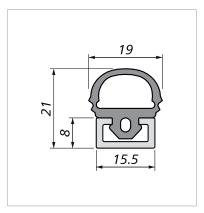


## **GP 15-1 NBR**

Safety edge	SL/W GP 15-1 NBR with SG-EFS 104/2W
Testing basis	In accordance with ISO 13856-2
Switching characteristics at v <sub>test</sub> =	= 10 mm/s
Switching operations Actuation force	10,000
Test piece (cylinder) Ø 80 mm Actuation distance	< 139 N
Test piece (cylinder) Ø 80 mm Actuation angle	2.8 mm
Test piece (cylinder) Ø 80 mm	±35°
Response time	295 ms
Finger detection	No
Safety classifications	
ISO 13856: reset function	With/without
ISO 13849-1:2015	Category 3 PL d
MTTF <sub>D</sub> (PSPD)	192 a
MTTF <sub>D</sub> (sensor)	761 a
B <sub>10D</sub> (sensor)	$4 \times 10^{6}$
n <sub>op</sub> (assumption)	52,560/a
Mechanical operating conditions	5
Sensor length (min./max.)	20 cm / 6 m
Cable length (min./max.) Bend radii, minimum	2.0 m / 100 m
$B_1$ / $B_2$ / $B_3$ / $B_4$ Bend angles, maximum	Not possible
K <sub>1</sub> / K <sub>2</sub> / K <sub>3</sub> / K <sub>4</sub>	Not possible
Operating velocity	10 mm/s
Load capacity (max.)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: degree of protection	1P67
Humidity (max. at 23 °C)	95% (non-condensing)
Operating temperature	−10 to +50 °C −10 to +50 °C
Storage temperature Weight (without / with aluminium	-10 t0 +50 C
profile C 15)	0.14 / 0.28 kg/m
Electrical operating conditions	
Connection cable	Ø 3.8 mm TPU, 2 × 0.25 mm <sup>2</sup>
Sensor	24 V DC / max. 10 mA
Number of /BK-type sensors	Max. 10 in series



GP 15-1 NBR (1:1)



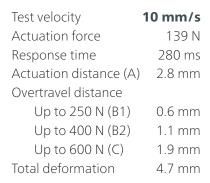
Dimensional tolerances according to ISO 3302 E2/L2

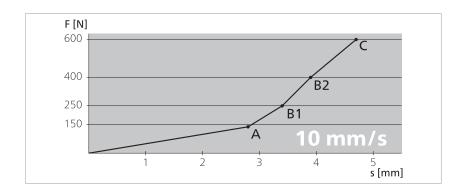
#### **Test conditions**

according to ISO 13856-2

- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.

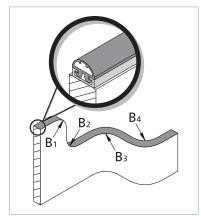


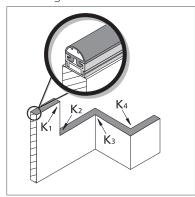


## **GP 22-1 NBR**

Safety edge	SL/W GP 22-1 NBR with SG-EFS 104/2W
Testing basis	In accordance with ISO 13856-2
Switching characteristics at v <sub>test</sub> =	10 mm/s
Switching operations	10,000
Actuation force Test piece (cylinder) Ø 80 mm	< 60 N
Actuation distance	
Test piece (cylinder) Ø 80 mm	3.1 mm
Actuation angle Test piece (cylinder) Ø 80 mm	±35°
Response time	325 ms
Finger detection	No
Safety classifications	
ISO 13856: reset function	With/without
ISO 13849-1:2015	Category 3 PL d
MTTF <sub>D</sub> (PSPD)	192a
MTTF <sub>D</sub> (sensor)	761a
B <sub>10D</sub> (sensor)	$4 \times 10^{6}$
n <sub>op</sub> (assumption)	52,560/a
Mechanical operating conditions	
Sensor length (min./max.)	20 cm / 6 m
Cable length (min./max.)	2.0 m / 100 m
Bend radii, minimum	With C 25 only
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	300 / 350 / 300 / 300 mm
Bend angles, maximum	
K <sub>1</sub> / K <sub>2</sub> / K <sub>3</sub> / K <sub>4</sub>	25° / 10° / 90° / 90°
Operating velocity	10 mm/s
Load capacity (max.)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: degree of protection	IP67
Humidity (max. at 23 °C)	95% (non-condensing)
Operating temperature	+5 to +40 °C
Storage temperature	+5 to +40 °C
Weight (without / with aluminium profile C 25)	0.26 / 0.58 kg/m
Electrical operating conditions	<u> </u>
Connection cable	Ø 3.8 mm TPU, 2 × 0.25 mm <sup>2</sup>
Sensor	24 V DC / max. 10 mA
Number of /BK-type sensors	Max. 10 in series
71:	1

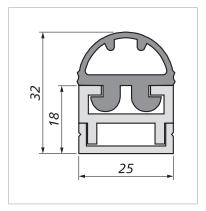
#### Bend radii:







GP 22-1 NBR (1:1)



Dimensional tolerances according to ISO 3302 E2/L2

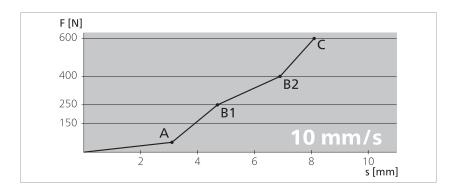
#### **Test conditions**

according to ISO 13856-2

- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.

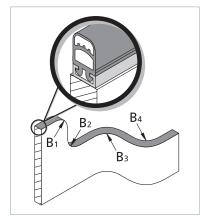
Test velocity	10 mm/s
Actuation force	60 N
Response time	310 ms
Actuation distance (A)	3.1 mm
Overtravel distance	
Up to 250 N (B1)	1.6 mm
Up to 400 N (B2)	3.8 mm
Up to 600 N (C)	5.0 mm
Total deformation	8.1 mm

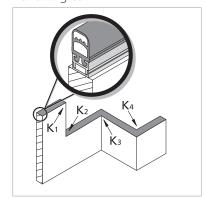


## **GP 39-1 NBR**

Safety edge	SL/W GP 39-1 NBR with SG-EFS 104/2W	
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2	
Switching characteristics at v <sub>test</sub> =	100 mm/s	
Switching operations Actuation force Test piece (cylinder) Ø 80 mm Actuation distance	10,000 < 150 N 3.5 mm	
Test piece (cylinder) Ø 80 mm Actuation angle Test piece (cylinder) Ø 80 mm Response time Finger detection	±55° 50 ms No	
Safety classifications		
ISO 13856: reset function ISO 13849-1:2015  MTTF <sub>D</sub> (PSPD)  MTTF <sub>D</sub> (sensor) $B_{10D}$ (sensor) $n_{op}$ (assumption)	With/without Category 3 PL d 192 a 761a 4 × 10 <sup>6</sup> 52,560/a	
Mechanical operating conditions		
Sensor length (min./max.) Cable length (min./max.) Bend radii, minimum B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub> Bend angles, maximum K <sub>1</sub> / K <sub>2</sub> / K <sub>3</sub> / K <sub>4</sub> Operating velocity (min. / max.) Load capacity (max.) Tensile load, cable (max.) IEC 60529: degree of protection Humidity (max. at 23 °C) Operating temperature Storage temperature Weight (without / with aluminium profile C 25)	20 cm / 6 m 2.0 m / 100 m With C 25 only 300 / 350 / 300 / 300 mm 20° / 10° / 90° / 90° 10 mm/s / 100 mm/s 600 N 20 N IP67 95% (non-condensing) -10 to +50 °C -10 to +50 °C 0.51 / 0.83 kg/m	
Electrical operating conditions		
Connection cable Sensor Number of /BK-type sensors	Ø 3.8 mm TPU, 2 × 0.25 mm <sup>2</sup> 24 V DC / max. 10 mA Max. 10 in series	

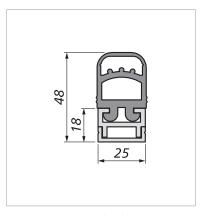
#### Bend radii:







GP 39-1 NBR (1:2)



Dimensional tolerances according to ISO 3302 E2/L2

#### **Test conditions**

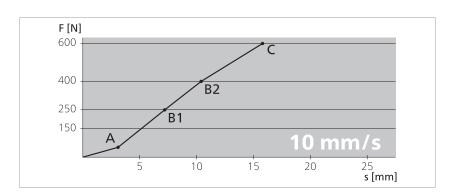
according to ISO 13856-2

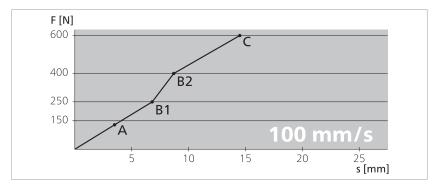
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.



Test velocity 10	00 mm/s
Actuation force	129 N
Response time	35 ms
Actuation distance (A)	3.5 mm
Overtravel distance	
Up to 250 N (B1)	3.3 mm
Up to 400 N (B2)	5.2 mm
Up to 600 N (C)	11.0 mm
Total deformation	14.5 mm

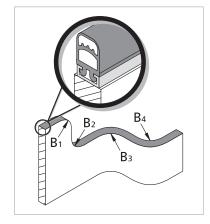


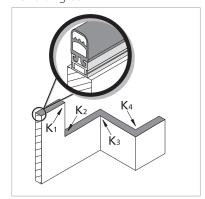


## **GP 39-1 EPDM**

Safety edge	SL/W GP 39-1 EPDM with SG-EFS 104/2W	
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2	
Switching characteristics at v <sub>test</sub> = 100 mm/s		
Switching operations Actuation force	10,000	
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N	
Test piece (cylinder) Ø 80 mm Actuation angle	4.4 mm	
Test piece (cylinder) Ø 80 mm Response time Finger detection	±40° 59 ms	
Safety classifications	TVO	
ISO 13856: reset function ISO 13849-1:2015 MTTF <sub>D</sub> (PSPD) MTTF <sub>D</sub> (sensor) B <sub>10D</sub> (sensor) n <sub>op</sub> (assumption)	With/without Category 3 PL d 192 a 761 a 4 × 10 <sup>6</sup> 52,560/a	
Mechanical operating conditions		
Sensor length (min./max.) Cable length (min./max.) Bend radii, minimum B1 / B2 / B3 / B4 Bend angles, maximum K1 / K2 / K3 / K4 Operating velocity (min. / max.) Load capacity (max.) Tensile load, cable (max.) IEC 60529: degree of protection Humidity (max. at 23 °C) Operating temperature Storage temperature Weight (without / with aluminium	20 cm / 6 m 2.0 m / 100 m With C 25 only 300 / 350 / 300 / 300 mm 20° / 10° / 90° / 90° 10 mm/s / 100 mm/s 600 N 20 N IP67 95% (non-condensing) -20 to +55 °C	
profile C 25)	0.43 / 0.75 kg/m	
Electrical operating conditions		
Connection cable Sensor Number of /BK-type sensors	Ø 3.7 mm TPE, 2 × 0.22 mm <sup>2</sup> 24 V DC / max. 10 mA Max. 10 in series	

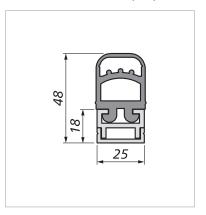
#### Bend radii:







GP 39-1 EPDM (1:2)



Dimensional tolerances according to ISO 3302 E2/L2

#### **Test conditions**

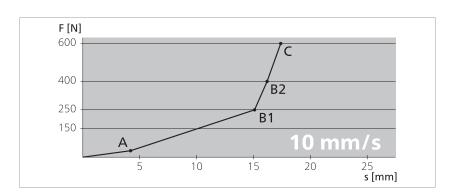
according to ISO 13856-2

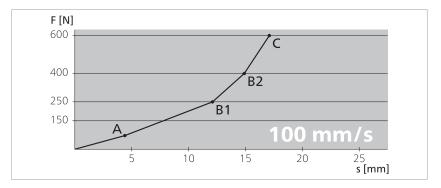
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.

Test velocity	10 mm/s
Actuation force	34 N
Response time	420 ms
Actuation distance (A)	4.2 mm
Overtravel distance	
Up to 250 N (B1)	10.9 mm
Up to 400 N (B2)	12.0 mm
Up to 600 N (C)	13.2 mm
Total deformation	17.4 mm

Test velocity <b>1</b>	00 mm/s
Actuation force	72 N
Response time	44 ms
Actuation distance (A)	4.4 mm
Overtravel distance	
Up to 250 N (B1)	7.7 mm
Up to 400 N (B2)	10.5 mm
Up to 600 N (C)	12.7 mm
Total deformation	17.1 mm

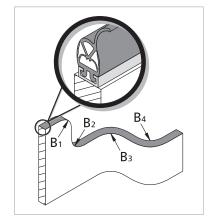


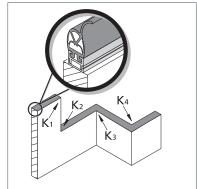


## GP 39L-1 EPDM

Safety edge	SL/W GP 39L-1 EPDM with SG-EFS 104/2W	
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2	
Switching characteristics at v <sub>test</sub> =	: 100 mm/s	
Switching operations Actuation force Test piece (cylinder) Ø 80 mm Actuation distance	10,000 < 150 N	
Test piece (cylinder) Ø 80 mm Actuation angle	18.9 mm	
Test piece (cylinder) Ø 80 mm Response time Finger detection	±60° 204 ms No	
Safety classifications		
ISO 13856: reset function ISO 13849-1:2015  MTTF <sub>D</sub> (PSPD)  MTTF <sub>D</sub> (sensor) $B_{10D}$ (sensor) $n_{op}$ (assumption)	With/without Category 3 PL d 192 a 761 a 4 × 10 <sup>6</sup> 52,560/a	
Mechanical operating conditions		
Sensor length (min./max.) Cable length (min./max.) Bend radii, minimum B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub> Bend angles, maximum K <sub>1</sub> / K <sub>2</sub> / K <sub>3</sub> / K <sub>4</sub> Operating velocity (min. / max.) Load capacity (max.) Tensile load, cable (max.) IEC 60529: degree of protection Humidity (max. at 23 °C) Operating temperature Storage temperature Weight (without / with aluminium profile C 25)	20 cm / 6 m 2.0 m / 100 m With C 25 only 300 / 350 / 300 / 300 mm 20° / 10° / 90° / 90° 10 mm/s / 100 mm/s 600 N 20 N IP67 95% (non-condensing) -20 to +55 °C -20 to +55 °C 0.52 / 0.84 kg/m	
Electrical operating conditions		
Connection cable Sensor Number of /BK-type sensors	Ø 3.7 mm TPE, 2 × 0.22 mm <sup>2</sup> 24 V DC / max. 10 mA Max. 10 in series	

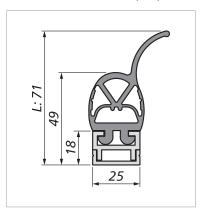
#### Bend radii:







GP 39L-1 EPDM (1:2)



Dimensional tolerances according to ISO 3302 E2/L2

#### **Test conditions**

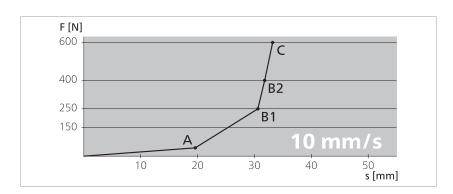
according to ISO 13856-2

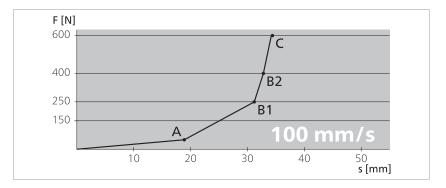
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.



