

Sicherheitstechnik - Safety Technology



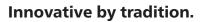
Produktkatalog · Product Catalogue



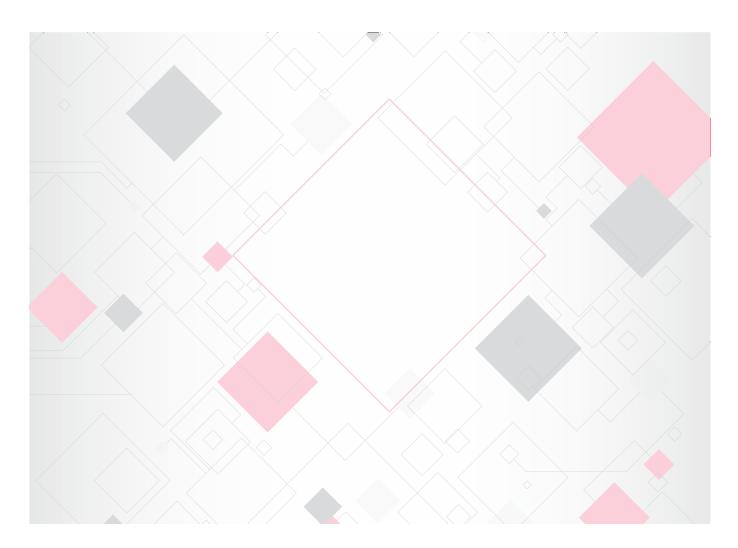
Sicherheitstechnik · Safety Technology Produktkatalog · Product Catalogue

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General



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Quality management

In addition to the important role played by our employees, another key ingredient of our success is the quality of our products. We want our customers to be excited about our products and solutions. To achieve this, we offer intensive support, critically examine the requirements of our customers and generate new ideas.

In addition, Mayser strives for continuous improvement of quality – both in production and in development. In this way, we can ensure that all products, systems and solutions fulfil the relevant quality standards and comply with the applicable standards and directives. This is also backed up by our certifications.

We are certified by **TÜV SÜD Management Service GmbH** for the areas of

- the development, construction and sale of safety technology products and electronic monitoring devices in accordance with ISO 9001 and ISO 14001
- the development and construction of anti-pinch protection systems and seat occupancy detectors – and their components – for the automotive industry in accordance with IATF 16949





Certificates

Quality management

Tip:

Detailed versions of all the certificates can be found in the Downloads area of our website at www.mayser.com. Alternatively, you can click the link to the relevant certificate on this page.

Quality management system	Certificate No.
According to ISO 9001:2015	12 100 22318 TMS
According to IATF 16949:2016	12 111 22318 TMS

Environmental management

Environmental management system	Certificate No.
According to ISO 14001:2015	12 104 22318 TMS

Safety mats

Safety mat	Certificate No.
SM and SM11	44 205 13043617 *

Safety edges

Safety edge	Certificate No.
SK SP 37	44 205 13043610 *
SK SP 57	44 205 13043611 *
SK SP 67	44 205 13043612 *
SK SP 87	44 205 13043614 *
SK SP according to CSA C22.2 No. 247	UL-CA-L496132-21-41508102-1
SK SP according to UL 325	UL-US-L496132-11-41508102-1
SL NC II GP 65 EPDM	IFA 2001029

Miniature safety edges

Miniature safety edge	Certificate No.
EKS and SE 1 TPE according to UL 325	20180912-E496132



Safety bumpers

Safety bumper	Certificate No.
SB	44 205 13043618 *

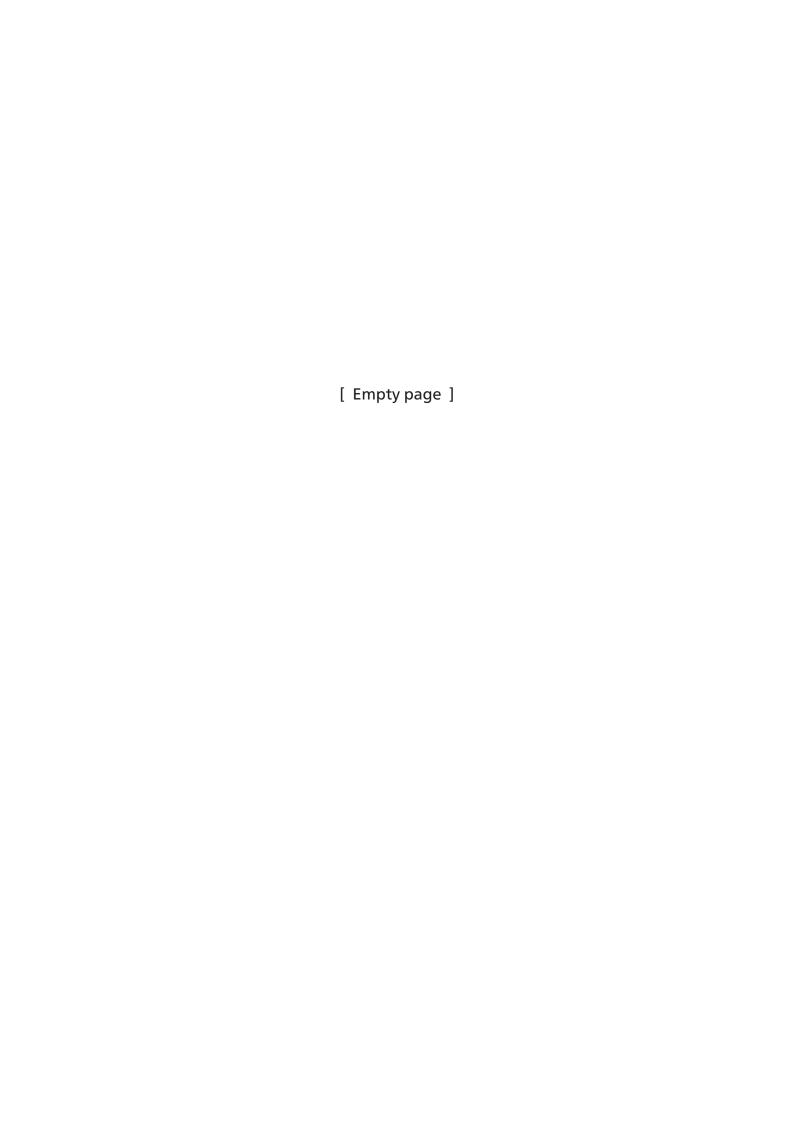
Control units

Control unit	Certificate No.
SG-EFS 104/4L	44 205 15176904
SG-EFS 104/4L according to UL 508	20150327-E471221
SG-EFS 104/2W	44 205 13127902
SG-RS 309-2	44 205 13043613

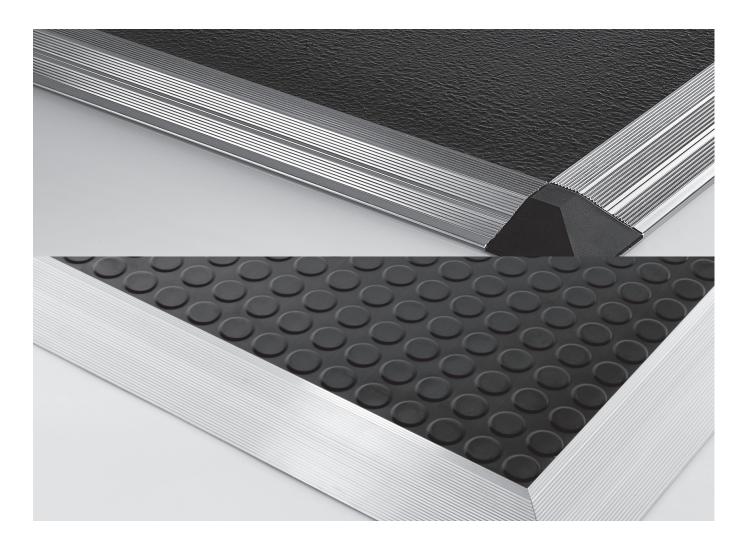
Signal transmission systems

Signal transmission system	Certificate No.
RB3 system: T868 + R868	44 207 13749706

^{*} EC type examination certificates apply exclusively to the combinations of sensor and control unit specified therein.







Safety mats SM and SM11



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Copyright

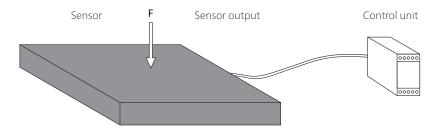
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Definitions

Pressure-sensitive protective device

A pressure-sensitive protective device consists of one or more pressure-sensitive sensors, a signal processing unit, and one or more output signal switching devices. The control unit is made up of the signal processing unit and output signal switching device(s). The pressure-sensitive protective device is triggered when the sensor is activated.

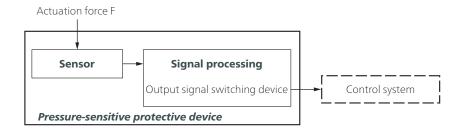


Sensor

The sensor is the part of the pressure-sensitive protective device that generates a signal when the actuation force F is applied. Mayser safety systems feature a sensor whose actuation area is deformed locally.

Signal processing

The signal processing unit is the part of the pressure-sensitive protective device that converts the output signal of the sensor and controls the status of the output signal switching device. The output signal switching device is the part of the signal processing unit which is connected to the downstream control system and which transmits safety output signals such as STOP.



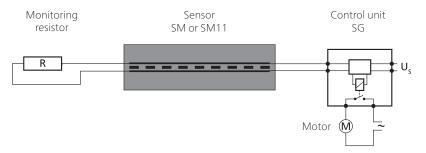
Tip: Terms are defined in ISO 13856-1 Section 3.



Criteria for selecting the sensor type

- Category according to ISO 13849-1
- Performance level of the pressure-sensitive protective device = at least PL,
- Temperature range
- Degree of protection in accordance with IEC 60529:
 IP65 is the standard for safety mats.
 Higher degrees of protection must be checked individually.
- Environmental influences such as swarf, oil, coolant, outdoor use...
- Is it necessary to detect people who weigh < 35 kg?

Operation principle of 2-wire technology



The monitoring resistor must be compatible with the control unit. The standard type is 8k2.

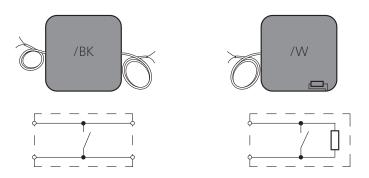
For your safety:

The sensor and connection cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on controlled bridging of the contact surfaces with a monitoring resistor (closed-circuit principle).

Types

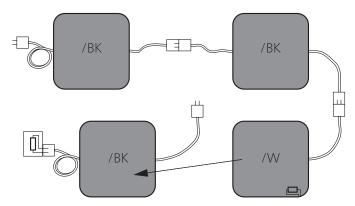
/BK With cables on both sides for use as a through sensor or with an external monitoring resistor for use as an end sensor

/W With an integrated monitoring resistor for use as an end sensor





Sensor combination



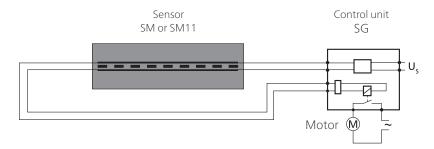
Version with external resistor, therefore no variety of models

Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety mats can be combined to create an overall surface of any size and shape



Operation principle of 4-wire technology



The 4-wire technology can only be used together with control unit SG-EFS 104/4L.

For your safety:

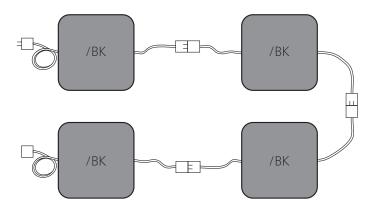
The sensor and connection cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on signal transmission feedback – without a monitoring resistor.

Types

/BK With cables on both sides for use as a through sensor



Sensor combination



Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety mats can be combined to create an overall surface of any size and shape



Safety

Intended use

A safety mat detects a person standing on it or who steps onto it. It is a flat protective device that is capable of monitoring when somebody is present. Its purpose is to prevent possible hazardous situations for personnel within a danger zone.

Typical areas of application are moving parts on machines and systems. Safe operation of a safety mat depends entirely on

- the surface condition of the mounting surface,
- the correct selection of the size and resistance rating as well as
- correct installation.

Tip: This is illustrated clearly by Figures B.1 and B.2 in ISO 13856-1.

Due to the design, the actuation area is actually smaller than it looks because of the non-sensitive edges. Once these have been allowed for, what remains is the effective actuation area (see chapter *Effective actuation area*).

Limits

- No more than 10 /BK-type sensors can be connected to one control unit.
- No more than 9 /BK-type sensors and 1 /W-type sensor can be connected to one control unit.
- Max. system size: 15 m²
 - = max. quantity \times max. sensor size

Exclusions

Sensors are not suitable for:

- Detecting walking aids
- Detecting people who weigh less than 20 kg
- Driving on with industrial trucks

Sensor SM with GM 5 is not suitable for:

• Detecting people who weigh less than 35 kg

Sensor combinations are not suitable for:

• Detecting people who weigh less than 35 kg



Selecting the appropriate product line

The size and shape of safety mats can be customised to create a bespoke solution. SM safety mats are highly resistant to environmental influences and normal chemical influences.

If your sensor requirements are lower, our SM11 or SM8 safety mat products may be right for you.

Other safety aspects

The following safety aspects relate to pressure-sensitive protective devices consisting of a sensor and a control unit.

Performance Level (PL)

The PL has been determined using the procedure defined by ISO 13849-1. Fault exclusion according to ISO 13849-2 Table D.8: Non-closing of contacts in the case of pressure-sensitive protective devices according to ISO 13856. In this case, the diagnostic coverage (DC) is not calculated or taken into account when determining the PL. Assuming a high MTTF $_D$ value for the control unit, a performance level of up to PL d can be achieved by the safety mat system (pressure-sensitive protective device) as a whole.

Is the protective device suitable?

First, the integrator must decide what PL_r is required for the hazard. After that, they must select the protective device.

Finally, the integrator needs to check whether the category and PL of the selected protective device are appropriate.

Risk and safety assessment

For the risk and safety assessment of your machine, we recommend ISO 12100 "Safety of machinery — General principles for design".

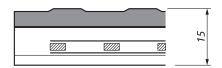
Without reset function

When a protective device without reset function is used (automatic reset), the reset function must be provided in some other way.



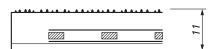
Design

Design of the SM





Design of the SM11



SM with GM 1

Moulded onto a plastic plate. The rubber studded covering provides the necessary non-slip properties and ensures mechanical protection.

SM with GM 5

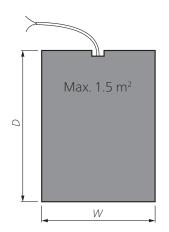
Moulded onto a plastic plate. The high-strength rubber studded covering provides the necessary non-slip properties and ensures a high level of mechanical protection.

SM11

Moulded onto a plastic plate. The surface texture provides the necessary non-slip properties and ensures mechanical protection.

Available sizes

Sensors are available up to a max. size of 1.5 m². The side lengths must be within a range of 200 to 3000 mm.



W: Width (broad side)D: Depth (long side)

 $W \times D \le 1.5 \text{ m}^2$

The cable exit can be on the broad or long side.

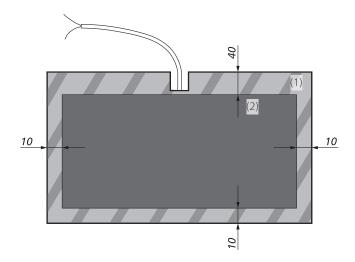
According to ISO 13855, the minimum depth to the danger zone must be taken into account (see chapter *Calculation of the necessary actuation area*). The non-sensitive edges must be taken into account (see chapter *Effective actuation area*).



Effective actuation area

A non-sensitive edge (1) surrounds the effective actuation area (2):

- 40 mm = on the cable exit side
- 10 mm = on the remaining sides



Sensor combinations

When sensor combinations are used:

- Only the sides with 10 mm edges should be placed next to one another.
- Each side is only allowed to touch one other sensor.



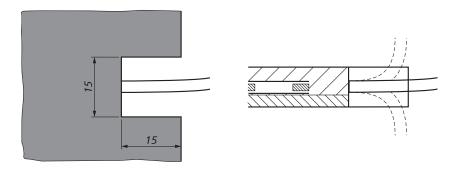
Connection

Cable exit

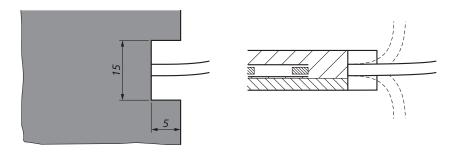
The multifunction cut-out also allows the cable to be laid so that it exits upwards or downwards.

The cable exit is located in the middle of the side.

SM cable exit



SM11 cable exit



Cable connection

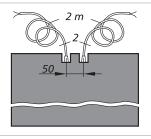
- Standard cable lengths L = 2.0 m
- Maximum total cable length to the control unit $L_{max} = 100 \text{ m}$

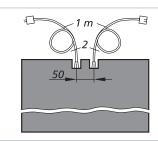


Without plug (standard)	With plug (M8)
Suitable for universal useVariable cable length	Service-friendlyEasy assemblySecure connectionWatertight plug connection
/W-type sensor with 1 line	
2 m	0.25 m

- As an individual /W-type sensor or a /W-type end sensor
- Integrated resistor
- 1 two-wire cable

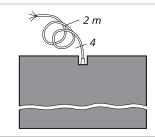
/BK-type sensor with 2 lines

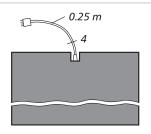




- As a /BK-type through sensor
- Without resistor
- 2 two-wire cables

/BK-type sensor with 1 line





- As a /BK-type through sensor
- Without resistor
- 1 four-wire cable



Colour codingBK Black

Brown Blue

Red

White

BN

ВU

RD WH

Wire colours

Without plug (standard)	With plug (M8)	
	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	
/W-type sensor with 1 line		
BK	3	
/BK-type sensor with 2 lines		
BK [] BK	3	
/BK-type sensor with 1 line		
BU Ç — — — — BK	3	

Connection examples

Key:

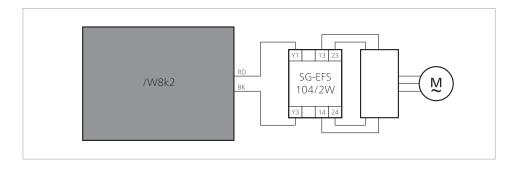
/W8k2 Sensor for 2-wire technology with resistor 8k2

/BK Sensor for 4-wire technology

M Motor

Colour coding

BK Black RD Red





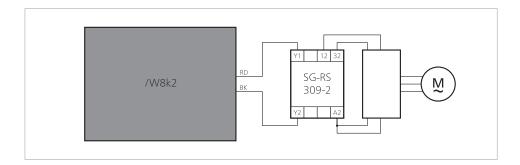
Colour coding

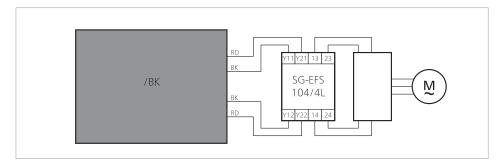
BK Black BN Brown

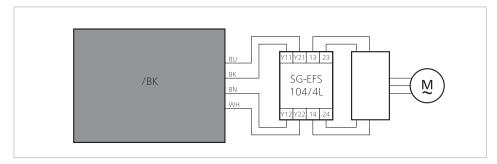
BU Blue

RD Red

WH White







Sensor surface

Sensor surface of the SM

The rubber studded covering is glued in place at the factory. It provides the necessary non-slip properties and ensures mechanical protection.

GM 1

Black covering with circular studs Yellow covering with circular studs

Material: NBR

Thickness: $4.5 \text{ mm}^{\pm 0.5}$ Max. size: $1.0 \text{ m} \times 10 \text{ m}$

 $1.2 \text{ m} \times 10 \text{ m}$





GM 5

Green covering with circular studs With high mechanical strength Material: NBR

Thickness: 9 mm ±0.5

Max. size: $1.2 \text{ m} \times 10 \text{ m}$



Sensor surface of the SM11

The rough surface texture is applied at the factory. It provides the necessary non-slip properties and ensures mechanical protection.

Surface texture

Grey

Material: PUR Thickness: 1.0 mm



Resistance

The resistance ratings listed below (at a room temperature of 23 $^{\circ}$ C) depend on the sensor having:

- A rubber studded covering that is bonded face to face with the sensor (SM only)
- An undamaged surface (SM and SM11)

Physical resistance

	NBR (SM)	PUR (SM11)
DIN 53516: Abrasion DIN 4102: Fire behaviour	120 mg B2	< 150 mg B2
Alternating climate stress conditions UV resistance	+ ±	+ +

Explanation of symbols:

- + = resistant
- ± = resistant to a certain extent
- = not resistant



Chemical resistance

The sensor is resistant to a certain extent to normal chemical influences such as diluted acids and alkalis, as well as alcohol, over an exposure period of 24 hrs.

The values in the table are the results of tests carried out in our laboratory. You must always conduct your own practical tests to verify that our products are suitable for your specific area of application.

Explanation of symbols:

- + = resistant
- ± = resistant to a certain extent
- = not resistant

	NBR (SM)	PUR (SM11)
Acetone	+	_
Ammonia	+	+
Brake fluid	±	
Cutting emulsion	±	+
Acetic acid	±	
Greases	+	_
Caustic potash solution	+	
Cooling lubricant	+	<u>±</u>
Metal working oil	+	+
Methyl alcohol	±	_
Sodium hydroxide	+	
Cellulose thinner	±	_
Hydrochloric acid 10%	+	±
Suds	+	
Spirit (ethyl alcohol)	+	_
Water	+	+
Petroleum ether / petrol	+	_
Citric acid	+	
Drawing compound	±	_



Mounting

The sensors must be mounted immediately in front of the danger zone. They must be fixed in place using ramp edges, Z-profiles or cable conduits (optional), which must be screwed to the floor. Ramp edges are required on the access sides to minimise the risk of tripping.

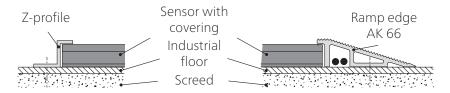
Overview of fixing materials

SM with GM 1	SM with GM 5	SM11
Overall height 15 mm	Overall height 19 mm	Overall height 11 mm
Z-profile (machine side)	Z/1 profile (machine side)	Z/2-profile or AP 45 cable conduit (machine side)
Sensor with rubber studded covering	Sensor with rubber studded covering	Sensor with surface texture
Ramp edge AK 66 or AK 105 (access side)	Ramp edge AK 105/1 (access side)	Ramp edge AK 56 (access side)
	Other fixing materials	
		Outer corner connector E1 AK 56
Sealing plug	_	Connecting wedge Vk AK 56
		Inner corner connector E2 AK 56



Fixing the SM with GM 1

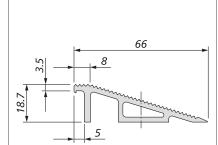
Ramp edge AK 66 with Z-profile



- Not suitable for plug-in cable connections
- Cable conduit for max. 2 cables

Aluminium ramp edge AK 66

- 1-piece with cable conduit
- For sensor combinations with up to 2 sensors
- Sensor without plug
- Aluminium ramp edge for sensors with GM 1
- Rod 3 m (7500053), rod 6 m (1000008) or fixed length

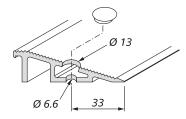


Stepped hole for AK 66

• For fixing aluminium ramp edge AK 66

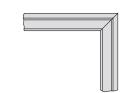
Sealing plug

• Seals the stepped hole (1000615)



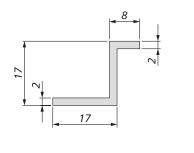
Mitre cut

For corner connections



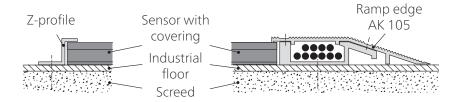
Aluminium Z-profile

- Edging at the machine or wall side
- Aluminium Z-profile for sensors with GM 1
- Aluminium Z-profile: Rod 3 m (7500054), rod 6 m (1000011) or fixed length





Ramp edge AK 105 with Z-profile



- Suitable for plug-in cable connections
- Cable conduit for max. 10 cables

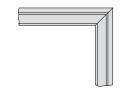
Aluminium ramp edge AK 105

- 2-piece with cable conduit
- For sensor combinations
- Sensors with or without plugs
- Aluminium ramp edge AK 105 for sensors with GM 1
- Aluminium ramp edge AK 105: Rod 3 m upper and lower sections (7500052), rod 6 m upper section (1000009), rod 6 m lower section (1000010), or fixed length

105 50 5

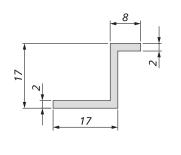
Mitre cut

For corner connections



Aluminium Z-profile

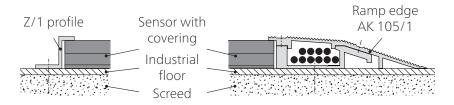
- Edging at the machine or wall side
- Aluminium Z-profile for sensors with GM 1
- Aluminium Z-profile: Rod 3 m (7500054), rod 6 m (1000011) or fixed length





Fixing the SM with GM 5

Ramp edge AK 105/1 with Z/1-profile

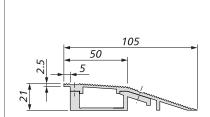


- Suitable for plug-in cable connections
- Cable conduit for max. 10 cables

Ramp edge AK 105/1 and Z/1-profile only suitable for sensors with GM 5.

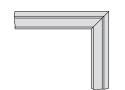
Aluminium ramp edge AK 105/1

- 2-piece with cable conduit
- For sensor combinations
- Sensors with or without plugs
- Aluminium ramp edge AK 105/1 for sensors with GM 5
- Aluminium ramp edge AK 105/1: Rod 3 m upper and lower sections (7500224),
 - rod 6 m upper section (1000992), rod 6 m lower section (1000010), or fixed length



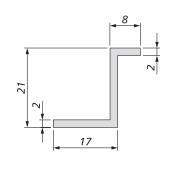
Mitre cut

For corner connections



Aluminium Z/1-profile

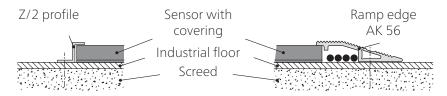
- Edging at the machine or wall side
- Aluminium Z/1-profile for sensors with GM 5
- Aluminium Z/1-profile: Rod 3 m (7500738), rod 6 m (1001478) or fixed length





Fixing the SM11

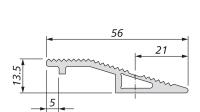
Ramp edge AK 56 with Z/2-profile



- Not suitable for plug-in cable connections
- Cable conduit for max. 4 cables

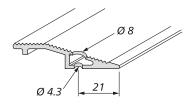
Aluminium ramp edge AK 56

- 1-piece with cable conduit
- For sensor combinations
- Sensors with or without plugs
- Rod 3 m (7501014), rod 6 m (1002684) or fixed length



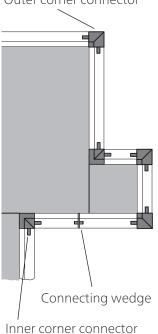
Stepped hole for AK 56

• For fixing ramp edge AK 56



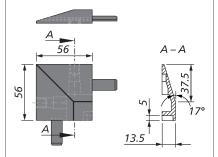
Example:

Outer corner connector



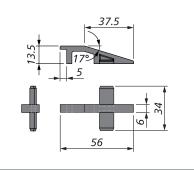
Outer connector E1 AK 56

- For connecting the corners of ramp edge AK 56
- Material: Black plastic (1002751)



Connecting wedge Vk AK 56

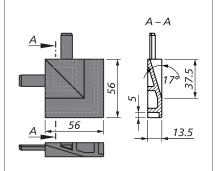
- For connecting several ramp edges AK 56 lengthwise
- Material: Black plastic (1002996)





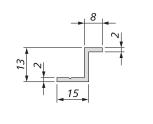
Inner corner connector E2 AK 56

- For connecting the corners of ramp edge AK 56
- Material: Black plastic (1002752)



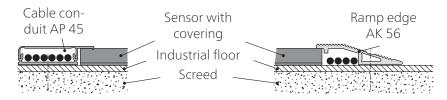
Aluminium Z/2-profile

- Edging at the machine or wall side
- Rod 3 m (7500385), rod 6 m (1001666) or fixed length



Optional: Ramp edge AK 56 with cable conduit AP 45

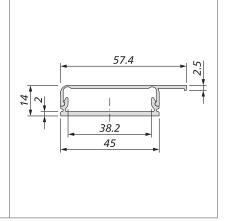
Instead of using a Z/2 profile, you can also use cable conduit AP 45 to fix the sensor in place.



- Cable conduit AP 45 instead of Z/2-profile
- Suitable for plug-in cable connections
- Cable conduit AP 45 for max. 6 cables

Aluminium cable conduit AP 45

- 2-piece cable conduit
- For sensor combinations
- Sensors with or without plugs
- Upper section is clipped into lower section
- Rod 3 m upper section (1002546), rod 3 m lower section (1002547) or fixed length upper and lower sections





S = Minimum distance

sensor [mm]

between the dan-

Calculation of the necessary actuation area

According to ISO 13855, the effective actuation area that is required with reference to the danger zone is calculated using the following formula:

$$S = (K \times T) + C$$

where.

$$K = 1600 \text{ mm/s}$$

$$T = t_1 + t_2$$

C = 1200 mm - 0.4 H

ger zone and the furthest edge of the **With instal**

K = Approximation
 parameter [mm/s]

T = Follow-through of the complete system

t₁ = Response time of the protective device

t₂ = Stopping time of the machine

C = Safety margin [mm]

H = Step height [mm]

With installation at floor level

H = 0; thus:

 $S = (1600 \text{ mm/s} \times \text{T}) + 1200 \text{ mm}$

With installation on a step

 $H \neq 0$; thus:

 $S = (1600 \text{ mm/s} \times \text{T}) + (1200 \text{ mm} - 0.4\text{H})$

Calculation examples

Calculation example 1

A safety mat detects when someone inadvertently accesses the danger zone of an automated movement. The mat is installed at floor level, i.e. H=0.

The follow-through time of the movement is 300 ms, the response time of the protective device is 18 ms.

 $S = (1600 \text{ mm/s} \times (300 \text{ ms} + 18 \text{ ms})) + 1200 \text{ mm}$

 $S = (1600 \text{ mm/s} \times 0.318 \text{ s}) + 1200 \text{ mm}$

S = 509 mm + 1200 mm

S = 1709 mm

Calculation example 2

The same conditions as Example 1, except that there is a step with a height of 150 mm leading up to the danger zone that has to be dealt with.

 $S = (1600 \text{ mm/s} \times (300 \text{ ms} + 18 \text{ ms})) + (1200 - (0.4 \times 150)) \text{ mm}$

 $S = (1600 \text{ mm/s} \times 0.318 \text{ s}) + (1200 - 60) \text{ mm}$

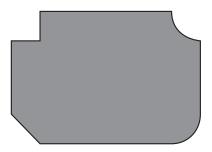
S = 509 mm + 1140 mm

S = 1649 mm



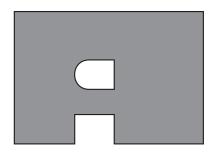
Customised designs

Special shapes



e.g. different corner shapes

Different shapes such as circles, circle segments, trapeziums etc. are possible.



e.g. cut-outs

Mats can be ready-manufactured with cut-outs, e.g. for machine feet, switch cabinets, and so on.

Special versions

Special versions are available for particular ambient conditions, e.g. aggressive substances (fuels, solvents etc.).

Maintenance and cleaning

The sensors are virtually maintenance-free.

The control unit also monitors the sensor at the same time.

Regular inspection

Depending on the operational demands, the sensors must be inspected at regular intervals (at least monthly)

- for proper functioning,
- for damage and
- for correct fixing.

Cleaning

If the sensors become dirty, they can be cleaned with a mild cleaning product.



Technical data

	Safety mat SM/W or SM11/W with control unit SG-EFS 104/2W	Safety mat SM/BK or SM11/BK with control unit SG-EFS 104/4L	Sensor* SM/W, SM/BK or SM11/W, SM11/BK (without control unit)
Testing basis	ISO 13849-1, ISO 1385	6-1	ISO 13856-1
Switching characteristics at v _{tes}	= 250 mm/s		
Switching operations at 0.1 A Actuation forces	> 4× 10 ⁶	> 4× 10 ⁶	> 4× 10 ⁶
Test piece (cylinder) Ø 11 mm Test piece (cylinder) Ø 80 mm Test piece (cylinder) Ø 200 mm Response time	< 300 N < 300 N < 600 N 23 ms	< 300 N < 300 N < 600 N DC: 38 ms	< 300 N < 300 N < 600 N 8 ms
Safety classifications			
ISO 13856: reset function ISO 13849-1:2015 MTTF _D (pressure-sensitive protective device) B _{10D} (sensor) n _{op} (assumption)	With/without Category 3 PL d 257 a 6× 10 ⁶ 52560/a	With/without Category 3 PL d 100 a 6× 10 ⁶ 52560/a	- Category 1 - 6× 10 ⁶
Mechanical operating condition	ns		
Sensor size Side length (min./max.) Cable length (min./max.) Static load (up to 8 h) SM with GM 1 SM with GM 5 SM11	Max. 1.5 m ² 200 mm / 3000 mm 10 cm / 100 m Max. 800 N/cm ² Max. 1200 N/cm ² Max. 800 N/cm ²		Max. 1.5 m ² 200 mm / 3000 mm 10 cm / 100 m Max. 800 N/cm ² Max. 1200 N/cm ² Max. 800 N/cm ²
Driving on with industrial trucks Tensile load, cable (max.) IEC 60529: degree of protection Sensor Control unit	Not suitable 100 N IP65 IP20		Not suitable 100 N IP65
Max. humidity (23 °C) Operating temperature Individual sensor SM Individual sensor SM11 Sensor combination Storage temperature	95% (non-condensing -5 to +55 °C -20 to +55 °C +5 to +55 °C -20 to +55 °C)	95% (non-condensing) -5 to +55 °C -20 to +55 °C +5 to +55 °C -20 to +55 °C
Weight SM with GM 1 SM with GM 5 SM11	17.3 kg/m² (without co 23.9 kg/m² (without co 12.0 kg/m² (without co	ontrol unit)	17.3 kg/m² 23.9 kg/m² 12.0 kg/m²

^{*} See footnote on page 26.



	Safety mat SM/W or SM11/W with control unit SG-EFS 104/2W	Safety mat SM/BK or SM11/BK with control unit SG-EFS 104/4L	Sensor* SM/W, SM/BK or SM11/W, SM11/BK (without control unit)
Electrical operating conditions			
Connection cable	Ø 5.0 mm PVC 2× 0.5 mm ²	Ø 5.0 mm PVC 2×0.5 mm ² or 4×0.34 mm ²	Ø 5.0 mm PVC 2×0.5 mm ² or 4×0.34 mm ²
Sensor	24 V DC / max. 100 mA	24 V DC / max. 100 mA	24 V DC / max. 100 mA
Number of sensors	Max. 10 in series $(9 \times /BK + 1 \times /W)$	Max. 10 in series (10×/BK)	Max. 10 in series $(9 \times /BK + 1 \times /W)$
Dimensional tolerances			
Length dimension	ISO 2768 – c		
Perpendicularity	ISO 2768 – c		

^{*} If you combine sensors with control units and thereby place pressure-sensitive protective devices on the market, you should observe the basic requirements according to ISO 13856.

Declarations of Conformity only apply to pressure-sensitive protective devices. In the case of sensors that are going to be used to make pressure-sensitive protective devices, Declarations of Incorporation are issued instead.

Conformity



The CE symbol indicates that this Mayser product complies with the relevant EC directives and that the stipulated conformity assessments have been carried out.

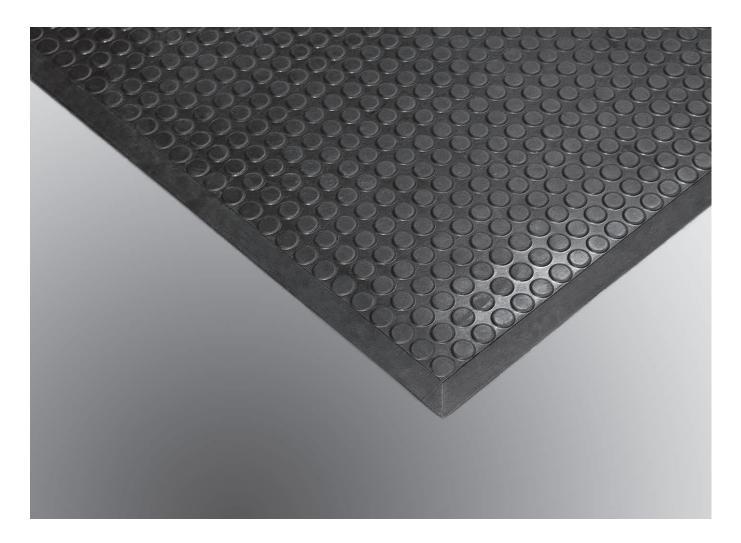
The design type of the pressure-sensitive protective device complies with the basic requirements of the following directives:

- 2006/42/EC (Safety of Machinery)
- 2011/65/EU (RoHS)
- 2014/30/EU (EMC)

The Declaration of Conformity is available in the Downloads section of our website: www.mayser.com.

As well as meeting technical requirements, this also means – in particular – observing any that relate to marking and information for use.





Safety mats SM8



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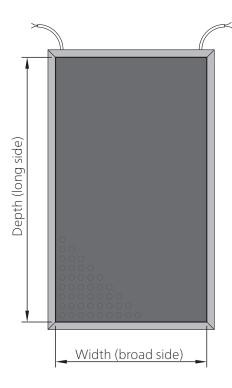


Available sizes

SM8 sensors are only available in fixed sizes:

Part number	SM8/BK	Width ×	Depth
5006626	SM8/BK	750 ×	1000 mm
5006627	SM8/BK	750 ×	1250 mm
5006628	SM8/BK	750 ×	1500 mm
5006623	SM8/BK	1000 ×	1000 mm
5006624	SM8/BK	1000 ×	1250 mm
5006625	SM8/BK	1000 ×	1500 mm

The dimensions refer solely to the contact surface. An extra 25 mm must be added on each side that has a moulded ramp.



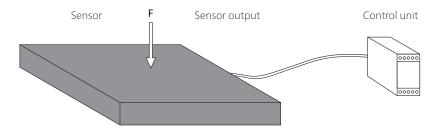
According to ISO 13855, the minimum depth to the danger zone must be taken into account (see chapter *Calculation of the necessary actuation area*). The non-sensitive edges must be taken into account (see chapter *Effective actuation area*).



Definitions

Pressure-sensitive protection device

A pressure-sensitive protection device consists of one or more pressure-sensitive sensors, a signal processing unit, and one or more output signal switching devices. The control unit is made up of the signal processing unit and output signal switching device(s). The pressure-sensitive protection device is triggered when the sensor is activated.

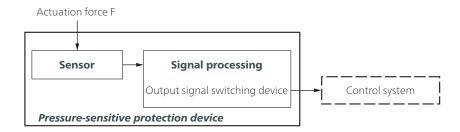


Sensor

The sensor is the part of the pressure-sensitive protection device that generates a signal when the actuation force F is applied. Mayser safety systems feature a sensor whose actuation area is deformed locally.

Signal processing

The signal processing unit is the part of the pressure-sensitive protection device that converts the output signal of the sensor and controls the status of the output signal switching device. The output signal switching device is the part of the signal processing unit which is connected to the forwarding control system and which transmits safety output signals such as STOP.



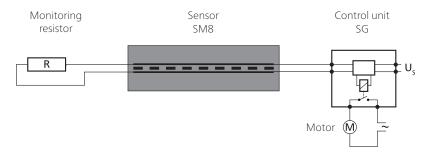
Tip: Terms are defined in ISO 13856-1 Section 3.



Criteria for selecting the sensor type

- Category according to ISO 13849-1
- Performance level of the pressure-sensitive protection device
 at least PL,
- Temperature range
- Degree of protection in accordance with IEC 60529:
 IP65 is the standard for safety mats.
 Higher degrees of protection must be checked individually.
- Environmental influences such as swarf, oil, coolant, outdoor use...
- Is it necessary to detect people who weigh < 35 kg?

Operation principle of 2-wire technology



The monitoring resistor must be compatible with the control unit. The standard type is 8k2.

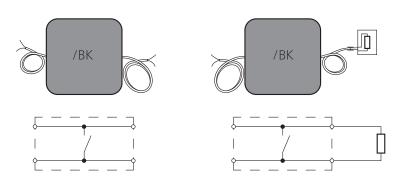
For your safety:

The sensor and connecting cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on controlled bridging of the contact surfaces with a monitoring resistor (closed-circuit principle).

Types

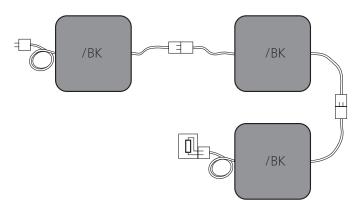
/BK

With cables on both sides for use as a through sensor or with an external monitoring resistor for use as an end sensor





Sensor combination

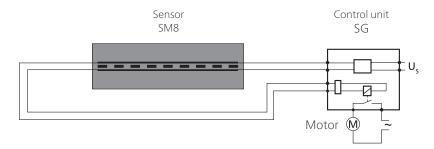


Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety mats can be combined to create an overall surface of any size and shape



Operation principle of 4-wire technology



The 4-wire technology can only be used together with control unit SG-EFS 104/4L.

For your safety:

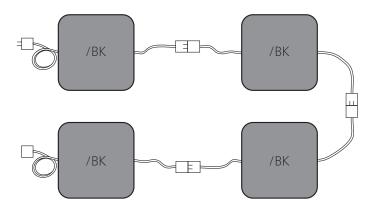
The sensor and connecting cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on signal transmission feedback – without a monitoring resistor.

Types

/BK With cables on both sides for use as a through sensor



Sensor combination



Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety mats can be combined to create an overall surface of any size and shape



Safety

Intended use

A safety mat detects a person standing on it or who steps onto it. It is a flat protection device that is capable of monitoring when somebody is present. Its purpose is to prevent possible hazardous situations for personnel within a danger zone.

Typical areas of application are moving parts on machines and systems. Safe operation of a safety mat depends entirely on

- the surface condition of the mounting surface,
- the correct selection of the size and resistance rating as well as
- correct installation.

Tip: This is illustrated clearly by Figures B.1 and B.2 in ISO 13856-1.

Due to the design, the actuation area is actually smaller than it looks because of the non-sensitive edges. Once these have been allowed for, what remains is the effective actuation area (see chapter *Effective actuation area*).

Limits

- No more than 10 /BK-type sensors can be connected to one control unit.
- Max. system size: 15 m²
 - = max. quantity \times max. sensor size

Exclusions

Sensors are not suitable for:

- Detecting walking aids
- Detecting people who weigh less than 20 kg
- Driving on with industrial trucks

Sensor combinations are not suitable for:

• Detecting people who weigh less than 35 kg

Selecting the appropriate product line

Sensors from our SM8 line of safety mat products are only available in a rectangular shape. The surface is resistant to external influences and normal chemical influences to a degree.

If your sensor requirements are higher, only our SM safety mat products will be able to meet them



Other safety aspects

The following safety aspects relate to pressure-sensitive protection devices consisting of a sensor and a control unit.

Performance Level (PL)

The PL has been determined using the procedure defined by ISO 13849-1. Fault exclusion according to ISO 13849-2 Table D.8: Non-closing of contacts in the case of pressure-sensitive protection devices according to ISO 13856. In this case, no characteristic values of the sensor whatsoever are included when determining the PL. Assuming a high MTTF $_{\rm D}$ value for the control unit, a performance level of up to PL d can be achieved by the safety mat system (pressure-sensitive protection device) as a whole.

Is the protection device suitable?

First, the integrator must decide what PL_r is required for the hazard. After that, they must select the protection device.

Finally, the integrator needs to check whether the category and PL of the selected protection device are appropriate.

Risk and safety assessment

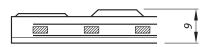
For the risk and safety assessment of your machine, we recommend ISO 12100 "Safety of machinery — General principles for design".

Without reset function

When a protection device without reset function is used (automatic reset), the reset function must be provided in some other way.



Design



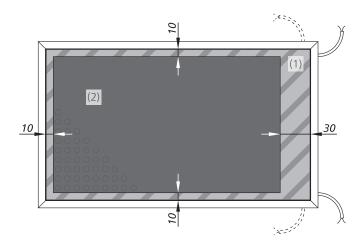
SM8

Moulded onto a plastic plate. The surface texture provides the necessary non-slip properties and ensures mechanical protection.

Effective actuation area

A non-sensitive edge (1) surrounds the effective actuation area (2):

- 30 mm = on the cable exit side
- 10 mm = on the remaining sides



The ramps running around the sides are discounted when considering the effective actuation area.

Sensor combinations

When sensor combinations are used, only the sides with 10 mm edges should be placed next to one another.

The integrated ramps must be removed from these sides before combining the sensors.

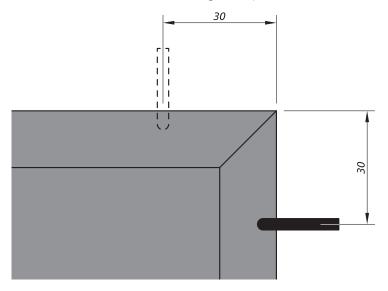


Connection

Cable exits

The cables are located at two corners.

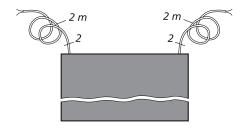
Two cable exits are available at each corner and you can either use the one on the broad side (width) or the one on the long side (depth). The required cable exit must be cut out on site at the designated point on the mat.



Cable connection

- Standard cable lengths
 L = 2.0 m
- Maximum total cable length to the control unit $L_{max} = 100 \text{ m}$

/BK-type sensor with 2 lines



- As a /BK-type through sensor
- Without resistor
- 2 two-wire cables

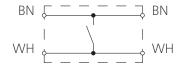


Wire colours

/BK-type sensor with 2 lines

Colour coding

BN Brown WH White

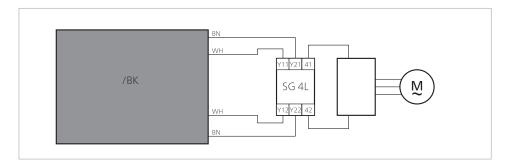




Connection example

Key:

SG 4L Evaluation with 4-wire technology





Sensor surface

The rubber surface structure is created at the factory during moulding. It provides the necessary non-slip properties and ensures mechanical protection. No further sensor cover is required.



Resistance

The resistance ratings listed below (at a room temperature of 23 $^{\circ}$ C) depend on the sensor having an undamaged surface.

Physical resistance

	PUR
DIN 53516: Abrasion DIN 4102: Fire behaviour Alternating climate stress conditions UV resistance	120 mg B2 + +

Explanation of symbols:

+ = resistant



Chemical resistance

The sensor is broadly resistant to normal chemical influences such as diluted acids and alkalis, as well as alcohol, over an exposure period of 24 hrs.

The values in the table are the results of tests carried out in our laboratory. You must always conduct your own practical tests to verify that our products are suitable for your specific area of application.

Explanation of symbols:

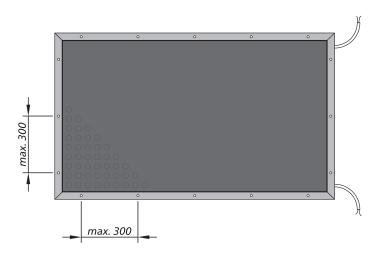
- + = resistant
- ± = resistant to a certain extent
- = not resistant

Material	PUR
Acetone	_
Formic acid 5%	+
Ammonia	+
ATF (automatic transmission fluid)	+
DOT 4 brake fluid	_
Cutting emulsion	+
Demineralised water	+
Diesel	±
Acetic acid 10%	+
Ethanol	_
Greases	_
Hydraulic oil	+
Caustic potash solution 10%	+
Saline solution 5%	+
Cooling lubricant	±
Metal working oil	+
Methanol	_
Mineral oil	+
Caustic soda 10%	±
Cellulose thinner	_
Hydrochloric acid 10%	±
Brine 10%	+
Suds 5%	+
Spirit (ethyl alcohol)	_
Universal thinner	_
Water	+
Petroleum ether / petrol	_
Citric acid 10%	+
Drawing compound	_



Mounting

To minimise the risk of tripping, the sensor has integrated ramps all the way round the edges. No separate ramp edges are required.



The sensor must be fixed to the floor using flat-head screws with a diameter of at least 5 mm (recommended: 6 x 50 mm flat-head screws). These parts are not supplied as standard. The screws must be spaced no further than 300 mm apart.

Calculation of the necessary actuation area

S = Minimum distance between the danger zone and the furthest edge of the sensor [mm]

K = Approximation parameter [mm/s]

T = Follow-through of the complete system [s]

t₁ = Response time of the protection device

t₂ = Stopping time of the machine

C = Safety margin [mm]
H = Step height [mm]

According to ISO 13855, the effective actuation area that is required with reference to the danger zone is calculated using the following formula:

$$S = (K \times T) + C$$
 where: $K = 1600 \text{ mm/s}$

 $T = t_1 + t_2$

C = 1200 mm - 0.4 H

With installation at floor level

H = 0; thus:

 $S = (1600 \text{ mm/s} \times \text{T}) + 1200 \text{ mm}$

With installation on a step

 $H \neq 0$: thus:

 $S = (1600 \text{ mm/s} \times \text{T}) + (1200 \text{ mm} - 0.4\text{H})$



Calculation examples

Calculation example 1

A safety mat detects when someone inadvertently accesses the danger zone of an automated movement. The mat is installed at floor level, i.e. H = 0.

The follow-through time of the movement is 140 ms, the response time of the protection device is 38 ms.

```
S = (1600 \text{ mm/s} \times (140 \text{ ms} + 38 \text{ ms})) + 1200 \text{ mm}
```

 $S = (1600 \text{ mm/s} \times 0.178 \text{ s}) + 1200 \text{ mm}$

S = 285 mm + 1200 mm

S = 1485 mm

Calculation example 2

The same conditions as Example 1, except that there is a step with a height of 150 mm leading up to the danger zone that has to be dealt with.

```
S = (1600 \text{ mm/s} \times (140 \text{ ms} + 38 \text{ ms})) + (1200 - (0.4 \times 150)) \text{ mm}
```

 $S = (1600 \text{ mm/s} \times 0.178 \text{ s}) + (1200 - 60) \text{ mm}$

S = 285 mm + 1140 mm

S = 1425 mm

Maintenance and cleaning

The sensors are virtually maintenance-free.

The control unit also monitors the sensor at the same time.

Regular inspection

Depending on the operational demands, the sensors must be inspected at regular intervals (at least monthly)

- for proper functioning,
- for damage and
- for correct mounting.

Cleaning

If the sensors become dirty, they can be cleaned with a mild cleaning product.



Technical data

	Safety mat SM8/BK with control unit SG-EFS 104/4L	Sensor* SM8/BK (without control unit)	
Testing basis	ISO 13856-1		
Switching characteristics at v _{test}	= 250 mm/s		
Switching operations at 0.1 A Actuation forces Test piece (cylinder) Ø 80 mm Test piece (cylinder) Ø 200 mm Response time		8 ms	
Safety classifications			
ISO 13856: reset function ISO 13849-1:2015 MTTF _D (pressure-sensitive protection device) B _{10D} (sensor) n _{op} (assumption)	With/without Category 3 PL d 65 a 6 × 10 ⁶ 52560/a	- Category 1 - 6 × 10 ⁶	
Mechanical operating condition	ns		
Sensor size Cable length (min./max.) Static load (up to 8 h) Driving on with industrial trucks Weight IEC 60529: degree of protection Sensor Max. humidity (23 °C) Operating temperature Individual sensor Sensor combination Storage temperature	Max. 1.5 m ² 10 cm / 100 m Max. 800 N/cm ² Not suitable 13.0 kg/m ² IP65 95% (non-condensing) -25 to +55 °C +5 to +55 °C -25 to +55 °C		
Electrical operating conditions	T		
Connection cable Sensor Number of /BK-type sensors	Ø 3.8 mm PVC 2 × 0.25 mm ² 24 V DC / max. 100 mA Max. 10 in series		
Dimensional tolerances			
Length dimension Perpendicularity	ISO 2768 – c ISO 2768 – c		

^{*} If you combine sensors with control units and thereby place pressure-sensitive protection devices on the market, you should observe the basic requirements according to ISO 13856.

Declarations of Conformity only apply to pressure-sensitive protection devices. In the case of sensors that are going to be used to make pressure-sensitive protection devices, Declarations of Incorporation are issued instead.

As well as meeting technical requirements, this also means – in particular – observing any that relate to marking and information for use.



Conformity



The CE symbol indicates that this Mayser product complies with the relevant EC directives and that the stipulated conformity assessments have been carried out.

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- 2011/65/EU (RoHS)
- 2014/30/EU (EMC)

The Declaration of Conformity is available in the Downloads section of our website:

www.mayser.com/de/download.





SP DIY sensor profiles



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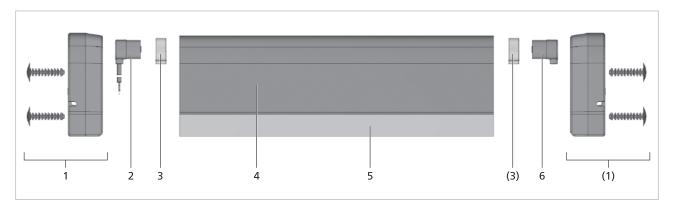


SK SP 67-2 TPE	39
SK SP 87-2 TPE	
Marking	
Conformity	
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UL certification	

Overview

Contact profile - Sensor profile

The semi-finished contact profile (No. 4) is cut to length and assembled with the other components. This results in a functioning product called a sensor profile.



Nos. 2, 3 and 6 are identical for all sensor profiles.

No. 2Closing plug with 2.5 m cable7502873No. 3Ear clamp1005684No. 6Closing plug with resistor7502875

Alternatives for No. 2:

Closing plug with 5.0 m cable 7503774 Closing plug with 10 m cable 7503775

Sensor profile	No. 1 Set of end caps	No. 4 Contact profile			o. 5 um profile
SP 17-3 without end caps	1005786	SP 17-3	7503461	C 15	1000016
SP 37-1 without end caps	1000606	SP 37-1	7502853	C 25	1000004
SP 37-1 with end caps	7503008	SP 37-1	7502853	C 25	1000004
SP 37-2 with end caps	7503988	SP 37-2	7503318	C 26	1004330
SP 37L-2 with end caps	7503988	SP 37L-2	7504192	C 26	1004330
SP 37-3 with end caps	7503505 (7503654)	SP 37-3	7503343	C 25	1000004
SP 57-2 with end caps	7503603	SP 57-2	7503055	C 30	1005844
SP 57L-2 with end caps	7503603	SP 57L-2	7503412	C 30	1005844

Materials list

Part No.	Designation	PU
7503461	Contact profile SP 17-3 TPE	80 m
7502853	Contact profile SP 37-1 TPE	30 m
7503318	Contact profile SP 37-2 TPE	30 m
7504192	Contact profile SP 37L-2 TPE	30 m
7503343	Contact profile SP 37-3 TPE "black"	30 m
7503534	Contact profile SP 37-3 TPE "red"	30 m
7503055	Contact profile SP 57-2 TPE	30 m
7503412	Contact profile SP 57L-2 TPE	30 m
7503521	Contact profile SP 57-3 TPE	25 m
7503633	Contact profile SP 57-4 TPE	25 m
7503711	Contact profile SP 57L-4 TPE	25 m
7503285	Contact profile SP 67-2 TPE	30 m
7503722	Contact profile SP 87-2 TPE	25 m
7502875	Closing plug with 8k2 resistor	10 pcs.
7502873	Closing plug with 2.5 m PUR cable, angled 90°	10 pcs.
7503774	Closing plug with 5.0 m PUR cable, angled 90°	10 pcs.
7503775	Closing plug with 10 m PUR cable, angled 90°	10 pcs.
7503708	Closing plug without resistor	10 pcs.
1005684	Ear clamp for closing plug	20 pcs.
1005786	Countersunk tapping screw 3.5 x 25 for SP 17-3	20 pcs.
7503008	Set of end caps for SP 37-1: 2 end caps, 2 fixing stoppers and 2 screws 3.9 × 25	10 pcs.
7503988	Set of end caps for SP 37(L)-2: 2 end caps and 4 pine tree clips	10 pcs.

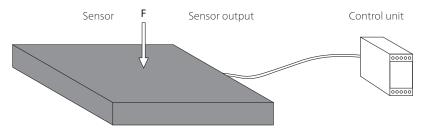
Part No.	Designation	PU
7503505	Set of end caps for SP 37-3 "black":	
	2 end caps and 2 pine tree clips	10 pcs.
7503654	Set of end caps for SP 37-3 "red":	10 pcs
7503603	2 end caps and 2 pine tree clips Set of end caps for SP 57(L)-2 with clips:	10 pcs.
7503603	2 end caps and 4 pine tree clips	10 pcs.
7503618	Set of end caps for SP 57-3 and SP 57(L)-4: 2 end caps and 6 pine tree clips	10 pcs.
7503655	Set of end caps for SP 67-2: 2 end caps and 4 pine tree clips	10 pcs.
7504118	Set of end caps for SP 87-2: 2 end caps and 8 pine tree clips	10 pcs.
1000016	Aluminium profile C 15	6 m
1000854	Aluminium profile C 25M, upper section	6 m
1000855	Aluminium profile C 25M, lower section	6 m
1000829	Aluminium profile C 25L	6 m
1000012	Aluminium profile C 25S	6 m
1000004	Aluminium profile C 25	6 m
1004626	Aluminium profile C 26M, upper section	6 m
1004627	Aluminium profile C 26M, lower section	6 m
1004330	Aluminium profile C 26, perforated	6 m
1005844	Aluminium profile C 30	6 m
1001398	Aluminium profile C 35M, upper section	6 m
1001399	Aluminium profile C 35M, lower section	6 m
1000013	Aluminium profile C 35S	6 m
1000006	Aluminium profile C 35	6 m
1004629	Aluminium profile C 36M, upper section	6 m
1004630	Aluminium profile C 36M, lower section	6 m
1003849	Aluminium profile C 36L, perforated	6 m
1003850	Aluminium profile C 36S, perforated	6 m
1003848	Aluminium profile C 36, perforated	6 m
1001223	End stopper for C 25M, for SP without end caps	1 pc.
1000606	End stopper for C 25 or C 25S, for SP without end caps	1 pc.
1005906	Section cutter, cutting length 87 mm	1 pc.
7502868	Assembly aid SH3	1 pc.
1005741	Notching pliers Knipex 7742115	1 pc.
1005729	Vice-grip pliers, Knipex System Oetiker 1099	1 pc.



Definitions

Pressure-sensitive protection device

A pressure-sensitive protection device consists of one or more pressure-sensitive sensors, a signal processing unit, and one or more output signal switching devices. The control unit is made up of the signal processing unit and output signal switching device(s). The pressure-sensitive protection device is triggered when the sensor is activated.

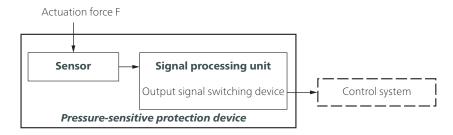


Sensor

The sensor is the part of the pressure-sensitive protection device that generates a signal when the actuation force F is applied. Mayser safety systems feature a sensor whose actuating surface is deformed locally.

Signal processing unit

The signal processing unit is the part of the pressure-sensitive protection device that converts the output signal of the sensor and controls the status of the output signal switching device. The output signal switching device is the part of the signal processing unit which is connected to the forwarding control system and which transmits safety output signals such as STOP.

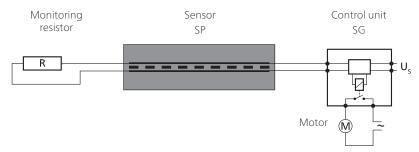


Tip: Terms are defined in ISO 13856-2 Section 3.

Criteria for selecting the sensor type

- Category according to ISO 13849-1
- Performance level of the pressure-sensitive protection device
 at least PL₂
- Temperature range
- Degree of protection in accordance with IEC 60529:
 IP67 is the standard for safety edges.
 Higher degrees of protection must be checked individually.
- Environmental influences such as swarf, oil, coolant, outdoor use...
- Finger detection necessary?

Operation principle of 2-wire technology



The monitoring resistor must be compatible with the control unit. The standard type is 8k2.

For your safety:

The sensor and connecting cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on controlled bridging of the contact surfaces with a monitoring resistor (closed-circuit principle).

Types

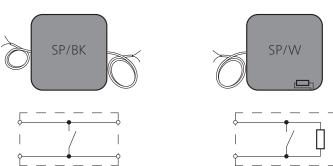
SP/BK With cables on both sides for use as a through sensor or

with an external monitoring resistor for use as an end

sensor

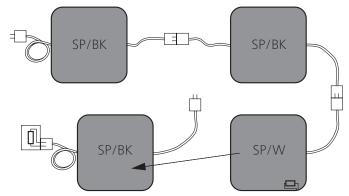
SP/W With an integrated monitoring resistor for use as an end

sensor





Sensor combination

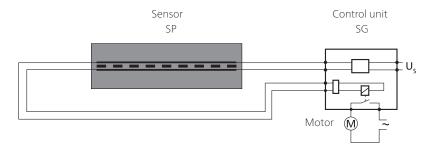


Version with external resistor, therefore no variety of models

Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety edge design with custom lengths and angles

Operation principle of 4-wire technology



The 4-wire technology can only be used together with control unit SG-EFS 104/4L.

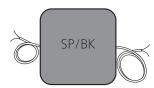
For your safety:

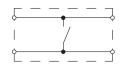
The sensor and connecting cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on signal transmission feedback – without a monitoring resistor.

Types

SP/BK

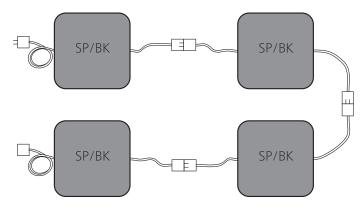
With cables on both sides for use as a through sensor







Sensor combination



Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety edge design with custom lengths and angles

Safety

Intended use

A safety edge detects a person or part of the body when pressure is applied to the effective actuation area. It is a linear tripping device. Its task is to prevent possible hazardous situations that could affect someone within a danger zone, such as shearing and pinching edges.

Typical areas of application are door and gate systems, moving parts on machines, platforms and lifting devices.

Safe operation of a safety edge depends entirely on

- the surface condition of the mounting surface,
- the correct selection of the size and resistance rating as well as
- correct installation.

For additional application guidelines, please refer to ISO 13856-2 Annex E.

Due to the design, the actuation area is actually smaller than it looks because of the non-sensitive edges. Once these have been allowed for, what remains is the effective actuation area (see chapter *Effective actuation area*).

Limits

- No more than 5 /BK-type sensors can be connected to one control unit.
- No more than 4 /BK-type sensors and 1 /W-type sensor can be connected to one control unit.

Exclusions

The sensors are not suitable for:

• performing a sealing function. Constant actuation of sensors can result in permanent damage.

Exception: The L version with an attached lip seal.

The lip seal can be in full contact with the closing edge, which allows it to repel wind and water.

Selecting the appropriate product line

If you opt for our line of SP DIY sensor profiles that have to be assembled with tools, the maximum class of protection that can be achieved is IP68 and IPX8 (20 weeks). If a class of protection of IP67 or IPX8 (13 days) is sufficient for your application, we recommend using our line of SP DIY sensor profiles for **toolless** self-assembly instead.

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Other safety aspects

The following safety aspects relate to pressure-sensitive protection devices consisting of a sensor and a control unit.

Performance Level (PL)

The PL has been determined using the procedure defined by ISO 13849-1.

Fault exclusion according to ISO 13849-2 Table D.8: Non-closing of contacts by pressure-sensitive equipment according to ISO 13856. In this case, the diagnostic coverage (DC) is not calculated or taken into account when determining the PL. Assuming a high MTTF_D value for the control unit, a performance level of up to PL d can be achieved by the safety edge system (pressure-sensitive protection device) as a whole.

Is the protection device suitable?

First, the integrator must decide what PL_r is required for the hazard. After that, they must select the protection device.

Finally, the integrator needs to check whether the category and PL of the selected protection device are appropriate.

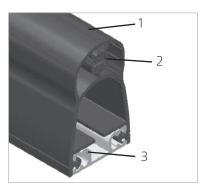
Risk and safety assessment

For the risk and safety assessment of your machine, we recommend ISO 12100 "Safety of machinery — General principles for design".

Without reset function

When a protection device without reset function is used (automatic reset), the reset function must be provided in some other way.

Design



one sensor (1 to 3)
(1) SP contact profile with
(2) integrated normally open
switching element,
(3) aluminium profile and an
evaluating control unit SG.

The SP sensor profile consists of

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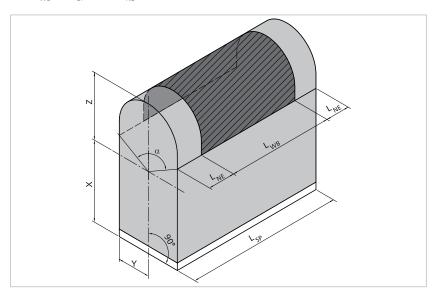


Effective actuation area

The parameters X, Y, Z, L_{WB} and the angle $\,\alpha\,$ describe the effective actuation area.

For the effective actuation area, the following applies:

$$L_{WB} = L_{SP} - 2 \times L_{NE}$$



Parameters:

 L_{WB} = effective actuation length

 L_{SP} = total length of sensor profile

 L_{NE} = non-sensitive length at end of sensor profile

 α = effective actuation angle

	SP 17-3 ¹⁾	SP 37-1	SP 37(L)-2	SP 37-3	SP 57(L)-2	SP 57-3	SP 57(L)-4	SP 67-2	SP 87-2
	8								
Incl.	C 15	C 25	C 26	C 25	C 30	C 35	C 35	C 30	C 36
α	90°	100°	100°	100°	90°	90°	90°	90°	90°
L _{NE}	60 mm	20 mm	20 mm	20 mm	10 mm ²⁾	10 mm ²⁾	10 mm ²⁾	20 mm ²⁾	10 mm ²⁾
Υ	6.7 mm	12.5 mm	13 mm	12.5 mm	17 mm	17.5 mm	17.5 mm	17 mm	18.1 mm
X	15.3 mm	28.5 mm	30 mm	29 mm	44 mm	52 mm	52 mm	57.3 mm	72 mm
Z	5 mm	9 mm	9 mm ³⁾	9 mm	12 mm ³⁾	12 mm	12 mm ³⁾	10 mm	15 mm
X + Z	20.3 mm	37.5 mm	39 mm ³⁾	38 mm	56 mm ³⁾	64 mm	64 mm ³⁾	67.3 mm	87 mm

¹⁾ without end cap

Installation position

The installation position can be selected as required, i.e. all installation positions from A to D as per ISO 13856-2 are possible.

²⁾ with finger protection

³⁾ without lip

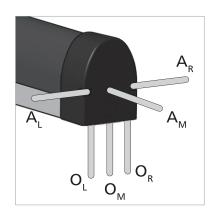
Connection

Cable exits

Depending on the end cap, the following cable exits are available.

 $\begin{array}{lll} \textbf{A}_{L} &=& \text{axial left} \\ \textbf{A}_{M} &=& \text{axial middle} \\ \textbf{A}_{R} &=& \text{axial right} \\ \textbf{O}_{L} &=& \text{orthogonal left} \\ \textbf{O}_{M} &=& \text{orthogonal middle} \end{array}$

 O_R = orthogonal right



			Cable	e exit			
Lateral exit				A_R			
	Axial exit		A _M				
	90° exit				O _L	O _M	O _R
Combi	nation						
Contact profile	Set of end caps						
SP 17-3	_					•	
SP 37-1	7503008	•		•	•		•
SP 37(L)-2	7503988	•	•	•		•	
SP 37-3 black	7503505	•		•	•		•
SP 37-3 red	7503654	•		•	•		•
	7503062	•	•	•		•	
SP 57(L)-2	7503603	•	•	•		•	
SP 57-3	7503618	•	•	•		•	
SP 57(L)-4	7503796	•	•	•	•		•
SP 67-2	7503655	•	•	•		•	
SP 87-2	7504118	•	•	•		•	

• = possible



Cable connection

- Standard cable lengthsL = 2.5 m / 5.0 m / 10 m
- Maximum total cable length to the control unit $L_{max} = 100 \text{ m}$

/W-type sensor with 1 line	/BK-type sensor with 2 lines
 As an individual /W-type sensor or a /W-type end sensor Integrated resistor 1 two-wire cable 	 As a /BK-type through sensor Without resistor 2 two-wire cables

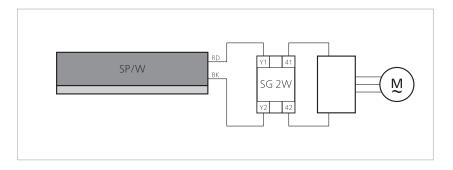
Wire colours

/W-type sensor with 1 line	/BK-type sensor with 2 lines	
RD I BK	RD ← ← → RD BK ← → BK	

Connection examples

Key:

SG 2W evaluation with 2-wire technology SG 4L evaluation with 4-wire technology



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Subject to technical modifications.

Colour coding

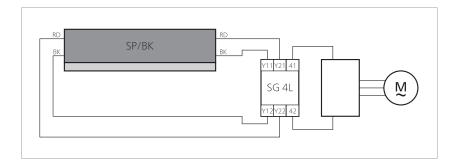
Black

Red

ВК

RD





Sensor surface

Resistance

The resistance ratings listed below (at a room temperature of 23 °C) depend on the sensor having an undamaged surface.

Physical resistance

	TPE
UV resistance	Yes

Chemical resistance

The sensor is broadly resistant to normal chemical influences such as diluted acids and alkalis, as well as alcohol, over an exposure period of 24 hrs.