Test velocity 1	00 mm/s
Actuation force	50 N
Response time	189 ms
Actuation distance (A)	18.9 mm
Overtravel distance	
Up to 250 N (B1)	12.3 mm
Up to 400 N (B2)	13.9 mm
Up to 600 N (C)	14.5 mm
Total deformation	34.4 mm

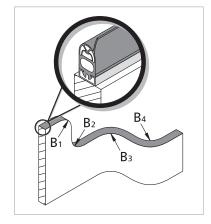


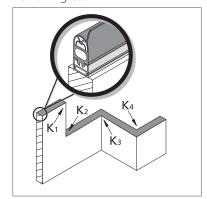


## GP 50(L)-1 EPDM

Safety edge	SL/W GP 50(L)-1 EPDM with SG-EFS 104/2W	
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2	
Switching characteristics at v <sub>test</sub> = 100 mm/s		
Switching operations Actuation force	10,000	
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N	
Test piece (cylinder) Ø 80 mm Actuation angle	6.3 mm	
Test piece (cylinder) Ø 80 mm	±45°	
Response time	78 ms	
Finger detection	No	
Safety classifications		
ISO 13856: reset function	With/without	
ISO 13849-1:2015	Category 3 PL d	
MTTF <sub>D</sub> (PSPD)	192 a	
MTTF <sub>D</sub> (sensor)	761 a	
B <sub>10D</sub> (sensor)	$4 \times 10^6$	
n <sub>op</sub> (assumption)	52,560/a	
Mechanical operating conditions		
Sensor length (min./max.)	20 cm / 6 m	
Cable length (min./max.)	2.0 m / 100 m	
Bend radii, minimum	With C 35 only	
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	400 / 450 / 550 / 550 mm	
Bend angles, maximum K <sub>1</sub> / K <sub>2</sub> / K <sub>3</sub> / K <sub>4</sub>	15° / 10° / 90° / 90°	
Operating velocity	13 / 10 / 90 / 90	
(min. / max.)	10 mm/s / 100 mm/s	
Load capacity (max.)	600 N	
Tensile load, cable (max.)	20 N	
IEC 60529: degree of protection	IP67	
Humidity (max. at 23 °C)	95% (non-condensing)	
Operating temperature	−20 to +55 °C	
Storage temperature	−20 to +55 °C	
Weight (without / with aluminium		
profile C 35)	1.1 / 1.5 kg/m	
Electrical operating conditions		
Connection cable	Ø 3.7 mm TPE, 2 × 0.22 mm <sup>2</sup>	
Sensor	24 V DC / max. 10 mA	
Number of /BK-type sensors	Max. 10 in series	

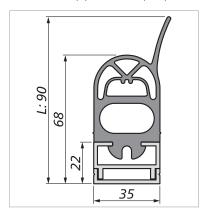
#### Bend radii:







GP 50(L)-1 EPDM (1:2)



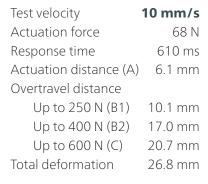
Dimensional tolerances according to ISO 3302 E2/L2

#### **Test conditions**

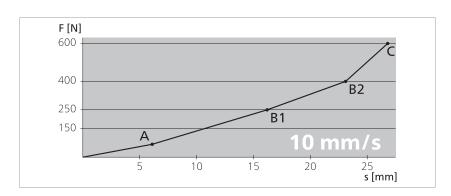
according to ISO 13856-2

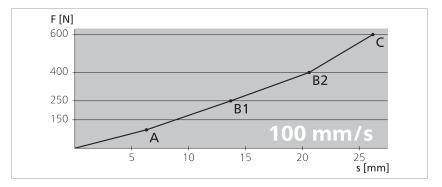
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.



Test velocity 1	00 mm/s
Actuation force	97 N
Response time	63 ms
Actuation distance (A)	6.3 mm
Overtravel distance	
Up to 250 N (B1)	7.4 mm
Up to 400 N (B2)	14.3 mm
Up to 600 N (C)	19.9 mm
Total deformation	26.2 mm

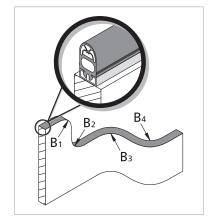


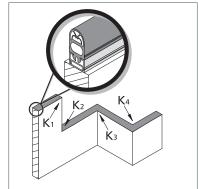


## GP 50-1 CR

Safety edge	SL/W GP 50-1 CR with SG-EFS 104/2W
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at $v_{test}$ =	= 100 mm/s
Switching operations	10,000
Actuation force	
Test piece (cylinder) Ø 80 mm	< 150 N
Actuation distance Test piece (cylinder) Ø 80 mm	4.8 mm
Actuation angle	4.011111
Test piece (cylinder) Ø 80 mm	±45°
Response time	63 ms
Finger detection	No
Safety classifications	
ISO 13856: reset function	With/without
ISO 13849-1:2015	Category 3 PL d
MTTF <sub>D</sub> (PSPD)	192 a
MTTF <sub>D</sub> (sensor)	761 a
B <sub>10D</sub> (sensor)	$4 \times 10^{6}$
n <sub>op</sub> (assumption)	52,560/a
Mechanical operating conditions	5
Sensor length (min./max.)	20 cm / 6 m
Cable length (min./max.)	2.0 m / 100 m
Bend radii, minimum	With C 35 only
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	400 / 450 / 550 / 550 mm)
Bend angles, maximum	
K <sub>1</sub> / K <sub>2</sub> / K <sub>3</sub> / K <sub>4</sub>	15° / 10° / 90° / 90°
Operating velocity	10 mm/s / 100 mm/s
(min. / max.)	10 mm/s / 100 mm/s 600 N
Load capacity (max.)	
Tensile load, cable (max.)	20 N IP67
IEC 60529: degree of protection Humidity (max. at 23 °C)	95% (non-condensing)
	-20 to +55 °C
Operating temperature	-20 to +55 °C
Storage temperature Weight (without / with aluminium	-20 to +33 C
profile C 35)	1.05 / 1.45 kg/m
Electrical operating conditions	
Connection cable	Ø 3.8 mm TPU, 2 × 0.25 mm <sup>2</sup>
Sensor	24 V DC / max. 10 mA
e e	

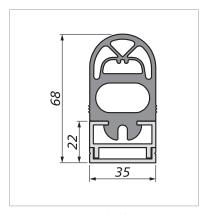
#### Bend radii:







GP 50-1 CR (1:2)



Dimensional tolerances according to ISO 3302 E2/L2

#### **Test conditions**

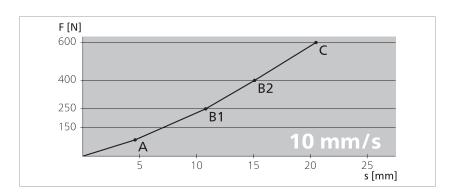
according to ISO 13856-2

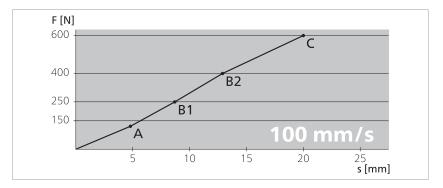
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.



Test velocity 10	00 mm/s
Actuation force	121 N
Response time	48 ms
Actuation distance (A)	4.8 mm
Overtravel distance	
Up to 250 N (B1)	3.9 mm
Up to 400 N (B2)	8.1 mm
Up to 600 N (C)	15.2 mm
Total deformation	20.0 mm

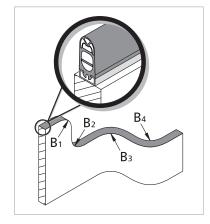


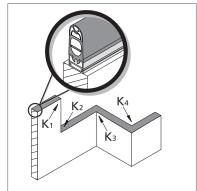


## **GP 60-1 EPDM**

Safety edge	SL/W GP 60-1 EPDM with SG-EFS 104/2W
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v <sub>test</sub> =	100 mm/s
Switching operations Actuation force	10,000
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	5.5 mm
Test piece (cylinder) Ø 80 mm	±60°
Response time	70 ms
Finger detection	No
Safety classifications	
ISO 13856: reset function ISO 13849-1:2015  MTTF <sub>D</sub> (PSPD)  MTTF <sub>D</sub> (sensor) $B_{10D}$ (sensor) $n_{op}$ (assumption)	With/without Category 3 PL d 192 a 761 a 4 × 10 <sup>6</sup> 52,560/a
Mechanical operating conditions	
Sensor length (min./max.) Cable length (min./max.) Bend radii, minimum B1 / B2 / B3 / B4 Bend angles, maximum K1 / K2 / K3 / K4 Operating velocity (min. / max.) Load capacity (max.) Tensile load, cable (max.) IEC 60529: degree of protection Humidity (max. at 23 °C) Operating temperature Storage temperature Weight (without / with aluminium profile C 35)	20 cm / 6 m 2.0 m / 100 m With C 35 only 450 / 550 / 550 / 550 mm 15° / 10° / 90° / 90° 10 mm/s / 100 mm/s 600 N 20 N IP67 95% (non-condensing) -20 to +55 °C -20 to +55 °C 1.16 / 1.56 kg/m
<b>Electrical operating conditions</b>	
Connection cable Sensor Number of /BK-type sensors	Ø 3.7 mm TPE, 2 × 0.22 mm <sup>2</sup> 24 V DC / max. 10 mA Max. 10 in series

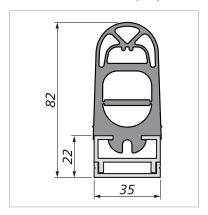
#### Bend radii:







GP 60-1 EPDM (1:2)



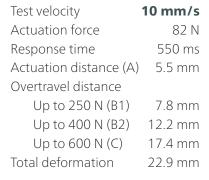
Dimensional tolerances according to ISO 3302 E2/L2

#### **Test conditions**

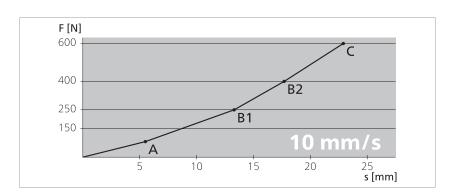
according to ISO 13856-2

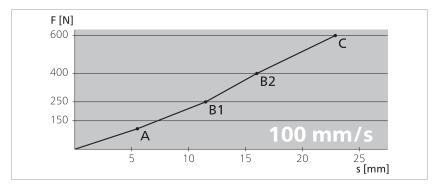
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.



Test velocity 1	00 mm/s
Actuation force	108 N
Response time	55 ms
Actuation distance (A)	5.5 mm
Overtravel distance	
Up to 250 N (B1)	6.0 mm
Up to 400 N (B2)	10.5 mm
Up to 600 N (C)	17.3 mm
Total deformation	22.8 mm

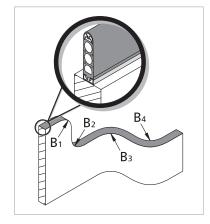


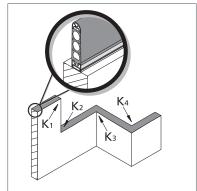


## **GP 120-1 EPDM**

Safety edge	SL/W GP 120-1 EPDM with SG-EFS 104/2W
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v <sub>test</sub> =	= 100 mm/s
Switching operations Actuation force	10,000
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	8.0 mm
Test piece (cylinder) Ø 80 mm	±60°
Response time	95 ms
Finger detection	No
Safety classifications	
ISO 13856: reset function	With/without
ISO 13849-1:2015	Category 3 PL d
MTTF <sub>D</sub> (PSPD)	192 a
MTTF <sub>D</sub> (sensor)	761 a
B <sub>10D</sub> (sensor)	$4 \times 10^{6}$
n <sub>op</sub> (assumption)	52,560/a
Mechanical operating conditions	<b>3</b>
Sensor length (min./max.)	20 cm / 6 m
Cable length (min./max.)	2.0 m / 100 m
Bend radii, minimum	With C 35 only
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	-/-/550/550 mm
Bend angles, maximum	
K <sub>1</sub> / K <sub>2</sub> / K <sub>3</sub> / K <sub>4</sub>	15° / 10° / 90° / 90°
Operating velocity	10 / 100 /
(min. / max.)	10 mm/s / 100 mm/s
Load capacity (max.)	600 N 20 N
Tensile load, cable (max.) IEC 60529: degree of protection	IP67
Humidity (max. at 23 °C)	95% (non-condensing)
Operating temperature	-10 to +50 °C
Storage temperature	-10 to +50 °C
Weight (without / with aluminium	10 10 100
profile C 35)	2.24 / 2.64 kg/m
Electrical operating conditions	·
Connection cable	Ø 3.7 mm TPE, 2 × 0.22 mm <sup>2</sup>
Sensor	24 V DC / max. 10 mA
Number of /BK-type sensors	Max. 10 in series

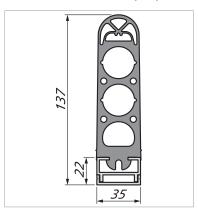
#### Bend radii:







#### GP 120-1 EPDM (1:3)



Dimensional tolerances according to ISO 3302 E2/L2

#### **Test conditions**

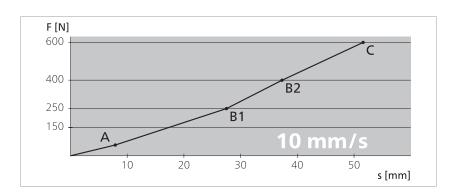
according to ISO 13856-2

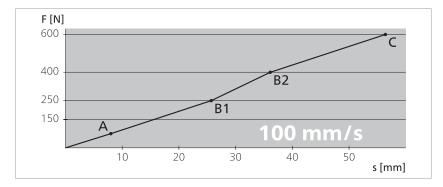
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.



Test velocity <b>1</b>	00 mm/s
Actuation force	75 N
Response time	80 ms
Actuation distance (A)	8.0 mm
Overtravel distance	
Up to 250 N (B1)	17.7 mm
Up to 400 N (B2)	28.1 mm
Up to 600 N (C)	48.4 mm
Total deformation	56.4 mm







## **Conformity**

The CE symbol indicates that this Mayser product complies with the relevant EC directives and that the stipulated conformity assessments have been carried out.



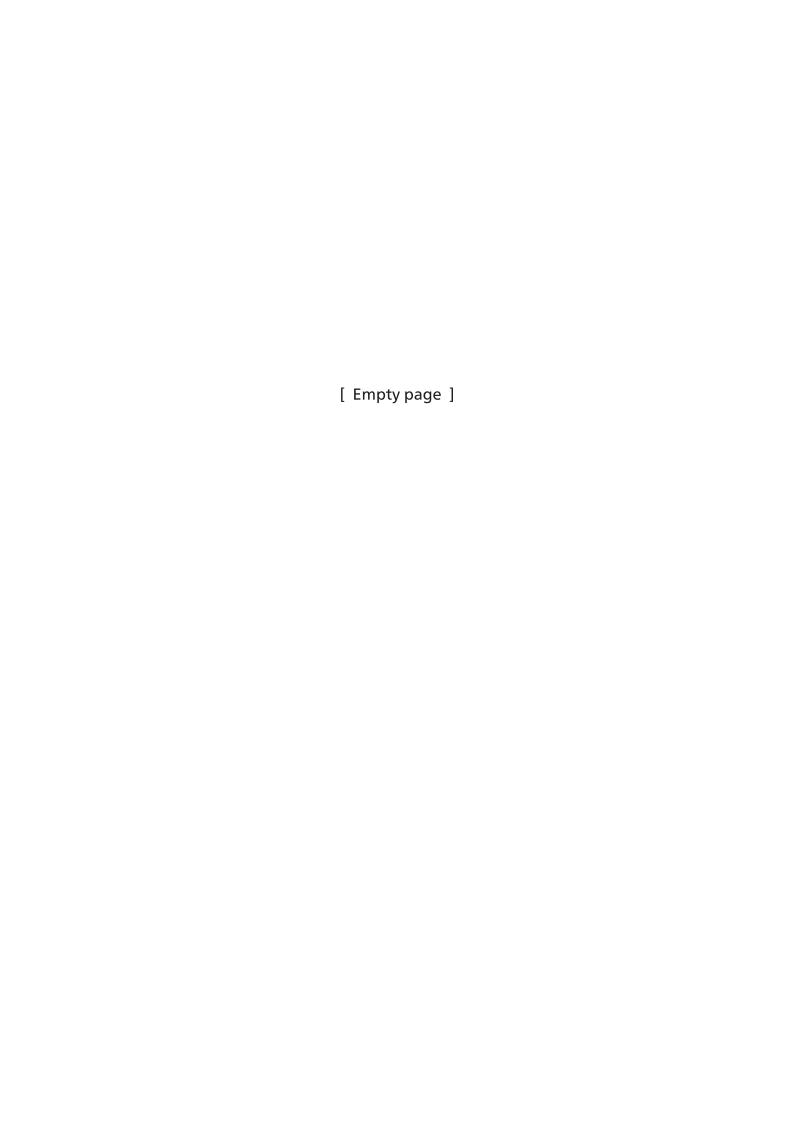
The design type of the product complies with the basic requirements of the following directives:

- 2006/42/EC (Safety of Machinery)
- 2011/65/EU (RoHS)
- 2014/30/EU (EMC)

The Declaration of Conformity is available in the Downloads section of our website:

www.mayser.com/de/download.

www.mayser.com







## Normally closed safety edges SL NC II



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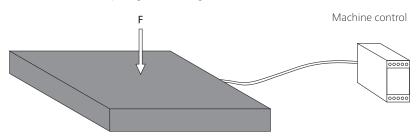


#### **Definitions**

### Pressure-sensitive protection device

A pressure-sensitive protection device consists of pressure-sensitive sensor(s), signal processing and output signal switching device(s). A pressure-sensitive protection device with switching type NC combines a sensor and an output signal switching device. That means that such a pressure-sensitive protection device can be used without a control unit. The pressure-sensitive protection device is triggered when the sensor is activated.