The values in the table are the results of tests carried out in our laboratory. You must always conduct your own practical tests to verify that our products are suitable for your specific area of application.



Explanation of symbols:

+ = resistant

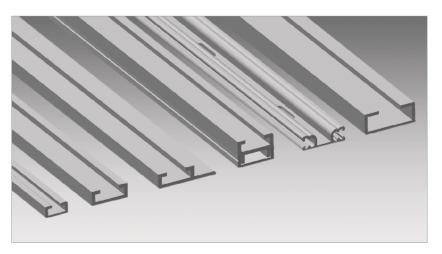
 \pm = resistant to a certain extent

- = not resistant

Material	TPE
Acetone	-
Formic acid	-
Armor All	+
Car shampoo	+
Petrol	_
Brake fluid	+
Buraton	+
Butanol	_
Sodium hypochlorite	-
Disinfectant 1%	+
Diesel	-
Acetic acid 10%	-
Ethanol	+
Ethyl acetate	_
Ethylene glycol	+
Greases	±
Anti-frost agent	+
Skin cream	+
Incidin	+
Incidin Plus	+
Cooling lubricant	_
Plastic cleaner	+
Lyso FD 10	+
Metal working oil	_
Microbac	+
Microbac forte	+
Minutil	+
Saline solution 5%	+
Spirit (ethyl alcohol)	+
Terralin	+
Centring oil	-

Mounting

The sensors are mounted directly onto the main and secondary closing edges that present a danger. They are fixed using special aluminium profiles. The profiles are fastened with screws or rivets.



Material properties

- AlMgSi0.5 F22
- Wall thickness at least
 2.0 mm
 C 15: at least 1.7 mm

C 30: at least 1.5 mm

- Extruded
- Hot hardened
- Tolerances as per EN 755-9

Aluminium profiles: Overview of combinations

Sensor pr	ofile foot	C 15	C 25 C 25M C 25S C 25L	C 26 C 26M	C 30	C 35 C 35M C 35S	C 36 C 36M C 36S C 36L
Snap-in foot (middle)	1	-	SP 37-1	_	_	_	_
Clip bars (outside)	2	_	_	SP 37(L)-2	SP 57(L)-2 SP 67-2	_	SP 87-2
T-foot (middle)	3	SP 17-3	SP 37-3	_	_	SP 57-3	_
T-foot narrow (middle)	4	-	_	_	_	SP 57(L)-4	_



Aluminium profiles: Mounting types

Standard profile

First the aluminium profile must be mounted onto the closing edge and then the sensor profile clipped into the aluminium profile.

C 15	C 25	C 26	C 30	C 35	C 36
		<u> </u>			

Two-part profile, type M

For convenient assembly and disassembly. The sensor profile is clipped into the upper section and the upper section inserted into the installed lower section and fastened.

-	C 25M	C 26M	C 35M	C 36M

Flange profile, type S

Final assembly is also possible when the sensor profile is already clipped into the aluminium profile.

-	C 25S	-	C 35S	C 36S

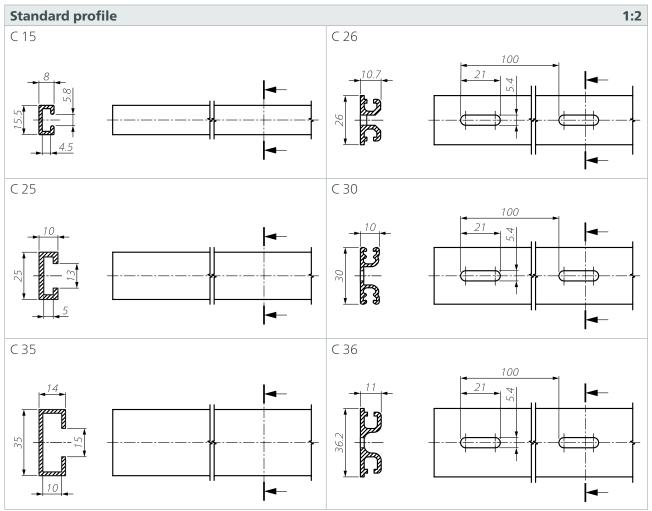
Angle profile, type L

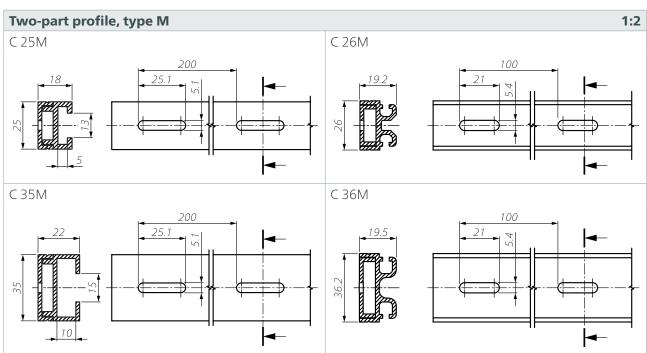
If the closing edge should or must not have assembly holes, this "round-the-corner" solution is suitable. Final assembly is also possible when the sensor profile is already clipped into the aluminium profile.

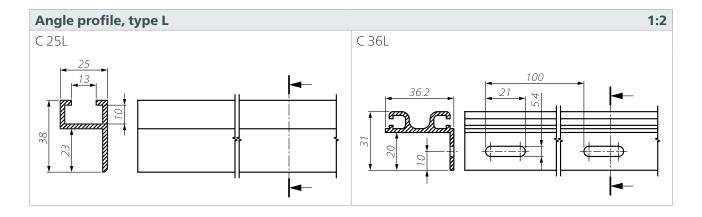


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Aluminium profiles: Dimensions









s₁ = Stopping distance of the dangerous movement

v = Velocity of the dangerous movement [mm/s]

[mm]

- T = Follow-through time of the complete system [s]
- t_1 = Safety edge response time
- t₂ = Stopping time of the machine
- s = Minimum overtravel distance of the safety edge to ensure that the stipulated limit forces are not exceeded [mm]
- C = Safety factor; if components susceptible to failures (braking system) exist in the system, a higher factor must be selected.

SP: Making the right selection

Calculation for selection of the safety edge height

The stopping distance of the dangerous movement is calculated using the following formula:

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$

In accordance with ISO 13856-2, the minimum overtravel distance of the safety edge is calculated using the following formula:

$$s = s_1 \times C$$
 where: $C = 1.2$

A suitable safety edge profile can now be selected based on the result. For details of the overtravel distances for safety edge profiles, see chapter *Technical data*.

Calculation examples

Calculation example 1

The dangerous movement on your machine has a velocity of v=10 mm/s and can be brought to a standstill within $t_2=200$ ms. The relatively low velocity suggests that a short overtravel distance is to be expected. Therefore, the sensor profile SP 37-1 TPE could be sufficient. The response time of the safety edge (SP 37-1 TPE + control unit*) is $t_1=600$ ms.

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$
 $s_1 = 1/2 \times 10 \text{ mm/s} \times (0.6 \text{ s} + 0.2 \text{ s})$
 $s_1 = 1/2 \times 10 \text{ mm/s} \times 0.8 \text{ s} = 4.0 \text{ mm}$

$$s = s_1 \times C$$
 where: $C = 1.2$
 $s = 4.0 \text{ mm} \times 1.2 = 4.8 \text{ mm}$

The safety edge must have a minimum overtravel distance of s = 4.8 mm. The selected SP 37-1 TPE has an overtravel distance of at least 9.2 mm. This is more than the required 4.8 mm.

Result: The SP 37-1 TPE is **suitable** for this case.

Subject to technical modifications.

^{*} Assumption: Typical reaction time of a control unit = 20 ms



Calculation example 2

The same conditions apply as in calculation example 1 with the exception of the velocity of the dangerous movement. This is now v = 200 mm/s. The response time of the safety edge (SP 37-1 TPE + control unit*) is $t_1 = 55 \text{ ms}$.

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$
 $s_1 = 1/2 \times 200 \text{ mm/s} \times (0.055 \text{ s} + 0.2 \text{ s})$
 $s_1 = 1/2 \times 200 \text{ mm/s} \times 0.255 \text{ s} = 25.5 \text{ mm}$

$$s = s_1 \times C$$
 where: $C = 1.2$
 $s = 25.5 \text{ mm} \times 1.2 = 30.6 \text{ mm}$

The safety edge must have a minimum overtravel distance of s = 30.6 mm. The selected SP 37-1 TPE has an overtravel distance of at least 3.8 mm. This is less than the required 30.6 mm.

Result: The SP 37-1 TPE is **not suitable** for this case.

Calculation example 3

The same conditions apply as in calculation example 2. Instead of SP 37-1 EPDM, the SP 67-1 TPE is selected. The response time of the safety edge (SP 67-2 TPE + control unit*) is $t_1 = 72$ ms.

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$
 $s_1 = 1/2 \times 200 \text{ mm/s} \times (0.072 \text{ s} + 0.2 \text{ s})$
 $s_1 = 1/2 \times 200 \text{ mm/s} \times 0.272 \text{ s} = 27.2 \text{ mm}$

$$s = s_1 \times C$$
 where: $C = 1.2$
 $s = 27.2 \text{ mm} \times 1.2 = 32.6 \text{ mm}$

The safety edge must have a minimum overtravel distance of s = 32.6 mm. The selected SP 67-2 TPE has an overtravel distance of at least 36.5 mm. This is more than the required 32.6 mm.

Result: The SP 67-2 TPE is **suitable** for this case.

131221 V3.12-1

^{*} Assumption: Typical reaction time of a control unit = 20 ms



Maintenance and cleaning

The sensors are virtually maintenance-free.

The control unit also monitors the sensor at the same time.

Regular inspection

Depending on the operational demands, the sensors must be inspected at regular intervals (at least monthly)

- for proper functioning,
- for damage and
- for correct mounting

Cleaning

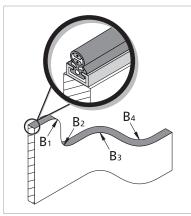
If the sensors become dirty, they can be cleaned with a mild cleaning product.

31221 v3 12



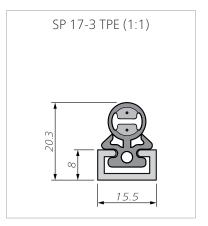
SK SP 17-3 TPE

Sensor profile (without control unit)	SK SP/W 17-3 TPE or SK SP/BK 17-3 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} = 10 mm/s	
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	1.5 mm
Test piece (cylinder) Ø 80 mm	±45°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B _{10D}	2× 10 ⁶
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 80 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum $B_1 / B_2 / B_3 / B_4$ On a rating up to gift.	200 / 200 / 50 / 50 mm
Operating velocity (min. / max.)	10 mm/s / 10 mm/s
Max. load capacity (impulse)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: Degree of protection	IP68
SP in water: 9 cm bottom edge	IPX8: 20 weeks
Operating temperature	−25 to +55 °C
short-term (15 min)	−40 to +80 °C
Storage temperature	−40 to +80 °C
Weight	SP 17-3
without aluminium profile	0.12 kg/m
with aluminium profile C 15	0.28 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm ²





Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

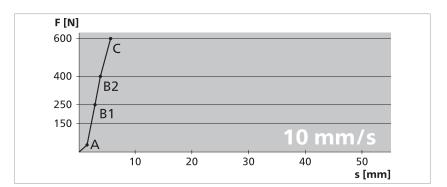
Test conditions according to ISO 13856-2

- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø
 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.

Force-distance ratios

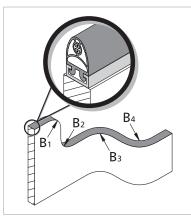
Test velocity	10 mm/s
Actuation force	38 N
Response time	140 ms
Actuation distance (A)	1.4 mm
Overtravel distance	
up to 250 N (B1)	1.4 mm
up to 400 N (B2)	2.3 mm
up to 600 N (C)	4.1 mm
Total deformation	5.5 mm





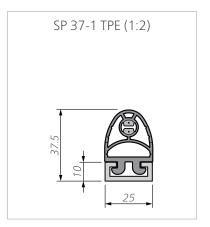
SK SP 37-1 TPE

Sensor profile (without control unit)	SK SP/W 37-1 TPE or SK SP/BK 37-1 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} =	100 mm/s
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	6 mm
Test piece (cylinder) Ø 80 mm	±50°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B _{10D}	2× 10 ⁶
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 30 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	
B ₁ / B ₂ / B ₃ / B ₄	500 / 500 / 200 / 200 mm
Operating velocity	10 mana /a / 200 mana /a
(min. / max.)	10 mm/s / 200 mm/s 600 N
Max. load capacity (impulse) Tensile load, cable (max.)	20 N
IEC 60529: Degree of protection	IP68
SP in water: 9 cm bottom edge	IPX8: 20 weeks
Operating temperature	-25 to +55 °C
short-term (15 min)	-40 to +80 °C
Storage temperature	−40 to +80 °C
Weight	SP 37-1
without aluminium profile	0.33 kg/m
with aluminium profile C 25	0.64 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm ²





Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

Test conditions according to ISO 13856-2

- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø
 80 mm

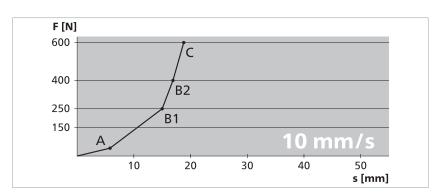
All datal soute connered is raio cumented in EC type examination certificates.

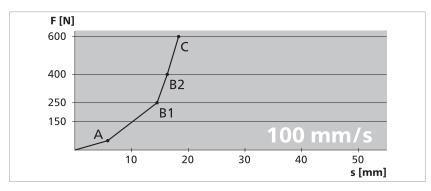
Force-distance ratios

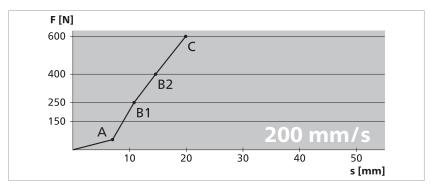
Test velocity	10 mm/s
Actuation force	42 N
Response time	580 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	9.2 mm
up to 400 N (B2)	11.1 mm
up to 600 N (C)	13.0 mm
Total deformation	18.8 mm

Test velocity 1	00 mm/s
Actuation force	50 N
Response time	58 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	8.7 mm
up to 400 N (B2)	10.5 mm
up to 600 N (C)	12.5 mm
Total deformation	18.3 mm

Test velocity 2	00 mm/s
Actuation force	54 N
Response time	35 ms
Actuation distance (A)	7.0 mm
Overtravel distance	
up to 250 N (B1)	3.8 mm
up to 400 N (B2)	7.6 mm
up to 600 N (C)	12.9 mm
Total deformation	19.9 mm



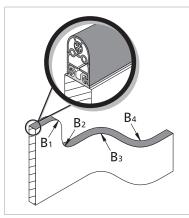






SK SP 37(L)-2 TPE

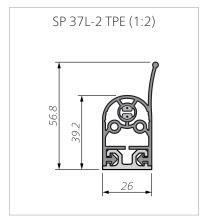
Sensor profile (without control unit)	SK SP/W 37(L)-2 TPE or SK SP/BK 37(L)-2 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} = 1	00 mm/s
Switching operations	10,000
Actuation force	
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm	< 150 N
Actuation distance	
Test piece (cylinder) Ø 80 mm	6 mm
Actuation angle	±50°
Test piece (cylinder) Ø 80 mm Finger detection	Yes
	163
Safety classifications	2 106
ISO 13849-1: B _{10D}	2× 10 ⁶
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 30 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	
B ₁ / B ₂ / B ₃ / B ₄	500 / 500 / 200 / 200 mm
Operating velocity	
(min. / max.)	10 mm/s / 200 mm/s
Max. load capacity (impulse)	600 N
Tensile load, cable (max.)	20 N IP68
IEC 60529: Degree of protection SP in water: 9 cm bottom edge	IPX8: 20 weeks
Operating temperature	-25 to +55 °C
short-term (15 min)	-40 to +80 °C
Storage temperature	-40 to +80 °C
Weight	SP 37-2 SP 37L-2
without aluminium profile	0.36 kg/m 0.41 kg/m
with aluminium profile C 26	0.69 kg/m 0.74 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm ²



SP 37-2 TPE (1:2)

Dimensional tolerances according to ISO 3302 E2/L2

Dimensions and distances



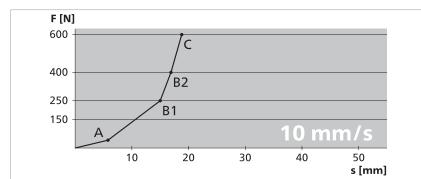
Dimensional tolerances according to ISO 3302 E2/L2

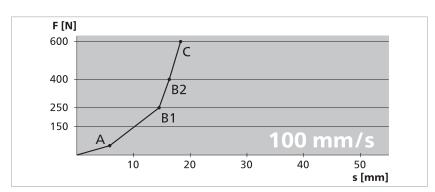
Test conditions according to ISO 13856-2

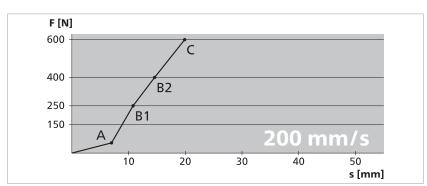
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit
- Lip not taken into account

All data stated here is documented in EC type examination certificates.

Force-distance ratios







10 mm/s

Actuation force 42 N 580 ms Response time Actuation distance (A) 5.8 mm Overtravel distance

Test velocity

up to 250 N (B1) 9.2 mm up to 400 N (B2) 11.1 mm up to 600 N (C) 13.0 mm Total deformation 18.8 mm

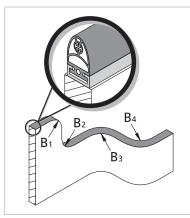
Test velocity 1	00 mm/s
Actuation force	50 N
Response time	58 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	8.7 mm
up to 400 N (B2)	10.5 mm
up to 600 N (C)	12.5 mm
Total deformation	18.3 mm

Test velocity 20	00 mm/s
Actuation force	54 N
Response time	35 ms
Actuation distance (A)	7.0 mm
Overtravel distance	
up to 250 N (B1)	3.8 mm
up to 400 N (B2)	7.6 mm
up to 600 N (C)	12.9 mm
Total deformation	19.9 mm



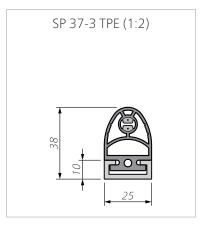
SK SP 37-3 TPE

Sensor profile (without control unit)	SK SP/W 37-3 TPE or SK SP/BK 37-3 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} = 100 mm/s	
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	6 mm
Test piece (cylinder) Ø 80 mm	±50°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B _{10D}	2× 10 ⁶
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 30 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	F00 / F00 / 200 / 200
B ₁ / B ₂ / B ₃ / B ₄ Operating velocity	500 / 500 / 200 / 200 mm
(min. / max.)	10 mm/s / 200 mm/s
Max. load capacity (impulse)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: Degree of protection	IP68
SP in water: 9 cm bottom edge	IPX8: 20 weeks
Operating temperature	−25 to +55 °C
short-term (15 min)	−40 to +80 °C
Storage temperature	−40 to +80 °C
Weight	SP 37-3
without aluminium profile	0.34 kg/m
with aluminium profile C 25	0.66 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm ²





Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

Test conditions according to ISO 13856-2

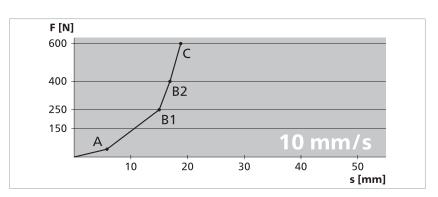
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

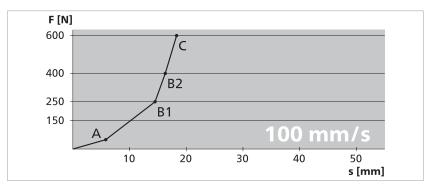
Force-distance ratios

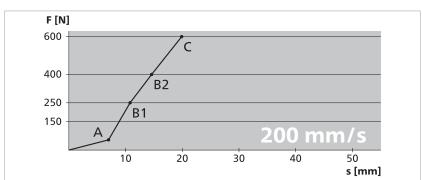
Test velocity	10 mm/s
Actuation force	42 N
Response time	580 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	9.2 mm
up to 400 N (B2)	11.1 mm
up to 600 N (C)	13.0 mm
Total deformation	18.8 mm

Test velocity 1	00 mm/s
Actuation force	50 N
Response time	58 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	8.7 mm
up to 400 N (B2)	10.5 mm
up to 600 N (C)	12.5 mm
Total deformation	18.3 mm

Test velocity 2	00 mm/s
Actuation force	54 N
Response time	35 ms
Actuation distance (A)	7.0 mm
Overtravel distance	
up to 250 N (B1)	3.8 mm
up to 400 N (B2)	7.6 mm
up to 600 N (C)	12.9 mm
Total deformation	19.9 mm



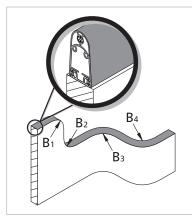






SK SP 57(L)-2 TPE

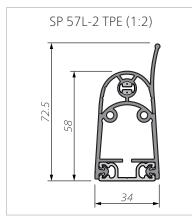
Sensor profile (without control unit)	SK SP/W 57(L)-2 TPE or SK SP/BK 57(L)-2 TPE	
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2	
Switching characteristics at v _{test} =	100 mm/s	
Switching operations Actuation force	10,000	
Test piece (rod) Ø 20 mm	< 50 N	
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N	
Test piece (cylinder) Ø 80 mm Actuation angle	8 mm	
Test piece (cylinder) Ø 80 mm	±45°	
Finger detection	Yes	
Safety classifications		
ISO 13849-1: B _{10D}	2× 10 ⁶	
Mechanical operating conditions		
Sensor length (min./max.)	10 cm / 30 m	
Cable length (min./max.)	10 cm / 100 m	
Bend radii, minimum		
B ₁ / B ₂ / B ₃ / B ₄	1000 / 1000 / 200 / 200 mm	
Operating velocity		
(min. / max.)	10 mm/s / 200 mm/s	
Max. load capacity (impulse)	600 N	
Tensile load, cable (max.)	20 N	
IEC 60529: Degree of protection	IP68	
SP in water: 9 cm bottom edge	IPX8: 20 weeks	
Operating temperature	-25 to +55 °C	
short-term (15 min)	-40 to +80 °C	
Storage temperature	-40 to +80 °C	
Weight	SP 57-2 SP 57L-2	
without aluminium profile	0.44 kg/m 0.47 kg/m	
with aluminium profile C 30	0.74 kg/m 0.77 kg/m	
Electrical operating conditions		
Terminal resistance	8k2 ±1%	
Nominal output (max.)	250 mW	
Contact transition resistance	< 400 ohms (per sensor)	
Number of BK-type sensors	Max. 5 in series	
Switching voltage (max.)	DC 24 V	
Switching current (min./max.)	1 mA / 10 mA	
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm ²	



SP 57-2 TPE (1:2)

Dimensional tolerances according to ISO 3302 E2/L2

Dimensions and distances



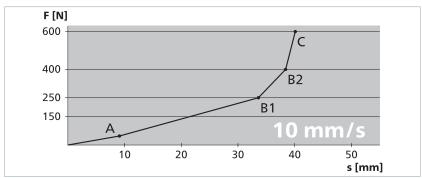
Dimensional tolerances according to ISO 3302 E2/L2

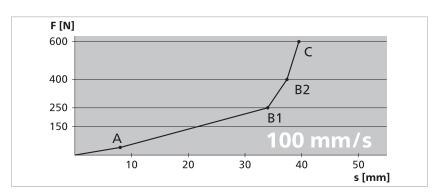
Test conditions according to ISO 13856-2

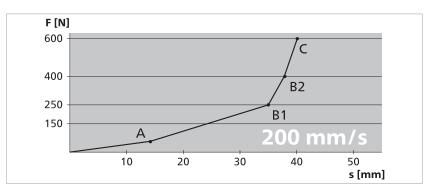
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit
- Lip not taken into account

All data stated here is documented in EC type examination certificates.

Force-distance ratios







10 mm/s

Test velocity Actuation force 48 N 910 ms Response time Actuation distance (A) 9.1 mm Overtravel distance up to 250 N (B1) 24 5 mm up to 400 N (B2) 29.3 mm up to 600 N (C) 31.0 mm Total deformation 40.1 mm

Test velocity
Actuation force
41 N
Response time
80 ms
Actuation distance (A)
8.0 mm
Overtravel distance
up to 250 N (B1)
26.0 mm
up to 400 N (B2)
29.4 mm
up to 600 N (C)
31.5 mm

39.5 mm

40.1 mm

Total deformation

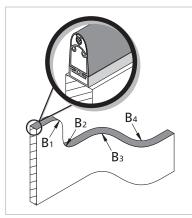
Test velocity 200 mm/s
Actuation force 58 N
Response time 71 ms
Actuation distance (A) 14.2 mm
Overtravel distance
up to 250 N (B1) 20.8 mm
up to 400 N (B2) 23.7 mm
up to 600 N (C) 25.9 mm

Total deformation



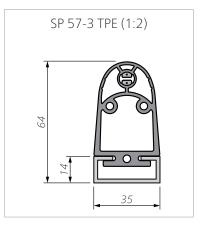
SK SP 57-3 TPE

Sensor profile (without control unit)	SK SP/W 57-3 TPE or SK SP/BK 57-3 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} =	100 mm/s
Switching operations	10,000
Actuation force	- FO N
Test piece (rod) Ø 20 mm Test piece (cylinder) Ø 80 mm	< 50 N < 150 N
Actuation distance	~ 130 TV
Test piece (cylinder) Ø 80 mm	8 mm
Actuation angle	
Test piece (cylinder) Ø 80 mm	±45°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B _{10D}	2× 10 ⁶
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 25 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	
B ₁ / B ₂ / B ₃ / B ₄	1000 / 1000 / 200 / 200 mm
Operating velocity (min. / max.)	10 mm/s / 200 mm/s
Max. load capacity (impulse)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: Degree of protection	IP68
SP in water: 9 cm bottom edge	IPX8: 20 weeks
Operating temperature	−25 to +55 °C
short-term (15 min)	−40 to +80 °C
Storage temperature	−40 to +80 °C
Weight	SP 57-3
without aluminium profile	0.60 kg/m
with aluminium profile C 35	1.00 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.) Switching current (min./max.)	DC 24 V 1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm ²
Connection capic	5 2.5 111111 01(2\(\times\) 0.25 111111





Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

Test conditions according to ISO 13856-2

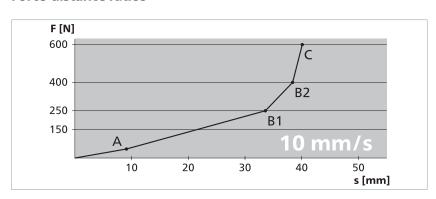
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø
 80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

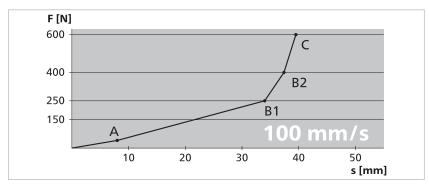
Force-distance ratios

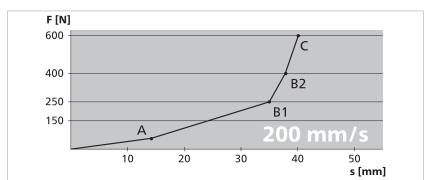
Test velocity	10 mm/s
Actuation force	48 N
Response time	910 ms
Actuation distance (A)	9.1 mm
Overtravel distance	
up to 250 N (B1)	24.5 mm
up to 400 N (B2)	29.3 mm
up to 600 N (C)	31.0 mm
Total deformation	40.1 mm

Test velocity 1	00 mm/s
Actuation force	41 N
Response time	80 ms
Actuation distance (A)	8.0 mm
Overtravel distance	
up to 250 N (B1)	26.0 mm
up to 400 N (B2)	29.4 mm
up to 600 N (C)	31.5 mm
Total deformation	39.5 mm

Test velocity 2	00 mm/s
Actuation force	58 N
Response time	71 ms
Actuation distance (A)	14.2 mm
Overtravel distance	
up to 250 N (B1)	20.8 mm
up to 400 N (B2)	23.7 mm
up to 600 N (C)	25.9 mm
Total deformation	40.1 mm



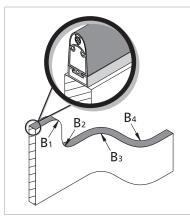






SK SP 57(L)-4 TPE

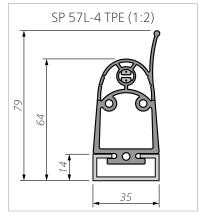
Sensor profile (without control unit)	SK SP/W 57(L)-4 TPE or SK SP/BK 57(L)-4 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} = 1	100 mm/s
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm	< 150 N
Actuation distance	0, 100, 100
Test piece (cylinder) Ø 80 mm Actuation angle	8 mm
Test piece (cylinder) Ø 80 mm	±45°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B _{10D}	2× 10 ⁶
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 25 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	
B ₁ / B ₂ / B ₃ / B ₄	1000 / 1000 / 200 / 200 mm
Operating velocity (min. / max.)	10 mm/s / 200 mm/s
Max. load capacity (impulse)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: Degree of protection	IP68
SP in water: 9 cm bottom edge	IPX8: 20 weeks
Operating temperature	−25 to +55 °C
short-term (15 min)	−40 to +80 °C
Storage temperature	-40 to +80 °C
Weight	SP 57-4 SP 57L-4
without aluminium profile with aluminium profile C 35	0.58 kg/m 0.62 kg/m 0.99 kg/m 1.03 kg/m
	0.99 kg/111 1.03 kg/111
Electrical operating conditions	
Terminal resistance Nominal output (max.)	8k2 ±1% 250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm ²



SP 57-4 TPE (1:2)

Dimensional tolerances according to ISO 3302 E2/L2

Dimensions and distances



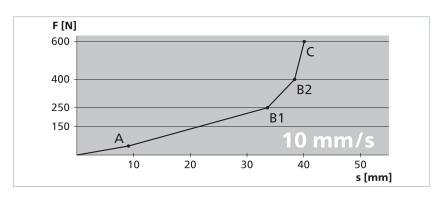
Dimensional tolerances according to ISO 3302 E2/L2

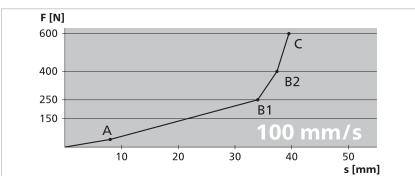
Test conditions according to ISO 13856-2

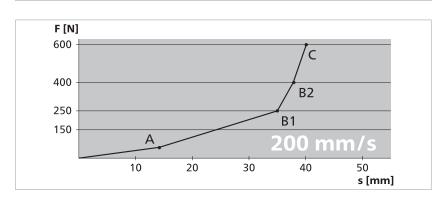
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit
- Lip not taken into account

All data stated here is documented in EC type examination certificates.

Force-distance ratios







10 mm/s 48 N

Actuation force 48 N Response time 910 ms Actuation distance (A) 9.1 mm

Overtravel distance

Test velocity

up to 250 N (B1) 24.5 mm up to 400 N (B2) 29.3 mm up to 600 N (C) 31.0 mm Total deformation 40.1 mm

Test velocity 100 mm/s
Actuation force 41 N
Response time 80 ms
Actuation distance (A) 8.0 mm
Overtravel distance

up to 250 N (B1) 26.0 mm up to 400 N (B2) 29.4 mm up to 600 N (C) 31.5 mm Total deformation 39.5 mm

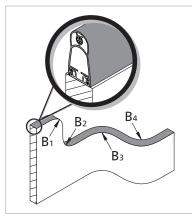
Test velocity 200 mm/s
Actuation force 58 N
Response time 71 ms
Actuation distance (A) 14.2 mm
Overtravel distance

up to 250 N (B1) 20.8 mm up to 400 N (B2) 23.7 mm up to 600 N (C) 25.9 mm Total deformation 40.1 mm

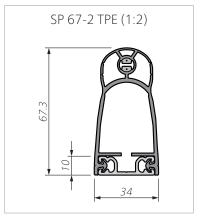


SK SP 67-2 TPE

Sensor profile (without control unit)	SK SP/W 67-2 TPE or SK SP/BK 67-2 TPE	
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2	
Switching characteristics at v _{test} =	100 mm/s	
Switching operations Actuation force	10,000	
Test piece (rod) Ø 20 mm Test piece (cylinder) Ø 80 mm Actuation distance	< 50 N < 150 N	
Test piece (cylinder) Ø 80 mm Actuation angle	11 mm	
Test piece (cylinder) Ø 80 mm Finger detection	± 45° Yes	
Safety classifications		
ISO 13849-1: B _{10D}	2× 10 ⁶	
Mechanical operating conditions		
Sensor length (min./max.) Cable length (min./max.) Bend radii, minimum B1 / B2 / B3 / B4 Operating velocity (min. / max.) Max. load capacity (impulse) Tensile load, cable (max.) IEC 60529: Degree of protection SP in water: 9 cm bottom edge Operating temperature short-term (15 min) Storage temperature Weight without aluminium profile C 30	10 cm / 30 m 10 cm / 100 m 1000 / 1000 / 200 / 200 mm 10 mm/s / 200 mm/s 600 N 20 N IP68 IPX8: 20 weeks -25 to +55 °C -40 to +80 °C -40 to +80 °C SP 67-2 0.49 kg/m 0.79 kg/m	
Electrical operating conditions		
Terminal resistance Nominal output (max.) Contact transition resistance Number of BK-type sensors Switching voltage (max.) Switching current (min./max.) Connection cable	8k2 ±1% 250 mW < 400 ohms (per sensor) Max. 5 in series DC 24 V 1 mA / 10 mA Ø 2.9 mm PUR 2× 0.25 mm ²	



Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

Test conditions according to ISO 13856-2

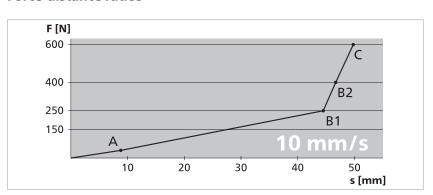
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

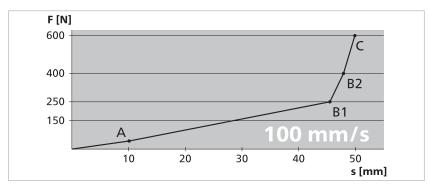
Force-distance ratios

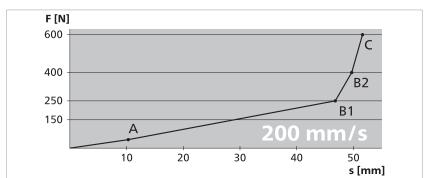
Test velocity	10 mm/s
Actuation force	41 N
Response time	880 ms
Actuation distance (A)	8.8 mm
Overtravel distance	
up to 250 N (B1)	35.7 mm
up to 400 N (B2)	37.9 mm
up to 600 N (C)	41 mm
Total deformation	49.8 mm

Test velocity 1	00 mm/s
Actuation force	43 N
Response time	101 ms
Actuation distance (A)	10.1 mm
Overtravel distance	
up to 250 N (B1)	35.4 mm
up to 400 N (B2)	37.8 mm
up to 600 N (C)	39.8 mm
Total deformation	49.9 mm

Test velocity 20	00 mm/s
Actuation force	45 N
Response time	51.5 ms
Actuation distance (A)	10.3 mm
Overtravel distance	
up to 250 N (B1)	36.5 mm
up to 400 N (B2)	39.4 mm
up to 600 N (C)	41.3 mm
Total deformation	51.6 mm



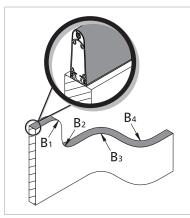




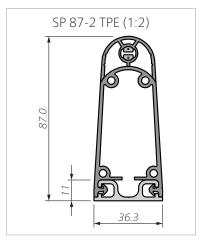


SK SP 87-2 TPE

Sensor profile (without control unit)	SK SP/W 87-2 TPE or SK SP/BK 87-2 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} =	100 mm/s
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	9 mm
Test piece (cylinder) Ø 80 mm	± 45°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B _{10D}	2× 10 ⁶
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 25 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	
B ₁ / B ₂ / B ₃ / B ₄	1000 / 1000 / 200 / 200 mm
Operating velocity	10 / 200
(min. / max.)	10 mm/s / 200 mm/s
Max. load capacity (impulse) Tensile load, cable (max.)	600 N 20 N
IEC 60529: Degree of protection	IP68
SP in water: 9 cm bottom edge	IPX8: 20 weeks
Operating temperature	-25 to +55 °C
short-term (15 min)	-40 to +80 °C
Storage temperature	-40 to +80 °C
Weight	SP 87-2
without aluminium profile	0.64 kg/m
with aluminium profile C 36	1.06 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm ²



Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

Test conditions according to ISO 13856-2

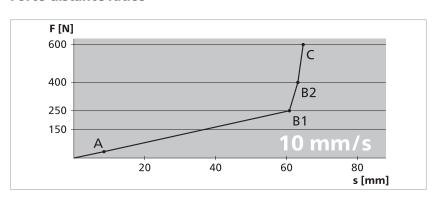
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø
 80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

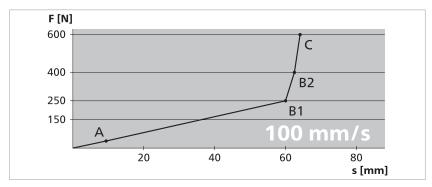
Force-distance ratios

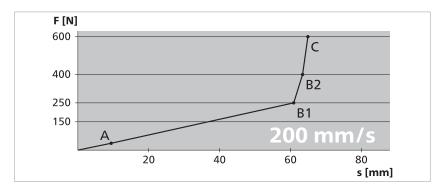
Test velocity	10 mm/s
Actuation force	34 N
Response time	850 ms
Actuation distance (A)	8.5 mm
Overtravel distance	
up to 250 N (B1)	52.3 mm
up to 400 N (B2)	54.7 mm
up to 600 N (C)	56.2 mm
Total deformation	64.7 mm

Test velocity 1	00 mm/s
Actuation force	38 N
Response time	81 ms
Actuation distance (A)	8.1 mm
Overtravel distance	
up to 250 N (B1)	51.9 mm
up to 400 N (B2)	54.4 mm
up to 600 N (C)	56.0 mm
Total deformation	64.1 mm

Test velocity 20	00 mm/s
Actuation force	37 N
Response time	47 ms
Actuation distance (A)	9.4 mm
Overtravel distance	
up to 250 N (B1)	51.5 mm
up to 400 N (B2)	54.0 mm
up to 600 N (C)	55.5 mm
Total deformation	64.9 mm









Marking

If you combine sensors with control units and thereby place pressure-sensitive protection devices on the market, you should observe the basic requirements according to ISO 13856.