Sensor with output signal switching device

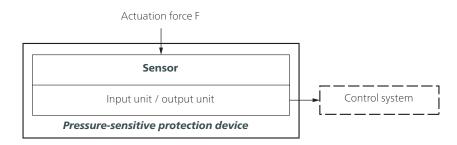


#### **Sensor**

The sensor is the part of the pressure-sensitive protection device that generates a signal when the actuating force F is applied. Mayser safety systems have a sensor whereby the actuating surface is deformed locally.

#### Signal processing

A pressure-sensitive protection device with switching type NC is designed only with an input and output unit for signal processing. The output unit is connected directly to the downstream control.



Tip: Terms are defined in ISO 13856-1, Chapter 3.

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#### Criteria for selecting the sensor type

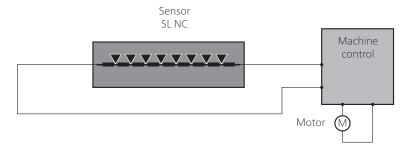
- Category according to ISO 13849-1
- Performance level of pressure-sensitive protection device = at least PL
- Temperature range
- Degree of protection in accordance with IEC 60529:
   IP67 is the standard for safety edges.
   Higher degrees of protection must be checked individually.
- Environmental influences such as swarf, oil, coolant, outdoor use...
- Finger detection necessary?

Tip: For additional sensor selection criteria, please refer to ISO 13856-2 Appendix C and Appendix E.

### Operation principle 2-wire-technology

The sensor is designed with integrated **positive break** safety elements in the form of contact chains. A control unit is not necessary, since the NC contact principle provides the output signal directly to the downstream control.

Optionally, the sensor can also be operated with an emergency stop component or a control unit.



For your safety:

Sensor and connecting cables are constantly monitored for function. This is possible because of signal transmission feedback – without a monitoring resistor.

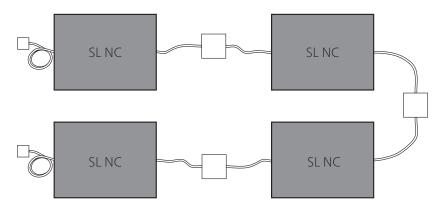


#### Design

SL NC with two 1-strand cables as a through sensor



#### **Combination of sensors**



#### Combination:

- Connection of more than one sensor
- only one emergency stop component necessary
- Safety edge design with custom lengths and angles



### **Safety**

### Intended use

A safety edge detects a person or part of the body when pressure is applied to the actuation area. It is a linear tripping device. Its task is to avoid possible hazardous situations for a person within a danger zone, such as shearing and pinching edges.

Typical areas of application are door and gate systems, moving parts on machines, platforms and lifting devices.

Safe operation of a safety edge depends entirely on

- the surface condition of the mounting surface,
- the correct selection of the size and resistance as well as
- correct installation.

For additional application guidelines refer to ISO 13856-2 Annex E.

Due to the design, the visible actuation area is reduced by the non-sensitive edges. What remains is the actual effective actuation area (see chapter *Effective actuation area*).

#### Limits

A maximum of 10 sensors may be operated in series. GP 48-2 deviates with respect to the actuation angle from the requirements in ISO 13856-2 and EN 12978; the suitability for doors and gates must be examined on an individual basis.

#### **Exclusions**

The sensors are not suitable:

- for detecting fingers
- for areas of application with high levels of vibration
- for performing a sealing function. Continuous actuation can cause permanent damage to sensors.

### Other safety aspects

#### **Performance Level (PL)**

The PL was determined during a simplified procedure according to ISO 13849-1. Exclusion of error according to ISO 13849-2, Table D.4: Short circuit between two conductors that are permanently installed and protected against external damage. In this case the diagnostic coverage (DC) of the cables is not calculated and is not used in determining the PL. Assuming the control unit has a high MTTF<sub>D</sub> value, the entire safety edge system (pressure-sensitive safety device) can achieve the maximum value PL d.

#### Is the safeguard appropriate?

The PL required for the hazard must be decided by the integrator. This is followed by the choice of safeguard.

Finally, the integrator needs to check whether the category and PL of the safeguard chosen are appropriate.

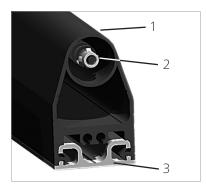
#### Risk and safety assessment

For the risk and safety assessment of your machine we recommend ISO 12100 "Safety of machinery – general principles for design".

#### Without reset function

When a safeguard without a reset function is used (automatic reset), the reset function must be made available in some other way.

### **Design**



The Normally closed safety edge SL/NC II consists of

- (1) Rubber profile GP,
- (2) Contact chain made of connected positive break normally closed contacts and (3) Aluminium profile C 26 or C 36.

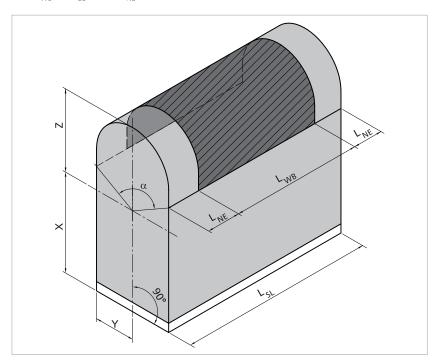
The positive break contact chain simultaneously carries out the functions of the sensor, signal processing and output signal switching device. Therefore, a special control unit is not necessary.

#### Effective actuation area

The parameters X, Y, Z,  $L_{WB}$  and the angle  $\alpha$  describe the effective actuation area.

For the effective actuation area, the following applies:

$$L_{WB} = L_{SL} - 2 \times L_{NE}$$



#### Parameters:

 $L_{WB}$ = effective actuation length

L<sub>SL</sub> = overall length of the safety edge

 $L_{NE}$  = non-sensitive length at the end of the safety edge

 $\alpha$  = effective actuation angle

SL NC II	GP 48-2	GP 65-2	GP 100-2
α	60°	90°	90°
L <sub>NE</sub>	50 mm	50 mm	40 mm
X	40 mm	52 mm	85 mm
Υ	13 mm	18 mm	18 mm
Z	8 mm	13 mm	14 mm

The effective actuation angle  $\alpha$  (60°) for GP 48-2 falls below the requirements of ISO 13856-2 and EN 12978.

### Installation position

The installation position can be selected as required, i.e. all installation positions A to D as per ISO 13856-2 are possible.

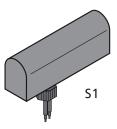


#### **Connection**

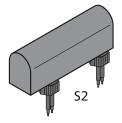
### Cable exits

#### 90° exit

Distance to front end each 60 mm



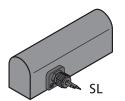
S1:1 connection



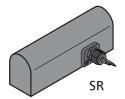
S2: 2 connections

#### **Lateral exit**

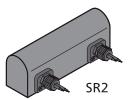
Distance to front end each 60 mm



SL: lateral exit left



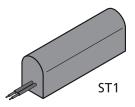
SR: lateral exit right



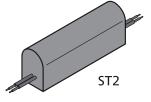
SR2: 2 connections

#### **Axial exit**

without PG-screw connection



ST1: Axial exit



ST2: 2 connections

In the case of several sensors connected in sequence, we recommend version S2, SR2 or ST2. These versions provide an additional line in the rubber profile for feedback to the control.



#### Cable connection

- Cable: Ø 3.3 mm PVC,  $1 \times 0.5$  mm<sup>2</sup>; double insulated, short-circuit-proof, highly flexible
- Cable length depends on the sensor length:

A cable with a length of 7.5 m is installed in the sensor as standard equipment. Due to internal cable routing from the connections the cable exits, the connection cable length is determined as follows: Standard cable length minus sensor length.

For example, 7.5 m - 6 m = 1.5 m

Option: can be expanded up to a maximum length of 100 m

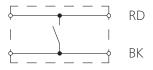
Cable ends: wires stripped
 Option: Cable ends available with plug and coupling

For the wiring between the sensor and the downstream control the cables must be installed permanently and protected against external damage, for example in cable conduits or armoured conduits. In areas where this is not possible, each cable must be routed in a separate sheath.

This prevents

- line termination and therefore loss of the protective function and
- downgrading of the safety classification.

#### Wire colours



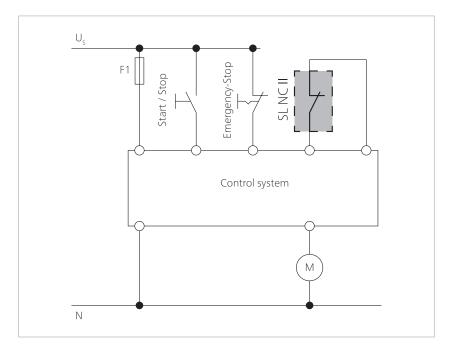
#### **Colour coding**

BK Black RD Red

### Connection examples

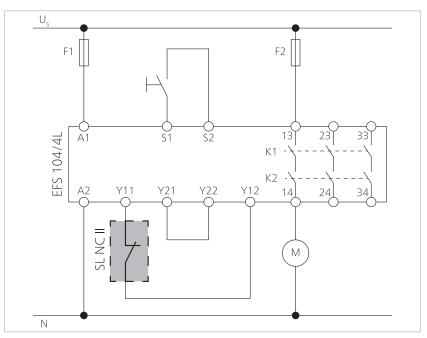
#### **Connection example 1**

NC safety edge connected directly to the control. Protective devices in accordance with ISO 13849 1 to PL d are possible, if the control has a performance level of d or higher.



#### **Connection example 2**

NC safety edge connected to the Mayser SG-EFS 104/4L control unit. Performance level up to PL d in accordance with ISO 13849-1 is possible.



The NC safety edge and the SG EFS 104/4L sensor are certified to UL 508.



#### **Sensor surface**

### Physical resistance

Rubber profile GP	EPDM	NBR
Degree of protection (IEC 60529)	IP67	IP67
Hardness per Shore A	65 ±5	70 ±5

### Chemical resistance

The sensor is resistant against normal chemical influences such as diluted acids and alkalis as well as alcohol over an exposure period of 24 hrs.

The specifications in the table are the result of tests conducted in our lab at room temperature (+23 °C). The suitability of our products for your special area of application must always be verified with your own practical tests.

Material	EPDM	NBR
Acetone	+	±
Formic acid	+	+
Ammonia	+	+
Petrol	-	+
Brake fl uid	±	<u>±</u>
Chloride solutions	+	+
Diesel oils	-	+
Greases	-	+
Household-/sanitary cleaners	+	+
Isopropyl alcohol	+	+
Cooling lubricant	-	+
Metal working oil	-	+
Methyl alcohol	+	+
Oils	-	+
Ozone and weather conditions	+	-
Hydrochloric acid 10 %	+	+
Spirit (ethyl alcohol)	+	+
Carbon tetrachloride	-	+
Hydrogen peroxide 10 %	+	+
Water and frost	+	-

#### **Explanation of symbols:**

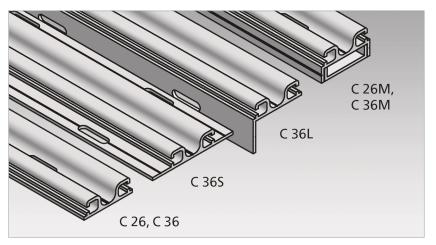
+ = resistant

 $\pm$  = resistant to a certain extent

- = not resistant

#### **Attachment**

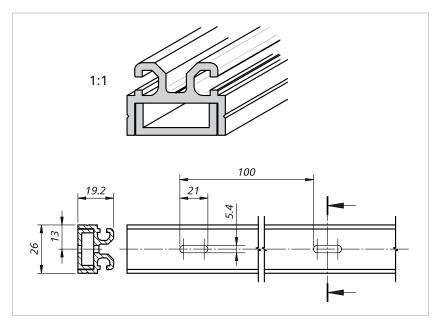
The sensors are mounted directly to the dangerous main and secondary closing edges. The aluminium profiles C 26 and C 36 are used for mounting. The aluminium profiles are mounted with screws M5 or rivets.



#### **Material properties**

- AlMgSi0.5 F22
- Wall thickness 2 mm
- Tolerances as per EN 755-9
- extruded
- hot hardened

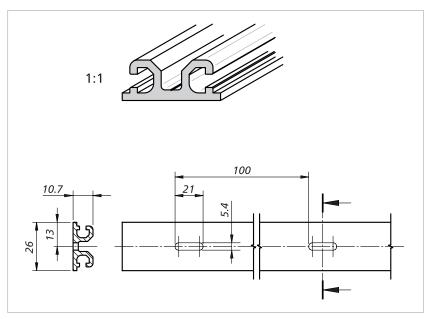
### Aluminium profile C 26M



Two-part profile for GP 48-2:

For convenient assembly and disassembly. The rubber profile is clipped into the upper section and the upper section inserted in the installed lower section and fastened.

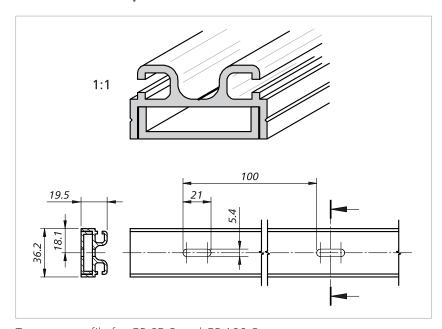
### Aluminium profile C 26



Standard profile for GP 48-2:

First the aluminium profile must be mounted to the closing edge and then the rubber profile clipped into the aluminium profile.

### Aluminium profile C 36M

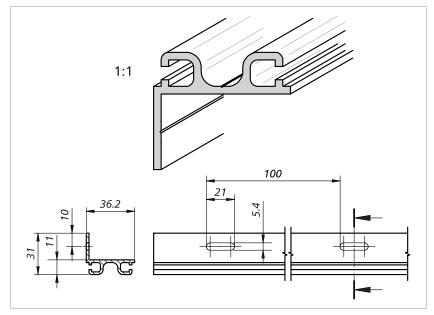


Two-part profile for GP 65-2 and GP 100-2:

For convenient assembly and disassembly. The rubber profile is clipped into the upper section and the upper section inserted in the installed lower section and fastened.



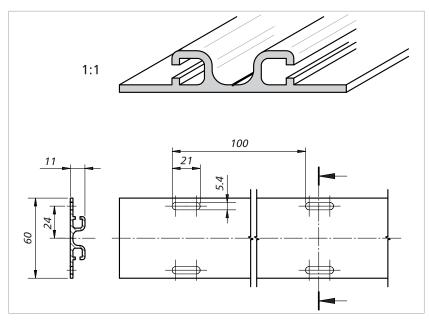
### Aluminium profile C 36L



Angle profile for GP 65-2 and GP 100-2:

If the closing edge should or must not have assembly holes, this "round-the-corner" solution is suitable. Final assembly is also possible when the rubber profile is already clipped into the aluminium profile.

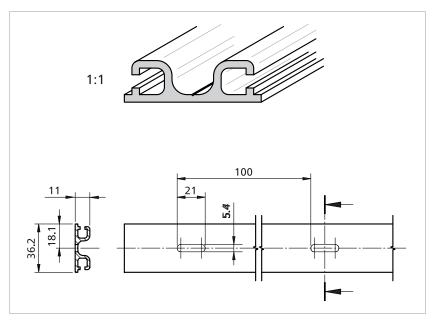
### Aluminium profile C 36S



Flange profile for GP 65-2 and GP 100-2:

Final assembly is also possible when the rubber profile is already clipped into the aluminium profile.

### Aluminium profile C 36



Standard profile for GP 65-2 and GP 100-2:

First the aluminium profile must be mounted to the closing edge and then the rubber profile clipped into the aluminium profile.

# Aluminium profiles: Overview of combinations

Aluminium profiles for		GP 48-2	GP 65-2	GP 100-2
External clip bars	2	C 26 C 26M	C 36 C 36M, C 36L, C 36S	C 36 C 36M, C 36L, C 36S

### **MAYSER®**

- s<sub>1</sub> = Stopping distance of the
   dangerous movement
  [ mm ]
- v = Velocity of the dangerous movement [ mm/s ]
- T = Follow-through of the complete system [s]
- $t_1$  = Response time safety edge
- t<sub>2</sub> = Stopping time of the machine
- s = Minimum overtravel distance of the safety edge so that the required limit forces are not exceeded [ mm ]
- C = Safety factor; if components susceptible to failures (braking system) exist in the system, a higher factor must be selected

### **SL NC II: The right selection**

# Calculation for selection of the safety edge height

The stopping distance of the dangerous movement is calculated using the following formula:

$$s_1 = 1/2 \times v \times Twhere: T = t_1 + t_2$$

The NC safety edge is a sensor, signal processor and output signal switching device in one (see chapter *Design*). For this reason the response time t, of the safety edge = the sensor response time.

In accordance with ISO 13856-2, the minimum overtravel distance of the safety edge is calculated using the following formula:

$$s = s_1 \times C$$
 where:  $C = 1.2$ 

A suitable safety edge profile can now be selected based on the result. Overtravel distances of safety edge profiles: see chapter *Technical data*.

### Calculation examples

#### **Example 1**

The dangerous movement on your machine has a velocity of v=10 mm/s and can be brought to a standstill within  $t_2=250$  ms. The relatively low velocity suggests that a short overtravel distance is to be expected. Therefore the normally closed safety edge SL NC II GP 48-2 NBR could be sufficient. The response time of the safety edge is  $t_1=1300$  ms.

$$s_1 = 1/2 \times v \times T$$
 where:  $T = t_1 + t_2$   
 $s_1 = 1/2 \times 10 \text{ mm/s} \times (1300 \text{ ms} + 250 \text{ ms})$   
 $s_1 = 1/2 \times 10 \text{ mm/s} \times 1.55 \text{ s} = 6.55 \text{ mm}$   
 $s = s_1 \times C$  where:  $C = 1.2$ 

$$s = s_1 \times C$$
 where:  $C = 1$   
 $s = 6.55 \text{ mm} \times 1.2 = 7.86 \text{ mm}$ 

The safety edge must have a minimum overtravel distance of s = 7.9 mm. The selected SL NC II GP 48-2 NBR has an overtravel distance of at least 12.4 mm. This is more than the required 7.9 mm.

**Result:** The SL NC II GP 48-2 NBR is **suitable** for this case.

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#### **Example 2**

The same conditions as in calculation example 1 with the exception of the velocity of the dangerous movement. This is now v = 100 mm/s. This reduces the response time of the safety edge to  $t_1 = 83$  ms.

$$s_1 = 1/2 \times v \times T$$
 where:  $T = t_1 + t_2$   
 $s_1 = 1/2 \times 100 \text{ mm/s} \times (83 \text{ ms} + 250 \text{ ms})$   
 $s_1 = 1/2 \times 100 \text{ mm/s} \times 0.333 \text{ s} = 16.65 \text{ mm}$   
 $s = s_1 \times C$  where:  $C = 1.2$   
 $s = 16.65 \text{ mm} \times 1.2 = 19.98 \text{ mm}$ 

The safety edge must have a minimum overtravel distance of s = 20 mm. The selected SL NC II GP 48-2 NBR has an overtravel distance of at least 16.8 mm. This is less than the required 20 mm.

**Result:** The SL NC II GP 48-2 NBR is **not suitable** for this case.

#### **Example 3**

The same conditions as in calculation example 2. Instead of SL NC II GP 48-2 NBR the SL NC II GP 100-2 EPDM is selected. The response time of the safety edge is  $t_1 = 76$  ms.

$$s_1 = 1/2 \times v \times T$$
 where:  $T = t_1 + t_2$   
 $s_1 = 1/2 \times 100 \text{ mm/s} \times (76 \text{ ms} + 250 \text{ ms})$   
 $s_1 = 1/2 \times 100 \text{ mm/s} \times 0.326 \text{ s} = 16.3 \text{ mm}$   
 $s = s_1 \times C$  where:  $C = 1.2$   
 $s = 16.3 \text{ mm} \times 1.2 = 19.56 \text{ mm}$ 

The safety edge must have a minimum overtravel distance of s = 20 mm. The selected SL NC II GP 100-2 EPDM has an overtravel distance of at least 36.8 mm at 100 mm/s. This is more than the required 20 mm.

**Result:** The SL NC II GP 100-2 EPDM is **suitable** for this case.



#### **Accessories**

#### **Extension kit**

For extension of connection cable by customer (contents: double insulated wire, crimp connector and heat-shrinkable sleeves)

Extension kit: 5 m 1003870 Extension kit: 10 m 1003871

#### Wiring aids

Special resistor: 1k2 1003873 Special resistor: 8k2 1003874

### **Maintenance and cleaning**

The sensors are virtually maintenance-free.

#### **Regular inspection**

Depending on the utilisation, sensors must be inspected at regular intervals (at least monthly)

- for proper functioning,
- damage,
- and correct mounting.

#### **Cleaning**

If the sensors become dirty, they can be cleaned with a mild cleaning product.



### **Technical data**

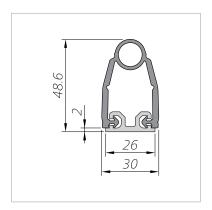
### GP 48-2 NBR with C 26

Normally closed safety edge SL NC II consisting of sensor and aluminium profile from the profile range C 26.

Testing basis	
ISO 13856-2	
Switching characteristics at v <sub>test</sub> =	= 200 mm/s
Switching operations Actuation force	>10,000
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	12 mm
Test piece (cylinder) Ø 80 mm	60°
Response time	60 ms
Finger detection	yes
Safety classifications	
ISO 13856: Reset function	without
ISO 13849-1:2015	Category 3 PL d
B <sub>10D</sub> (Sensor)	2× 10 <sup>6</sup>
Mechanical operating conditions	5
Sensor length (min./max.)	30 cm / 6 m
Cable length (min./max.)	1.5 m / 100 m
Bend radii	not possible
Operating speed	
(min. / max.)	10 mm/s / 200 mm/s
max. load capacity	600 N
IEC 60529: Degree of protection	IP67
Humidity (max. at 23 °C)	95 % (non-condensing)
Operating temperature	+5 to +55 °C
Storage temperature	-20 to +80 °C
Weight	1.0 kg/m
Electrical operating conditions	
Contact transition resistance (max.)	5 Ohm
Number of sensors type BK	max. 10 in series
Switching voltage (PELV) (max.)	48 V DC 48 V AC 50/60 Hz
Protection class	III
Switching current (max.)	20 mA
Contact fuse protection, external	250 mA slow-acting
Connection cable	Ø 3.3 mm PVC $1 \times 0.5$ mm <sup>2</sup>

#### Dimensions and distances

GP 48-2 NBR (1:2)



Dimensional tolerances according to ISO 3302 E2/L2.

#### **Test conditions**

according to ISO 13856-2

- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- without control unit

All data stated here is documented in EC design type test certificates.

#### **Force-distance ratios**

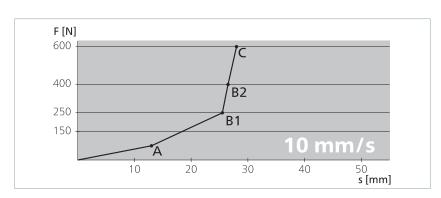
Actuation force 69 N
Response time 1300 ms
Actuation distance (A) 13 mm
Overtravel distance
up to 250 N (B1) 12.4 mm
up to 400 N (B2) 13.5 mm
up to 600 N (C) 14.9 mm
Total deformation 27.9 mm

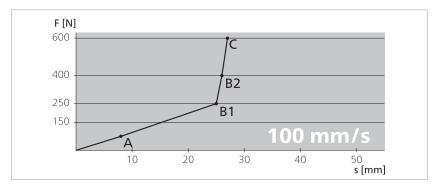
Actuation force 71 N
Response time 83 ms
Actuation distance (A) 8.3 mm
Overtravel distance
up to 250 N (B1) 16.8 mm
up to 400 N (B2) 17.7 mm
up to 600 N (C) 18.9 mm
Total deformation 27.2 mm

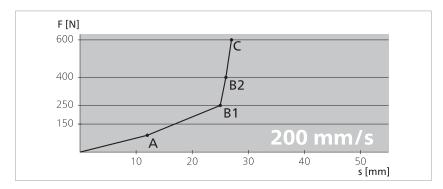
Response time 60 ms
Actuation distance (A) 12 mm
Overtravel distance
up to 250 N (B1) 13.2 mm
up to 400 N (B2) 14.1 mm
up to 600 N (C) 15.2 mm

Actuation force

Total deformation







71 N

27.2 mm



### **Technical data**

### GP 48-2 EPDM with C 26

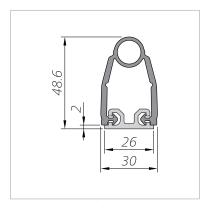
Normally closed safety edge SL NC II consisting of sensor and aluminium profile from the profile range C 26.

Testing basis	
ISO 13856-2	
Switching characteristics at v <sub>test</sub> =	= 100 mm/s
Switching operations Actuation force	>10,000
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	14.8 mm
Test piece (cylinder) Ø 80 mm	90°
Response time	148 ms
Finger detection	no
Safety classifications	
ISO 13856: Reset function	without
ISO 13849-1:2015	Category 3 PL d
B <sub>10D</sub> (Sensor)	2× 10 <sup>6</sup>
Mechanical operating conditions	;
Sensor length (min./max.)	30 cm / 6 m
Cable length (min./max.)	1.5 m / 100 m
Bend radii	not possible
Operating speed	10 / 100
(min. / max.)	10 mm/s / 200 mm/s
max. load capacity	600 N
IEC 60529: Degree of protection	IP67
Humidity (max. at 23 °C)	95 % (non-condensing)
Operating temperature	-10 to +55 °C -20 to +80 °C
Storage temperature	
Weight	1.0 kg/m
Electrical operating conditions	
Contact transition resistance (max.)	5 Ohm
Number of sensors type BK	max. 10 in series
Switching voltage (PELV) (max.)	48 V DC 48 V AC 50/60 Hz
Protection class	III
Switching current (max.)	20 mA
Contact fuse protection, external	250 mA slow-acting
Connection cable	Ø 3.3 mm PVC $1 \times 0.5$ mm <sup>2</sup>



#### Dimensions and distances

GP 48-2 EPDM (1:2)



Dimensional tolerances according to ISO 3302 E2/L2.

#### **Test conditions**

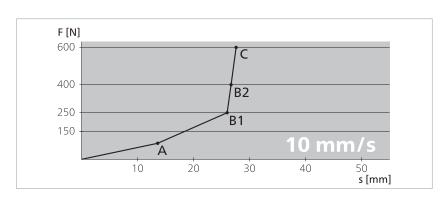
according to ISO 13856-2

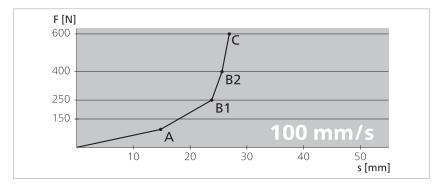
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- without control unit

#### **Force-distance ratios**

Actuation force 86 N
Response time 1440 ms
Actuation distance (A) 14.4 mm
Overtravel distance
up to 250 N (B1) 11.3 mm
up to 400 N (B2) 12.3 mm
up to 600 N (C) 13.2 mm
Total deformation 27.1 mm

Actuation force 95 N
Response time 148 ms
Actuation distance (A) 14.8 mm
Overtravel distance
up to 250 N (B1) 10.8 mm
up to 400 N (B2) 11.6 mm
up to 600 N (C) 12.6 mm
Total deformation 26.9 mm







### **Technical data**

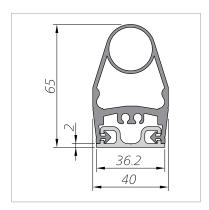
### GP 65-2 EPDM with C 36

Normally closed safety edge SL NC II consisting of sensor and aluminium profile from the profile range C 36.

Testing basis	
ISO 13856-2	
Switching characteristics at v <sub>test</sub> =	= 200 mm/s
Switching operations	>10,000
Actuation force	
Test piece (cylinder) Ø 80 mm	< 150 N
Actuation distance	7
Test piece (cylinder) Ø 80 mm	7 mm
Actuation angle Test piece (cylinder) Ø 80 mm	90°
Response time	35 ms
Finger detection	no
Safety classifications	110
<u> </u>	
ISO 13856: Reset function ISO 13849-1:2015	without
B <sub>10D</sub> (Sensor)	Category 3 PL d 2× 10 <sup>6</sup>
100	-
Mechanical operating conditions	
Sensor length (min./max.)	30 cm / 6 m
Cable length (min./max.)	1.5 m / 100 m
Bend radii	not possible
Operating speed (min. / max.)	10 mm/s / 200 mm/s
	600 N
max. load capacity IEC 60529: Degree of protection	IP67
Humidity (max. at 23 °C)	95 % (non-condensing)
Operating temperature	-10 to +55 °C
Storage temperature	-20 to +80 °C
Weight	1.9 kg/m
Electrical operating conditions	
Contact transition resistance (max.)	5 Ohm
Number of sensors type BK	max. 10 in series
Switching voltage (PELV) (max.)	48 V DC
	48 V AC 50/60 Hz
Protection class	III
Switching current (max.)	20 mA
Contact fuse protection, external	250 mA slow-acting
Connection cable	Ø 3.3 mm PVC $1 \times 0.5$ mm <sup>2</sup>

#### Dimensions and distances

GP 65-2 EPDM (1:2)



Dimensional tolerances according to ISO 3302 E2/L2.

#### **Test conditions**

according to ISO 13856-2

- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- without control unit

All data stated here is documented in EC design type test certificates.

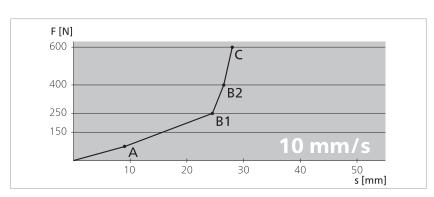
#### **Force-distance ratios**

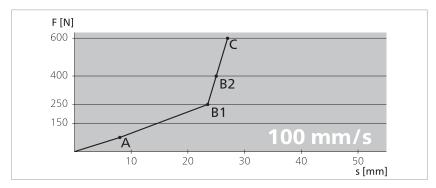
Actuation force 69 N
Response time 890 ms
Actuation distance (A) 8.9 mm
Overtravel distance
up to 250 N (B1) 15.6 mm
up to 400 N (B2) 17.5 mm
up to 600 N (C) 19.3 mm
Total deformation 28.2 mm

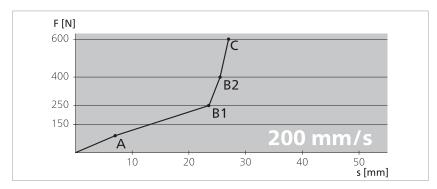
Actuation force 71 N
Response time 80 ms
Actuation distance (A) 8 mm
Overtravel distance
up to 250 N (B1) 15.5 mm
up to 400 N (B2) 17.3 mm
up to 600 N (C) 19.1 mm
Total deformation 27.1 mm

Actuation force 64 N
Response time 34.5 ms
Actuation distance (A) 6.9 mm
Overtravel distance
up to 250 N (B1) 16.5 mm
up to 400 N (B2) 18.5 mm
up to 600 N (C) 20 mm

Total deformation







26.9 mm



### **Technical data**

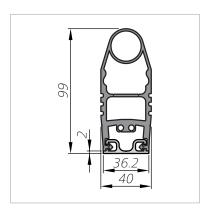
### GP 100-2 EPDM with C 36

Normally closed safety edge SL NC II consisting of sensor and aluminium profile from the profile range C 36.

Testing basis	
ISO 13856-2	
Switching characteristics at v <sub>test</sub> =	= 200 mm/s
Switching operations Actuation force	>10,000
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	17 mm
Test piece (cylinder) Ø 80 mm	90°
Response time	82 ms
Finger detection	no
Safety classifications	
ISO 13856: Reset function	without
ISO 13849-1:2015	Category 3 PL d
B <sub>10D</sub> (Sensor)	2× 10 <sup>6</sup>
Mechanical operating conditions	<b>5</b>
Sensor length (min./max.)	30 cm / 6 m
Cable length (min./max.)	1.5 m / 100 m
Bend radii	not possible
Operating speed	
(min. / max.)	10 mm/s / 200 mm/s
max. load capacity	600 N
IEC 60529: Degree of protection	IP67
Humidity (max. at 23 °C)	95 % (non-condensing)
Operating temperature	-10 to +55 °C
Storage temperature	-20 to +80 °C
Weight	2.1 kg/m
<b>Electrical operating conditions</b>	
Contact transition resistance (max.)	5 Ohm
Number of sensors type BK	max. 10 in series
Switching voltage (PELV) (max.)	48 V DC
	48 V AC 50/60 Hz
Protection class	
Switching current (max.)	20 mA
Contact fuse protection, external	250 mA slow-acting
Connection cable	Ø 3.3 mm PVC 1× 0.5 mm <sup>2</sup>

#### Dimensions and distances

GP 100-2 EPDM (1:3)



Dimensional tolerances according to ISO 3302 E2/L2.

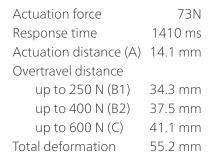
#### **Test conditions**

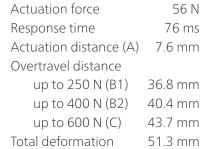
according to ISO 13856-2

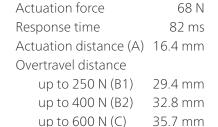
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- without control unit

All data stated here is documented in EC design type test certificates.