As well as meeting technical requirements, this also means – in particular – observing any that relate to marking and information for use.

Conformity

EC type examination

The product was tested by an independent institute.

There is an EC type examination certificate to confirm conformity.

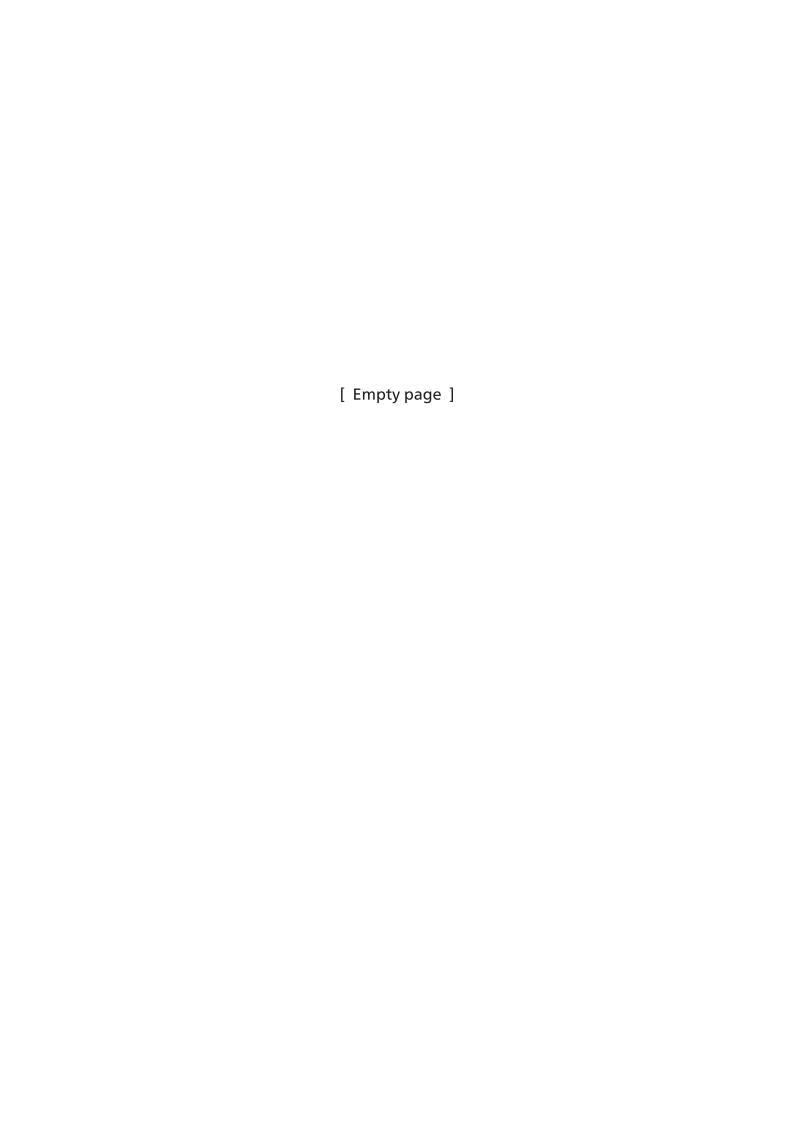
The EC type examination certificate is stored in the Downloads section of our website: www.mayser.com.

UL certification



The design type of the product conforms to the basic requirements of UL certification:

• UL 325







SP DIY sensor profiles for toolless self-assembly



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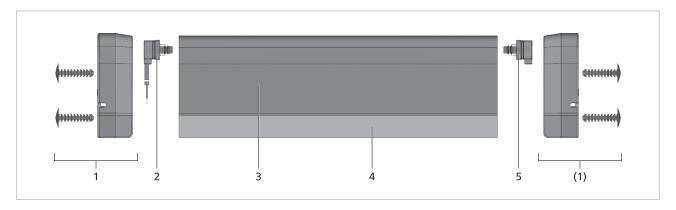


SK SP 67-2 TPE	39
SK SP 87-2 TPE	41
Marking	
Conformity	
EC type examination	

Overview

Contact profile - Sensor profile

The semi-finished contact profile (No. 3) is cut to length and assembled with the other components. This results in a functioning product called a sensor profile.



Nos. 2 and 5 are identical for all sensor profiles.

No. 2 Closing plug with 2.5 m cable 7504038No. 5 Closing plug with resistor 7504039

Alternatives for No. 2:

Closing plug with 5.0 m cable 7504103 Closing plug with 10 m cable 7504102

Sensor profile	No. 1 Set of end caps	No. 3 Contact profile			o. 4 um profile
SP 17-3 without end caps	1005786	SP 17-3	7503461	C 15	1000016
SP 37-1 without end caps	1000606	SP 37-1	7502853	C 25	1000004
SP 37-1 with end caps	7503008	SP 37-1	7502853	C 25	1000004
SP 37-2 with end caps	7503988	SP 37-2	7503318	C 26	1004330
SP 37L-2 with end caps	7503988	SP 37L-2	7504192	C 26	1004330
SP 37-3 with end caps	7503505 (7503654)	SP 37-3	7503343	C 25	1000004
SP 57-2 with end caps	7503603	SP 57-2	7503055	C 30	1005844
SP 57L-2 with end caps	7503603	SP 57L-2	7503412	C 30	1005844
SP 57-3 with end caps	7503618	SP 57-3	7503521	C 35	1000006

Subject to technical modifications.



Sensor profile	No. 1 Set of end caps	No. 3 Contact profile			o. 4 um profile
SP 57-4 with end caps	7503618	SP 57-4	7503633	C 35	1000006
SP 57L-4 with end caps	7503618	SP 57L-4	7503711	C 35	1000006
SP 67-2 with end caps	7503655	SP 67-2	7503285	C 30	1005844
SP 87-2 with end caps	7504118	SP 87-2	7503722	C 36	1003848

Materials list

Part No.	Designation	Pack- ing unit
7503461	Contact profile SP 17-3 TPE	80 m
7502853	Contact profile SP 37-1 TPE	30 m
7503318	Contact profile SP 37-2 TPE	30 m
7504192	Contact profile SP 37L-2 TPE	30 m
7503343	Contact profile SP 37-3 TPE "black"	30 m
7503534	Contact profile SP 37-3 TPE "red"	30 m
7503055	Contact profile SP 57-2 TPE	30 m
7503412	Contact profile SP 57L-2 TPE	30 m
7503521	Contact profile SP 57-3 TPE	25 m
7503633	Contact profile SP 57-4 TPE	25 m
7503711	Contact profile SP 57L-4 TPE	25 m
7503285	Contact profile SP 67-2 TPE	30 m
7503722	Contact profile SP 87-2 TPE	25 m
7504039	Closing plug with resistor 8k2	10 pcs.
7504038	Closing plug with 2.5 m PUR cable, angled 90°	10 pcs.
7504103	Closing plug with 5.0 m PUR cable, angled 90°	10 pcs.
7504102	Closing plug with 10 m PUR cable, angled 90°	10 pcs.
7504101	Closing plug without resistor	10 pcs.
1005786	Countersunk tapping screw 3.5 x 25 for SP 17-3	20 pcs.
7503008	Set of end caps for SP 37-1: 2 end caps, 2 fixing stoppers and 2 screws 3.9 × 25	10 pcs.
7503988	Set of end caps for SP 37(L)-2: 2 end caps and 4 pine tree clips	10 pcs.



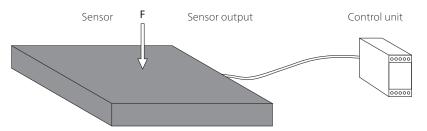
Part No.	Designation	Pack- ing unit
7503505	Set of end caps for SP 37-3 "black":	
	2 end caps and 2 pine tree clips	10 pcs.
7503654	Set of end caps for SP 37-3 "red": 2 end caps and 2 pine tree clips	10 pcs.
7503603	Set of end caps for SP 57(L)-2 with clips: 2 end caps and 4 pine tree clips	10 pcs.
7503618	Set of end caps for SP 57-3 and SP 57(L)-4: 2 end caps and 6 pine tree clips	10 pcs.
7503655	Set of end caps for SP 67-2: 2 end caps and 4 pine tree clips	10 pcs.
7504118	Set of end caps for SP 87-2: 2 end caps and 8 pine tree clips	10 pcs.
1000016	Aluminium profile C 15	6 m
1000854	Aluminium profile C 25M, upper section	6 m
1000855	Aluminium profile C 25M, lower section	6 m
1000829	Aluminium profile C 25L	6 m
1000012	Aluminium profile C 25S	6 m
1000004	Aluminium profile C 25	6 m
1004626	Aluminium profile C 26M, upper section	6 m
1004627	Aluminium profile C 26M, lower section	6 m
1004330	Aluminium profile C 26, perforated	6 m
1005844	Aluminium profile C 30	6 m
1001398	Aluminium profile C 35M, upper section	6 m
1001399	Aluminium profile C 35M, lower section	6 m
1000013	Aluminium profile C 35S	6 m
1000006	Aluminium profile C 35	6 m
1004629	Aluminium profile C 36M, upper section	6 m
1004630	Aluminium profile C 36M, lower section	6 m
1003849	Aluminium profile C 36L, perforated	6 m
1003850	Aluminium profile C 36S, perforated	6 m
1003848	Aluminium profile C 36, perforated	6 m
1001223	End stopper for C 25M, for SP without end caps	1 pc.
1000606	End stopper for C 25 or C 25S, for SP without end caps	1 pc.
1005906	Section cutter, cutting length 87 mm	1 pc.



Definitions

Pressure-sensitive protection device

A pressure-sensitive protection device consists of one or more pressure-sensitive sensors, a signal processing unit, and one or more output signal switching devices. The control unit is made up of the signal processing unit and output signal switching device(s). The pressure-sensitive protection device is triggered when the sensor is activated.

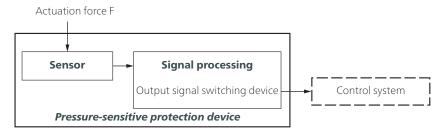


Sensor

The sensor is the part of the pressure-sensitive protection device that generates a signal when the actuation force F is applied. Mayser safety systems feature a sensor whose actuating surface is deformed locally.

Signal processing

The signal processing unit is the part of the pressure-sensitive protection device that converts the output signal of the sensor and controls the status of the output signal switching device. The output signal switching device is the part of the signal processing unit which is connected to the forwarding control system and which transmits safety output signals such as STOP.

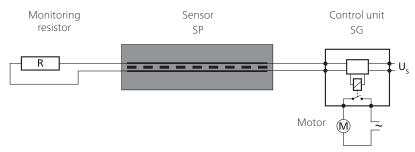


Tip: Terms are defined in ISO 13856-2 Section 3.

Criteria for selecting the sensor type

- Category according to ISO 13849-1
- Performance level of the pressure-sensitive protection device
 at least PL₂
- Temperature range
- Degree of Protection in accordance with IEC 60529:
 IP67 is the standard for safety edges.
 Higher degrees of protection must be checked individually.
- Environmental influences such as swarf, oil, coolant, outdoor use...
- Finger detection necessary?

Operation principle of 2-wire technology



The monitoring resistor must be compatible with the control unit. The standard type is 8k2.

For your safety:

The sensor and connecting cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on controlled bridging of the contact surfaces with a monitoring resistor (closed-circuit principle).

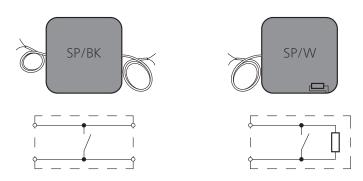
Types

SP/BK With cables on both sides for use as a through sensor or

with an external monitoring resistor for use as an end sen-

sor

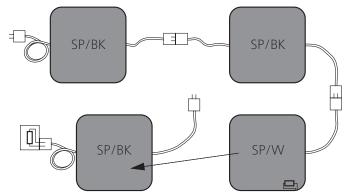
SP/W With an integrated monitoring resistor for use as an end



Subject to technical modifications.



Sensor combination

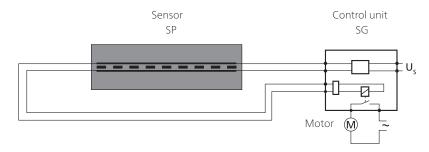


Version with external resistor, therefore no variety of models

Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety edge design with custom lengths and angles

Operation principle of 4-wire technology



The 4-wire technology can only be used together with control unit SG-EFS 104/4L.

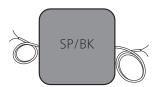
For your safety:

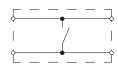
The sensor and connecting cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on signal transmission feedback – without a monitoring resistor.

Types

SP/BK

With cables on both sides for use as a through sensor

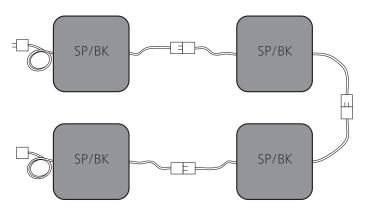




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Sensor combination



Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety edge design with custom lengths and angles



Safety

Intended use

A safety edge detects a person or part of the body when pressure is applied to the effective actuation area. It is a linear tripping device. Its task is to prevent possible hazardous situations that could affect someone within a danger zone, such as shearing and pinching edges.

Typical areas of application are door and gate systems, moving parts on machines, platforms and lifting devices.

Safe operation of a safety edge depends entirely on

- the surface condition of the mounting surface,
- the correct selection of the size and resistance rating as well as
- correct installation.

For additional application guidelines, please refer to ISO 13856-2 Annex E.

Due to the design, the actuation area is actually smaller than it looks because of the non-sensitive edges. Once these have been allowed for, what remains is the effective actuation area (see chapter *Effective actuation area*).

Limits

- No more than 5 /BK-type sensors can be connected to one control unit.
- No more than 4 /BK-type sensors and 1 /W-type sensor can be connected to one control unit.

Exclusions

The sensors are not suitable for:

• performing a sealing function. Constant actuation of sensors can result in permanent damage.

Exception: The L version with an attached lip seal.

The lip seal can be in full contact with the closing edge, which allows it to repel wind and water.

Selecting the appropriate product line

If you opt for our line of SP DIY sensor profiles for toolless self-assembly, the maximum class of protection that can be achieved is IP67 and IPX8 (13 days). If a higher protection class of IP68 or IPX8 (20 weeks) is required for your application, we recommend using our line of SP DIY sensor profiles for **assembly with tools** instead.

Subject to technical modifications.



Other safety aspects

The following safety aspects relate to pressure-sensitive protection devices consisting of a sensor and a control unit.

Performance Level (PL)

The PL has been determined using the procedure defined by ISO 13849-1.

Fault exclusion according to ISO 13849-2 Table D.8: Non-closing of contacts by pressure-sensitive equipment according to ISO 13856. In this case, the diagnostic coverage (DC) is not calculated or taken into account when determining the PL. Assuming a high MTTF_D value for the control unit, a performance level of up to PL d can be achieved by the safety edge system (pressure-sensitive protection device) as a whole.

Is the protection device suitable?

First, the integrator must decide what PL_r is required for the hazard. After that, they must select the protection device.

Finally, the integrator needs to check whether the category and PL of the selected protection device are appropriate.

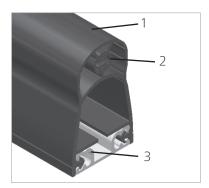
Risk and safety assessment

For the risk and safety assessment of your machine, we recommend ISO 12100 "Safety of machinery — General principles for design".

Without reset function

When a protection device without reset function is used (automatic reset), the reset function must be provided in some other way.

Design



The SP sensor profile consists of one sensor (1 to 3)

- (1) SP contact profile with
- (2) integrated normally open switching element,
- (3) aluminium profile and an evaluating control unit SG.

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Subject to technical modifications.

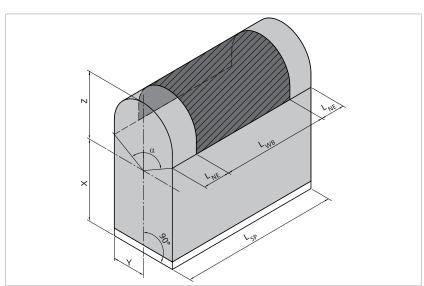


Effective actuation area

The parameters X, Y, Z, L_{WB} and the angle $\,\alpha\,$ describe the effective actuation area.

For the effective actuation area, the following applies:

$$L_{WB} = L_{SP} - 2 \times L_{NE}$$



Parameters:

 L_{WB} = effective actuation length

 L_{SP} = total length of sensor profile

 $L_{NE} = non-sensitive length at end of sensor profile$

 α = effective actuation angle

	SP 17-3 ¹⁾	SP 37-1	SP 37(L)-2	SP 37-3	SP 57(L)-2	SP 57-3	SP 57(L)-4	SP 67-2	SP 87-2
			SIG.						
Incl.	C 15	C 25	C 26	C 25	C 30	C 35	C 35	C 30	C 36
α	90°	100°	100°	100°	90°	90°	90°	90°	90°
L _{NE}	60 mm	20 mm	20 mm	20 mm	10 mm ²⁾	10 mm ²⁾	10 mm ²⁾	20 mm ²⁾	10 mm ²⁾
Υ	6.7 mm	12.5 mm	13 mm	12.5 mm	17 mm	17.5 mm	17.5 mm	17 mm	18.1 mm
X	15.3 mm	28.5 mm	30 mm	29 mm	44 mm	52 mm	52 mm	57.3 mm	72 mm
Z	5 mm	9 mm	9 mm ³⁾	9 mm	12 mm ³⁾	12 mm	12 mm ³⁾	10 mm	15 mm
X + Z	20.3 mm	37.5 mm	39 mm ³⁾	38 mm	56 mm ³⁾	64 mm	64 mm ³⁾	67.3 mm	87 mm

¹⁾ without end cap

Installation position

The installation position can be selected as required, i.e. all installation positions from A to D as per ISO 13856-2 are possible.

²⁾ with finger protection

³⁾ without lip

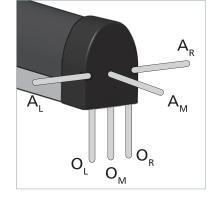
Connection

Cable exits

Depending on the end cap, the following cable exits are available.

 $\begin{array}{lll} \textbf{A}_{L} &=& \text{axial left} \\ \textbf{A}_{M} &=& \text{axial middle} \\ \textbf{A}_{R} &=& \text{axial right} \\ \textbf{O}_{L} &=& \text{orthogonal left} \\ \textbf{O}_{M} &=& \text{orthogonal middle} \end{array}$

 O_R = orthogonal right



Orientation				Cable	e exit		
Lateral exit				A_R			
	Axial exit		A _M				
	90° exit				O _L	O _M	O _R
Combi	nation						
Contact profile	Set of end caps						
SP 17-3	_					•	
SP 37-1	7503008	•		•	•		•
SP 37(L)-2	7503988	•	•	•		•	
SP 37-3 black	7503505	•		•	•		•
SP 37-3 red	7503654	•		•	•		•
CD [7/1] 2	7503062	•	•	•		•	
SP 57(L)-2	7503603	•	•	•		•	
SP 57-3	7503618	•	•	•		•	
SP 57(L)-4	7503796	•	•	•	•		•
SP 67-2	7503655	•	•	•		•	
SP 87-2	7504118	•	•	•		•	

• = possible

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Cable connection

- Standard cable lengths L = 2.5 m / 5.0 m / 10 m
- Maximum total cable length to the control unit $L_{max} = 100 \text{ m}$

/W-type sensor with 1 line	/BK-type sensor with 2 lines
 As an individual /W-type sensor or a /W-type end sensor Integrated resistor 1 two-wire cable 	 As a /BK-type through sensor Without resistor 2 two-wire cables

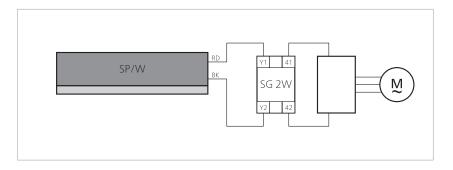
Wire colours

/W-type sensor with 1 line	/BK-type sensor with 2 lines
RD BK	RD ← ← → RD BK ← → BK

Connection examples

Key:

SG 2W evaluation with 2-wire technology SG 4L evaluation with 4-wire technology

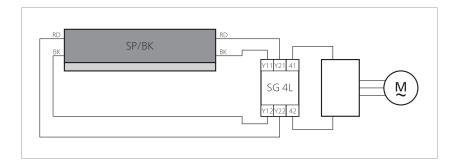


Colour coding

BK Black RD Red

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Sensor surface

Resistance

The resistance ratings listed below (at a room temperature of 23 °C) depend on the sensor having an undamaged surface.

Physical resistance

	TPE
UV resistance	Yes

Chemical resistance

The sensor is broadly resistant to normal chemical influences such as diluted acids and alkalis, as well as alcohol, over an exposure period of 24 hrs.

The values in the table are the results of tests carried out in our laboratory. You must always conduct your own practical tests to verify that our products are suitable for your specific area of application.



Explanation of symbols:

+ = resistant

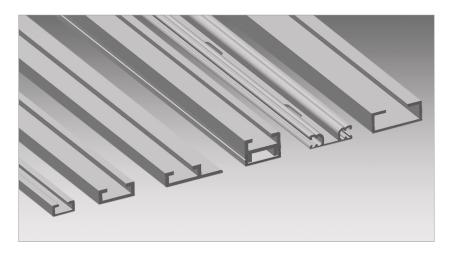
 \pm = resistant to a certain extent

- = not resistant

Material	TPE
Acetone	-
Formic acid	-
Armor All	+
Car shampoo	+
Petrol	_
Brake fluid	+
Buraton	+
Butanol	-
Sodium hypochlorite	_
Disinfectant 1%	+
Diesel	-
Acetic acid 10%	-
Ethanol	+
Ethyl acetate	_
Ethylene glycol	+
Greases	±
Anti-frost agent	+
Skin cream	+
Incidin	+
Incidin Plus	+
Cooling lubricant	_
Plastic cleaner	+
Lyso FD 10	+
Metal working oil	_
Microbac	+
Microbac forte	+
Minutil	+
Saline solution 5%	+
Spirit (ethyl alcohol)	+
Terralin	+
Centring oil	-

Mounting

The sensors are mounted directly onto the main and secondary closing edges that present a danger. They are fixed using special aluminium profiles. The profiles are fastened with screws or rivets.



Material properties

- AlMgSi0.5 F22
- Wall thickness at least
 2.0 mm
 C 15: at least 1.7 mm
 - C 30: at least 1.5 mm
- Extruded
- Hot hardened
- Tolerances as per EN 755-9

Aluminium profiles: Overview of combinations

Sensor pr	ofile foot	C 15	C 25 C 25M C 25S C 25L	C 26 C 26M	C 30	C 35 C 35M C 35S	C 36 C 36M C 36S C 36L
Snap-in foot (middle)	1	-	SP 37-1	_	_	_	_
Clip bars (outside)	2	_	_	SP 37(L)-2	SP 57(L)-2 SP 67-2	_	SP 87-2
T-foot (middle)	3	SP 17-3	SP 37-3	_	_	SP 57-3	_
T-foot narrow (middle)	4	-	_	_	_	SP 57(L)-4	_



Aluminium profiles: Mounting types

Standard profile

First the aluminium profile must be mounted onto the closing edge and then the sensor profile clipped into the aluminium profile.

C 15	C 25	C 26	C 30	C 35	C 36
		<u> </u>			

Two-part profile, type M

For convenient assembly and disassembly. The sensor profile is clipped into the upper section and the upper section inserted into the installed lower section and fastened.

-	C 25M	C 26M	C 35M	C 36M

Flange profile, type S

Final assembly is also possible when the sensor profile is already clipped into the aluminium profile.

-	C 25S	-	C 35S	C 36S

Angle profile, type L

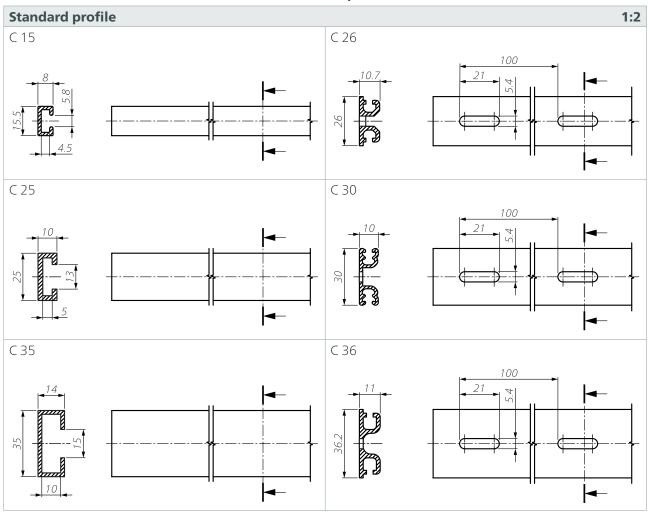
If the closing edge should or must not have assembly holes, this "round-the-corner" solution is suitable. Final assembly is also possible when the sensor profile is already clipped into the aluminium profile.

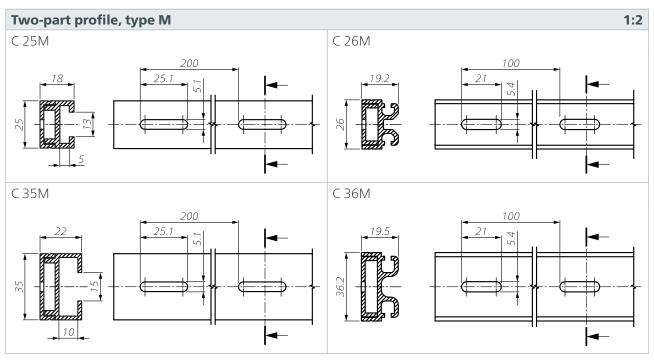


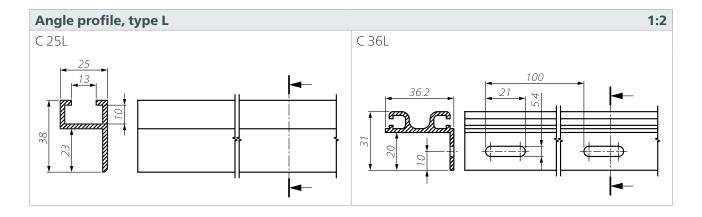
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Aluminium profiles: Dimensions









- s₁ = Stopping distance of the dangerous movement [mm]
- v = Velocity of the dangerous movement [mm/s]
- T = Follow-through time of the complete system [s]
- t_1 = Safety edge response time
- t₂ = Stopping time of the machine
- s = Minimum overtravel distance of the safety edge to ensure that the stipulated limit forces are not exceeded [mm]
- C = Safety factor; if components susceptible to failures (braking system) exist in the system, a higher factor must be selected.

SP: Making the right selection

Calculation for selection of the safety edge height

The stopping distance of the dangerous movement is calculated using the following formula:

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$

In accordance with ISO 13856-2, the minimum overtravel distance of the safety edge is calculated using the following formula:

$$s = s_1 \times C$$
 where: $C = 1.2$

A suitable safety edge profile can now be selected based on the result. For details of the overtravel distances for safety edge profiles, see chapter *Technical data*.

Calculation examples

Calculation example 1

The dangerous movement on your machine has a velocity of v=10 mm/s and can be brought to a standstill within $t_2=200$ ms. The relatively low velocity suggests that a short overtravel distance is to be expected. Therefore, the sensor profile SP 37-1 TPE could be sufficient. The response time of the safety edge (SP 37-1 TPE + control unit*) is $t_1=600$ ms.

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$
 $s_1 = 1/2 \times 10 \text{ mm/s} \times (0.6 \text{ s} + 0.2 \text{ s})$
 $s_1 = 1/2 \times 10 \text{ mm/s} \times 0.8 \text{ s} = 4.0 \text{ mm}$

$$s = s_1 \times C$$
 where: $C = 1.2$

 $s = 4.0 \text{ mm} \times 1.2 = 4.8 \text{ mm}$

The safety edge must have a minimum overtravel distance of s = 4.8 mm. The selected SP 37-1 TPE has an overtravel distance of at least 9.2 mm. This is more than the required 4.8 mm.

Result: The SP 37-1 TPE is **suitable** for this case.

Subject to technical modifications.

^{*} Assumption: Typical reaction time of a control unit = 20 ms



Calculation example 2

The same conditions apply as in calculation example 1 with the exception of the velocity of the dangerous movement. This is now v = 200 mm/s. The response time of the safety edge (SP 37-1 TPE + control unit*) is $t_1 = 55$ ms.

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$
 $s_1 = 1/2 \times 200 \text{ mm/s} \times (0.055 \text{ s} + 0.2 \text{ s})$
 $s_1 = 1/2 \times 200 \text{ mm/s} \times 0.255 \text{ s} = 25.5 \text{ mm}$

$$s = s_1 \times C$$
 where: $C = 1.2$

 $s = 25.5 \text{ mm} \times 1.2 = 30.6 \text{ mm}$

The safety edge must have a minimum overtravel distance of s = 30.6 mm. The selected SP 37-1 TPE has an overtravel distance of at least 3.8 mm. This is less than the required 30.6 mm.

Result: The SP 37-1 TPE is **not suitable** for this case.

Calculation example 3

The same conditions apply as in calculation example 2. Instead of SP 37-1 EPDM, the SP 67-1 TPE is selected. The response time of the safety edge (SP 67-2 TPE + control unit*) is $t_1 = 72$ ms.

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$
 $s_1 = 1/2 \times 200 \text{ mm/s} \times (0.072 \text{ s} + 0.2 \text{ s})$
 $s_1 = 1/2 \times 200 \text{ mm/s} \times 0.272 \text{ s} = 27.2 \text{ mm}$

$$s = s_1 \times C$$
 where: $C = 1.2$
 $s = 27.2 \text{ mm} \times 1.2 = 32.6 \text{ mm}$

The safety edge must have a minimum overtravel distance of s = 32.6 mm. The selected SP 67-2 TPE has an overtravel distance of at least 36.5 mm. This is more than the required 32.6 mm.

Result: The SP 67-2 TPE is **suitable** for this case.

Subject to technical modifications.

* Assumption: Typical reaction time of a control unit = 20 ms



Maintenance and cleaning

The sensors are virtually maintenance-free.

The control unit also monitors the sensor at the same time.

Regular inspection

Depending on the operational demands, the sensors must be inspected at regular intervals (at least monthly)

- for proper functioning,
- for damage and
- for correct mounting.

Cleaning

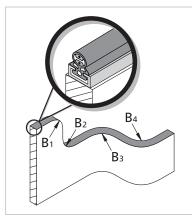
If the sensors become dirty, they can be cleaned with a mild cleaning product.

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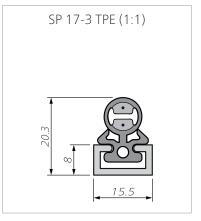
SK SP 17-3 TPE

Sensor profile (without control unit)	SK SP/W 17-3 TPE or SK SP/BK 17-3 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} = 1	I0 mm/s
Switching operations	10,000
Actuation force	
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm	< 150 N
Actuation distance	
Test piece (cylinder) Ø 80 mm	1.5 mm
Actuation angle	450
Test piece (cylinder) Ø 80 mm	±45°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B _{10D}	2× 10 ⁶
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 80 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	
$B_1 / B_2 / B_3 / B_4$	200 / 200 / 50 / 50 mm
Operating velocity	
(min. / max.)	10 mm/s / 10 mm/s
Max. load capacity (impulse)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: Degree of protection	IP67
SP in water: 9 cm bottom edge	IPX8: 13 days
Operating temperature	−25 to +55 °C
short-term (15 min)	-40 to +80 °C
Storage temperature	-40 to +80 °C
Weight	SP 17-3
without aluminium profile	0.12 kg/m
with aluminium profile C 15	0.28 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm ²





Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

Test conditions according to ISO 13856-2

- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø
 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.