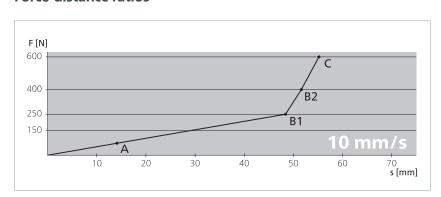
#### **Force-distance ratios**

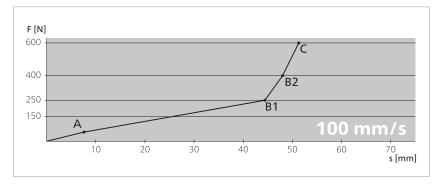


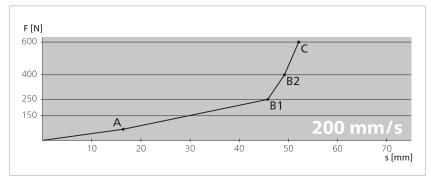




Total deformation







52.1 mm



### **Conformity**

### Conformity

The CE symbol indicates that this Mayser product complies with the relevant EC directives and that the stipulated conformity assessments have been carried out.



The design type of the product complies with the basic requirements of the following directives:

- 2006/42/EC (Safety of machinery)
- 2014/30/EU (EMC)

The Declaration of Conformity is available in the download section of the website: www.mayser.com/en/downloads

### EC design test

The product was tested by an independent institute.

An EC design type test certificate confirms conformity.

The EC design type test certificate is available in the download section of the website: www.mayser.com/en/downloads

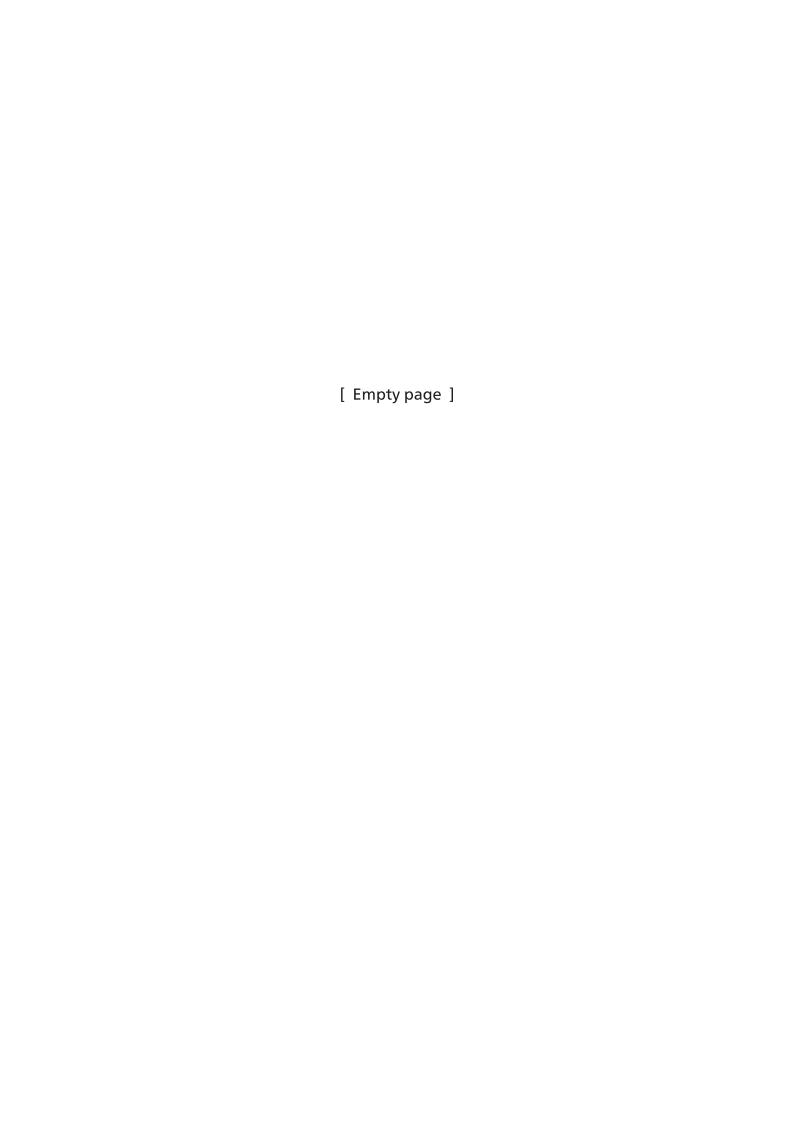
### **UL** certification

#### Certificates

UL certification

U8V 07 10 31146 006







## Miniature Safety Edges ...

### Product Information Miniature Safety Edges

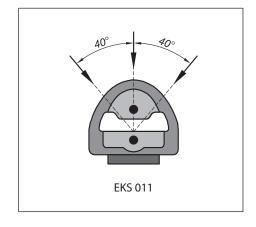
# Miniature Safety Edges (EKS) – the "invisible" protection against trapping and nipping

Tiny dimensions, enormous reliability.

The Miniature Safety Edges are the result of consistent further development and miniaturisation of our Safety Edges which are well known for their reliability in safety applications. Endowed with the same safety and reliability features, the Miniature Safety Edges also have a visual advantage: absolutely tiny and the profile comes in almost any shape and size.

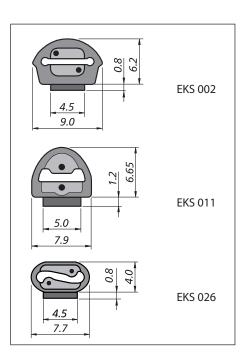
#### ... inside values

- The heart of the Miniature Safety Edges is the switching chamber which is integrated in the profile. A small amount of pressure to the Miniature Safety Edge suffices to short-circuit two conductive areas which are separated from each other. A sure signal for the evaluating unit connected up.
- Electrically, the Miniature Safety Edge works on the closed circuit principle, i.e. a break in connection is recognized, the danger- bringing movement is brought to a halt.



#### ... outside values

- In addition to the three standard shapes depicted we can also provide customized profiles.
- The design of the Miniature Safety Edge can be practically effortlessly adapted to suit the surroundings.
- The Miniature Safety Edge is in its element in places where only very short overtravel distances are possible.
- Thanks to the minimal dimensions (see to the right) the Miniature Safety Edge can be intregrated into its surroundings in an optimal way.





#### ... diverse uses

### Product Information Miniature Safety Edges

## Miniature Safety Edges (EKS) – the "invisible" protection against trapping and nipping

Medical Technology

- Diagnostic equipment
- Radiation apparatus
- Electrically adjustable tables/chairs
- Movable protective hoods
- Rehabilitation equipment (Sports Medicine)

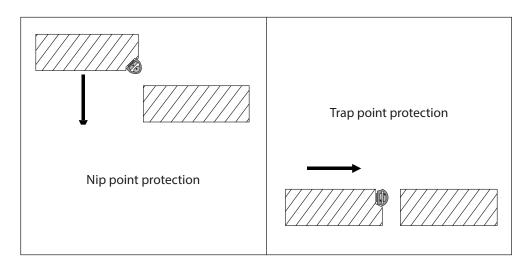
Elevator doors Bus doors and electric roof lights (finger protection) Electrically operated screens

- Cash dispensers
- Skylights
- Glass sliding doors

Electrically adjustable furniture

- Computer tables
- Recliners
- Electrically operated writing boards

#### ... sure performance



#### ... technichal details

Distinctive features

- thermoplastic elastomer
- customized TPE-covering
- environment-friendly
- can be recycled

**Electrical operating conditions** 

- max. voltage 24 V DC
- max. current 10 mA

**Protection class** 

• IP65

Operating characteristics

• Response angle: > 90° (depends on shape of profile!)

• Actuating distance:  $\leq$  1,0 mm • Actuating force: < 25 N (Test piece: Ø 200 mm) • Actuating force: < 15 N

Ø 4 mm)

Application temperatures

(Test piece:

- 40 °C to + 80 °C (short-time exposure to temperatures up to + 95 °C also possible)

### **MAYSER®**

#### **Technical Data**

Miniature Safety Edge consisting of sensor type EKS 0XX TPE

IP65

### Miniature Safety Edges

(Illustration scale 1:1)

### **Protection class**

**Switching operations** 

Test piece Ø 10 mm / F=100 N > 100,000

#### Actuating force, actuating distance and response angle

	and response angle						
3.1	Actuating force	EKS 002		EKS 011		EKS 026	
	v <sub>test</sub> = 50 mm/min	23 °C	- 25 °C	23 °C	- 25 °C	23 °C	- 25 °C
	Test piece Ø 4 mm	< 10 N	< 15 N	< 15 N	< 30 N	< 10 N	< 20 N
	Test piece Ø 200 mm	< 20 N	< 25 N	< 25 N	< 50 N	< 15 N	< 35 N
3.2	Actuating distance						
	v <sub>test</sub> = 50 mm/min	23 °C		23 °C		23 °C	
	Test piece Ø 80 mm cyl.	< 1.5 mm		< 2 mm		< 1 mm	
3.3	Response angle	< 60°		< 80°		< 80°	
4	Mechanical operating and applic	cation cond	itions				
	Sensor length (min./max.)	70 mm / 15	60 m	70 mm / 15	60 m	70 mm / 150 m	1
4.2	Bending radii			100		> 80 mm	
	Convex profile curvature	> 50 mm		> 120 mm			
	Concave profile curvature	> 80 mm		> 150 mm		> 50 mm	
4.0	Across the profile axis	> 120 mm		> 20 mm		> 120 mm	
	Tensile load, cable	max. 60 N	00.00	max . 50 N		max. 20 N	
4.4	Working temperature	-25 °C to +		-25 °C to		-25 °C to +80	
	Permissible short term exposure	-40 °C to +	-100 °C	-40 °C to	+100 °C	-40 °C to +10	0 °C
5	Electric operating conditions						
5.1	End resistor (standard)	$1.2 \text{ k}\Omega \pm 1\%$	, D	1.2 kΩ ±1%	, D	1.2 kΩ ±1%	
	Performance	max. 250 m	ηW	max. 250 n	ηW	max. 250 mW	
5.2	Transition resistance	$<$ 400 $\Omega$ (u	nder load)	< 400 Ω (u	nder load)	$<$ 400 $\Omega$ (unde	r load)
5.3	Electric rating	without end	d resistor	without end	d resistor	without end res	sistor
	Voltage	max. 24 V	/ DC	max. 24 V	DC	max. 24 V DC	
	Current	max. 10 n	nA	max. 10 m	nΑ	max. 10 mA	
		min. 1 n	nA	min. 1 m	nΑ	min. 1 mA	
5.3	Connecting cable	Ø 3.7 mm		Ø 3.4 mm		Ø 1,4 mm per	strand
	•	2x 0.25 mn	n²	2x 0.25 mn	n²	2× 0.35 mm <sup>2</sup>	

#### Application using acrylic-foam-adhesive tape

Class according to IEC 60228

Peel strength Applied to:	15 N/cm	without promoter	
ABS	+	without promotor	
Aluminium	+	+	Tests carried out at 23 °C (room
Aluminium, anodised	T .	т	temperature).
	+	-	
Wood: native	-	-	
Wood: varnished, veneer	or		Note: check with adhesion tests
laminated	+	-	before serial use whether bonding is
PA6	+	-	possible on the selected installation
PA66	+	+	surface.
PE, HDPE	-	-	Suridoc.
PMMA	+	+	
PP	+	-	Key to symbols:
PS, CAB	-	-	+ = OK
PVC	+	+	
SAN	+	-	- = not OK
Steel, stainless steel	+	+	

6

### Miniature Safety Edges

#### 7 Behaviour in fire

According to DIN 75200 40 mm/min

Compliance with StVZO, TA 29, BMW N601 21.0

8. Dimensions tolerances length according to DIN ISO 3302 L2

section according to DIN ISO 3302 E2

#### 9. Chemical resistance

Miniature Safety Edge EKS	TPE
Material characteristics	
Shore A hardness	55 ±5
Chemical resistance	
Acetone	-
Formic acid	-
Armor All	+
Carwash agent	+
Fuel	-
Brake fluid	±
Buraton	+
Butanol	-
Chlorinated bleaching lye	-
Disinfectant 1 %	+
Diesel	-
Acetic acid 10 %	-
Ethyl alcohol	+
Ethyl acetate	-
Ethylene glycol	+
Greases	±
Antifreeze	+
Skin cream	+
Icidin	+
Incidin	+
Incidin plus	+
Cooling lubricants	-
Plastics cleaning agent	+
Lyso FD 10	+
Metal processing oil	-
Microbac	+
Microbac forte	+
Minutil	+
Saline solution 5 %	+
Spirit (ethyl alcohol)	+
Terralin	+
UV-resistance	+
Centering oil	-

Tests carried out at 23 °C (room temperature).

Key to symbols

+ = resistant

± = limited resistance

= not resistant

The data given are results of tests which were carried out in our laboratory to the best of our knowledge and belief. We cannot accept any obligations being deduced from them. You must always test the suitability of our products for your special application purpose under practical conditions.



#### **Technical Data**

#### Miniature Safety Edge consisting of sensor type EKS 01X TPE

### Miniature Safety Edges

#### 1. Protection class IP65

#### 2. Switching opertions

Test piece Ø 10 mm / F=100 N > 100.000

3.	Actuating force, actuating distart and response angle	nce			
3.1	Actuating force Test speed v <sub>test</sub>	EKS 014 50 mm/min	<b>3</b>	EKS 015 100 mm/min	705
	Test temperature Testing basis: 74/60/EWG and FMVSS118	23 °C	-25 °C	23 °C	-25 °C
	Test piece Ø 200 mm	< 25 N	< 50 N	_	_
	Test piece Ø 4 mm Testing basis: EN 1760-2	< 15 N	< 30 N	_	_
	Test piece 1 Ø 80 mm cyl.	_	_	< 25 N	<110N
3.2	Test piece 3 Ø 20 mm Actuating distance	_	_	< 15 N	<25 N
	Test speed v <sub>test</sub>	50 mm/min		100 mm/min	
	Test temperature Test piece 1 Ø 80 mm cyl.	23 °C < 2 mm		23 °C 2 mm	
3.3	Response angle	< 80°		< 40°	
4.	Mechanical operating and appli				
	Sensor length (min./max.) Bending radii	70 mm / 150	0 m	70 mm / 150	m
7.2	Convex profile curvature	> 120 mm		> 800 mm	
	Concave profile curvature	> 150 mm		> 1000 mm	
4.3	Across the profile axis Working temperature	> 20 mm - 40 °C to	+ 80 °C	> 200 mm - 40 °C to	+ 80 °C
	Permissible short term exposure	- 40 °C to		- 40 °C to	
	Electric operating conditions				
5.1	End resistor (standard) Performance	1.2 kΩ ±1% max. 250 m		1.2 k $\Omega$ ±1% max. 250 mV	V
5.2	Transition resistance	$<$ 400 $\Omega$ (ur		$<$ 400 $\Omega$ (und	
5.3	Electric rating	without end		without end	
	Voltage Current		V DC mA	max. 24 \	√DC mA
			mA		mA
5.4	Connecting cable	Ø 3.4 mm 2x 0.25 mm	2	Ø 3.7 mm 2x 0.25 mm <sup>2</sup>	
	Class according to VDE 0295	6		5	
6.	Application with clip-in foot	0.5		_	
	Clip-in foot width Al-rail type	3.5 mm C10		7 mm C15	
_					

7. Dimensions tolerances

**Length according to ISO 3302 L2**Cross section according to ISO 3302 E2

#### 8. Chemical resistance

Miniature Safety Edge EKS 01X	TPE
Material characteristics	
Shore A hardness	55 ±5
Chemical resistance	
Acetone	-
Formic caid	-
Armor All	+
Carwash agent	+
Fuel	-
Brake fluid	±
Buraton	+
Butanol	-
Chlorinated bleaching lye	-
Disinfectant 1 %	+
Diesel	-
Acetic acid 10 %	-
Ethyl alcohol	+
Ethyl acetate	-
Ethylene glycol	+
Greases	±
Antifreeze	+
Skin cream	+
Icidin	+
Incidin	+
Incidin plus	+
Cooling lubricants	-
Plastics cleanging agent	+
Lyso FD 10	+
Metal processing oil	-
Microbac	+
Microbac forte	+
Minutil	+
Saline solution 5 %	+
Spirit (ethyl alcohol)	+
Terralin	+
UV-resistance	+
Centering oil	-

### Miniature Safety Edges

Tests carried out at 23 °C (room temperature).

Key to symbols:

+ = resistant

± = limited resistance

= not resistant

The data given are results of tests carried out in our laboratory to the best of our knowledge and belief. We cannot accept any obligations being deduced from them. You must always test the suitability of our products for your special application under practical conditions.