Force-distance ratios

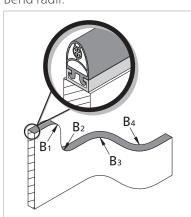
Test velocity	10 mm/s
Actuation force	38 N
Response time	140 ms
Actuation distance (A)	1.4 mm
Overtravel distance	
up to 250 N (B1)	1.4 mm
up to 400 N (B2)	2.3 mm
up to 600 N (C)	4.1 mm
Total deformation	5.5 mm

F [N]					
600	С				
400 B	2				
250 B1					
150 A				10 m	m/s
V	10	20	30	40	50 s [mm]



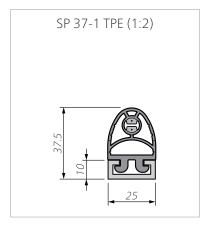
SK SP 37-1 TPE

Sensor profile (without control unit)	SK SP/W 37-1 TPE or SK SP/BK 37-1 TPE		
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2		
Switching characteristics at v _{test} = 100 mm/s			
Switching operations Actuation force	10,000		
Test piece (rod) Ø 20 mm	< 50 N		
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N		
Test piece (cylinder) Ø 80 mm Actuation angle	6 mm		
Test piece (cylinder) Ø 80 mm	±50°		
Finger detection	Yes		
Safety classifications			
ISO 13849-1: B _{10D}	2× 10 ⁶		
Mechanical operating conditions			
Sensor length (min./max.)	10 cm / 30 m		
Cable length (min./max.)	10 cm / 100 m		
Bend radii, minimum	F00 / F00 / 300 / 300 maga		
B ₁ / B ₂ / B ₃ / B ₄ Operating velocity	500 / 500 / 200 / 200 mm		
(min. / max.)	10 mm/s / 200 mm/s		
Max. load capacity (impulse)	600 N		
Tensile load, cable (max.)	20 N		
IEC 60529: Degree of protection	IP67		
SP in water: 9 cm bottom edge	IPX8: 13 days		
Operating temperature	−25 to +55 °C		
short-term (15 min)	-40 to +80 °C		
Storage temperature	-40 to +80 °C		
Weight	SP 37-1		
without aluminium profile	0.33 kg/m		
with aluminium profile C 25	0.64 kg/m		
Electrical operating conditions			
Terminal resistance	8k2 ±1%		
Nominal output (max.)	250 mW		
Contact transition resistance Number of BK-type sensors	< 400 ohms (per sensor) Max. 5 in series		
Switching voltage (max.)	DC 24 V		
Switching voltage (max.)	1 mA / 10 mA		
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm ²		





Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

Test conditions according to ISO 13856-2

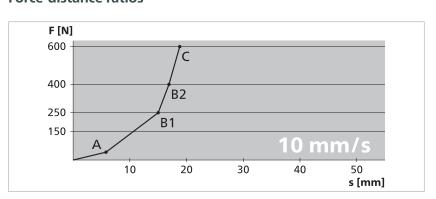
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

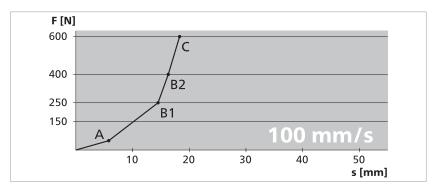
Force-distance ratios

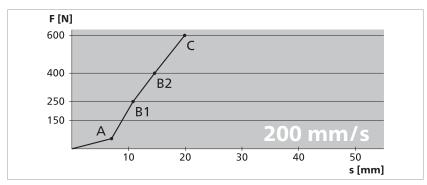
Test velocity	10 mm/s
Actuation force	42 N
Response time	580 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	9.2 mm
up to 400 N (B2)	11.1 mm
up to 600 N (C)	13.0 mm
Total deformation	18.8 mm

Test velocity 10	00 mm/s
Actuation force	50 N
Response time	58 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	8.7 mm
up to 400 N (B2)	10.5 mm
up to 600 N (C)	12.5 mm
Total deformation	18.3 mm

Test velocity 2	00 mm/s
Actuation force	54 N
Response time	35 ms
Actuation distance (A)	7.0 mm
Overtravel distance	
up to 250 N (B1)	3.8 mm
up to 400 N (B2)	7.6 mm
up to 600 N (C)	12.9 mm
Total deformation	19.9 mm



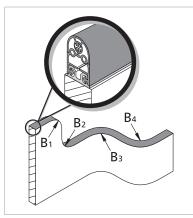






SK SP 37(L)-2 TPE

Sensor profile (without control unit)	SK SP/W 37(L)-2 TPE or SK SP/BK 37(L)-2 TPE		
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2		
Switching characteristics at v _{test} = 100 mm/s			
Switching operations Actuation force	10,000		
Test piece (rod) Ø 20 mm	< 50 N		
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N		
Test piece (cylinder) Ø 80 mm Actuation angle	6 mm		
Test piece (cylinder) Ø 80 mm Finger detection	±50° Yes		
Safety classifications			
ISO 13849-1: B _{10D}	2× 10 ⁶		
Mechanical operating conditions			
Sensor length (min./max.) Cable length (min./max.) Bend radii, minimum	10 cm / 30 m 10 cm / 100 m		
B ₁ / B ₂ / B ₃ / B ₄ Operating velocity	500 / 500 / 200 / 200 mm		
(min. / max.)	10 mm/s / 200 mm/s		
Max. load capacity (impulse)	600 N		
Tensile load, cable (max.)	20 N		
IEC 60529: Degree of protection	IP67		
SP in water: 9 cm bottom edge	IPX8: 13 days		
Operating temperature	-25 to +55 °C		
short-term (15 min)	-40 to +80 °C		
Storage temperature Weight	-40 to +80 °C SP 37-2 SP 37L-2		
without aluminium profile	0.36 kg/m 0.41 kg/m		
with aluminium profile C 26	0.69 kg/m 0.74 kg/m		
Electrical operating conditions			
Terminal resistance	8k2 ±1%		
Nominal output (max.)	250 mW		
Contact transition resistance	< 400 ohms (per sensor)		
Number of BK-type sensors	Max. 5 in series		
Switching voltage (max.)	DC 24 V		
Switching current (min./max.) Connection cable	1 mA / 10 mA Ø 2.9 mm PUR 2× 0.25 mm ²		

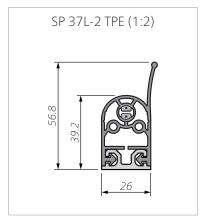


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SP 37-2 TPE (1:2)

Dimensional tolerances according to ISO 3302 E2/L2

Dimensions and distances



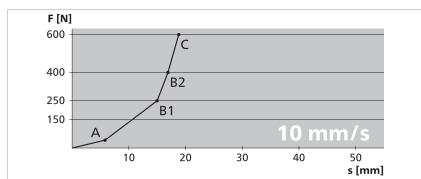
Dimensional tolerances according to ISO 3302 E2/L2

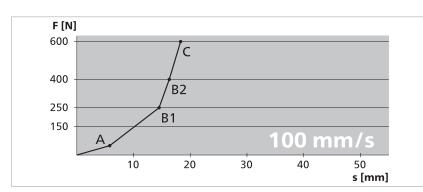
Test conditions according to ISO 13856-2

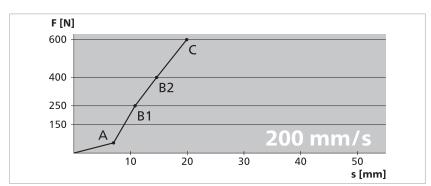
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit
- Lip not taken into account

All data stated here is documented in EC type examination certificates.

Force-distance ratios







10 mm/s 42 N

Response time 580 ms Actuation distance (A) 5.8 mm Overtravel distance

Test velocity

Actuation force

up to 250 N (B1) 9.2 mm up to 400 N (B2) 11.1 mm up to 600 N (C) 13.0 mm Total deformation 18.8 mm

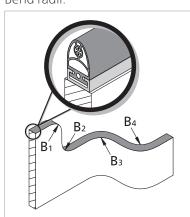
Test velocity 10	00 mm/s
Actuation force	50 N
Response time	58 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	8.7 mm
up to 400 N (B2)	10.5 mm
up to 600 N (C)	12.5 mm
Total deformation	18.3 mm

Test velocity 20	00 mm/s
Actuation force	54 N
Response time	35 ms
Actuation distance (A)	7.0 mm
Overtravel distance	
up to 250 N (B1)	3.8 mm
up to 400 N (B2)	7.6 mm
up to 600 N (C)	12.9 mm
Total deformation	19.9 mm



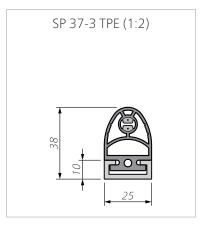
SK SP 37-3 TPE

Sensor profile (without control unit)	SK SP/W 37-3 TPE or SK SP/BK 37-3 TPE		
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2		
Switching characteristics at v _{test} = 100 mm/s			
Switching operations	10,000		
Actuation force			
Test piece (rod) Ø 20 mm	< 50 N		
Test piece (cylinder) Ø 80 mm	< 150 N		
Actuation distance			
Test piece (cylinder) Ø 80 mm	6 mm		
Actuation angle	500		
Test piece (cylinder) Ø 80 mm	±50°		
Finger detection	Yes		
Safety classifications			
ISO 13849-1: B _{10D}	2× 10 ⁶		
Mechanical operating conditions			
Sensor length (min./max.)	10 cm / 30 m		
Cable length (min./max.)	10 cm / 100 m		
Bend radii, minimum			
B ₁ / B ₂ / B ₃ / B ₄	500 / 500 / 200 / 200 mm		
Operating velocity			
(min. / max.)	10 mm/s / 200 mm/s		
Max. load capacity (impulse)	600 N		
Tensile load, cable (max.)	20 N		
IEC 60529: Degree of protection	IP67		
SP in water: 9 cm bottom edge	IPX8: 13 days		
Operating temperature	−25 to +55 °C		
short-term (15 min)	-40 to +80 °C		
Storage temperature	-40 to +80 °C		
Weight	SP 37-3		
without aluminium profile	0.34 kg/m		
with aluminium profile C 25	0.66 kg/m		
Electrical operating conditions			
Terminal resistance	8k2 ±1%		
Nominal output (max.)	250 mW		
Contact transition resistance	< 400 ohms (per sensor)		
Number of BK-type sensors	Max. 5 in series		
Switching voltage (max.)	DC 24 V		
Switching current (min./max.)	1 mA / 10 mA		
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm ²		





Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

Test conditions according to ISO 13856-2

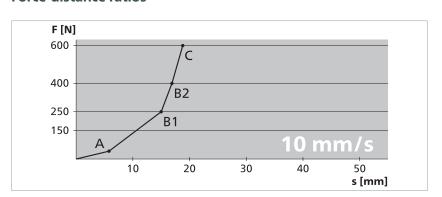
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

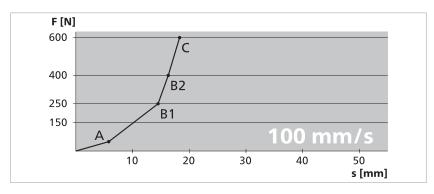
Force-distance ratios

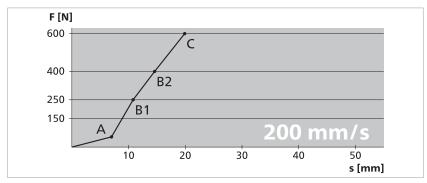
Test velocity	10 mm/s
Actuation force	42 N
Response time	580 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	9.2 mm
up to 400 N (B2)	11.1 mm
up to 600 N (C)	13.0 mm
Total deformation	18.8 mm

Test velocity 10	00 mm/s
Actuation force	50 N
Response time	58 ms
Actuation distance (A)	5.8 mm
Overtravel distance	
up to 250 N (B1)	8.7 mm
up to 400 N (B2)	10.5 mm
up to 600 N (C)	12.5 mm
Total deformation	18.3 mm

Test velocity 20	00 mm/s
Actuation force	54 N
Response time	35 ms
Actuation distance (A)	7.0 mm
Overtravel distance	
up to 250 N (B1)	3.8 mm
up to 400 N (B2)	7.6 mm
up to 600 N (C)	12.9 mm
Total deformation	19.9 mm



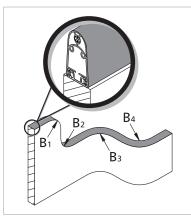




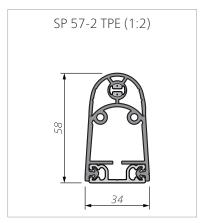


SK SP 57(L)-2 TPE

Sensor profile (without control unit)	SK SP/W 57(L)-2 TPE or SK SP/BK 57(L)-2 TPE	
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2	
Switching characteristics at v _{test} =	100 mm/s	
Switching operations Actuation force	10,000	
Test piece (rod) Ø 20 mm	< 50 N	
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N	
Test piece (cylinder) Ø 80 mm Actuation angle	8 mm	
Test piece (cylinder) Ø 80 mm	±45°	
Finger detection	Yes	
Safety classifications		
ISO 13849-1: B _{10D}	2× 10 ⁶	
Mechanical operating conditions		
Sensor length (min./max.)	10 cm / 30 m	
Cable length (min./max.)	10 cm / 100 m	
Bend radii, minimum		
B ₁ / B ₂ / B ₃ / B ₄	1000 / 1000 / 200 / 200 mm	
Operating velocity	10 mm/s / 200 mm/s	
(min. / max.) Max. load capacity (impulse)	600 N	
Tensile load, cable (max.)	20 N	
IEC 60529: Degree of protection	IP67	
SP in water: 9 cm bottom edge	IPX8: 13 days	
Operating temperature	−25 to +55 °C	
short-term (15 min)	−40 to +80 °C	
Storage temperature	−40 to +80 °C	
Weight	SP 57-2 SP 57L-2	
without aluminium profile	0.44 kg/m 0.47 kg/m	
with aluminium profile C 30	0.74 kg/m 0.77 kg/m	
Electrical operating conditions		
Terminal resistance	8k2 ±1%	
Nominal output (max.)	250 mW	
Contact transition resistance	< 400 ohms (per sensor)	
Number of BK-type sensors	Max. 5 in series	
Switching voltage (max.) Switching current (min./max.)	DC 24 V 1 mA / 10 mA	
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm ²	
CONTRCUOTECADIE	₩ Z.J IIIIII UN ZA U.ZJ IIIIII	



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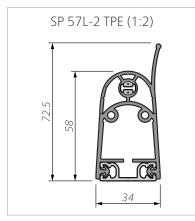


Dimensional tolerances according to ISO 3302 E2/L2

Test velocity

Actuation force

Dimensions and distances



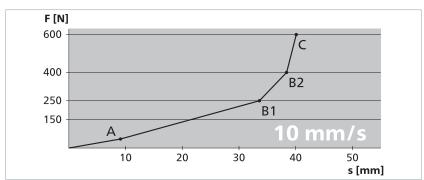
Dimensional tolerances according to ISO 3302 E2/L2

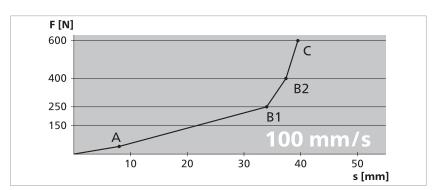
Test conditions according to ISO 13856-2

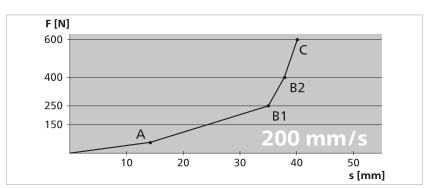
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit
- Lip not taken into account

All data stated here is documented in EC type examination certificates.

Force-distance ratios







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Response time 910 ms
Actuation distance (A) 9.1 mm
Overtravel distance
up to 250 N (B1) 24.5 mm
up to 400 N (B2) 29.3 mm
up to 600 N (C) 31.0 mm
Total deformation 40.1 mm

Test velocity 100 mm/s

10 mm/s

48 N

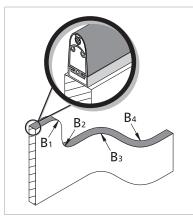
Test velocity 1	00 mm/s
Actuation force	41 N
Response time	80 ms
Actuation distance (A)	8.0 mm
Overtravel distance	
up to 250 N (B1)	26.0 mm
up to 400 N (B2)	29.4 mm
up to 600 N (C)	31.5 mm
Total deformation	39.5 mm

Test velocity 2	00 mm/s
Actuation force	58 N
Response time	71 ms
Actuation distance (A)	14.2 mm
Overtravel distance	
up to 250 N (B1)	20.8 mm
up to 400 N (B2)	23.7 mm
up to 600 N (C)	25.9 mm
Total deformation	40.1 mm



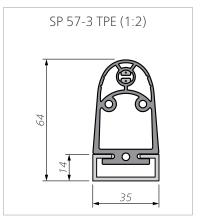
SK SP 57-3 TPE

Sensor profile (without control unit)	SK SP/W 57-3 TPE or SK SP/BK 57-3 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} = 100 mm/s	
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	8 mm
Test piece (cylinder) Ø 80 mm	±45°
Finger detection	Yes
Safety classifications	·
ISO 13849-1: B _{10D}	2× 10 ⁶
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 25 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	
B ₁ / B ₂ / B ₃ / B ₄	1000 / 1000 / 200 / 200 mm
Operating velocity	
(min. / max.)	10 mm/s / 200 mm/s
Max. load capacity (impulse)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: Degree of protection	IP67
SP in water: 9 cm bottom edge	IPX8: 13 days
Operating temperature	-25 to +55 °C
short-term (15 min)	-40 to +80 °C
Storage temperature	-40 to +80 °C
Weight without aluminium profile	SP 57-3
without aluminium profile	0.60 kg/m
with aluminium profile C 35	1.00 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm ²





Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

Test conditions according to ISO 13856-2

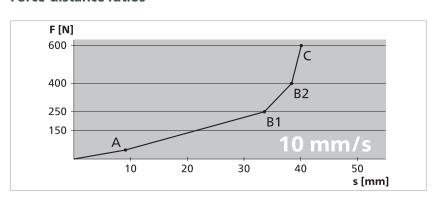
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø
 80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

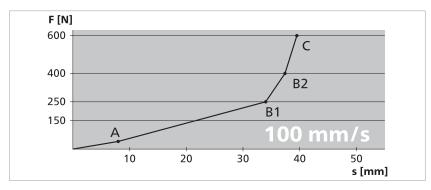
Force-distance ratios

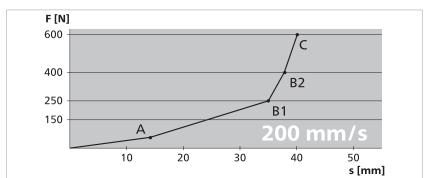
Test velocity	10 mm/s
Actuation force	48 N
Response time	910 ms
Actuation distance (A)	9.1 mm
Overtravel distance	
up to 250 N (B1)	24.5 mm
up to 400 N (B2)	29.3 mm
up to 600 N (C)	31.0 mm
Total deformation	40.1 mm

Test velocity 1	00 mm/s
Actuation force	41 N
Response time	80 ms
Actuation distance (A)	8.0 mm
Overtravel distance	
up to 250 N (B1)	26.0 mm
up to 400 N (B2)	29.4 mm
up to 600 N (C)	31.5 mm
Total deformation	39.5 mm

Test velocity 2	00 mm/s
Actuation force	58 N
Response time	71 ms
Actuation distance (A)	14.2 mm
Overtravel distance	
up to 250 N (B1)	20.8 mm
up to 400 N (B2)	23.7 mm
up to 600 N (C)	25.9 mm
Total deformation	40.1 mm



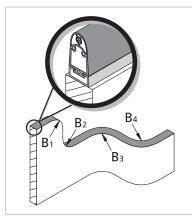




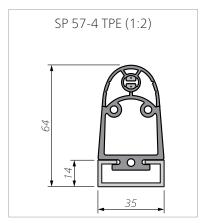


SK SP 57(L)-4 TPE

Sensor profile (without control unit)	SK SP/W 57(L)-4 TPE or SK SP/BK 57(L)-4 TPE	
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2	
Switching characteristics at v _{test} =	100 mm/s	
Switching operations Actuation force	10,000	
Test piece (rod) Ø 20 mm	< 50 N	
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N	
Test piece (cylinder) Ø 80 mm Actuation angle	8 mm	
Test piece (cylinder) Ø 80 mm	±45°	
Finger detection	Yes	
Safety classifications		
ISO 13849-1: B _{10D}	2× 10 ⁶	
Mechanical operating conditions		
Sensor length (min./max.)	10 cm / 25 m	
Cable length (min./max.)	10 cm / 100 m	
Bend radii, minimum	1000 / 1000 / 200 / 200	
B ₁ / B ₂ / B ₃ / B ₄ Operating velocity	1000 / 1000 / 200 / 200 mm	
(min. / max.)	10 mm/s / 200 mm/s	
Max. load capacity (impulse)	600 N	
Tensile load, cable (max.)	20 N	
IEC 60529: Degree of protection	IP67	
SP in water: 9 cm bottom edge	IPX8: 13 days	
Operating temperature	−25 to +55 °C	
short-term (15 min)	−40 to +80 °C	
Storage temperature	-40 to +80 °C	
Weight without aluminium profile	SP 57-4 SP 57L-4	
with aluminium profile C 35	0.58 kg/m 0.62 kg/m 0.99 kg/m 1.03 kg/m	
	0.99 kg/111 1.05 kg/111	
Electrical operating conditions	01.2 - 4.0/	
Terminal resistance	8k2 ±1%	
Nominal output (max.) Contact transition resistance	250 mW < 400 ohms (per sensor)	
Number of BK-type sensors	Max. 5 in series	
Switching voltage (max.)	DC 24 V	
Switching current (min./max.)	1 mA / 10 mA	
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm ²	

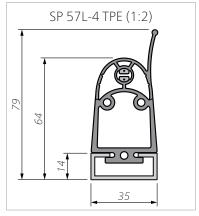


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Dimensional tolerances according to ISO 3302 E2/L2

Dimensions and distances



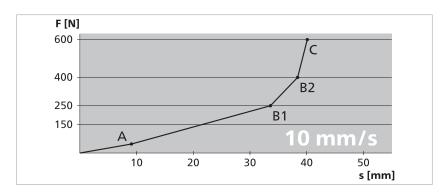
Dimensional tolerances according to ISO 3302 E2/L2

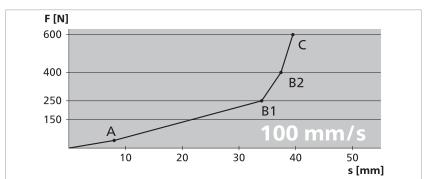
Test conditions according to ISO 13856-2

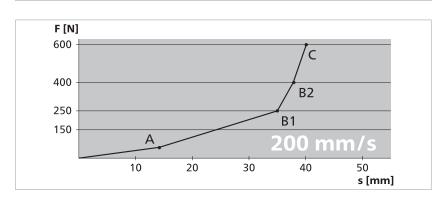
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit
- Lip not taken into account

All data stated here is documented in EC type examination certificates.

Force-distance ratios







10 mm/s 48 N

Actuation force Response time 910 ms Actuation distance (A) 9.1 mm Overtravel distance

Test velocity

up to 250 N (B1) 24 5 mm up to 400 N (B2) 29.3 mm up to 600 N (C) 31.0 mm Total deformation 40.1 mm

Test velocity 100 mm/s Actuation force 41 N Response time 80 ms Actuation distance (A) 8.0 mm Overtravel distance

up to 250 N (B1) 26.0 mm up to 400 N (B2) 29.4 mm up to 600 N (C) 31.5 mm Total deformation 39.5 mm

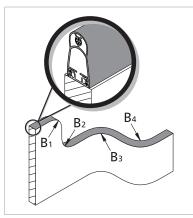
Test velocity 200 mm/s 58 N Actuation force Response time 71 ms Actuation distance (A) 14.2 mm Overtravel distance

up to 250 N (B1) 20.8 mm up to 400 N (B2) 23.7 mm up to 600 N (C) 25.9 mm Total deformation 40.1 mm



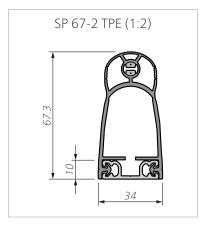
SK SP 67-2 TPE

Sensor profile (without control unit)	SK SP/W 67-2 TPE or SK SP/BK 67-2 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} =	100 mm/s
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm Test piece (cylinder) Ø 80 mm Actuation distance	< 50 N < 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	11 mm
Test piece (cylinder) Ø 80 mm Finger detection	± 45° Yes
Safety classifications	
ISO 13849-1: B _{10D}	2× 10 ⁶
Mechanical operating conditions	
Sensor length (min./max.) Cable length (min./max.) Bend radii, minimum B1 / B2 / B3 / B4 Operating velocity (min. / max.) Max. load capacity (impulse) Tensile load, cable (max.) IEC 60529: Degree of protection SP in water: 9 cm bottom edge Operating temperature short-term (15 min) Storage temperature Weight without aluminium profile C 30	10 cm / 30 m 10 cm / 100 m 1000 / 1000 / 200 / 200 mm 10 mm/s / 200 mm/s 600 N 20 N IP67 IPX8: 13 days -25 to +55 °C -40 to +80 °C -40 to +80 °C SP 67-2 0.49 kg/m 0.79 kg/m
Electrical operating conditions	
Terminal resistance Nominal output (max.) Contact transition resistance Number of BK-type sensors Switching voltage (max.) Switching current (min./max.) Connection cable	8k2 ±1% 250 mW < 400 ohms (per sensor) Max. 5 in series DC 24 V 1 mA / 10 mA Ø 2.9 mm PUR 2× 0.25 mm ²





Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

Test conditions according to ISO 13856-2

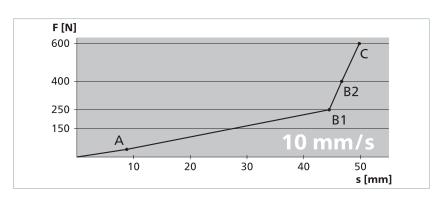
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

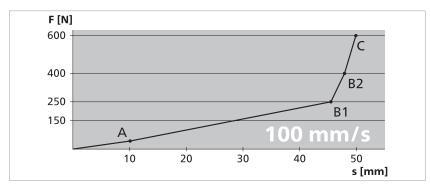
Force-distance ratios

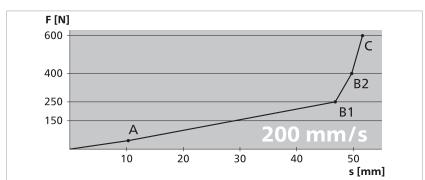
Test velocity	10 mm/s
Actuation force	41 N
Response time	880 ms
Actuation distance (A)	8.8 mm
Overtravel distance	
up to 250 N (B1)	35.7 mm
up to 400 N (B2)	37.9 mm
up to 600 N (C)	41 mm
Total deformation	49.8 mm

Test velocity 1	00 mm/s
Actuation force	43 N
Response time	101 ms
Actuation distance (A)	10.1 mm
Overtravel distance	
up to 250 N (B1)	35.4 mm
up to 400 N (B2)	37.8 mm
up to 600 N (C)	39.8 mm
Total deformation	49.9 mm

Test velocity 2	00 mm/s
Actuation force	45 N
Response time	51.5 ms
Actuation distance (A)	10.3 mm
Overtravel distance	
up to 250 N (B1)	36.5 mm
up to 400 N (B2)	39.4 mm
up to 600 N (C)	41.3 mm
Total deformation	51.6 mm



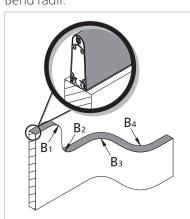






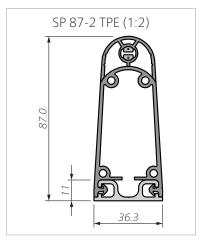
SK SP 87-2 TPE

Sensor profile (without control unit)	SK SP/W 87-2 TPE or SK SP/BK 87-2 TPE
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} =	100 mm/s
Switching operations Actuation force	10,000
Test piece (rod) Ø 20 mm	< 50 N
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	9 mm
Test piece (cylinder) Ø 80 mm	± 45°
Finger detection	Yes
Safety classifications	
ISO 13849-1: B _{10D}	2× 10 ⁶
Mechanical operating conditions	
Sensor length (min./max.)	10 cm / 25 m
Cable length (min./max.)	10 cm / 100 m
Bend radii, minimum	
B ₁ / B ₂ / B ₃ / B ₄	1000 / 1000 / 200 / 200 mm
Operating velocity	10 / 200
(min. / max.)	10 mm/s / 200 mm/s
Max. load capacity (impulse) Tensile load, cable (max.)	600 N 20 N
IEC 60529: Degree of protection	IP67
SP in water: 9 cm bottom edge	IPX8: 13 days
Operating temperature	-25 to +55 °C
short-term (15 min)	-40 to +80 °C
Storage temperature	-40 to +80 °C
Weight	SP 87-2
without aluminium profile	0.64 kg/m
with aluminium profile C 36	1.06 kg/m
Electrical operating conditions	
Terminal resistance	8k2 ±1%
Nominal output (max.)	250 mW
Contact transition resistance	< 400 ohms (per sensor)
Number of BK-type sensors	Max. 5 in series
Switching voltage (max.)	DC 24 V
Switching current (min./max.)	1 mA / 10 mA
Connection cable	Ø 2.9 mm PUR 2× 0.25 mm ²





Dimensions and distances



Dimensional tolerances according to ISO 3302 E2/L2

Test conditions according to ISO 13856-2

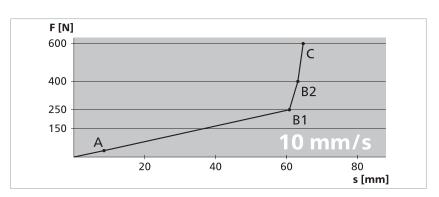
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit All data stated here is documented in EC type examination certificates.

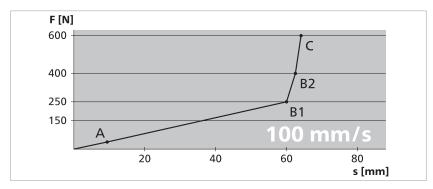
Force-distance ratios

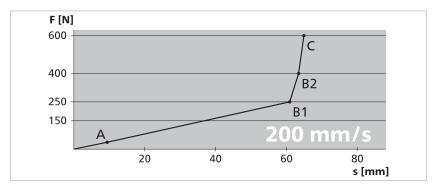
Test velocity	10 mm/s
Actuation force	34 N
Response time	850 ms
Actuation distance (A)	8.5 mm
Overtravel distance	
up to 250 N (B1)	52.3 mm
up to 400 N (B2)	54.7 mm
up to 600 N (C)	56.2 mm
Total deformation	64.7 mm

Test velocity 1	00 mm/s
Actuation force	38 N
Response time	81 ms
Actuation distance (A)	8.1 mm
Overtravel distance	
up to 250 N (B1)	51.9 mm
up to 400 N (B2)	54.4 mm
up to 600 N (C)	56.0 mm
Total deformation	64.1 mm

Test velocity 2	00 mm/s
Actuation force	37 N
Response time	47 ms
Actuation distance (A)	9.4 mm
Overtravel distance	
up to 250 N (B1)	51.5 mm
up to 400 N (B2)	54.0 mm
up to 600 N (C)	55.5 mm
Total deformation	64.9 mm









Marking

If you combine sensors with control units and thereby place pressure-sensitive protection devices on the market, you should observe the basic requirements according to ISO 13856.

As well as meeting technical requirements, this also means – in particular – observing any that relate to marking and information for use.

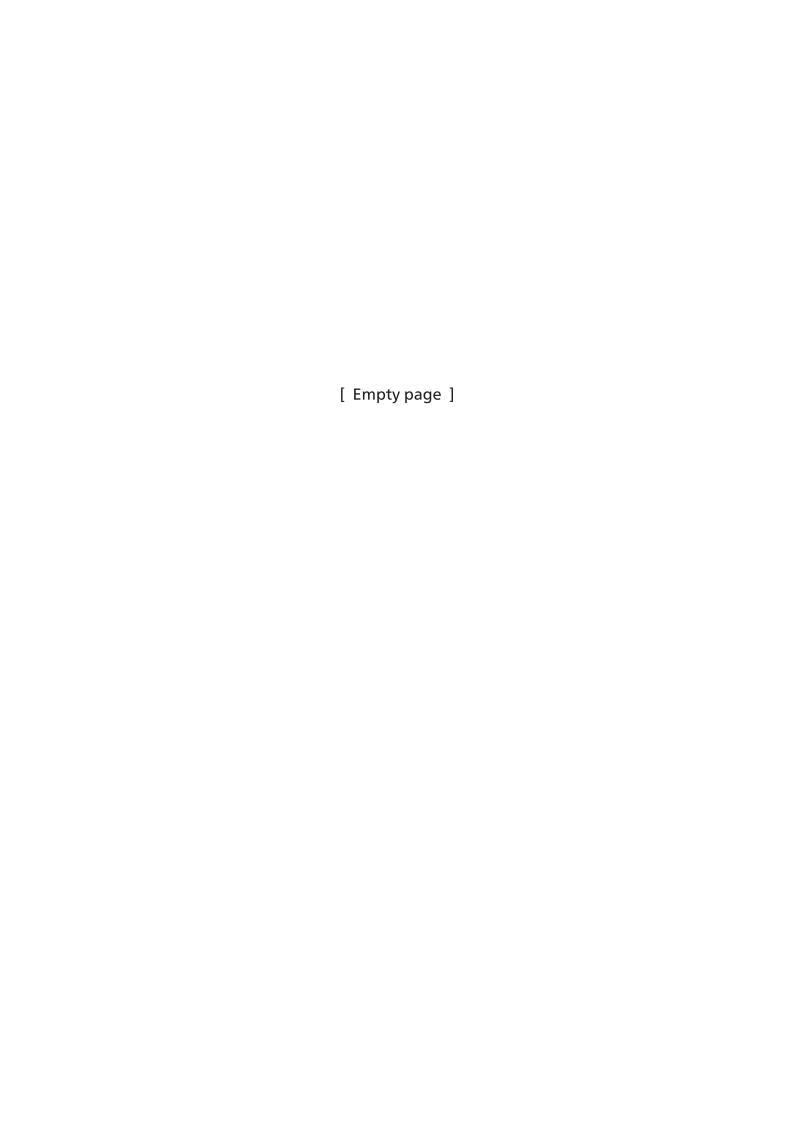
Conformity

EC type examination

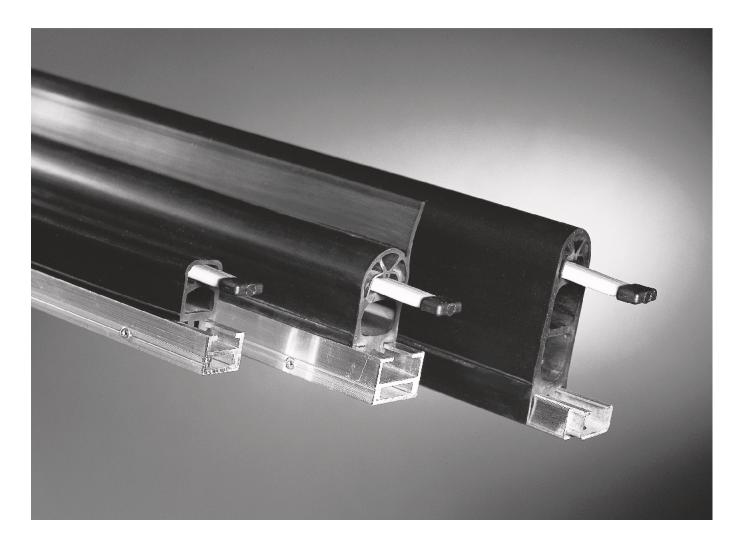
The product has been tested by an independent institute.