#### **MAYSER®**

#### **Technical Data**

Miniature Safety Edge consisting of sensor type EKS 030 TPE

#### 1 Protection class IP65

#### 2 Switching operations

Test piece Ø 10 mm / F=100 N > 100 000

#### 3 Actuating force, actuating distance and response angle

3.1	Actuating force	EKS 030	
	v <sub>test</sub> = 50 mm/min	23 °C	-25 °C
	Test piece Ø 4 mm	< 15 N	< 25 N
	Test piece Ø 200 mm	< 20 N	< 40 N

#### 3.2 Actuating distance

 $v_{test} = 50 \text{ mm/min}$  23 °C Test piece Ø 80 mm < 2,0 mm 3.3 Response angle < 100°

#### 4 Mechanical operating and application conditions

4.1 Sensor length (min./max.)	70 mm / 150 m
-------------------------------	---------------

4.2 Bending radii, minimum

A / B / C / D 70 / 60 / 30 / 30 mm

4.3 Tensile load, cable max. 40 N

4.4 Working temperature -25 °C to +80 °C Permissible short term exposure -40 °C to +100 °C

#### 5 Electric operating conditions

5.1	End resistor (standard) Performance	1.2 k $\Omega$ ±1% max. 250 mW
5.2	Transition resistance	$<$ 400 $\Omega$ (under load)
5.3	Electric rating Voltage Current	without end resistor max. 24 V DC max. 10 mA min. 1 mA
5.4	Connecting cable	Ø 4.1 mm

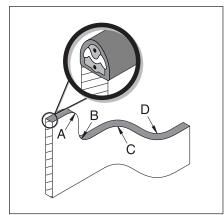
#### 6 Application using acrylic-foam-adhesive tape

Peel strength	15 N/cm		
Applied to:	using promoter	without promoter	
ABS	+	-	
Aluminium	+	+	
Aluminium: anodised	+	-	
Wood: native	-	-	
Wood: varnished, vene	er or		
laminated	+	-	
PA6	+	-	
PA66	+	+	
PE, HDPE	-	-	
PMMA	+	+	
PP, SAN	+	-	
PS, CAB	-	-	
PVC	+	+	
Steel, stainless steel	+	+	

2× 0.35 mm<sup>2</sup>

### Miniature Safety Edges

#### Bending radii:



Tests carried out at 23 °C (room temperature).

**Note:** check with adhesion tests before serial use whether bonding is possible on the selected installation surface.

Key to symbols: + = OK - = not OK

### Miniature Safety Edges

#### 7 Behaviour in fire

According to DIN 75200

Compliance with StVZO, TA 29, BMW N601 21.0

40 mm/min

**8 Dimensions tolerances** length according to ISO 3302 L2 section according to ISO 3302 E2

#### 9 Chemical resistance

Miniature Safety Edge EKS	TPE		
Material characteristics			
Shore A hardness	52 ±5		
Chemical resistance			
Acetone	-		
Formic acid	-		
Armor All	+		
Carwash agent	+		
Fuel	-		
Brake fluid	±		
Buraton	+		
Butanol	-		
Chlorinated bleaching lye	-		
Disinfectant 1 %	+		
Diesel	-		
Acetic acid 10 %	-		
Ethyl alcohol	+		
Ethyl acetate	-		
Ethylene glycol	+		
Greases	±		
Antifreeze	+		
Skin cream	+		
Icidin	+		
Incidin	+		
Incidin plus	+		
Cooling lubricants	_		
Plastics cleaning agent	+		
Lyso FD 10	+		
Metal processing oil	-		
Microbac	+		
Microbac forte	+		
Minutil	+		
Saline solution 5 %	+		
Spirit (ethyl alcohol)	+		
Terralin	+		
UV-resistance	+		
Centering oil	-		

Tests carried out at 23 °C (room temperature).

#### Key to symbols:

+ = resistant

= limited resistance

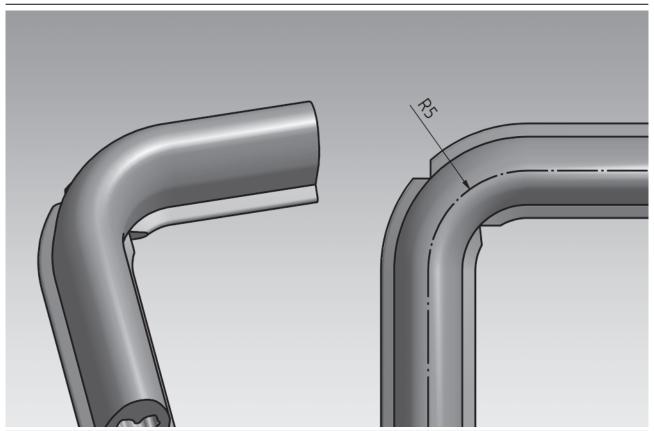
= not resistant

The data given are results of tests which were carried out in our laboratory to the best of our knowledge and belief. We cannot accept any obligations being deduced from them. You must always test the suitability of our products for your special application purpose under practical conditions.





## **Product Information**



## Miniature Safety Edge EKS 038

#### Mayser GmbH & Co. KG

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Intended use	3
Limits	3
Design	3
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Available lengths	
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#### **Important information**

Read through the product information carefully. It contains important information on operation, safety and maintenance of the product. Retain the product information for later reference. Always observe the safety instructions on the following pages under **ATTENTION.** Only use the product for the purpose described in the product information.

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#### **Definitions**

Miniature Safety Edges are sensors for tactile protective devices. A suitable Control Unit is required for evaluation of the signals.

#### Intended use

A Miniature Safety Edge detects a person or part of the body when pressure is applied to the actuation area. It is part of a linear tripping device. The task of the protective device is to avoid potential hazardous situations for a person within a danger zone such as shearing or pinching edges.

Typical application areas are automatic windows, covers on machines, medical diagnostic equipment and height-adjustable furniture.

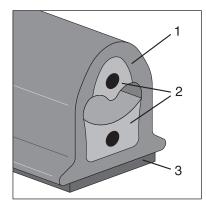
Safe operation of a Miniature Safety Edge depends entirely on

- the surface condition of the mounting surface,
- the correct selection of the size and resistance,
- correct installation as well as
- selection of the suitable Control Unit according to ISO 13849-1.

#### Limits

A maximum of 5 Miniature Safety Edges may be connected to one Control Unit.

## Design



The Miniature Safety Edge EKS 038 consists of (1) insulating TPE-covering, (2) conductive contact layers with embedded wires and (3) self-adhesive acrylic foam on the base of profile.

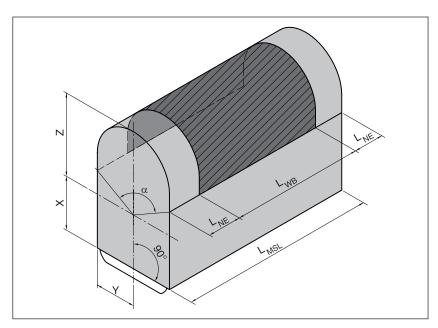


#### **Effective actuation area**

The parameters X, Y, Z,  $\rm L_{NE}$  and angle  $\alpha$  describe the effective actuation area.

For the effective actuation area, the following applies:

$$L_{WB} = L_{MSL} - 2 \times L_{NE}$$



MSL	EKS 038		
α	60°		
L <sub>NE</sub>	10 mm		
Х	2 mm		
Y	2.65 mm		
Z	2.9 mm		

#### Parameters:

 $L_{WB}$  = effective actuation length

L<sub>MSL</sub> = overall length of the Miniature Safety Edge

 $L_{NE}$  = non-sensitive length at the end

 $\alpha$  = effective actuation angle

### **Available lengths**



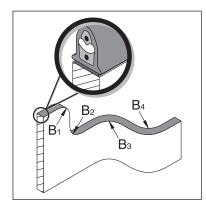


## Bend angles and bend radii

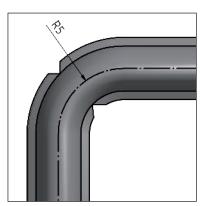
#### **Bend angles**

Bend angles are not possible on the Miniature Safety Edge.

#### **Bend radius**



Bend radius min.	EKS 038
B <sub>1</sub>	500 mm
B <sub>2</sub>	300 mm
<b>B</b> <sub>3</sub>	15 mm
B4	15 mm



Small 90° bends can also be implemented: Small bend radii up to 5 mm are possible for  $B_3$  and  $B_4$  with two opposite cuts in the protruding parts of the profile base.

#### **Installation position**

The installation position can be selected as required.

#### **CAUTION**

No pressure must be exerted on the Miniature Safety Edge in non-operative mode.



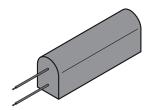
#### **Connection**

#### **Cable exits**

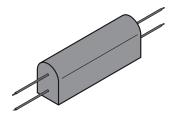
#### Tip

With more than one sensor connected one behind the other, we recommend the BK versions.

#### **Axial exit**







Version: EKS 038/BK

#### **Cable connection**

• Cable: 0.35 mm<sup>2</sup> per strand, Ø 1.4 mm, black

• Cable length: 2.0 m

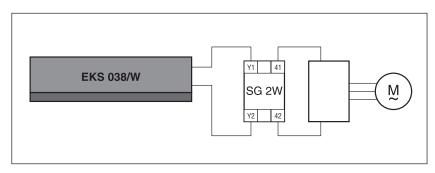
Option: to max. 200 m
• Cable ends: strands stripped

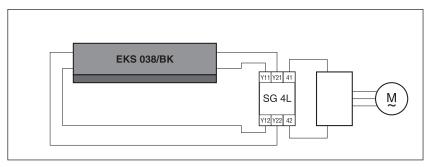
Option: cable ends available with plug and coupling

## CAUTION

The cables must be laid free of tension.

## **Connection example**





#### Key:

SG 2W 2-wire-technology evaluationSG 4L 4-wire-technology evaluation

Y11, Y12 lower cables; Y21, Y22 upper cables



## **Profiles**

## **Dimensions and operating paths**

EKS 038	
4.0	
Actuation force: < 50 N Actuation distance: < 1.2 mm	

## **Physical resistance**

Miniature Safety Edges EKS	TPE
Degree of protection (IEC 60529)	IP65
Hardness as per Shore A	50 ±5
Behaviour in fire	approx. 40
(DIN 75200)	mm/min



#### **Chemical resistance**

The Miniature Safety Edge is resistant against normal chemical influences such as diluted acids and alkalis as well as alcohol over an exposure period of 24 hrs.

The values in the table are results of tests carried out in our laboratory to the best of our knowledge and belief. The suitability of our products for your special area of application must always be verified with your own practical tests.

Explanation of symbols:

+ = resistant

± = resistant to a certain extent

- = not resistant

Miniature Safety Edge EKS	TPE
Acetone	-
Formic acid	-
Armor All	+
Car shampoo	+
Buraton	+
Butanol	-
Sodium hypochlorite	-
Disinfectant	+
Acetic acid 10 %	-
Ethanol	+
Ethyl acetate	-
Ethylene glycol	+
Window cleaner	
Alcohol-based	+
Alkaline cleaner	+
Neutral cleaner	+
Greases	±
Volatile softeners	-
Anti-frost agent	+
Skin cream	+
Icidine	+
Incidine	+
Incidine plus	+
Plastic cleaner	+
Lyso FD 10	+
Metal working oil	-
Microbac	+
Microbac forte	+
Minutil	+
Saline solution 5 %	+
Spirit (ethyl alcohol)	+
Terralin	+
UV-resistance	+
Centring oil	-

#### Note:

Tests are carried out at room temperature (+23 °C).

#### **Attachment**

### Per acrylic-foam adhesive tape

#### Requirements

For ideal bonding, the bonding surface must be

- + clean
- + dry
- + smooth.

#### Avoid

- very uneven
- sharp-edged bonding surfaces.

Recommended working temperature: +15 to +25°C.

#### Note:

Check with adhesion tests before serial use whether bonding is possible on the selected installation surface.

Bonding with on	with Primer	without Primer
ABS	1	-
Aluminium: natural	1	+
Aluminium: anodised	1/3	-
Aluminium: powder-coated	1	-
CAB	-	-
Glass	4/5	-
Wood: natural	=	-
Wood: glazed, varnished	2	-
Wood: veneered, light weight building board	2	-
PA6, PA66	3	-
PE, HDPE	-	-
PMMA	1	-
PP	1	-
PS		-
PVC	2	-
SAN	1	-
Steel, stainless steel	1/3	-

#### Explanation of symbols:

- + = suitable
- = not suitable
- 1 = Primer 4298UV
- 2 = Primer 4297
- 3 = Multiprimer
- 4 = Silan Primer 5 = Primer 4299

#### Note:

Tests are carried out at room temperature (+23 °C).

#### **Preparation**

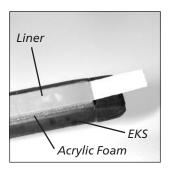
Only applies to bend radii < 15 mm.

- 1. Measure bend locations and mark on both sides.
- 2. Carefully cut into both profile sides at the markings, making sure you only cut the projecting part.

#### **CAUTION**

Damage to the rest of the TPE-covering renders the Miniature Safety Edge unusable. Dispose of faulty Miniature Safety Edge.





#### **Bonding**

- 1. Clean and degrease bonding surface (e.g. with isopropanol).
- 2. Apply primer as thinly as possible to complete bonding surface with brush.
- 3. Air dry primer for approx.10 minutes.
- 4. Remove 10 to 15 cm of liner from acrylic foam.
- 5. Place on bonding surface and press on firmly, without any tensile stress.
- 6. Repeat items 4. and 5. until EKS is completely bonded.
- 7. Maximum adhesion is achieved after 24 hrs.

#### Note:

If tensile stress is applied, the EKS can become several millimetres longer.

#### Tip:

For long straight sections, an extended try square may be useful for alignment.

#### Installation accessories

Part no.	Designation	Pack. unit
7500462	Primer 4298 type 3M, 125 ml, in can	1 pc.
7501995	Primer 4297 type 3M, 125 ml, in can	1 pc.
1003360	Multiprimer, 250 ml 24-P	1 pc.

#### **ATTENTION**

Smaller winding diameters cause separation of the liner and therefore damage to the selfadhesive acrylic foam.

## **Storage**

Correct storage of the Miniature Safety Edge requires a winding diameter of at least 600 mm.



Miniature Safety Edge EKS 038 cut-to-size with resistor (type W) or without resistor (type BK).



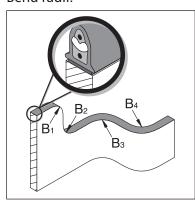
1:1

Switching characteristics at v <sub>test</sub> = 50	0 mm/min		
Switching operations	> 1× 10 <sup>5</sup>		
Actuating force	+23 °C	-25 °C	
Test piece (rod) Ø 4 mm	< 15 N	< 25 N	
Test piece (rod) Ø 200 mm	< 35 N	< 50 N	
Actuating distance			
Test piece (cylinder) Ø 80 mm	< 1.2 mm		
Actuation angle			
Test piece (cylinder) Ø 80 mm	± 30°		
Safety classifications			
B <sub>10d</sub> as per ISO 13849-1	2× 10 <sup>6</sup>		
Mechanical operating conditions			
Sensor length (min./max.)	70 mm / 150	) m	
Cable length (min./max.)	2 / 200 m		
Attachment	Using acrylic	-foam adhesive	
Peel force	15 N/cm		
Bend radii, minimum			
B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub>	500 / 300 / 15 / 15 mm		
IEC 60529: Degree of protection	IP65		
Operating temperature	-25 °C to +80 °C		
short-term (15 min)	-40 °C to +100 °C		
Electrical operating conditions			
Terminal resistance	1k2 ± 5%		
Output	max. 250 mV	V	
Contact transition resistance	< 400 Ohm (	per sensor)	
More than one sensor	max. 5 in ser	ies	
Electrical rating			
Voltage	max. 24 V D0	2	
Current (min./max.)	1 mA / 10 mA		
Connection cable	Ø 1.4 mm per strand		
	2× 0.35	mm <sup>2</sup>	
Control Unit (recommendation)			
ISO 13849-1 Cat. 3		2W (type W)	
ISO 13849-1 Cat. 3	SG-EFS 104/4	4L (type BK)	
Chemical resistance			
The Miniature Safety Edge is resistant			
fluences over a period of exposure of	24 hrs (see p. 8)		

ISO 3302 L2

ISO 3302 E2

#### Bend radii:



Length as per Profile section as per

**Dimensional tolerances** 



equest for qu	lotation		
From:			Fax:
Company			+49 731 2061-222
Department			
Name, first name			
P. O. Box	Post code	City	
Street	Post code	City	
Phone	Fax	E-mail	
Area of application			
(e.g window construction, transport,)  Mechanical condition	medical technology, machine	closing edges, public	
EKS	O Tuno PV		
EK3	O Type BK	esistor kΩ	
Length: m	Packing unit:		
Attachment per:	O Bonding	units	
Attaciment per.	O Snap-in foot		
☐ Angle piece	3 3hap iii 100t		
construction:	× per EKS		
☐ Cable length:	m (standard	l: 2.0 m)	
☐ Number of monito	oring circuits:	□ SG	
Pinching and shearin	g edges to be protecte	d:	
(Diagram incl. mounting pos	ssibility and cable routing)		





# **DIY Miniature safety edges**



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## **MAYSER®**

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### **Overview**

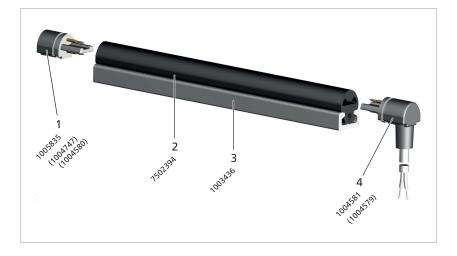
#### **Contact profile - Miniature safety edge**

The semi-finished contact profile is cut to length and assembled with the other components. The functioning product is then called a miniature safety edge.



#### **EKS 011 TPE**

- 1 End piece with resistor
- 2 Contact profile
- 3 End piece with cable



#### **EKS 014 TPE**

- 1 End piece with resistor
- 2 Contact profile
- 3 Aluminium profile
- 4 End piece with cable



#### **EKS 052 TPE**

- 1 End piece with resistor
- 2 Contact profile
- 3 End piece with cable



## **Materials list**

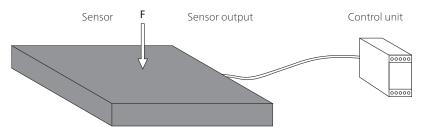
Part No.	Designation	PU
7502395	Contact profile EKS 011 TPE, self-adhesive	50 m
7502394	Contact profile EKS 014 TPE, with snap-in foot	50 m
7502773	Contact profile EKS 052 TPE, with clamp foot	45 m
1004580	End piece with resistor 1k2	50 pc.
1004747	End piece with resistor 2k2	50 pc.
1005835	End piece with resistor 8k2	50 pc.
1004579	End piece with PUR cable 2.5 m, axial	50 pc.
1004581	End piece with PUR cable 2.5 m, angled 90°	50 pc.
		,
1003436	Aluminium profile C 10 for EKS 014 with snap-in foot	6 m
1004988	Scissors with stop	1 pc.
7502412	Assembly aid set	1 pc.
1004987	Special adhesive Contact VA 250 Black, 12 g, for IP64	1 pc.
7501995	Primer 4297 Type 3M, 125 ml, in can	1 pc.



### **Definitions**

## Pressure-sensitive protection device

A pressure-sensitive protection device consists of pressure-sensitive sensor(s), signal processing and output signal switching device(s). The control unit is made up of the signal processing and output signal switching device(s). The pressure-sensitive protection device is triggered when the sensor is activated.

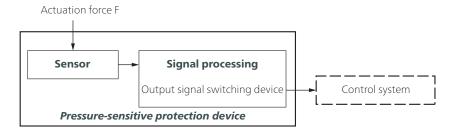


#### Sensor

The sensor is the part of the pressure-sensitive protection device that generates a signal when the actuating force F is applied. Mayser safety systems have a sensor whereby the actuating surface is deformed locally.

#### **Signal processing**

The signal processing is the part of the pressure-sensitive protection device that converts the output signal of the sensor and controls the status of the output signal switching device. The output signal switching device is that part of the signal processing which is connected to the machine controls and transmits safety output signals such as STOP.

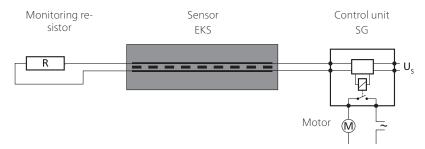




#### Criteria for selecting the sensor type

- Category according to ISO 13849-1
- Performance level of pressure-sensitive protection device = at least PL<sub>e</sub>
- Temperature range
- Degree of protection in accordance with IEC 60529:
   IP40 is the standard for diy miniature safety edges.
   Higher degree of protection possible with special adhesive (part no.: 1004987).
- Low switching forces
- Minimum overall height

## Operation principle 2-wire-technology



The monitoring resistor must be compatible with the control unit. Standard value is 8k2.

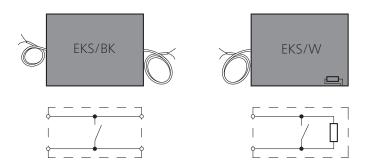
#### For your safety:

Sensor and connecting cables are constantly monitored for function. Monitoring is carried out by controlled bridging of the contact surfaces with a monitoring resistor (closed current principle).

#### Design

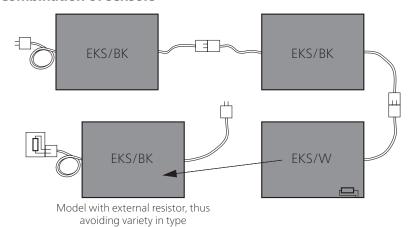
EKS/BK with cables on both sides as a through sensor or as an end sensor with external monitoring resistor

EKS/W as an end sensor with integrated monitoring resistor





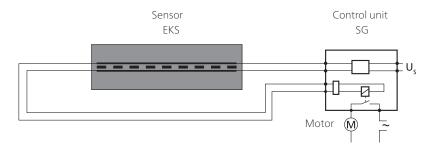
#### **Combination of sensors**



#### Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety edge design with custom lengths and angles

## Operation principle 4-wire-technology



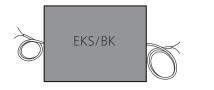
The 4-wire technology can be used only together with control unit SG-EFS 104/4L.

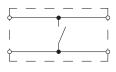
#### For your safety:

Sensor and connecting cables are constantly monitored for function. This is possible because of signal transmission feedback – without monitoring resistor.

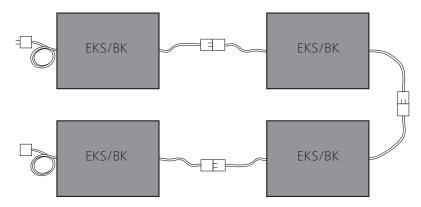
#### Design

EKS/BK with cables on both sides as a through sensor





#### **Combination of sensors**



#### Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety edge design with custom lengths and angles

## **Safety**

### Intended use

A safety edge detects a person or the person's limbs from the pressure exerted on the effective actuation area. It is a linear tripping device. It is designed to prevent potential hazardous situations such as shearing and pinching edges for a person within a danger zone.

Typical areas of use are automated windows and façade systems, automation technology and moving units in medical technology.

The reliable functioning of a safety edge depends on

- the surface condition of the mounting surface,
- the correct choice of EKS profile,
- and proper installation.

Due to the design, the visible actuation area is reduced by the non-sensitive edges. What remains is the actual effective actuation area (see chapter *Effective actuation area*).

#### Limits

- max. 3 sensors type BK on one control unit
- max. 2 sensors type BK and 1 sensor type W on one control unit If more sensors are required, please contact Mayser's service department.



#### **Exclusions**

The sensors are not suitable for performing a sealing function. Constant actuation of sensors can result in permanent damage.

## Other safety aspects

The following safety aspects relate to pressure-sensitive protection devices consisting of a sensor and a control unit

#### **Performance Level (PL)**

Exclusion of error according to ISO 13849-2, Table D.8: Non-closing of contacts in the case of pressure-sensitive safety devices according to ISO 13856. In this case, none of the sensor parameters are used for determining the PL. Assuming the control unit has a high MTTF $_{\rm D}$  value, the entire miniature safety edge system (pressure-sensitive safety device) can achieve the maximum value PL d.

#### Is the safeguard appropriate?

The PL required for the hazard must be decided by the integrator. This is followed by the choice of safeguard.

Finally, the integrator needs to check whether the category and PL of the safeguard chosen are appropriate.

#### **Risk and safety assessment**

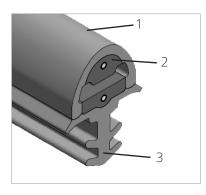
For the risk and safety assessment of your machine we recommend ISO 12100 "Safety of machinery – general principles for design".

#### Without reset function

When a safeguard without reset function is used (automatic reset), the reset function must be made available in some other way.

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## Design



The miniature safety edge consists of

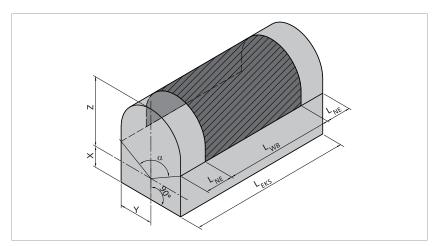
- a sensor (1 to 3)
- (1) contact profile EKS with
- (2) integrated NO contact safety element,
- (3) mounting element.

#### Effective actuation area

The parameters X, Y, Z,  $L_{\text{NE}}$  and the angle  $\alpha$  describe the effective actuation area.

For the effective actuation area, the following applies:

$$L_{WB} = L_{EKS} - 2 \times L_{NE}$$



#### **EKS 011 EKS 014 EKS 052** 80° 80° 80° α End piece W 27 mm 27 mm 27 mm End piece cable 28.5 mm 28.5 mm 28.5 mm $\mathsf{L}_{\mathsf{NE}}$ angled 90° End piece cable 32 mm 32 mm 32 mm axial Χ 2.05 mm 2.3 mm 2.1 mm Υ 3.95 mm 3.9 mm 4.7 mm Ζ 4.6 mm 4.5 mm 4.5 mm

Parameters:

 $L_{WB}$ = effective actuation length

L<sub>EKS</sub>= total length of miniature safety edge

 $L_{NE} = non-sensitive length at end$ of miniature safety edge

 $\alpha$  = effective actuation angle



## Installation position

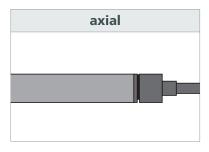
The installation position is variable.

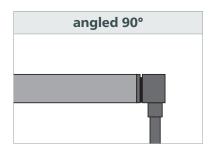
In idle state, it must be ensured that no pressure is exerted on the sensors.

## **Connection**

#### Cable exits

Two cable exits are available: axial and 90° angle.





### Cable connection

- Standard cable lengths
  - L = 2.5 m
- Maximum total cable length to the control unit

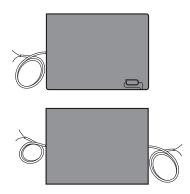
$$L_{max} = 100 \text{ m}$$

#### **Sensor type W**

- As a single sensor type W or an end sensor type W
- Integrated resistor
- 2-wire cable (Ø 2.9 mm PUR, 2× 0.25 mm<sup>2</sup> Cu)

#### Sensor type BK with 2 lines

- As a feed-through sensor type BK
- Without resistor
- Two 2-wire cables (Ø 2.9 mm PUR, 2× 0.25 mm<sup>2</sup> Cu)





#### **Colour coding**

BK Black

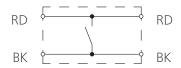
RD Red

#### Wire colours

#### Sensor type W



#### Sensor type BK with 2 lines



#### **Sensor surface**

## Physical resistance

Miniature safety edge EKS	TPE	
IEC 60529: Degree of protection	IP40	
UV-resistance	yes	

#### **Higher degree of protection**

A special adhesive (part no. 1004987) allows a higher degree of protection up to IP64.

### Chemical resistance

The sensor is resistant against normal chemical influences such as diluted acids and alkalis as well as alcohol over an exposure period of 24 hrs.

The specifications in the table are the result of tests conducted in our lab at room temperature (+23 °C). The suitability of our products for your special area of application must always be verified with your own practical tests.



Material	TPE
Acetone	
Formic acid	_
Armor All	+
Car shampoo	+
Petrol	_
Brake fluid	+
Buraton	+
Butanol	_
Sodium hypochlorite	_
Disinfectant 1 %	+
Diesel	_
Acetic acid 10 %	_
Ethanol	+
Ethyl acetate	
Ethylene glycol	+
Greases	±
Anti-frost agent	+
Skin cream	+
Icidine	+
Incidine	+
Incidine plus	+
Cooling lubricant	_
Plastic cleaner	+
Lyso FD 10	+
Metal working oil	_
Microbac	+
Microbac forte	+
Minutil	+
Saline solution 5 %	+
White spirit (ethyl alcohol)	+
Terralin	+
Centring oil	-
Centring oil	-

### **Explanation of symbols:**

+ = resistant

 $\pm$  = resistant to a certain extent

- = not resistant



#### **Attachment**

Three mounting types are available:

- Acrylic foam adhesion
- Snap-in foot
- Clamp foot

The mounting type depends on the selected contact profile.

Mounting type	EKS 011	EKS 014	EKS 052
Acrylic foam adhesion	•	_	_
Snap-in foot	_	•	_
Clamp foot	_	_	•

## Per acrylic foam adhesion

The miniature safety edge is equipped with double-sided foam adhesive tape. The double-sided foam adhesive tape (acrylic foam) is already affixed to the bottom side of the contact profile.

#### With primer

The clean, dry and smooth bonding surface must be treated with primer before the miniature safety edge is mounted.

#### Without primer

Only in the case of uncoated aluminium, the acrylic foam also adheres dependably without primer.

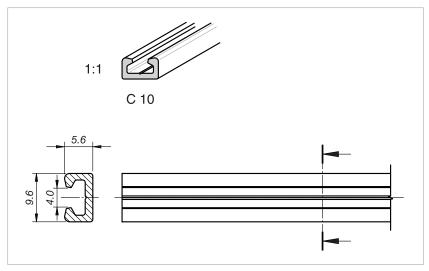
#### **Not suitable**

The following materials are not suitable for acrylic foam adhesive tape: CAB, glass, natural wood, PE, HDPE and PS.



## Per snap-in foot

The miniature safety edge is clipped into an aluminium profile.



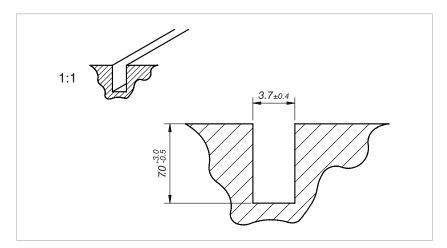
#### Aluminium profile C 10

Standard profile for EKS 014:

First the aluminium profile must be mounted onto the closing edge and then the miniature safety edge clipped into the aluminium profile.

## Per clamp foot

The miniature safety edge is pressed into a groove. A precise groove provides for an accurate and lasting fit.



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## **Maintenance and cleaning**

The sensors are virtually maintenance-free.

The control unit also monitors the sensor.

#### **Regular inspection**

Depending on the utilisation, sensors must be inspected at regular intervals (at least monthly)

- for proper functioning,
- damage,
- and correct mounting.

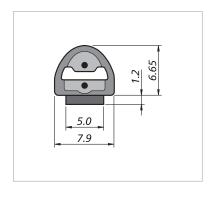
#### Cleaning

If the sensors become dirty, they can be cleaned with a mild cleaning product.

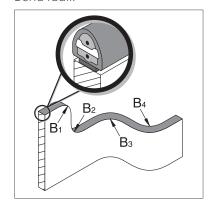
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## SK EKS 011 TPE

Miniature safety edge (without sensor)	SK EKS/W 011 TPE or SK EKS/BK 011 TPE				
Test principles	based on ISO 13856-2				
Switching characteristics at $v_{test} = 50 \text{ mm/s}$					
Switching operations Test piece Ø 10 mm, F = 100 N Actuation force Test piece Ø 4 mm Test piece (cylinder) Ø 200 mm Actuation distance Test piece (cylinder) Ø 80 mm	> 1× 10 <sup>5</sup> +23 °C < 15 N < 25 N < 20 mm				
Actuation angle Test piece (cylinder) Ø 80 mm Finger detection  Safety classifications	± 40° yes				
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>				
Mechanical operating conditions					
Sensor length (min./max.) Cable length Acrylic foam: Peel force Bend radii (min.): B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub> max. load capacity (signal) Tensile load, cable (max.) IEC 60529: Degree of protection Operating temperature short-term (15 min) Storage temperature DIN 75200: Behaviour in fire Weight (with Acrylic foam)	10 cm / 50 m 2.5 m 15 N/cm 120 / 150 / 20 / 20 mm 600 N 20 N IP40 -25 to +80 °C -40 to +100 °C -40 to +80 °C ca. 40 mm/min 43 g/m				
Electrical operating conditions					
Terminal resistance (±1%) Rated capacity (max.) Contact transition resistance Number of sensors type BK  Switching voltage (max.)	1k2, 2k2 or 8k2 250 mW < 400 Ohm (per sensor) max. 3 in series (For more information refer to the chapter <i>Limits</i> ) DC 24 V				
Switching current (min. / max.) Connection cable	1 mA / 10 mA Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>				
Dimensional tolerances	2.5 mm ON 2A 0.25 mm				
Length according to Profile section according to	ISO 3302 L2 ISO 3302 E2				



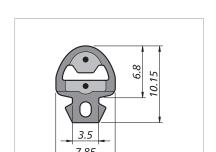
#### Bend radii:



## Higher degree of protection, higher tensile load

A special adhesive (part no. 1004987) allows a higher degree of protection up to IP64 and a tensile load on the cable up to 60 N.