There is an EC type examination certificate to confirm conformity.

The EC type examination certificate is stored in the Downloads section of our website: www.mayser.com.







Safety edges SL



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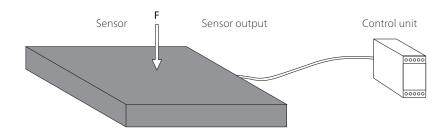
nical data21
GP 15-1 NBR21
GP 22-1 NBR
GP 39-1 NBR25
GP 39-1 EPDM27
GP 39L-1 EPDM
GP 50(L)-1 EPDM31
GP 50-1 CR
GP 60-1 EPDM35
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formity39



Definitions

Pressure-sensitive protection device

A pressure-sensitive protection device consists of one or more pressure-sensitive sensors, a signal processing unit, and one or more output signal switching devices. The control unit is made up of the signal processing unit and output signal switching device(s). The pressure-sensitive protection device is triggered when the sensor is activated.

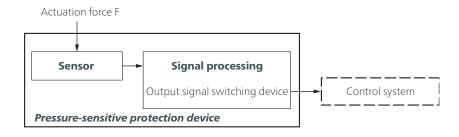


Sensor

The sensor is the part of the pressure-sensitive protection device that generates a signal when the actuation force F is applied. Mayser safety systems feature a sensor whose actuation area is deformed locally.

Signal processing

The signal processing unit is the part of the pressure-sensitive protection device that converts the output signal of the sensor and controls the status of the output signal switching device. The output signal switching device is the part of the signal processing unit which is connected to the forwarding control system and which transmits safety output signals such as STOP.



Tip: Terms are defined in ISO 13856-2 Section 3.

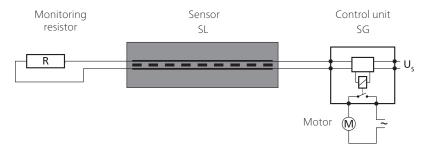
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Criteria for selecting the sensor type

- Category according to ISO 13849-1
- Performance level of the pressure-sensitive protection device
 at least PL_e
- Temperature range
- Degree of protection in accordance with IEC 60529:
 IP67 is standard for safety edges.
 Higher degrees of protection must be checked individually.
- Environmental influences such as swarf, oil, coolant, outdoor use...
- Finger detection necessary?

Tip: For further sensor selection criteria, see ISO 13856-2 Annex C and Annex E.

Operation principle of 2-wire technology



The monitoring resistor must be compatible with the control unit. The standard type is 8k2.

For your safety:

The sensor and connection cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on controlled bridging of the contact surfaces with a monitoring resistor (closed-circuit principle).

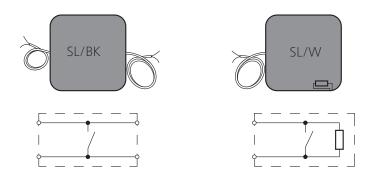


Types

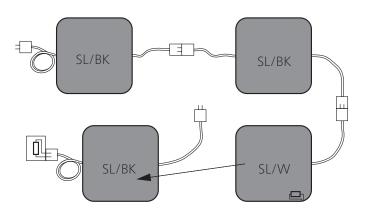
SL/BK With cables on both sides for use as a through sensor or with an external monitoring resistor for use as an end sen-

sor

SL/W With an integrated monitoring resistor for use as an end sensor



Sensor combination

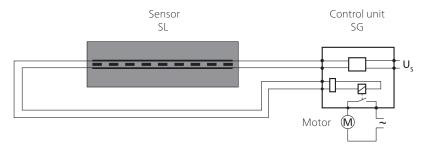


Version with external resistor, therefore no variety of models

Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety edges can be combined to achieve custom lengths and angles

Operation principle of 4-wire technology



The 4-wire technology can only be used together with control unit SG-EFS 104/4L.

For your safety:

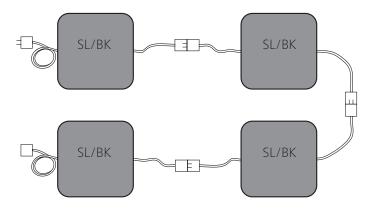
The sensor and connection cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on signal transmission feedback – without a monitoring resistor.

Types

SL/BK With cables on both sides for use as a through sensor



Sensor combination



Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety edges can be combined to achieve custom lengths and angles

Subject to technical modifications.



Safety

Intended use

A safety edge detects a person or part of the body when pressure is applied to the effective actuation area. It is a linear tripping device. Its purpose is to prevent possible hazardous situations that could affect someone within a danger zone, such as shearing and pinching edges. Typical areas of application are door and gate systems, and moving parts on machines, platforms and lifting devices.

Safe operation of a safety edge depends entirely on

- the surface condition of the mounting surface,
- the correct selection of the size and resistance rating as well as
- correct installation.

For additional application guidance, please refer to ISO 13856-2 Annex E.

Due to the design, the actuation area is actually smaller than it looks because of the non-sensitive edges. Once these have been allowed for, what remains is the effective actuation area (see chapter *Effective actuation area*).

Limits

- No more than 10 /BK-type sensors can be connected to one control unit.
- No more than 9 /BK-type sensors and 1 /W-type sensor can be connected to one control unit.

Exclusions

The sensors are not suitable for:

- Detecting fingers.
- Performing a sealing function. Constant actuation of sensors can result in permanent damage.

Exception: The L version with an attached lip seal.

The lip seal can be in full contact with the closing edge, which allows it to repel wind and water.

Other safety aspects

The following safety aspects relate to pressure-sensitive protection devices consisting of a sensor and a control unit.

Performance Level (PL)

The PL has been determined using the procedure defined by ISO 13849-1.

Fault exclusion according to ISO 13849-2 Table D.8: Non-closing of contacts in the case of pressure-sensitive protection devices according to ISO 13856. In this case, the diagnostic coverage (DC) is not calculated or taken into account when determining the PL. Assuming a high MTTF $_{\rm D}$ value for the control unit, a performance level of up to PL d can be achieved by the safety edge system (pressure-sensitive protection device) as a whole.

Is the protection device suitable?

First, the integrator must decide what ${\rm PL_r}$ is required for the hazard. After that, they must select the protection device.

Finally, the integrator needs to check whether the category and PL of the selected protection device are appropriate.

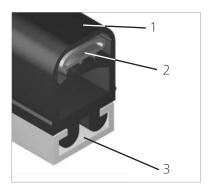
Risk and safety assessment

For the risk and safety assessment of your machine, we recommend ISO 12100 "Safety of machinery — General principles for design".

Without reset function

When a protection device without reset function is used (automatic reset), the reset function must be provided in some other way.

Design



The safety edge SL consists of a sensor (1 to 3) –

- (1) rubber profile GP,
- (2) switch element,
- (3) aluminium profile and an evaluating control unit SG.

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Subject to technical modifications.

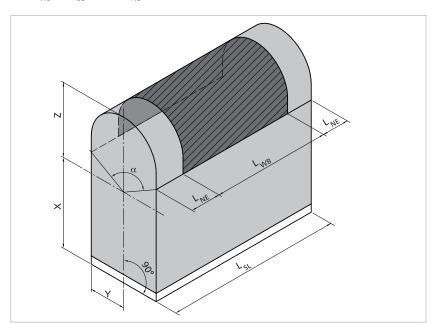


Effective actuation area

The parameters X, Y, Z, L_{WB} and the angle α describe the effective actuation area.

For the effective actuation area, the following applies:

$$L_{WB} = L_{SL} - 2 \times L_{NE}$$



Parameters:

 L_{WB} = effective actuation length

 L_{SL} = overall length of safety edge

 $L_{NE} = non-sensitive length at the end of the safety edge$

 α = effective actuation angle

	GP 15-1	GP 22-1	GP 39-1	GP 39L-1	GP 50(L)-1	GP 60-1	GP 120-1
Aluminium profile	C 15	C 25	C 25	C 25	C 35	C 35	C 35
α	70°	70°	110°	120°	90°	110°	120°
L _{NE}	35 mm	35 mm	35 mm	35 mm	35 mm	35 mm	35 mm
Υ	9.5 mm	12.5 mm	13 mm	14.5 mm	17.5 mm	18 mm	18 mm
X	14 mm	15 mm	33 mm	33 mm	40.5 mm	54.5 mm	110 mm
Z	7 mm	9 mm	7 mm	7 mm	21.5 mm	21.5 mm	19 mm
X + Z	21 mm	24 mm	40 mm	40 mm	62 mm	76 mm	129 mm

At 70°, the effective actuation angle $\,\alpha\,$ of GP 15-1 and GP 22-1 falls below the requirements of ISO 13856-2 and EN 12978.

Installation position

The installation position can be selected as required, i.e. all installation positions from A to D as per ISO 13856-2 are possible.

Subject to technical modifications.

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Connection

Cable exits

- With cable sleeves in some cases
- L-type (L) rubber profiles: the rubber lip is always located on the lefthand side when the product is viewed from the end
- Other designs (e.g. shorter non-sensitive ends) available on request

Cable exit (Cable exit (CE)			SL	GP		
		15-1	22-1	39 (L)-1	50 (L)-1	60-1	120-1
Distance betw. CE & en	At the bottom Distance betw. CE & end = 25 mm in each case; versions with cable sleeves						
Version 11: SL/W				•	•	•	•
Version 5: SL/BK				•	•	•	•
At the sid Distance betw. CE & en each case; versions witho	d = 25 mm in						
Version 12: SL/W				•	•	•	
Version 13: SL/W				•	•	•	
Version 14: SL/BK				•	•	•	
Axial exit at Versions without cal							
Version 9: SL/W		•	•	•	•	•	•
Version 10: SL/W				•	•	•	•
Version 1: SL/BK		•	•	•	•	•	•
Version 3: SL/BK				•	•	•	•
Version 4: SL/BK				•	•	•	•

• = available

Subject to technical modifications.



Cable connection

Standard cable lengths
 L = 2.0 m / 5.0 m / 10 m

• Maximum total cable length to the control unit $L_{max} = 100 \text{ m}$

• Cable ends: stripped wires
Option: Cable ends available with plug and coupling

/W-type sensor with 1 line	/BK-type sensor with 2 lines
 As an individual /W-type sensor or a /W-type end sensor Integrated resistor Two-wire cables 	 As a /BK-type through sensor Without resistor 2 two-wire cables

Wire colours

/W-type sensor with 1 line	/BK-type sensor with 2 lines
RD I BK	RD ← — — → RD

Connection examples

Key:

SG 2W Evaluation with 2-wire technology SG 4L Evaluation with 4-wire technology

Subject to technical modifications.

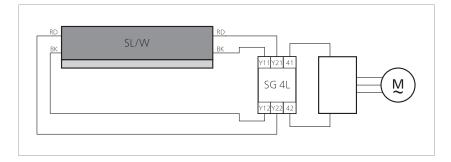
Colour coding

Black

Red

ВК

RD



Sensor surface

Resistance

The resistance ratings listed below (at a room temperature of 23 $^{\circ}$ C) depend on the sensor having an undamaged surface.

Physical resistance

Rubber profile GP	EPDM	NBR	CR
UV resistance	Yes	Yes	Yes

Chemical resistance

The sensor is broadly resistant to normal chemical influences such as diluted acids and alkalis, as well as alcohol, over an exposure period of 24 hrs.

The values in the table are the results of tests carried out in our laboratory. You must always conduct your own practical tests to verify that our products are suitable for your specific area of application.

Explanation of symbols:

+ = resistant

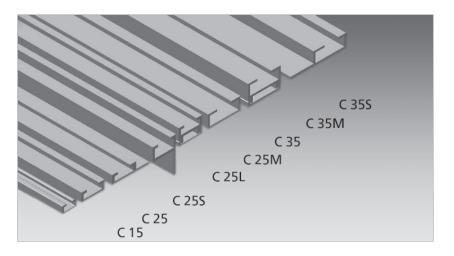
 \pm = resistant to a certain extent

– = not resistant

Chemical resistance	EPDM	NBR	CR
Acetone	+	±	+
Formic acid	+	+	+
Ammonia	+	+	+
Petrol	_	+	+
Brake fluid	<u>±</u>	±	<u>±</u>
Chloride solutions	+	+	+
Diesel oil	_	+	+
Greases	_	+	+
Household/sanitary cleaners	+	+	+
Isopropanol	+	+	+
Cooling lubricant	_	+	+
Metal working oil	_	+	+
Methanol	+	+	±
Oils	_	+	+
Ozone and weather conditions	+	_	+
Hydrochloric acid 10%	+	+	+
Ethyl alcohol (ethanol)	+	+	+
Carbon tetrachloride	_	+	+
Water and frost	+	_	+
Hydrogen peroxide 10%	+	+	_

Mounting

The sensors are mounted directly onto the main and secondary closing edges that present a danger. They are fixed using special aluminium profiles. The profiles are fastened with screws or rivets.



Material properties

- AlMgSi0.5 F22
- Wall thickness: at least 2.0 mm
 C 15: at least 1.7 mm
- Extruded
- Hot hardened
- Tolerances as per EN 755-9

Subject to technical modifications.

Aluminium profiles:

Overview of combinations

Sensor pr	ofile foot	C 15	C 25 C 25M C 25S C 25L	C 25 C 25M C 25S C 25L	C 35 C 35M C 35S	C 35 C 35M C 35S	C 35 C 35M C 35S
Snap-in foot (middle)	1	GP 15-1	GP 22-1	GP 39(L)-1	GP 50(L)-1	GP 60-1	GP 120-1

Aluminium profiles: Mounting types

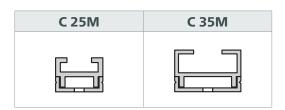
Standard profile

First the aluminium profile must be mounted onto the closing edge and then the sensor profile clipped into the aluminium profile.

C 15	C 25	C 35

Two-part profile, type M

For convenient assembly and disassembly. The sensor profile is clipped into the upper section and the upper section inserted into the installed lower section and fastened.



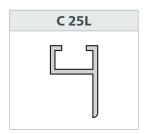
Flange profile, type S

Final assembly is also possible when the sensor profile is already clipped into the aluminium profile.

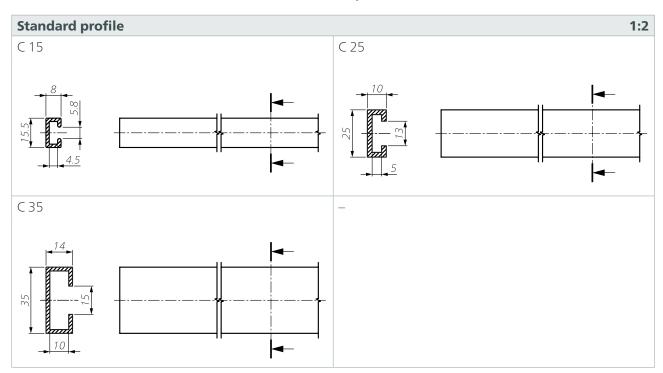
C 25S	C 35S

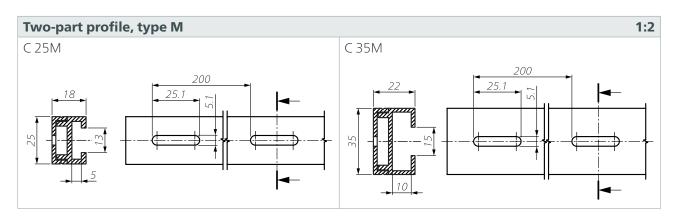
Angle profile, type L

If the closing edge should not or must not have assembly holes, this "round-the-corner" solution is suitable. Final assembly is also possible when the sensor profile is already clipped into the aluminium profile.

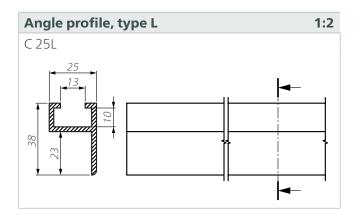


Aluminium profiles: Dimensions





Subject to technical modifications.





s₁ = Stopping distance of the dangerous movement [mm]

- v = Velocity of the dangerous movement [mm/s]
- T = Follow-through time of the complete system [s]
- t_1 = Safety edge response time
- t₂ = Stopping time of the machine
- s = Minimum overtravel distance of the safety edge to ensure that the stipulated limit forces are not exceeded [mm]
- C = Safety factor; if components susceptible to failures (braking system) exist in the system, a higher factor must be selected.

SL: Making the right selection

Calculation for selection of the safety edge height

The stopping distance of the dangerous movement is calculated using the following formula:

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$

In accordance with ISO 13856-2, the minimum overtravel distance of the safety edge is calculated using the following formula:

$$s = s_1 \times C$$
 where: $C = 1.2$

A suitable safety edge profile can now be selected based on the result. For details of the overtravel distances for safety edge profiles, see chapter *Technical data*.

Calculation examples

Calculation example 1

The dangerous movement on your machine has a velocity of v=10~mm/s and can be brought to a standstill within $t_2=190~\text{ms}$. The relatively low velocity suggests that a short overtravel distance is to be expected. Therefore, the normally closed safety edge SL GP 39-1 EPDM might be sufficient. The response time of the safety edge is $t_1=435~\text{ms}$.

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$
 $s_1 = 1/2 \times 10 \text{ mm/s} \times (435 \text{ ms} + 190 \text{ ms})$
 $s_1 = 1/2 \times 10 \text{ mm/s} \times 0.625 \text{ s} = 3.1 \text{ mm}$

$$s = s_1 \times C$$
 where: $C = 1.2$

 $s = 3.1 \text{ mm} \times 1.2 = 3.8 \text{ mm}$

The safety edge must have a minimum overtravel distance of s = 3.8 mm. The selected SL GP 39-1 EPDM has an overtravel distance of at least 10.9 mm. This is more than the required 3.8 mm.

Result: The SL GP 39-1 EPDM is **suitable** for this case.

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Calculation example 2

The same conditions apply as in calculation example 1 with the exception of the velocity of the dangerous movement. This is now v = 100 mm/s. As a result, the response time of the safety edge is reduced to $t_1 = 59$ ms.

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$
 $s_1 = 1/2 \times 100 \text{ mm/s} \times (59 \text{ ms} + 190 \text{ ms})$
 $s_1 = 1/2 \times 100 \text{ mm/s} \times 0.249 \text{ s} = 12.5 \text{ mm}$

$$s = s_1 \times C$$
 where: $C = 1.2$

$$s = 12.5 \text{ mm} \times 1.2 = 15.0 \text{ mm}$$

The safety edge must have a minimum overtravel distance of s = 15.0 mm. The selected SL GP 39-1 EPDM has an overtravel distance of at least 7.7 mm. This is less than the required 15.0 mm.

Result: The SL GP 39-1 EPDM is **not suitable** for this case.

Calculation example 3

The same conditions as in calculation example 2. Instead of the SL GP 39-1 EPDM, the SL GP 120-1 EPDM is selected. The response time of the safety edge is $t_1 = 95$ ms.

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$
 $s_1 = 1/2 \times 100 \text{ mm/s} \times (95 \text{ ms} + 190 \text{ ms})$
 $s_1 = 1/2 \times 100 \text{ mm/s} \times 0.285 \text{ s} = 14.3 \text{ mm}$
 $s = s_1 \times C$ where: $C = 1.2$

$$s = 14.3 \text{ mm} \times 1.2 = 17.2 \text{ mm}$$

The safety edge must have a minimum overtravel distance of s=17.2 mm. With a velocity of 100 mm/s, the selected SL GP 120-1 EPDM has an overtravel distance of at least 17.7 mm. This is more than the required 17.2 mm.

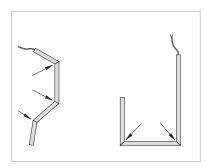
Result: The SL GP 120-1 EPDM is **suitable** for this case.



Customised designs

In addition to the standard range, special solutions are also possible, such as:

- Safety edges with sensitive ends
- Resistance to high temperatures:
 - short-term (< 15 min) up to +80 °C
 - long-term up to +55 °C
 - with degree of protection: IP50
- Resistance to low temperatures:
 - long-term down to −20 °C
- Angled safety edges with sensitive zones in the corner areas
- Safety edges GP 39-1, GP 50-1, GP 60-1 and GP 120-1 can be supplied with sensitive ends



Maintenance and cleaning

The sensors are virtually maintenance-free.

The control unit also monitors the sensor at the same time.

Regular inspection

Depending on the operational demands, the sensors must be inspected at regular intervals (at least monthly)

- for proper functioning,
- for damage and
- for correct mounting.

Cleaning

If the sensors become dirty, they can be cleaned with a mild cleaning product.

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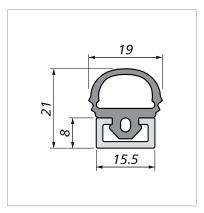


GP 15-1 NBR

Safety edge	SL/W GP 15-1 NBR with SG-EFS 104/2W
Testing basis	In accordance with ISO 13856-2
Switching characteristics at v _{test} =	= 10 mm/s
Switching operations Actuation force	10,000
Test piece (cylinder) Ø 80 mm Actuation distance	< 139 N
Test piece (cylinder) Ø 80 mm Actuation angle	2.8 mm
Test piece (cylinder) Ø 80 mm	±35°
Response time	295 ms
Finger detection	No
Safety classifications	
ISO 13856: reset function	With/without
ISO 13849-1:2015	Category 3 PL d
MTTF _D (PSPD)	192 a
MTTF _D (sensor)	761 a
B _{10D} (sensor)	4×10^{6}
n _{op} (assumption)	52,560/a
Mechanical operating conditions	5
Sensor length (min./max.)	20 cm / 6 m
Cable length (min./max.) Bend radii, minimum	2.0 m / 100 m
B_1 / B_2 / B_3 / B_4 Bend angles, maximum	Not possible
K ₁ / K ₂ / K ₃ / K ₄	Not possible
Operating velocity	10 mm/s
Load capacity (max.)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: degree of protection	IP67
Humidity (max. at 23 °C)	95% (non-condensing)
Operating temperature	-10 to +50 °C
Storage temperature	−10 to +50 °C
Weight (without / with aluminium profile C 15)	0.14 / 0.28 kg/m
Electrical operating conditions	
Connection cable	Ø 3.8 mm TPU, 2 × 0.25 mm ²
Sensor	24 V DC / max. 10 mA
Number of /BK-type sensors	Max. 10 in series



GP 15-1 NBR (1:1)



Dimensional tolerances according to ISO 3302 E2/L2

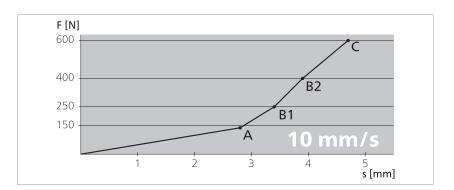
Test conditions

according to ISO 13856-2

- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.

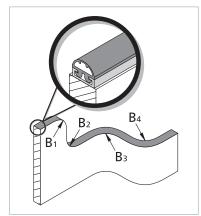
Test velocity	10 mm/s
Actuation force	139 N
Response time	280 ms
Actuation distance (A)	2.8 mm
Overtravel distance	
Up to 250 N (B1)	0.6 mm
Up to 400 N (B2)	1.1 mm
Up to 600 N (C)	1.9 mm
Total deformation	4.7 mm

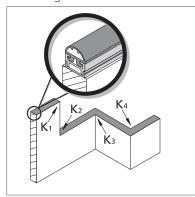


GP 22-1 NBR

Safety edge	SL/W GP 22-1 NBR with SG-EFS 104/2W
Testing basis	In accordance with ISO 13856-2
Switching characteristics at v _{test} =	10 mm/s
Switching operations	10,000
Actuation force Test piece (cylinder) Ø 80 mm	< 60 N
Actuation distance	2.1
Test piece (cylinder) Ø 80 mm Actuation angle	3.1 mm
Test piece (cylinder) Ø 80 mm	±35°
Response time	325 ms
Finger detection	No
Safety classifications	
ISO 13856: reset function	With/without
ISO 13849-1:2015	Category 3 PL d
MTTF _D (PSPD)	192a
MTTF _D (sensor)	761a
B _{10D} (sensor)	4×10^{6}
n _{op} (assumption)	52,560/a
Mechanical operating conditions	
Sensor length (min./max.)	20 cm / 6 m
Cable length (min./max.)	2.0 m / 100 m
Bend radii, minimum	With C 25 only
B ₁ / B ₂ / B ₃ / B ₄	300 / 350 / 300 / 300 mm
Bend angles, maximum	
K ₁ / K ₂ / K ₃ / K ₄	25° / 10° / 90° / 90°
Operating velocity	10 mm/s
Load capacity (max.)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: degree of protection	IP67
Humidity (max. at 23 °C)	95% (non-condensing)
Operating temperature	+5 to +40 °C
Storage temperature	+5 to +40 °C
Weight (without / with aluminium profile C 25)	0.26 / 0.58 kg/m
Electrical operating conditions	<u> </u>
Connection cable	Ø 3.8 mm TPU, 2 × 0.25 mm ²
Sensor	24 V DC / max. 10 mA
Number of /BK-type sensors	Max. 10 in series
71	1

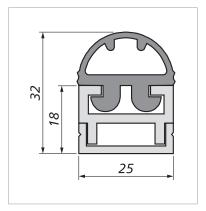
Bend radii:







GP 22-1 NBR (1:1)



Dimensional tolerances according to ISO 3302 E2/L2

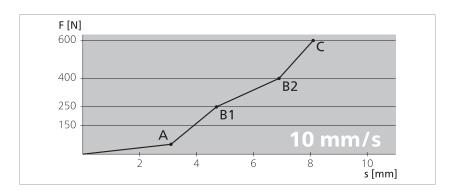
Test conditions

according to ISO 13856-2

- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.

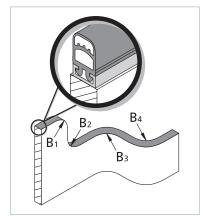
Test velocity	10 mm/s
Actuation force	60 N
Response time	310 ms
Actuation distance (A)	3.1 mm
Overtravel distance	
Up to 250 N (B1)	1.6 mm
Up to 400 N (B2)	3.8 mm
Up to 600 N (C)	5.0 mm
Total deformation	8.1 mm

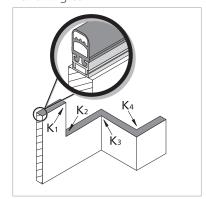


GP 39-1 NBR

Safety edge	SL/W GP 39-1 NBR with SG-EFS 104/2W
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} =	100 mm/s
Switching operations Actuation force Test piece (cylinder) Ø 80 mm Actuation distance	10,000 < 150 N 3.5 mm
Test piece (cylinder) Ø 80 mm Actuation angle Test piece (cylinder) Ø 80 mm Response time Finger detection	±55° 50 ms No
Safety classifications	
ISO 13856: reset function ISO 13849-1:2015 MTTF _D (PSPD) MTTF _D (sensor) B_{10D} (sensor) n_{op} (assumption)	With/without Category 3 PL d 192 a 761a 4 × 10 ⁶ 52,560/a
Mechanical operating conditions	
Sensor length (min./max.) Cable length (min./max.) Bend radii, minimum B ₁ / B ₂ / B ₃ / B ₄ Bend angles, maximum K ₁ / K ₂ / K ₃ / K ₄ Operating velocity (min. / max.) Load capacity (max.) Tensile load, cable (max.) IEC 60529: degree of protection Humidity (max. at 23 °C) Operating temperature Storage temperature Weight (without / with aluminium profile C 25)	20 cm / 6 m 2.0 m / 100 m With C 25 only 300 / 350 / 300 / 300 mm 20° / 10° / 90° / 90° 10 mm/s / 100 mm/s 600 N 20 N IP67 95% (non-condensing) -10 to +50 °C -10 to +50 °C 0.51 / 0.83 kg/m
Electrical operating conditions	
Connection cable Sensor Number of /BK-type sensors	Ø 3.8 mm TPU, 2 × 0.25 mm ² 24 V DC / max. 10 mA Max. 10 in series

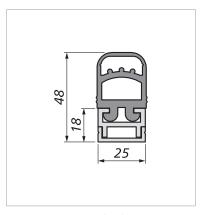
Bend radii:







GP 39-1 NBR (1:2)



Dimensional tolerances according to ISO 3302 E2/L2

Test conditions

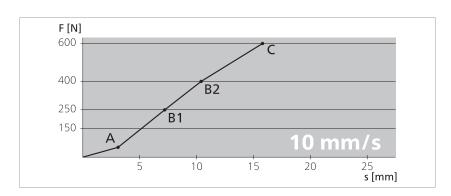
according to ISO 13856-2

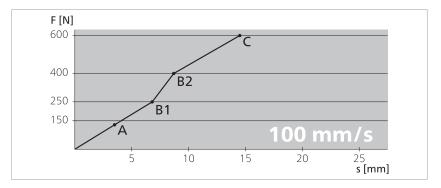
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.



Test velocity 10	00 mm/s
Actuation force	129 N
Response time	35 ms
Actuation distance (A)	3.5 mm
Overtravel distance	
Up to 250 N (B1)	3.3 mm
Up to 400 N (B2)	5.2 mm
Up to 600 N (C)	11.0 mm
Total deformation	14.5 mm

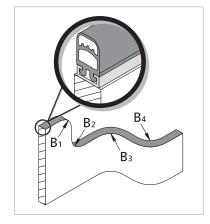


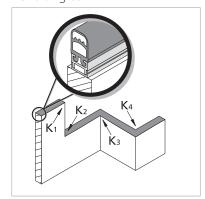


GP 39-1 EPDM

Safety edge	SL/W GP 39-1 EPDM with SG-EFS 104/2W
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} =	: 100 mm/s
Switching operations Actuation force	10,000
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	4.4 mm
Test piece (cylinder) Ø 80 mm Response time Finger detection	±40° 59 ms
Safety classifications	TVO
ISO 13856: reset function ISO 13849-1:2015 MTTF _D (PSPD) MTTF _D (sensor) B _{10D} (sensor) n _{op} (assumption)	With/without Category 3 PL d 192 a 761 a 4 × 10 ⁶ 52,560/a
Mechanical operating conditions	
Sensor length (min./max.) Cable length (min./max.) Bend radii, minimum B1 / B2 / B3 / B4 Bend angles, maximum K1 / K2 / K3 / K4 Operating velocity (min. / max.) Load capacity (max.) Tensile load, cable (max.) IEC 60529: degree of protection Humidity (max. at 23 °C) Operating temperature Storage temperature Weight (without / with aluminium	20 cm / 6 m 2.0 m / 100 m With C 25 only 300 / 350 / 300 / 300 mm 20° / 10° / 90° / 90° 10 mm/s / 100 mm/s 600 N 20 N IP67 95% (non-condensing) -20 to +55 °C
profile C 25)	0.43 / 0.75 kg/m
Electrical operating conditions	
Connection cable Sensor Number of /BK-type sensors	Ø 3.7 mm TPE, 2 × 0.22 mm ² 24 V DC / max. 10 mA Max. 10 in series

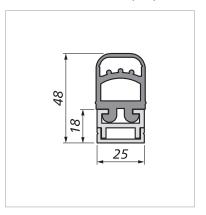
Bend radii:







GP 39-1 EPDM (1:2)



Dimensional tolerances according to ISO 3302 E2/L2

Test conditions

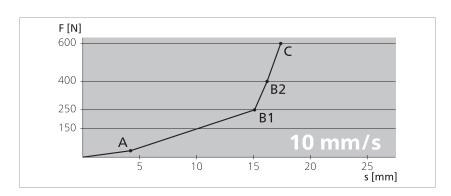
according to ISO 13856-2

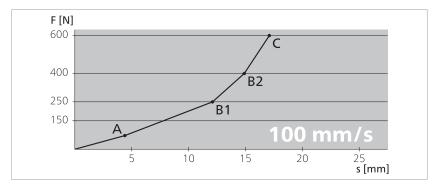
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.

Test velocity	10 mm/s
Actuation force	34 N
Response time	420 ms
Actuation distance (A)	4.2 mm
Overtravel distance	
Up to 250 N (B1)	10.9 mm
Up to 400 N (B2)	12.0 mm
Up to 600 N (C)	13.2 mm
Total deformation	17.4 mm

Test velocity 1	00 mm/s
Actuation force	72 N
Response time	44 ms
Actuation distance (A)	4.4 mm
Overtravel distance	
Up to 250 N (B1)	7.7 mm
Up to 400 N (B2)	10.5 mm
Up to 600 N (C)	12.7 mm
Total deformation	17.1 mm

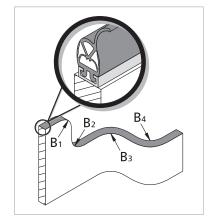


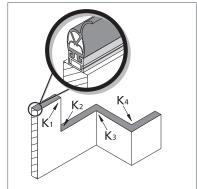


GP 39L-1 EPDM

Safety edge	SL/W GP 39L-1 EPDM with SG-EFS 104/2W
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} =	: 100 mm/s
Switching operations Actuation force Test piece (cylinder) Ø 80 mm Actuation distance	10,000 < 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	18.9 mm
Test piece (cylinder) Ø 80 mm Response time Finger detection	±60° 204 ms No
Safety classifications	
ISO 13856: reset function ISO 13849-1:2015 MTTF _D (PSPD) MTTF _D (sensor) B_{10D} (sensor) n_{op} (assumption)	With/without Category 3 PL d 192 a 761 a 4 × 10 ⁶ 52,560/a
Mechanical operating conditions	
Sensor length (min./max.) Cable length (min./max.) Bend radii, minimum B ₁ / B ₂ / B ₃ / B ₄ Bend angles, maximum K ₁ / K ₂ / K ₃ / K ₄ Operating velocity (min. / max.) Load capacity (max.) Tensile load, cable (max.) IEC 60529: degree of protection Humidity (max. at 23 °C) Operating temperature Storage temperature Weight (without / with aluminium profile C 25)	20 cm / 6 m 2.0 m / 100 m With C 25 only 300 / 350 / 300 / 300 mm 20° / 10° / 90° / 90° 10 mm/s / 100 mm/s 600 N 20 N IP67 95% (non-condensing) -20 to +55 °C -20 to +55 °C 0.52 / 0.84 kg/m
Electrical operating conditions	
Connection cable Sensor Number of /BK-type sensors	Ø 3.7 mm TPE, 2 × 0.22 mm ² 24 V DC / max. 10 mA Max. 10 in series

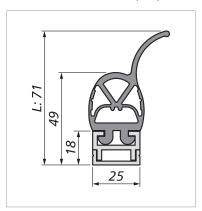
Bend radii:







GP 39L-1 EPDM (1:2)



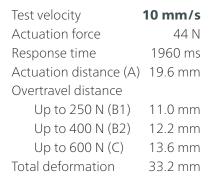
Dimensional tolerances according to ISO 3302 E2/L2

Test conditions

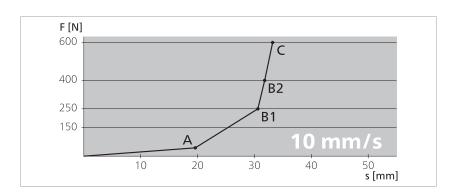
according to ISO 13856-2

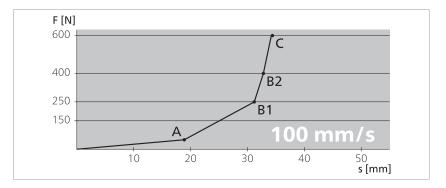
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.



Test velocity 1	00 mm/s
Actuation force	50 N
Response time	189 ms
Actuation distance (A)	18.9 mm
Overtravel distance	
Up to 250 N (B1)	12.3 mm
Up to 400 N (B2)	13.9 mm
Up to 600 N (C)	14.5 mm
Total deformation	34.4 mm

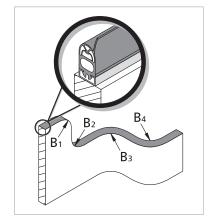


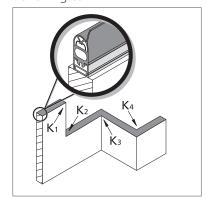


GP 50(L)-1 EPDM

Safety edge	SL/W GP 50(L)-1 EPDM with SG-EFS 104/2W
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} =	= 100 mm/s
Switching operations Actuation force	10,000
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	6.3 mm
Test piece (cylinder) Ø 80 mm	±45°
Response time	78 ms
Finger detection	No
Safety classifications	
ISO 13856: reset function	With/without
ISO 13849-1:2015	Category 3 PL d
MTTF _D (PSPD)	192 a
MTTF _D (sensor)	761 a
B _{10D} (sensor)	4×10^6
n _{op} (assumption)	52,560/a
Mechanical operating conditions	
Sensor length (min./max.)	20 cm / 6 m
Cable length (min./max.)	2.0 m / 100 m
Bend radii, minimum	With C 35 only
B ₁ / B ₂ / B ₃ / B ₄	400 / 450 / 550 / 550 mm
Bend angles, maximum K ₁ / K ₂ / K ₃ / K ₄	15° / 10° / 90° / 90°
Operating velocity	13 / 10 / 90 / 90
(min. / max.)	10 mm/s / 100 mm/s
Load capacity (max.)	600 N
Tensile load, cable (max.)	20 N
IEC 60529: degree of protection	IP67
Humidity (max. at 23 °C)	95% (non-condensing)
Operating temperature	−20 to +55 °C
Storage temperature	−20 to +55 °C
Weight (without / with aluminium	
profile C 35)	1.1 / 1.5 kg/m
Electrical operating conditions	
Connection cable	Ø 3.7 mm TPE, 2 × 0.22 mm ²
Sensor	24 V DC / max. 10 mA
Number of /BK-type sensors	Max. 10 in series

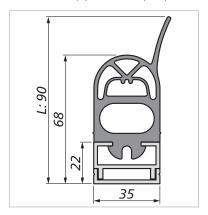
Bend radii:







GP 50(L)-1 EPDM (1:2)



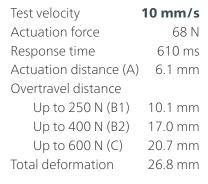
Dimensional tolerances according to ISO 3302 E2/L2

Test conditions

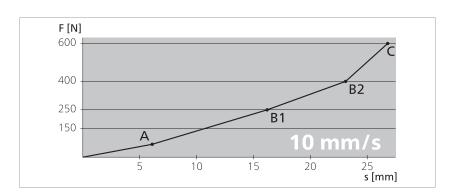
according to ISO 13856-2

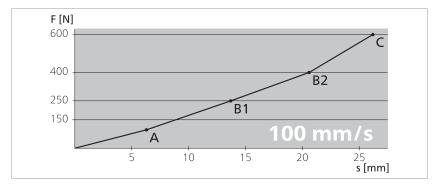
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.



Test velocity 1	00 mm/s
Actuation force	97 N
Response time	63 ms
Actuation distance (A)	6.3 mm
Overtravel distance	
Up to 250 N (B1)	7.4 mm
Up to 400 N (B2)	14.3 mm
Up to 600 N (C)	19.9 mm
Total deformation	26.2 mm

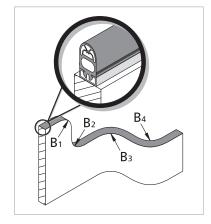


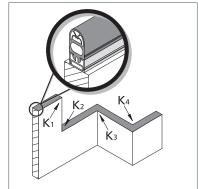


GP 50-1 CR

Safety edge	SL/W GP 50-1 CR with SG-EFS 104/2W
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} =	= 100 mm/s
Switching operations	10,000
Actuation force	
Test piece (cylinder) Ø 80 mm	< 150 N
Actuation distance Test piece (cylinder) Ø 80 mm	4.8 mm
Actuation angle	4.011111
Test piece (cylinder) Ø 80 mm	±45°
Response time	63 ms
Finger detection	No
Safety classifications	
ISO 13856: reset function	With/without
ISO 13849-1:2015	Category 3 PL d
MTTF _D (PSPD)	192 a
MTTF _D (sensor)	761 a
B _{10D} (sensor)	4×10^{6}
n _{op} (assumption)	52,560/a
Mechanical operating conditions	5
Sensor length (min./max.)	20 cm / 6 m
Cable length (min./max.)	2.0 m / 100 m
Bend radii, minimum	With C 35 only
B ₁ / B ₂ / B ₃ / B ₄	400 / 450 / 550 / 550 mm)
Bend angles, maximum	
K ₁ / K ₂ / K ₃ / K ₄	15° / 10° / 90° / 90°
Operating velocity	10 00 00 /5 / 100 00 00 /5
(min. / max.)	10 mm/s / 100 mm/s 600 N
Load capacity (max.)	20 N
Tensile load, cable (max.) IEC 60529: degree of protection	IP67
Humidity (max. at 23 °C)	95% (non-condensing)
Operating temperature	-20 to +55 °C
Storage temperature	-20 to +55 °C
Weight (without / with aluminium	2010 733 C
profile C 35)	1.05 / 1.45 kg/m
Electrical operating conditions	<u> </u>
Connection cable	Ø 3.8 mm TPU, 2 × 0.25 mm ²
Sensor	24 V DC / max. 10 mA
Number of /BK-type sensors	Max. 10 in series

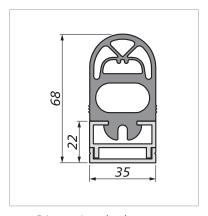
Bend radii:







GP 50-1 CR (1:2)



Dimensional tolerances according to ISO 3302 E2/L2

Test conditions

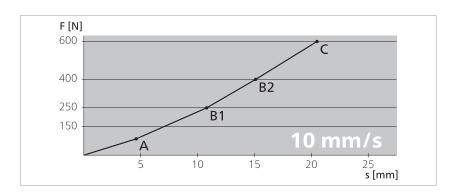
according to ISO 13856-2

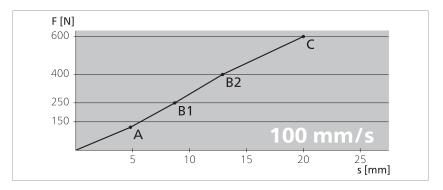
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.



Test velocity 1	00 mm/s
Actuation force	121 N
Response time	48 ms
Actuation distance (A)	4.8 mm
Overtravel distance	
Up to 250 N (B1)	3.9 mm
Up to 400 N (B2)	8.1 mm
Up to 600 N (C)	15.2 mm
Total deformation	20.0 mm

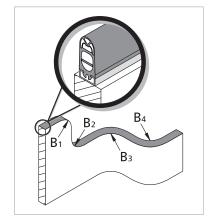


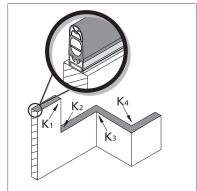


GP 60-1 EPDM

Safety edge	SL/W GP 60-1 EPDM with SG-EFS 104/2W	
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2	
Switching characteristics at v _{test} = 100 mm/s		
Switching operations Actuation force	10,000	
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N	
Test piece (cylinder) Ø 80 mm Actuation angle	5.5 mm	
Test piece (cylinder) Ø 80 mm	±60°	
Response time	70 ms	
Finger detection	No	
Safety classifications		
ISO 13856: reset function ISO 13849-1:2015 MTTF _D (PSPD) MTTF _D (sensor) B_{10D} (sensor) n_{op} (assumption)	With/without Category 3 PL d 192 a 761 a 4 × 10 ⁶ 52,560/a	
Mechanical operating conditions		
Sensor length (min./max.) Cable length (min./max.) Bend radii, minimum B1 / B2 / B3 / B4 Bend angles, maximum K1 / K2 / K3 / K4 Operating velocity (min. / max.) Load capacity (max.) Tensile load, cable (max.) IEC 60529: degree of protection Humidity (max. at 23 °C) Operating temperature Storage temperature Weight (without / with aluminium profile C 35)	20 cm / 6 m 2.0 m / 100 m With C 35 only 450 / 550 / 550 / 550 mm 15° / 10° / 90° / 90° 10 mm/s / 100 mm/s 600 N 20 N IP67 95% (non-condensing) -20 to +55 °C -20 to +55 °C 1.16 / 1.56 kg/m	
Electrical operating conditions		
Connection cable Sensor Number of /BK-type sensors	Ø 3.7 mm TPE, 2 × 0.22 mm ² 24 V DC / max. 10 mA Max. 10 in series	

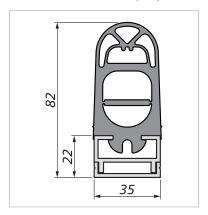
Bend radii:







GP 60-1 EPDM (1:2)



Dimensional tolerances according to ISO 3302 E2/L2

Test conditions

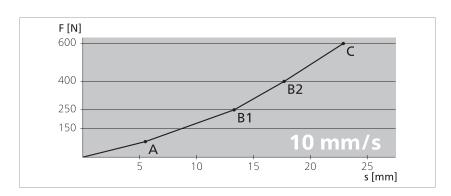
according to ISO 13856-2

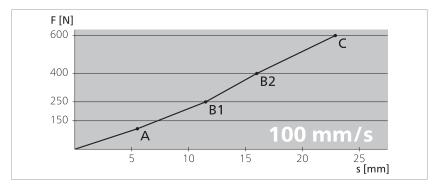
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.



Test velocity 1	00 mm/s
Actuation force	108 N
Response time	55 ms
Actuation distance (A)	5.5 mm
Overtravel distance	
Up to 250 N (B1)	6.0 mm
Up to 400 N (B2)	10.5 mm
Up to 600 N (C)	17.3 mm
Total deformation	22.8 mm

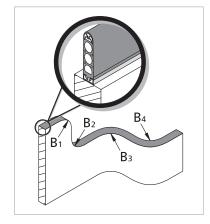


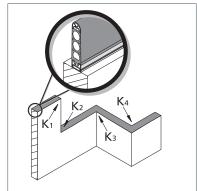


GP 120-1 EPDM

Safety edge	SL/W GP 120-1 EPDM with SG-EFS 104/2W
Testing basis	EN 12978, ISO 13849-1, ISO 13856-2
Switching characteristics at v _{test} =	= 100 mm/s
Switching operations Actuation force	10,000
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	8.0 mm
Test piece (cylinder) Ø 80 mm	±60°
Response time	95 ms
Finger detection	No
Safety classifications	
ISO 13856: reset function	With/without
ISO 13849-1:2015	Category 3 PL d
MTTF _D (PSPD)	192 a
MTTF _D (sensor)	761 a
B _{10D} (sensor)	4×10^{6}
n _{op} (assumption)	52,560/a
Mechanical operating conditions	3
Sensor length (min./max.)	20 cm / 6 m
Cable length (min./max.)	2.0 m / 100 m
Bend radii, minimum	With C 35 only
B ₁ / B ₂ / B ₃ / B ₄	-/-/550/550 mm
Bend angles, maximum	
K ₁ / K ₂ / K ₃ / K ₄	15° / 10° / 90° / 90°
Operating velocity	10 / 100 /
(min. / max.)	10 mm/s / 100 mm/s
Load capacity (max.)	600 N 20 N
Tensile load, cable (max.) IEC 60529: degree of protection	IP67
Humidity (max. at 23 °C)	95% (non-condensing)
Operating temperature	-10 to +50 °C
Storage temperature	-10 to +50 °C
Weight (without / with aluminium	10 10 100
profile C 35)	2.24 / 2.64 kg/m
Electrical operating conditions	·
Connection cable	Ø 3.7 mm TPE, 2 × 0.22 mm ²
Sensor	24 V DC / max. 10 mA
Number of /BK-type sensors	Max. 10 in series

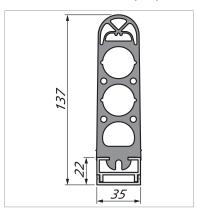
Bend radii:







GP 120-1 EPDM (1:3)



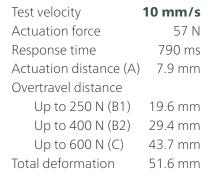
Dimensional tolerances according to ISO 3302 E2/L2

Test conditions

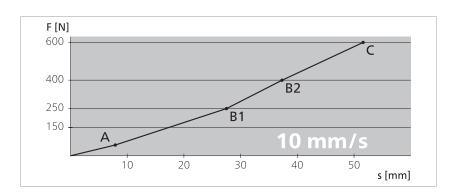
according to ISO 13856-2

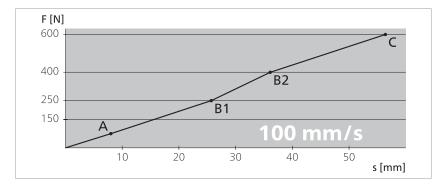
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.



Test velocity 1	00 mm/s
Actuation force	75 N
Response time	80 ms
Actuation distance (A)	8.0 mm
Overtravel distance	
Up to 250 N (B1)	17.7 mm
Up to 400 N (B2)	28.1 mm
Up to 600 N (C)	48.4 mm
Total deformation	56.4 mm







Conformity

The CE symbol indicates that this Mayser product complies with the relevant EC directives and that the stipulated conformity assessments have been carried out.



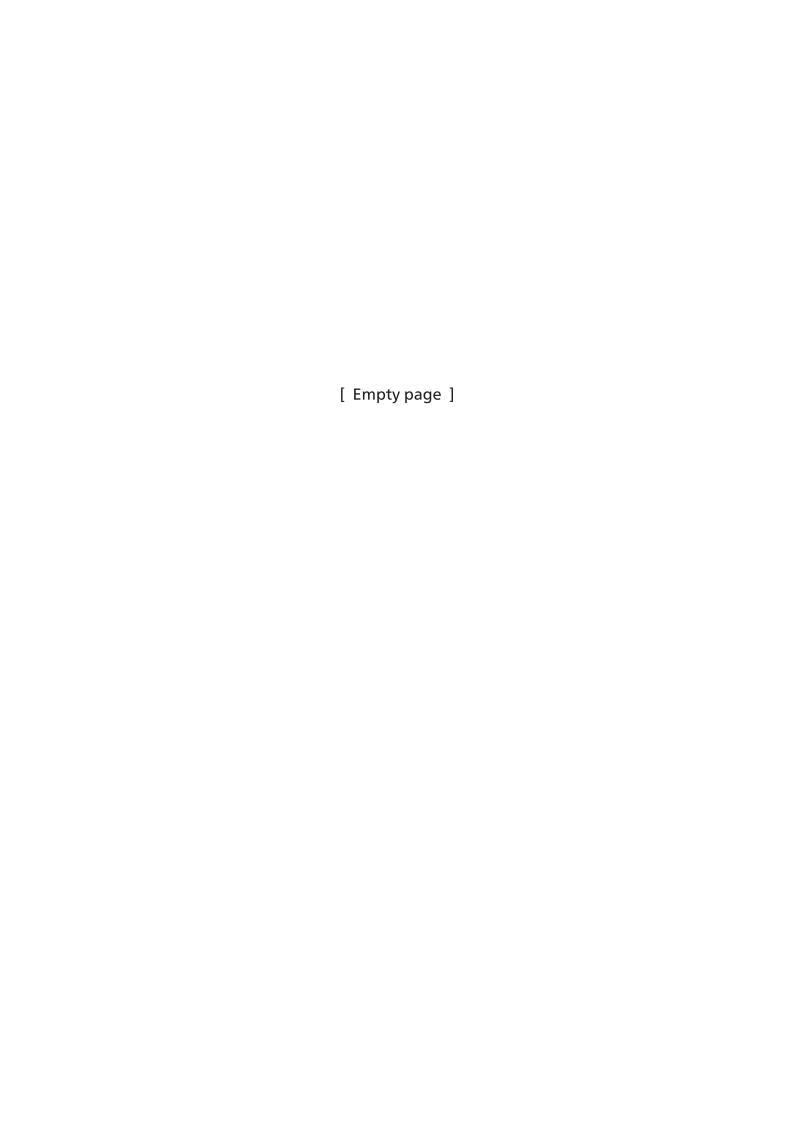
The design type of the product complies with the basic requirements of the following directives:

- 2006/42/EC (Safety of Machinery)
- 2011/65/EU (RoHS)
- 2014/30/EU (EMC)

The Declaration of Conformity is available in the Downloads section of our website:

www.mayser.com/de/download.

www.mayser.com







Normally closed safety edges SL NC II



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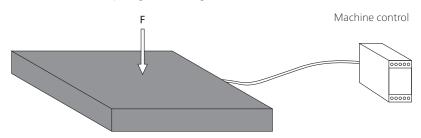


Definitions

Pressure-sensitive protection device

A pressure-sensitive protection device consists of pressure-sensitive sensor(s), signal processing and output signal switching device(s). A pressure-sensitive protection device with switching type NC combines a sensor and an output signal switching device. That means that such a pressure-sensitive protection device can be used without a control unit. The pressure-sensitive protection device is triggered when the sensor is activated.

Sensor with output signal switching device

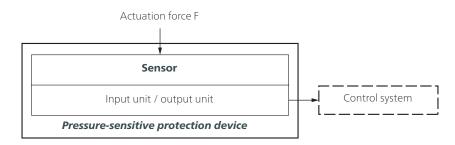


Sensor

The sensor is the part of the pressure-sensitive protection device that generates a signal when the actuating force F is applied. Mayser safety systems have a sensor whereby the actuating surface is deformed locally.

Signal processing

A pressure-sensitive protection device with switching type NC is designed only with an input and output unit for signal processing. The output unit is connected directly to the downstream control.



Tip: Terms are defined in ISO 13856-1, Chapter 3.

050320 v2.11-RiA

Criteria for selecting the sensor type

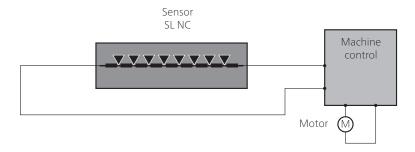
- Category according to ISO 13849-1
- Performance level of pressure-sensitive protection device = at least PL
- Temperature range
- Degree of protection in accordance with IEC 60529:
 IP67 is the standard for safety edges.
 Higher degrees of protection must be checked individually.
- Environmental influences such as swarf, oil, coolant, outdoor use...
- Finger detection necessary?

Tip: For additional sensor selection criteria, please refer to ISO 13856-2 Appendix C and Appendix E.

Operation principle 2-wire-technology

The sensor is designed with integrated **positive break** safety elements in the form of contact chains. A control unit is not necessary, since the NC contact principle provides the output signal directly to the downstream control.

Optionally, the sensor can also be operated with an emergency stop component or a control unit.



For your safety:

Sensor and connecting cables are constantly monitored for function. This is possible because of signal transmission feedback – without a monitoring resistor.

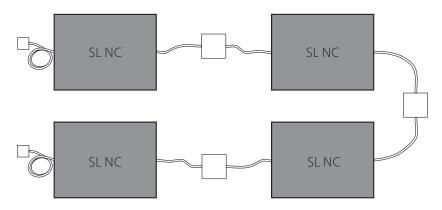


Design

SL NC with two 1-strand cables as a through sensor



Combination of sensors



Combination:

- Connection of more than one sensor
- only one emergency stop component necessary
- Safety edge design with custom lengths and angles



Safety

Intended use

A safety edge detects a person or part of the body when pressure is applied to the actuation area. It is a linear tripping device. Its task is to avoid possible hazardous situations for a person within a danger zone, such as shearing and pinching edges.

Typical areas of application are door and gate systems, moving parts on machines, platforms and lifting devices.

Safe operation of a safety edge depends entirely on

- the surface condition of the mounting surface,
- the correct selection of the size and resistance as well as
- correct installation.

For additional application guidelines refer to ISO 13856-2 Annex E.

Due to the design, the visible actuation area is reduced by the non-sensitive edges. What remains is the actual effective actuation area (see chapter *Effective actuation area*).

Limits

A maximum of 10 sensors may be operated in series. GP 48-2 deviates with respect to the actuation angle from the requirements in ISO 13856-2 and EN 12978; the suitability for doors and gates must be examined on an individual basis.

Exclusions

The sensors are not suitable:

- for detecting fingers
- for areas of application with high levels of vibration
- for performing a sealing function. Continuous actuation can cause permanent damage to sensors.

Other safety aspects

Performance Level (PL)

The PL was determined during a simplified procedure according to ISO 13849-1. Exclusion of error according to ISO 13849-2, Table D.4: Short circuit between two conductors that are permanently installed and protected against external damage. In this case the diagnostic coverage (DC) of the cables is not calculated and is not used in determining the PL. Assuming the control unit has a high MTTF_D value, the entire safety edge system (pressure-sensitive safety device) can achieve the maximum value PL d.

Is the safeguard appropriate?

The PL required for the hazard must be decided by the integrator. This is followed by the choice of safeguard.

Finally, the integrator needs to check whether the category and PL of the safeguard chosen are appropriate.

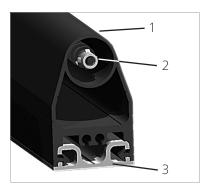
Risk and safety assessment

For the risk and safety assessment of your machine we recommend ISO 12100 "Safety of machinery – general principles for design".

Without reset function

When a safeguard without a reset function is used (automatic reset), the reset function must be made available in some other way.

Design



The Normally closed safety edge SL/NC II consists of

- (1) Rubber profile GP,
- (2) Contact chain made of connected positive break normally closed contacts and (3) Aluminium profile C 26 or C 36.

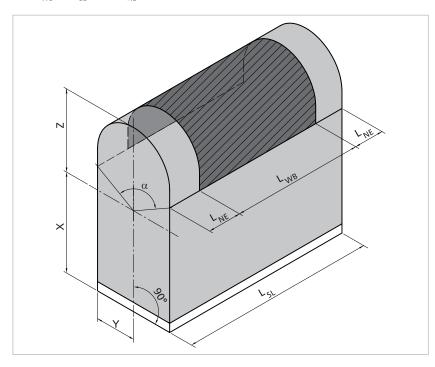
The positive break contact chain simultaneously carries out the functions of the sensor, signal processing and output signal switching device. Therefore, a special control unit is not necessary.

Effective actuation area

The parameters X, Y, Z, L_{WB} and the angle α describe the effective actuation area.

For the effective actuation area, the following applies:

$$L_{WB} = L_{SL} - 2 \times L_{NE}$$



Parameters:

 L_{WB} = effective actuation length

L_{SL} = overall length of the safety edge

 L_{NE} = non-sensitive length at the end of the safety edge

 α = effective actuation angle

SL NC II	GP 48-2	GP 65-2	GP 100-2
α	60°	90°	90°
L _{NE}	50 mm	50 mm	40 mm
X	40 mm	52 mm	85 mm
Υ	13 mm	18 mm	18 mm
Z	8 mm	13 mm	14 mm

The effective actuation angle α (60°) for GP 48-2 falls below the requirements of ISO 13856-2 and EN 12978.

Installation position

The installation position can be selected as required, i.e. all installation positions A to D as per ISO 13856-2 are possible.

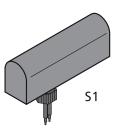


Connection

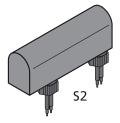
Cable exits

90° exit

Distance to front end each 60 mm



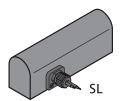
S1: 1 connection



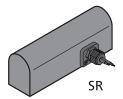
S2: 2 connections

Lateral exit

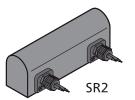
Distance to front end each 60 mm



SL: lateral exit left



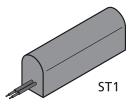
SR: lateral exit right



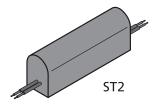
SR2: 2 connections

Axial exit

without PG-screw connection



ST1: Axial exit



ST2: 2 connections

In the case of several sensors connected in sequence, we recommend version S2, SR2 or ST2. These versions provide an additional line in the rubber profile for feedback to the control.



Cable connection

- Cable: Ø 3.3 mm PVC, 1×0.5 mm²; double insulated, short-circuit-proof, highly flexible
- Cable length depends on the sensor length:

A cable with a length of 7.5 m is installed in the sensor as standard equipment. Due to internal cable routing from the connections the cable exits, the connection cable length is determined as follows: Standard cable length minus sensor length.

For example, 7.5 m - 6 m = 1.5 m

Option: can be expanded up to a maximum length of 100 m

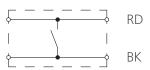
Cable ends: wires stripped
 Option: Cable ends available with plug and coupling

For the wiring between the sensor and the downstream control the cables must be installed permanently and protected against external damage, for example in cable conduits or armoured conduits. In areas where this is not possible, each cable must be routed in a separate sheath.

This prevents

- line termination and therefore loss of the protective function and
- downgrading of the safety classification.

Wire colours



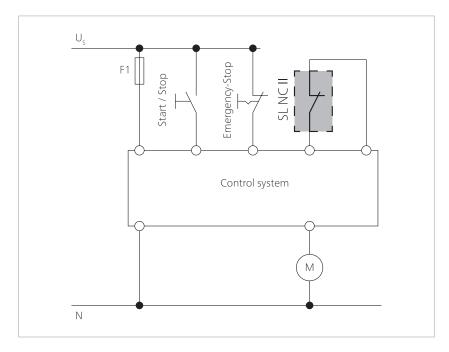
Colour coding

BK Black RD Red

Connection examples

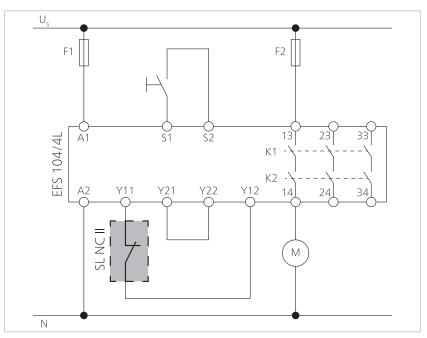
Connection example 1

NC safety edge connected directly to the control. Protective devices in accordance with ISO 13849 1 to PL d are possible, if the control has a performance level of d or higher.



Connection example 2

NC safety edge connected to the Mayser SG-EFS 104/4L control unit. Performance level up to PL d in accordance with ISO 13849-1 is possible.



The NC safety edge and the SG EFS 104/4L sensor are certified to UL 508.



Sensor surface

Physical resistance

Rubber profile GP	EPDM	NBR
Degree of protection (IEC 60529)	IP67	IP67
Hardness per Shore A	65 ±5	70 ±5

Chemical resistance

The sensor is resistant against normal chemical influences such as diluted acids and alkalis as well as alcohol over an exposure period of 24 hrs.

The specifications in the table are the result of tests conducted in our lab at room temperature (+23 °C). The suitability of our products for your special area of application must always be verified with your own practical tests.

Material	EPDM	NBR
Acetone	+	<u>+</u>
Formic acid	+	+
Ammonia	+	+
Petrol	-	+
Brake fl uid	±	±
Chloride solutions	+	+
Diesel oils	-	+
Greases	-	+
Household-/sanitary cleaners	+	+
Isopropyl alcohol	+	+
Cooling lubricant	-	+
Metal working oil	-	+
Methyl alcohol	+	+
Oils	-	+
Ozone and weather conditions	+	-
Hydrochloric acid 10 %	+	+
Spirit (ethyl alcohol)	+	+
Carbon tetrachloride	-	+
Hydrogen peroxide 10 %	+	+
Water and frost	+	-

Explanation of symbols:

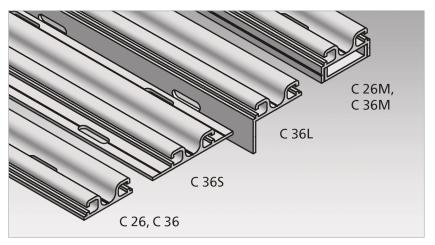
+ = resistant

 \pm = resistant to a certain extent

- = not resistant

Attachment

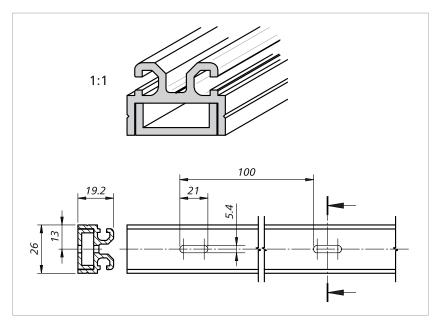
The sensors are mounted directly to the dangerous main and secondary closing edges. The aluminium profiles C 26 and C 36 are used for mounting. The aluminium profiles are mounted with screws M5 or rivets.



Material properties

- AlMgSi0.5 F22
- Wall thickness 2 mm
- Tolerances as per EN 755-9
- extruded
- hot hardened

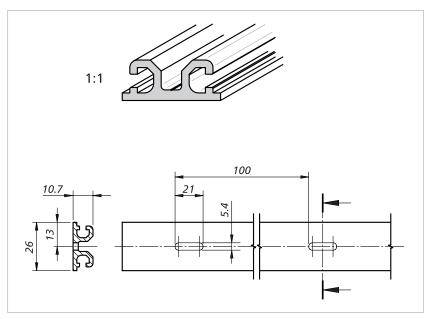
Aluminium profile C 26M



Two-part profile for GP 48-2:

For convenient assembly and disassembly. The rubber profile is clipped into the upper section and the upper section inserted in the installed lower section and fastened.

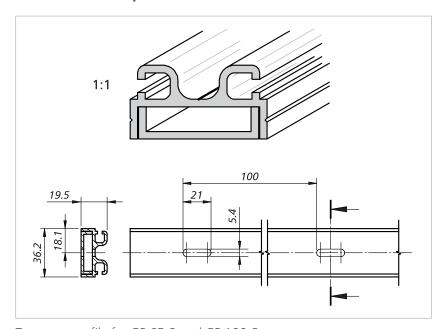
Aluminium profile C 26



Standard profile for GP 48-2:

First the aluminium profile must be mounted to the closing edge and then the rubber profile clipped into the aluminium profile.

Aluminium profile C 36M

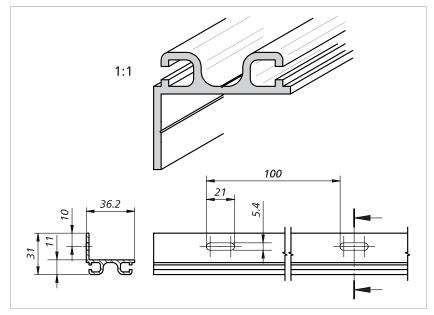


Two-part profile for GP 65-2 and GP 100-2:

For convenient assembly and disassembly. The rubber profile is clipped into the upper section and the upper section inserted in the installed lower section and fastened.



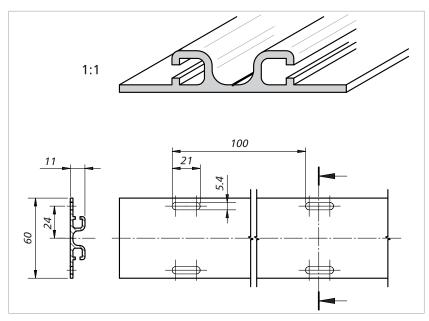
Aluminium profile C 36L



Angle profile for GP 65-2 and GP 100-2:

If the closing edge should or must not have assembly holes, this "round-the-corner" solution is suitable. Final assembly is also possible when the rubber profile is already clipped into the aluminium profile.

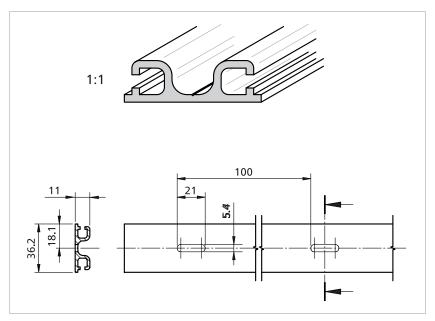
Aluminium profile C 36S



Flange profile for GP 65-2 and GP 100-2:

Final assembly is also possible when the rubber profile is already clipped into the aluminium profile.

Aluminium profile C 36



Standard profile for GP 65-2 and GP 100-2:

First the aluminium profile must be mounted to the closing edge and then the rubber profile clipped into the aluminium profile.

Aluminium profiles: Overview of combinations

Aluminium	profiles for	GP 48-2	GP 65-2	GP 100-2
External clip bars	2	C 26 C 26M	C 36 C 36M, C 36L, C 36S	C 36 C 36M, C 36L, C 36S

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- s₁ = Stopping distance of the dangerous movement [mm]
- v = Velocity of the dangerous movement [mm/s]
- T = Follow-through of the complete system [s]
- t_1 = Response time safety edge
- t₂ = Stopping time of the machine
- s = Minimum overtravel distance of the safety edge so that the required limit forces are not exceeded [mm]
- C = Safety factor; if components susceptible to failures (braking system) exist in the system, a higher factor must be selected

SL NC II: The right selection

Calculation for selection of the safety edge height

The stopping distance of the dangerous movement is calculated using the following formula:

$$s_1 = 1/2 \times v \times Twhere: T = t_1 + t_2$$

The NC safety edge is a sensor, signal processor and output signal switching device in one (see chapter Design). For this reason the response time t_1 of the safety edge = the sensor response time.

In accordance with ISO 13856-2, the minimum overtravel distance of the safety edge is calculated using the following formula:

$$s = s_1 \times C$$
 where: $C = 1.2$

A suitable safety edge profile can now be selected based on the result. Overtravel distances of safety edge profiles: see chapter *Technical data*.