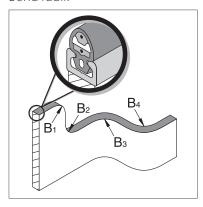
### SK EKS 014 TPE

Length according to

Profile section according to

Miniature safety edge (without sensor)	SK EKS/W 014 TPE or SK EKS/BK 014 TPE		
Test principles	based on ISO 13856-2		
Switching characteristics at v <sub>test</sub> = !	50 mm/s		
Switching operations Test piece Ø 10 mm, F = 100 N Actuation force Test piece Ø 4 mm Test piece (cylinder) Ø 200 mm Actuation distance	> 1× 10 <sup>5</sup> +23 °C -25 °C < 15 N < 30 N < 25 N < 50 N		
Test piece (cylinder) Ø 80 mm Actuation angle Test piece (cylinder) Ø 80 mm Finger detection	< 2.0 mm ± 40° yes		
Safety classifications			
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>		
Mechanical operating conditions			
Sensor length (min./max.) Cable length Snap-in foot width Alu-Profil (empfohlen) Bend radii (min.): B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub> max. load capacity (signal) Tensile load, cable (max.) IEC 60529: Degree of protection Operating temperature short-term (15 min) Storage temperature DIN 75200: Behaviour in fire Weight (without/with Aluuminium profile)	10 cm / 50 m 2.5 m 3.5 mm C 10 120 / 150 / 20 / 20 mm 600 N 20 N IP40 -25 to +80 °C -40 to +100 °C -40 to +80 °C ca. 40 mm/min 49 g/m / 125 g/m		
Electrical operating conditions			
Terminal resistance (±1%) Nennleistung (max.) Contact transition resistance Number of sensors type BK	1k2, 2k2 or 8k2 250 mW < 400 Ohm (per sensor) max. 3 in series (For more information refer to the chapter <i>Limits</i> )		
Switching voltage (max.) Switching current (min. / max.) Connection cable  Dimensional tolerances	DC 24 V 1 mA / 10 mA Ø 2.9 mm PUR 2× 0.25 mm <sup>2</sup>		

#### Bend radii:



## Higher degree of protection, higher tensile load

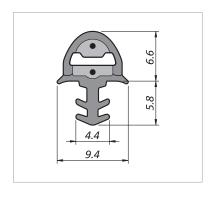
A special adhesive (part no. 1004987) allows a higher degree of protection up to IP64 and a tensile load on the cable up to 60 N.

ISO 3302 L2

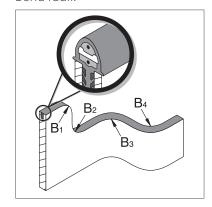
ISO 3302 E2

## SK EKS 052 TPE

Miniature safety edge (without sensor)	SK EKS/W 052 TPE oder SK EKS/BK 052 TPE based on ISO 13856-2				
Test principles					
Switching characteristics at v <sub>test</sub> = 50 mm/s					
Switching operations Test piece Ø 10 mm, F = 100 N Actuation force	> 1× 10 <sup>5</sup> +23 °C -25 °C				
Test piece Ø 4 mm Test piece (cylinder) Ø 200 mm Actuation distance	< 15 N < 30 N < 25 N < 50 N				
Test piece (cylinder) Ø 80 mm Actuation angle Test piece (cylinder) Ø 80 mm	< 2.0 mm ± 40°				
Finger detection	yes				
Safety classifications					
ISO 13849-1: B <sub>10D</sub>	2× 10 <sup>6</sup>				
Mechanical operating conditions					
Sensor length (min./max.)	10 cm / 45 m				
Cable length 2.5 m					
Groove width for clamp foot $3.7 \pm 0.4 \text{ mm}$					
Bend radii (min.): B <sub>1</sub> / B <sub>2</sub> / B <sub>3</sub> / B <sub>4</sub> 120 / 150 / 20 / 20 mm					
max. load capacity (signal)	600 N				
Tensile load, cable (max.)	20 N				
IEC 60529: Degree of protection	1P40				
Operating temperature	-25 to +80 °C				
short-term (15 min)	-40 to +100 °C				
Storage temperature	-40 to +80 °C				
DIN 75200: Behaviour in fire	ca. 40 mm/min				
Weight	54 g/m				
Electrical operating conditions  Terminal resistance (+10/)	1k2, 2k2 or 8k2				
Terminal resistance (±1%)	250 mW				
Nennleistung (max.) Contact transition resistance	< 400 Ohm (per sensor)				
Number of sensors type BK	max. 3 in series (For more information refer to the chapter <i>Limits</i> )				
Switching voltage (max.)	DC 24 V				
Switching current (min. / max.)	1 mA / 10 mA				
Connection cable					
Dimensional tolerances					
Length according to	ISO 3302 L2				
Profile section according to	ISO 3302 E2				



#### Bend radii:



## Higher degree of protection, higher tensile load

A special adhesive (part no. 1004987) allows a higher degree of protection up to IP64 and a tensile load on the cable up to 60 N.



## **Marking**

If you combine sensors with control units and thereby release pressure-sensitive safeguards onto the market, observe the basic regulations in ISO 13856.

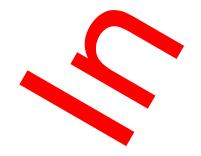
Apart from technical requirements, this applies in particular also to marking and information for use.

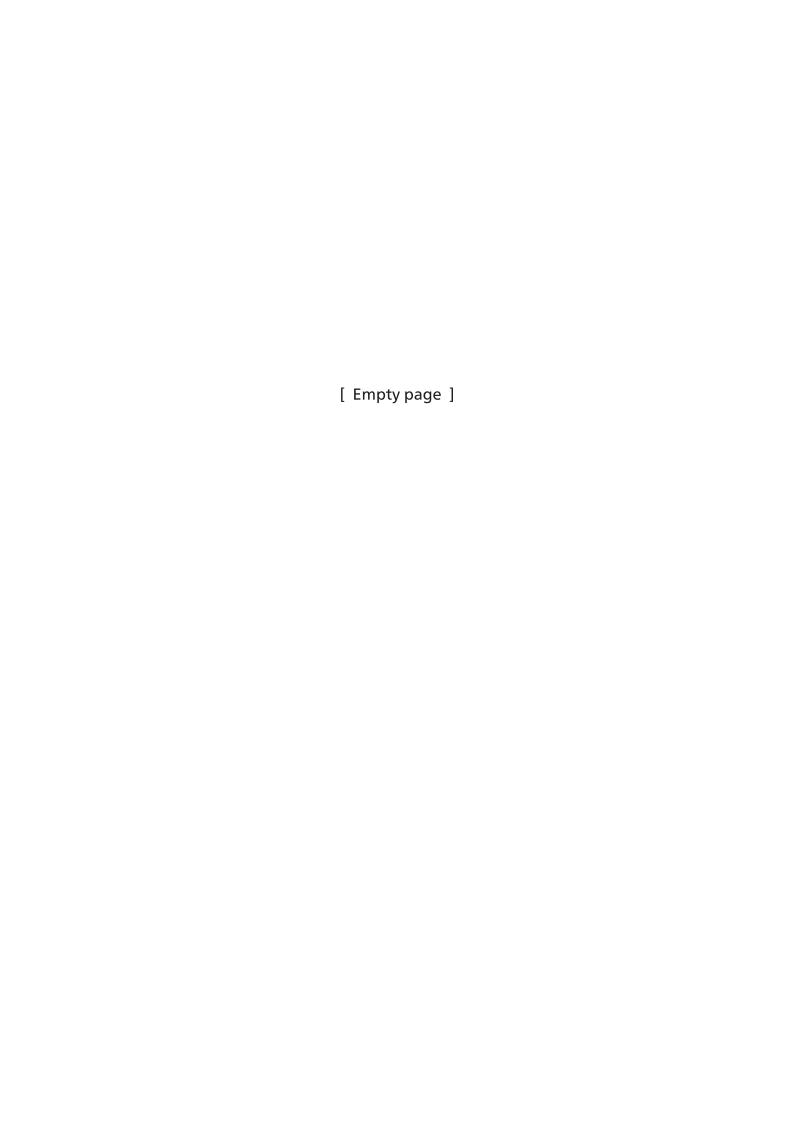


## Safety bumper

## **Contents**

Safety Bumper Programme	
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SB/M	7.9
Request for quotation	
Fax sheet	7.10





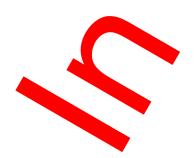
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# Control units G



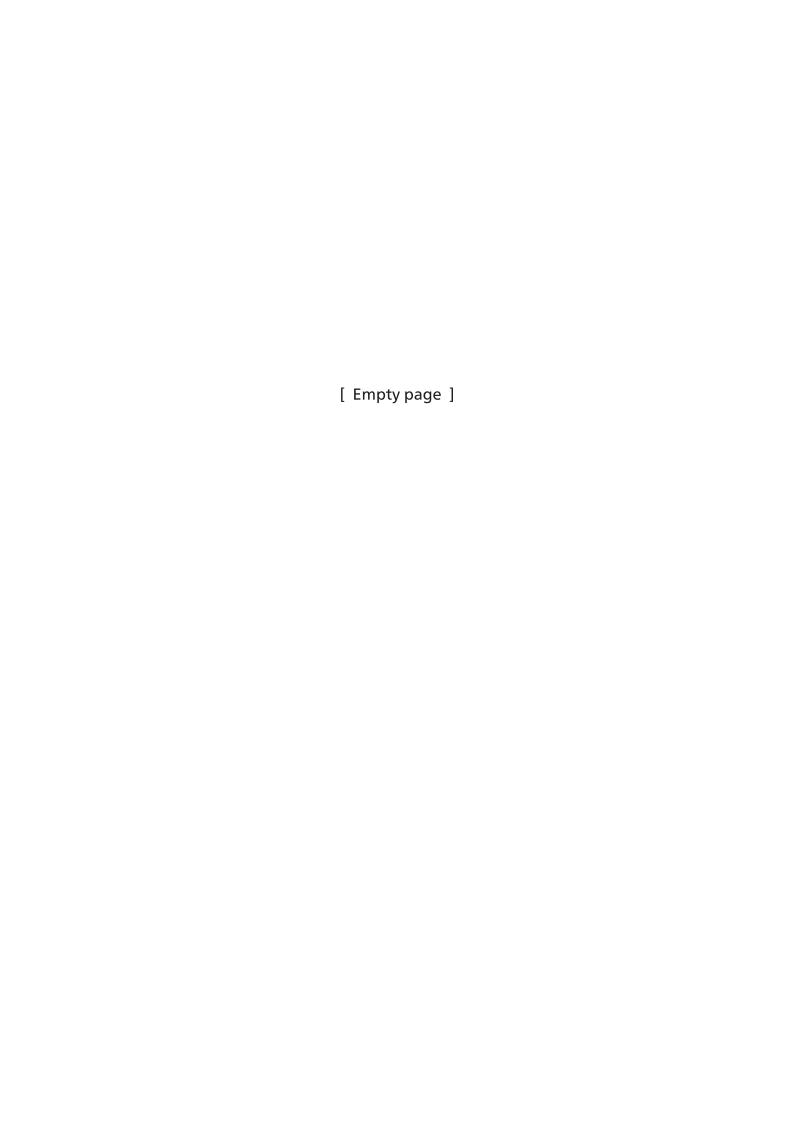
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## Signal transmission system WLS



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## **MAYSER®**



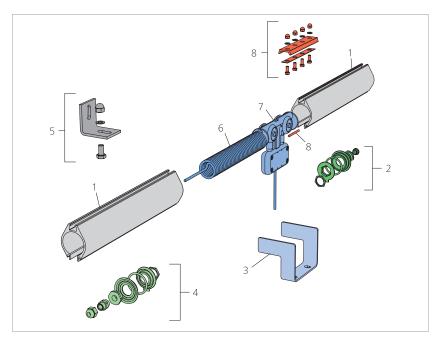
## **Areas of application**

The WLS signal transmission system is used as a protective conduit for cables in doors and gates. When it comes to making danger areas safe, the system is especially suitable for safe transmission of signals between tactile sensors e.g. safety edges and the control module.

#### **Examples:**

- Vertical and horizontal gates
- Machine hoods and windows
- Conservatories
- Sun blinds
- Moulding and textile machines

## **System design**



Pos.	Part No.	Designation	Comment
1	10038-0609	Profile tube WLS	aluminium anodised; 2, 3, 4 and 6 m
2	1003792	WLS-sealing cap	closed
3	1003771	Carrying fork for WLS	
4	1003791	WLS-sealing cap	PG7
6 + 7	75015-1324	Spiral cable with carriage	4× 0.14 mm <sup>2</sup>
8	1003802	Tube connector for WLS	stainless steel

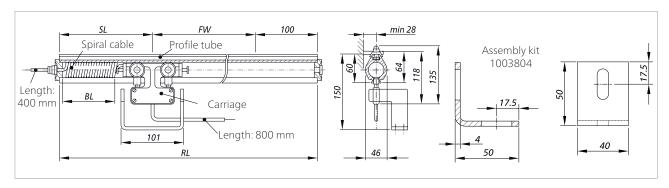
Acces	sories		
5	1003804	Fastening parts for WLS	incl. nuts and screws



## **Operation**

The system consists of an aluminium profile tube and a specially designed, abrasion-resistant and extremely dimensionally stable spiral cable with carriage. When the carriage is put into motion the cable is stretched inside the profile tube and returns to its original position when the carriage goes back. The system components were designed to co-ordinate with each other and can be used in gates both indoors and outdoors. The WLS is suitable for gates in high-frequency operation.

## **Dimensions and part numbers**



WLS complete	WLS-kit, no profile tube	Spiral cable with car-riage	Max. run- way	Profile tube length	Storage length	Block length
Part No.	Part No.	Part No.	FW [m]	RL [m]	SL [m]	BL [m]
7501482	7501501	7501513	1.5	2	0.3	0.12
7501483	7501502	7501514	1.6 2.5	3	0.4	0.29
7501484	7501502	7501514	2.6 3.5	4	0.4	0.29
7501485	7501503	7501515	3.6 4.3	5 = 2+3	0.6	0.46
7501486	7501503	7501515	4.4 5.3	6	0.6	0.46
7501487	7501504	7501516	5.4 6.1	7 = 3+4	0.8	0.63
7501488	7501504	7501516	6.2 7.1	8 = 4+4	0.8	0.63
7501489	7501505	7501517	7.2 8.0	9 = 3+6	0.9	0.80
7501490	7501505	7501517	8.1 9.0	10 = 4+6	0.9	0.80
7501491	7501506	7501518	9.1 9.8	11 = 3+4+4	1.05	0.96
7501492	7501506	7501518	9.9 10.8	12 = 6+6	1.05	0.96
7501493	7501506	7501518	10.9 11.8	13 = 3+4+6	1.05	0.96
7501494	7501507	7501519	11.9 12.6	14 = 2+6+6	1.25	1.13
7501495	7501507	7501519	12.7 13.6	15 = 3+6+6	1.25	1.13
7501496	7501508	7501520	13.7 15.3	17 = 2+3+6+6	1.60	1.48
7501497	7501509	7501521	15.4 17.1	19 = 3+4+6+6	1.80	1.65
7501498	7501510	7501522	17.2 19.0	21 = 3+6+6+6	1.90	1.78
7501499	7501511	7501523	19.1 20.9	23 = 2+3+6+6+6	2.00	1.85
7501500	7501512	7501524	21.0 23.5	26 = 2+6+6+6+6	2.40	2.28
Quantity buyers and dealers: please send us your request for quotation.						



Cable	special, wear-free, double insulated spiral cable
Number of wires/cross-section	4× 0.14 mm <sup>2</sup>
Operating voltage	max. 48 V AC/DC
Max. load (at +25 °C)	max. 1.5 A eff.
Temperature range	-20 to +80 °C
Moving speed	40 m/min
Runway lengths	1.5 m to 23.5 m
System lengths	2.0 m to 26.0 m in fixed lengths: 2, 3, 4 and 6 m
Conduit rail	aluminium, anodized, warp resistant

## At a glance

- Robust, simple, proven construction
- Quick and easy installation due to low number of components in modular form
- Maintenance-free
- Short envelope delay to meet the dynamic force and time parameters in accordance with EN 12453 and EN 12445