Calculation examples

Example 1

The dangerous movement on your machine has a velocity of v=10 mm/s and can be brought to a standstill within $t_2=250$ ms. The relatively low velocity suggests that a short overtravel distance is to be expected. Therefore the normally closed safety edge SL NC II GP 48-2 NBR could be sufficient. The response time of the safety edge is $t_1=1300$ ms.

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$
 $s_1 = 1/2 \times 10 \text{ mm/s} \times (1300 \text{ ms} + 250 \text{ ms})$
 $s_1 = 1/2 \times 10 \text{ mm/s} \times 1.55 \text{ s} = 6.55 \text{ mm}$
 $s = s_1 \times C$ where: $C = 1.2$

$$s = 6.55 \text{ mm} \times 1.2 = 7.86 \text{ mm}$$

The safety edge must have a minimum overtravel distance of s = 7.9 mm. The selected SL NC II GP 48-2 NBR has an overtravel distance of at least 12.4 mm. This is more than the required 7.9 mm.

Result: The SL NC II GP 48-2 NBR is **suitable** for this case.

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Example 2

The same conditions as in calculation example 1 with the exception of the velocity of the dangerous movement. This is now v = 100 mm/s. This reduces the response time of the safety edge to $t_1 = 83$ ms.

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$
 $s_1 = 1/2 \times 100 \text{ mm/s} \times (83 \text{ ms} + 250 \text{ ms})$
 $s_1 = 1/2 \times 100 \text{ mm/s} \times 0.333 \text{ s} = 16.65 \text{ mm}$
 $s = s_1 \times C$ where: $C = 1.2$
 $s = 16.65 \text{ mm} \times 1.2 = 19.98 \text{ mm}$

The safety edge must have a minimum overtravel distance of s = 20 mm. The selected SL NC II GP 48-2 NBR has an overtravel distance of at least 16.8 mm. This is less than the required 20 mm.

Result: The SL NC II GP 48-2 NBR is **not suitable** for this case.

Example 3

The same conditions as in calculation example 2. Instead of SL NC II GP 48-2 NBR the SL NC II GP 100-2 EPDM is selected. The response time of the safety edge is $t_1 = 76$ ms.

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$
 $s_1 = 1/2 \times 100 \text{ mm/s} \times (76 \text{ ms} + 250 \text{ ms})$
 $s_1 = 1/2 \times 100 \text{ mm/s} \times 0.326 \text{ s} = 16.3 \text{ mm}$
 $s = s_1 \times C$ where: $C = 1.2$
 $s = 16.3 \text{ mm} \times 1.2 = 19.56 \text{ mm}$

The safety edge must have a minimum overtravel distance of s=20 mm. The selected SL NC II GP 100-2 EPDM has an overtravel distance of at least 36.8 mm at 100 mm/s. This is more than the required 20 mm.

Result: The SL NC II GP 100-2 EPDM is **suitable** for this case.



Accessories

Extension kit

For extension of connection cable by customer (contents: double insulated wire, crimp connector and heat-shrinkable sleeves)

Extension kit: 5 m 1003870 Extension kit: 10 m 1003871

Wiring aids

Special resistor: 1k2 1003873 Special resistor: 8k2 1003874

Maintenance and cleaning

The sensors are virtually maintenance-free.

Regular inspection

Depending on the utilisation, sensors must be inspected at regular intervals (at least monthly)

- for proper functioning,
- damage,
- and correct mounting.

Cleaning

If the sensors become dirty, they can be cleaned with a mild cleaning product.



Technical data

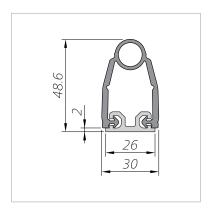
GP 48-2 NBR with C 26

Normally closed safety edge SL NC II consisting of sensor and aluminium profile from the profile range C 26.

Testing basis	
ISO 13856-2	
Switching characteristics at v _{test} =	= 200 mm/s
Switching operations Actuation force	>10,000
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	12 mm
Test piece (cylinder) Ø 80 mm	60°
Response time	60 ms
Finger detection	yes
Safety classifications	
ISO 13856: Reset function	without
ISO 13849-1:2015	Category 3 PL d
B _{10D} (Sensor)	2× 10 ⁶
Mechanical operating conditions	3
Sensor length (min./max.)	30 cm / 6 m
Cable length (min./max.)	1.5 m / 100 m
Bend radii	not possible
Operating speed	
(min. / max.)	10 mm/s / 200 mm/s
max. load capacity	600 N
IEC 60529: Degree of protection	IP67
Humidity (max. at 23 °C)	95 % (non-condensing)
Operating temperature	+5 to +55 °C
Storage temperature	-20 to +80 °C
Weight	1.0 kg/m
Electrical operating conditions	
Contact transition resistance (max.)	5 Ohm
Number of sensors type BK	max. 10 in series
Switching voltage (PELV) (max.)	48 V DC 48 V AC 50/60 Hz
Protection class	III
Switching current (max.)	20 mA
Contact fuse protection, external	250 mA slow-acting
Connection cable	Ø 3.3 mm PVC 1×0.5 mm ²

Dimensions and distances

GP 48-2 NBR (1:2)



Dimensional tolerances according to ISO 3302 E2/L2.

Test conditions

according to ISO 13856-2

- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- without control unit

All data stated here is documented in EC design type test certificates.

Force-distance ratios

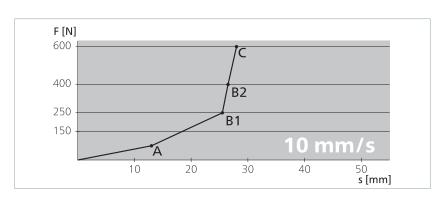
Actuation force 69 N
Response time 1300 ms
Actuation distance (A) 13 mm
Overtravel distance
up to 250 N (B1) 12.4 mm
up to 400 N (B2) 13.5 mm
up to 600 N (C) 14.9 mm
Total deformation 27.9 mm

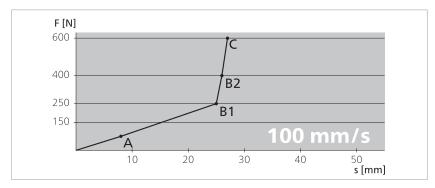
Actuation force 71 N
Response time 83 ms
Actuation distance (A) 8.3 mm
Overtravel distance
up to 250 N (B1) 16.8 mm
up to 400 N (B2) 17.7 mm
up to 600 N (C) 18.9 mm
Total deformation 27.2 mm

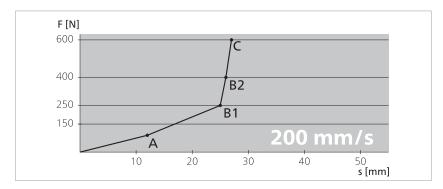
Response time 60 ms
Actuation distance (A) 12 mm
Overtravel distance
up to 250 N (B1) 13.2 mm
up to 400 N (B2) 14.1 mm
up to 600 N (C) 15.2 mm

Actuation force

Total deformation







71 N

27.2 mm



Technical data

GP 48-2 EPDM with C 26

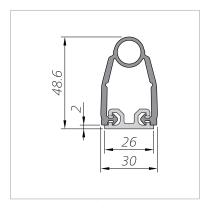
Normally closed safety edge SL NC II consisting of sensor and aluminium profile from the profile range C 26.

Testing basis	
ISO 13856-2	
Switching characteristics at v _{test} =	= 100 mm/s
Switching operations Actuation force	>10,000
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	14.8 mm
Test piece (cylinder) Ø 80 mm	90°
Response time	148 ms
Finger detection	no
Safety classifications	'
ISO 13856: Reset function	without
ISO 13849-1:2015	Category 3 PL d
B _{10D} (Sensor)	2× 10 ⁶
Mechanical operating conditions	5
Sensor length (min./max.)	30 cm / 6 m
Cable length (min./max.)	1.5 m / 100 m
Bend radii	not possible
Operating speed	
(min. / max.)	10 mm/s / 200 mm/s
max. load capacity	600 N
IEC 60529: Degree of protection	IP67
Humidity (max. at 23 °C)	95 % (non-condensing)
Operating temperature	-10 to +55 °C
Storage temperature	-20 to +80 °C
Weight	1.0 kg/m
Electrical operating conditions	
Contact transition resistance (max.)	5 Ohm
Number of sensors type BK	max. 10 in series
Switching voltage (PELV) (max.)	48 V DC 48 V AC 50/60 Hz
Protection class	III
Switching current (max.)	20 mA
Contact fuse protection, external	250 mA slow-acting
Connection cable	Ø 3.3 mm PVC 1×0.5 mm ²



Dimensions and distances

GP 48-2 EPDM (1:2)



Dimensional tolerances according to ISO 3302 E2/L2.

Test conditions

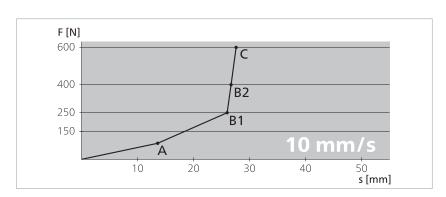
according to ISO 13856-2

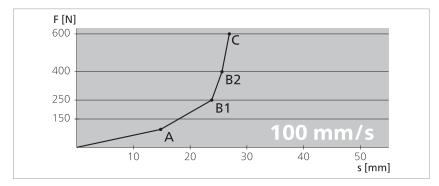
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- without control unit

Force-distance ratios

Actuation force 86 N
Response time 1440 ms
Actuation distance (A) 14.4 mm
Overtravel distance
up to 250 N (B1) 11.3 mm
up to 400 N (B2) 12.3 mm
up to 600 N (C) 13.2 mm
Total deformation 27.1 mm

Actuation force 95 N
Response time 148 ms
Actuation distance (A) 14.8 mm
Overtravel distance
up to 250 N (B1) 10.8 mm
up to 400 N (B2) 11.6 mm
up to 600 N (C) 12.6 mm
Total deformation 26.9 mm







Technical data

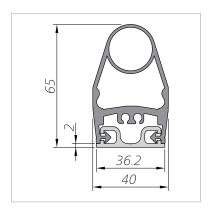
GP 65-2 EPDM with C 36

Normally closed safety edge SL NC II consisting of sensor and aluminium profile from the profile range C 36.

Testing basis	
ISO 13856-2	
Switching characteristics at v _{test} =	= 200 mm/s
Switching operations Actuation force	>10,000
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	7 mm
Test piece (cylinder) Ø 80 mm	90°
Response time	35 ms
Finger detection	no
Safety classifications	
ISO 13856: Reset function	without
ISO 13849-1:2015	Category 3 PL d
B _{10D} (Sensor)	2× 10 ⁶
Mechanical operating conditions	3
Sensor length (min./max.)	30 cm / 6 m
Cable length (min./max.)	1.5 m / 100 m
Bend radii	not possible
Operating speed	
(min. / max.)	10 mm/s / 200 mm/s
max. load capacity	600 N
IEC 60529: Degree of protection	IP67
Humidity (max. at 23 °C)	95 % (non-condensing)
Operating temperature	-10 to +55 °C
Storage temperature	-20 to +80 °C
Weight	1.9 kg/m
Electrical operating conditions	
Contact transition resistance (max.)	5 Ohm
Number of sensors type BK	max. 10 in series
Switching voltage (PELV) (max.)	48 V DC 48 V AC 50/60 Hz
Protection class	III
Switching current (max.)	20 mA
Contact fuse protection, external	250 mA slow-acting
Connection cable	Ø 3.3 mm PVC 1×0.5 mm ²

Dimensions and distances

GP 65-2 EPDM (1:2)



Dimensional tolerances according to ISO 3302 E2/L2.

Test conditions

according to ISO 13856-2

- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- without control unit

All data stated here is documented in EC design type test certificates.

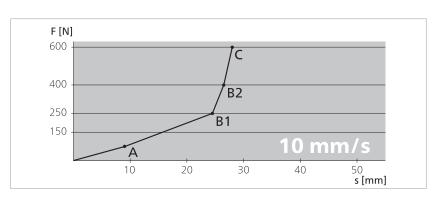
Force-distance ratios

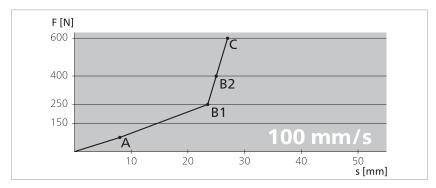
Actuation force 69 N
Response time 890 ms
Actuation distance (A) 8.9 mm
Overtravel distance
up to 250 N (B1) 15.6 mm
up to 400 N (B2) 17.5 mm
up to 600 N (C) 19.3 mm
Total deformation 28.2 mm

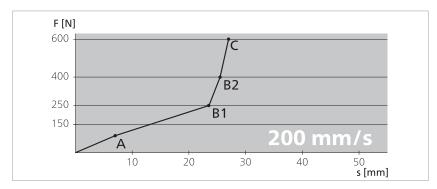
Actuation force 71 N
Response time 80 ms
Actuation distance (A) 8 mm
Overtravel distance
up to 250 N (B1) 15.5 mm
up to 400 N (B2) 17.3 mm
up to 600 N (C) 19.1 mm
Total deformation 27.1 mm

Actuation force 64 N
Response time 34.5 ms
Actuation distance (A) 6.9 mm
Overtravel distance
up to 250 N (B1) 16.5 mm
up to 400 N (B2) 18.5 mm
up to 600 N (C) 20 mm

Total deformation







26.9 mm



Technical data

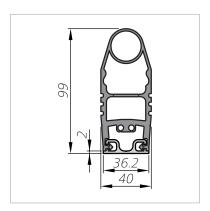
GP 100-2 EPDM with C 36

Normally closed safety edge SL NC II consisting of sensor and aluminium profile from the profile range C 36.

Testing basis	
ISO 13856-2	
Switching characteristics at v _{test} =	= 200 mm/s
Switching operations Actuation force	>10,000
Test piece (cylinder) Ø 80 mm Actuation distance	< 150 N
Test piece (cylinder) Ø 80 mm Actuation angle	17 mm
Test piece (cylinder) Ø 80 mm	90°
Response time	82 ms
Finger detection	no
Safety classifications	'
ISO 13856: Reset function	without
ISO 13849-1:2015	Category 3 PL d
B _{10D} (Sensor)	2× 10 ⁶
Mechanical operating conditions	5
Sensor length (min./max.)	30 cm / 6 m
Cable length (min./max.)	1.5 m / 100 m
Bend radii	not possible
Operating speed	
(min. / max.)	10 mm/s / 200 mm/s
max. load capacity	600 N
IEC 60529: Degree of protection	IP67
Humidity (max. at 23 °C)	95 % (non-condensing)
Operating temperature	-10 to +55 °C
Storage temperature	-20 to +80 °C
Weight	2.1 kg/m
Electrical operating conditions	
Contact transition resistance (max.)	5 Ohm
Number of sensors type BK	max. 10 in series
Switching voltage (PELV) (max.)	48 V DC 48 V AC 50/60 Hz
Protection class	III
Switching current (max.)	20 mA
Contact fuse protection, external	250 mA slow-acting
Connection cable	Ø 3.3 mm PVC 1×0.5 mm ²

Dimensions and distances

GP 100-2 EPDM (1:3)



Dimensional tolerances according to ISO 3302 E2/L2.

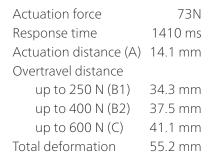
Test conditions

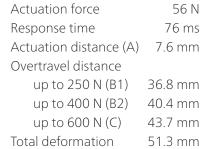
according to ISO 13856-2

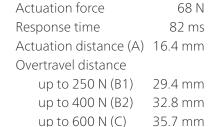
- Installation position B
- Temperature +20 °C
- Measurement point c3
- Test sample 1 with Ø 80 mm
- without control unit

All data stated here is documented in EC design type test certificates.

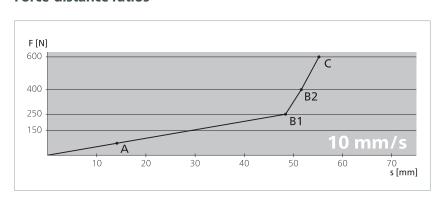
Force-distance ratios

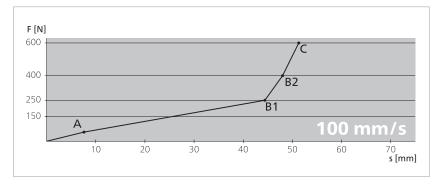


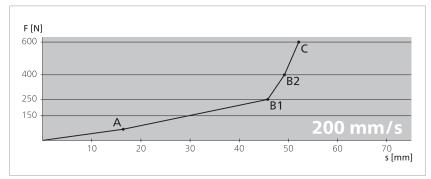




Total deformation







52.1 mm



Conformity

Conformity

The CE symbol indicates that this Mayser product complies with the relevant EC directives and that the stipulated conformity assessments have been carried out.



The design type of the product complies with the basic requirements of the following directives:

- 2006/42/EC (Safety of machinery)
- 2014/30/EU (EMC)

The Declaration of Conformity is available in the download section of the website: www.mayser.com/en/downloads

EC design test

The product was tested by an independent institute.

An EC design type test certificate confirms conformity.

The EC design type test certificate is available in the download section of the website: www.mayser.com/en/downloads

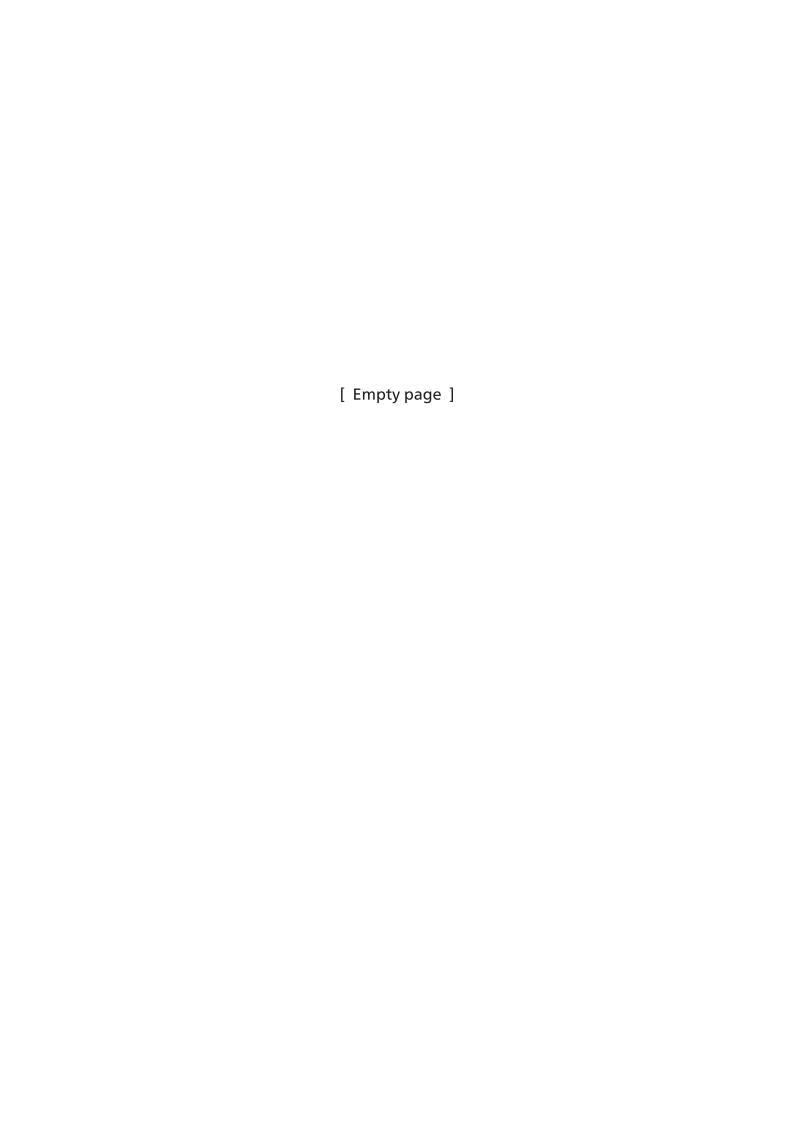
UL certification

Certificates

UL certification

U8V 07 10 31146 006





MAYSER®

Technical Data

Miniature Safety Edge consisting of sensor type EKS 0XX TPE

IP65

Miniature Safety Edges

(Illustration scale 1:1)

Protection class

Switching operations

Test piece Ø 10 mm / F=100 N > 100,000

Actuating force, actuating distance and response angle

and response angle			
	EKS 002	EKS 011 🖼	EKS 026
			23 °C - 25 °C
·			< 10 N < 20 N
	< 20 N < 25 N	< 25 N < 50 N	< 15 N < 35 N
			23 °C
•			< 1 mm
Response angle	< 60°	< 80°	< 80°
Mechanical operating and applic	cation conditions		
<u> </u>	70 mm / 150 m	70 mm / 150 m	70 mm / 150 m
	50	400	
		1	> 80 mm
•			> 50 mm
·		l · · · · · · · ·	> 120 mm
· ·			max. 20 N
• .			-25 °C to +80 °C
Permissible short term exposure	-40 °C to +100 °C	-40 °C to +100 °C	-40 °C to +100 °C
Electric operating conditions			
End resistor (standard)	1.2 kΩ ±1%	1.2 kΩ ±1%	1.2 kΩ ±1%
Performance	max. 250 mW	max. 250 mW	max. 250 mW
Transition resistance	$<$ 400 Ω (under load)	$< 400 \Omega$ (under load)	$<$ 400 Ω (under load)
Electric rating	without end resistor	without end resistor	without end resistor
•	max. 24 V DC	max. 24 V DC	max. 24 V DC
Current	max. 10 mA	max. 10 mA	max. 10 mA
	min. 1 mA		min. 1 mA
Connecting cable	Ø 3.7 mm		Ø 1,4 mm per strand
3 3	2x 0.25 mm ²	2x 0.25 mm ²	2× 0.35 mm ²
	Sensor length (min./max.) Bending radii Convex profile curvature Concave profile curvature Across the profile axis Tensile load, cable Working temperature Permissible short term exposure Electric operating conditions End resistor (standard) Performance Transition resistance Electric rating Voltage	Actuating force $v_{test} = 50 \text{ mm/min}$ $23 ^{\circ}\text{C}$ $-25 ^{\circ}\text{C}$ Test piece \varnothing 4 mm $< 10 \text{N}$ $< 15 \text{N}$ Test piece \varnothing 200 mm $< 20 \text{N}$ $< 25 \text{N}$ Actuating distance $v_{test} = 50 \text{mm/min}$ $23 ^{\circ}\text{C}$ Test piece \varnothing 80 mm cyl. $< 1.5 \text{mm}$ Response angle $< 60 ^{\circ}$ Mechanical operating and application conditions Sensor length (min./max.) 70mm / 150 m Bending radii Convex profile curvature $> 50 \text{mm}$ Across the profile axis $> 120 \text{mm}$ Across the profile axis $> 120 \text{mm}$ Tensile load, cable $max. 60 \text{N}$ Working temperature $-25 ^{\circ}\text{C}$ to $+80 ^{\circ}\text{C}$ Permissible short term exposure $-40 ^{\circ}\text{C}$ to $+100 ^{\circ}\text{C}$ Electric operating conditions End resistor (standard) $1.2 \text{k}\Omega \pm 1\%$ Performance $max. 250 \text{mW}$ Transition resistance $< 400 \Omega$ (under load) Electric rating without end resistor Voltage $max. 24 \text{V}$ DC Current $max. 10 \text{mA}$ min. 1mA Connecting cable	Actuating force $V_{test} = 50 \text{ mm/min}$ $23 ^{\circ}\text{C}$ $-25 ^{\circ}\text{C}$ $23 ^{\circ}\text{C}$ $-25 ^{\circ}\text{C}$ Test piece \emptyset 4 mm $< 10 \text{N}$ $< 15 \text{N}$ $< 15 \text{N}$ $< 30 \text{N}$ Test piece \emptyset 200 mm $< 20 \text{N}$ $< 25 \text{N}$ $< 25 \text{N}$ $< 50 \text{N}$ Actuating distance $V_{test} = 50 \text{mm/min}$ $23 ^{\circ}\text{C}$ $23 ^{\circ}\text{C}$ $= 23 ^{\circ}\text{C}$ $= 25 ^{\circ}\text{C}$ $= 20 ^{\circ}\text{C}$ $= 23 ^{$

Application using acrylic-foam-adhesive tape

Class according to IEC 60228

Peel strength Applied to:	15 N/cm	without promoter	
ABS	+	without promotor	
Aluminium	+	+	Tests carried out at 23 °C (room
Aluminium, anodised	T .	т	temperature).
	+	-	
Wood: native	-	-	
Wood: varnished, veneer	or		Note: check with adhesion tests
laminated	+	-	before serial use whether bonding is
PA6	+	-	possible on the selected installation
PA66	+	+	surface.
PE, HDPE	-	-	Suridoc.
PMMA	+	+	
PP	+	-	Key to symbols:
PS, CAB	-	-	+ = OK
PVC	+	+	
SAN	+	-	- = not OK
Steel, stainless steel	+	+	

6

Miniature Safety Edges

7 Behaviour in fire

According to DIN 75200 40 mm/min

Compliance with StVZO, TA 29, BMW N601 21.0

8. Dimensions tolerances length according to DIN ISO 3302 L2

section according to DIN ISO 3302 E2

9. Chemical resistance

Miniature Safety Edge EKS	TPE
Material characteristics	
Shore A hardness	55 ±5
Chemical resistance	
Acetone	-
Formic acid	-
Armor All	+
Carwash agent	+
Fuel	_
Brake fluid	±
Buraton	+
Butanol	-
Chlorinated bleaching lye	-
Disinfectant 1 %	+
Diesel	-
Acetic acid 10 %	-
Ethyl alcohol	+
Ethyl acetate	-
Ethylene glycol	+
Greases	±
Antifreeze	+
Skin cream	+
Icidin	+
Incidin	+
Incidin plus	+
Cooling lubricants	-
Plastics cleaning agent	+
Lyso FD 10	+
Metal processing oil	-
Microbac	+
Microbac forte	+
Minutil	+
Saline solution 5 %	+
Spirit (ethyl alcohol)	+
Terralin	+
UV-resistance	+
Centering oil	-

Tests carried out at 23 °C (room temperature).

Key to symbols

+ = resistant

± = limited resistance

= not resistant

The data given are results of tests which were carried out in our laboratory to the best of our knowledge and belief. We cannot accept any obligations being deduced from them. You must always test the suitability of our products for your special application purpose under practical conditions.



Technical Data

Miniature Safety Edge consisting of sensor type EKS 01X TPE

Miniature Safety Edges

1. Protection class IP65

2. Switching opertions

Test piece Ø 10 mm / F=100 N > 100.000

3.	Actuating force, actuating distartant and response angle	nce			
3.1	Actuating force Test speed v _{test}	EKS 014 50 mm/min	3	EKS 015 100 mm/min	705
	Test temperature Testing basis: 74/60/EWG and FMVSS118	23 °C	-25 °C	23 °C	-25 °C
	Test piece Ø 200 mm	< 25 N	< 50 N	_	_
	Test piece Ø 4 mm Testing basis: EN 1760-2	< 15 N	< 30 N	-	_
	Test piece 1 Ø 80 mm cyl.	_	_	< 25 N	<110N
3.2	Test piece 3 Ø 20 mm Actuating distance	_	_	< 15 N	<25 N
0.2	Test speed v _{test} Test temperature	50 mm/min 23 °C		100 mm/min 23 °C	
	Test piece 1 Ø 80 mm cyl.	< 2 mm		2 mm	
3.3	Response angle	< 80°		< 40°	
4.	Mechanical operating and appli				
	Sensor length (min./max.) Bending radii	70 mm / 150	0 m	70 mm / 150	m
4.2	Convex profile curvature	> 120 mm		> 800 mm	
	Concave profile curvature	> 150 mm		>1000 mm	
12	Across the profile axis Working temperature	> 20 mm - 40 °C to	. 80 °C	> 200 mm - 40 °C to	. 80 °C
4.0	Permissible short term exposure	- 40 °C to		- 40 °C to -	
5.	Electric operating conditions				
5.1	End resistor (standard)	1.2 kΩ ±1%		1.2 kΩ ±1%	N.
5.2	Performance Transition resistance	max. 250 m $<$ 400 Ω (un		max. 250 mV $<$ 400 Ω (und	
	Electric rating	without end	,	without end	,
	Voltage Current		V DC		/ DC
	Current		mA mA	max. 20 r min. 1 r	nA mA
5.4	Connecting cable	Ø 3.4 mm 2x 0.25 mm	,2	Ø 3.7 mm 2x 0.25 mm ²	
	Class according to VDE 0295	6		5	
6.	Application with clip-in foot			_	
	Clip-in foot width Al-rail type	3.5 mm C10		7 mm C15	
		0.10			

7. Dimensions tolerances

Length according to ISO 3302 L2Cross section according to ISO 3302 E2

8. Chemical resistance

Miniature Safety Edge EKS 01X	TPE
Material characteristics	
Shore A hardness	55 ±5
Chemical resistance	
Acetone	-
Formic caid	-
Armor All	+
Carwash agent	+
Fuel	-
Brake fluid	±
Buraton	+
Butanol	-
Chlorinated bleaching lye	-
Disinfectant 1 %	+
Diesel	-
Acetic acid 10 %	-
Ethyl alcohol	+
Ethyl acetate	-
Ethylene glycol	+
Greases	±
Antifreeze	+
Skin cream	+
Icidin	+
Incidin	+
Incidin plus	+
Cooling lubricants	-
Plastics cleanging agent	+
Lyso FD 10	+
Metal processing oil	-
Microbac	+
Microbac forte	+
Minutil	+
Saline solution 5 %	+
Spirit (ethyl alcohol)	+
Terralin	+
UV-resistance	+
Centering oil	-

Miniature Safety Edges

Tests carried out at 23 °C (room temperature).

Key to symbols:

+ = resistant

± = limited resistance

= not resistant

The data given are results of tests carried out in our laboratory to the best of our knowledge and belief. We cannot accept any obligations being deduced from them. You must always test the suitability of our products for your special application under practical conditions.

MAYSER®

Technical Data

Miniature Safety Edge consisting of sensor type EKS 030 TPE

1 Protection class IP65

2 Switching operations

Test piece Ø 10 mm / F=100 N > 100 000

3 Actuating force, actuating distance and response angle

3.1	Actuating force	EKS 030	
	v _{test} = 50 mm/min	23 °C	-25 °C
	Test piece Ø 4 mm	< 15 N	< 25 N
	Test piece Ø 200 mm	< 20 N	< 40 N

3.2 Actuating distance

 $v_{test} = 50 \text{ mm/min}$ 23 °C Test piece Ø 80 mm < 2,0 mm 3.3 Response angle < 100°

4 Mechanical operating and application conditions

4.1 Sensor length (min./max.)	70 mm / 150 m
-------------------------------	---------------

4.2 Bending radii, minimum

A / B / C / D 70 / 60 / 30 / 30 mm

4.3 Tensile load, cable max. 40 N

4.4 Working temperature -25 °C to +80 °C
Permissible short term exposure -40 °C to +100 °C

5 Electric operating conditions

5.1	End resistor (standard) Performance	1.2 k Ω ±1% max. 250 mW
5.2	Transition resistance	$<$ 400 Ω (under load)
5.3	Electric rating Voltage Current	without end resistor max. 24 V DC max. 10 mA min. 1 mA
5.4	Connecting cable	Ø 4.1 mm

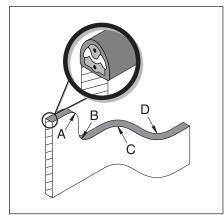
6 Application using acrylic-foam-adhesive tape

Peel strength	15 N/cm		
Applied to:	using promoter	without promoter	
ABS	+	-	
Aluminium	+	+	
Aluminium: anodised	+	-	
Wood: native	-	-	
Wood: varnished, venee	r or		
laminated	+	-	
PA6	+	-	
PA66	+	+	
PE, HDPE	-	-	
PMMA	+	+	
PP, SAN	+	-	
PS, CAB	-	-	
PVC	+	+	
Steel, stainless steel	+	+	

2× 0.35 mm²

Miniature Safety Edges

Bending radii:



Tests carried out at 23 °C (room temperature).

Note: check with adhesion tests before serial use whether bonding is possible on the selected installation surface.

Key to symbols: + = OK - = not OK

Miniature Safety Edges

7 Behaviour in fire

According to DIN 75200

Compliance with StVZO, TA 29, BMW N601 21.0

40 mm/min

8 Dimensions tolerances length according to ISO 3302 L2 section according to ISO 3302 E2

9 Chemical resistance

Miniature Safety Edge EKS	TPE
Material characteristics	
Shore A hardness	52 ±5
Chemical resistance	
Acetone	-
Formic acid	-
Armor All	+
Carwash agent	+
Fuel	-
Brake fluid	±
Buraton	+
Butanol	-
Chlorinated bleaching lye	-
Disinfectant 1 %	+
Diesel	-
Acetic acid 10 %	-
Ethyl alcohol	+
Ethyl acetate	-
Ethylene glycol	+
Greases	±
Antifreeze	+
Skin cream	+
Icidin	+
Incidin	+
Incidin plus	+
Cooling lubricants	_
Plastics cleaning agent	+
Lyso FD 10	+
Metal processing oil	_
Microbac	+
Microbac forte	+
Minutil	+
Saline solution 5 %	+
Spirit (ethyl alcohol)	+
Terralin	+
UV-resistance	+
Centering oil	-

Tests carried out at 23 °C (room temperature).

Key to symbols:

+ = resistant

= limited resistance

= not resistant

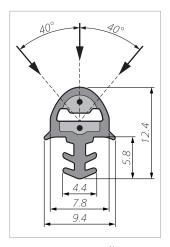
The data given are results of tests which were carried out in our laboratory to the best of our knowledge and belief. We cannot accept any obligations being deduced from them. You must always test the suitability of our products for your special application purpose under practical conditions.





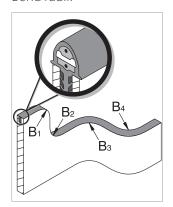
EN | Data sheet

EKS 052 TPE



Dimensions in millimetres (mm) Dimensional tolerances according to ISO 3302 E2/L2

Bend radii:



Miniature safety edge (without control unit)	EKS/W8k2 052 TPE or EKS/BK 052 TPE
Testing basis Sensor colour	In accordance with ISO 13856-2 Black, window grey (RAL 7040) or light grey (RAL 7035)
Switching characteristics at v _{test} = !	50 mm/min
Switching operations Actuation force Test piece (rod) Ø 4 mm Test piece (rod) Ø 200 mm Actuation distance Test piece (cylinder) Ø 80 mm	10,000 +23 °C -25 °C < 25 N < 30 N < 40 N < 50 N
Actuation angle Test piece (cylinder) Ø 80 mm Finger detection	±40° Yes
Safety classifications	
ISO 13849-1: B _{10D}	2× 10 ⁶
Mechanical operating conditions	
Sensor length (min. max.) Cable length (min. max.) Fixing method Groove width for clamp foot Bend radii, minimum B1 B2 B3 B4 Maximum load (impulse) Tensile load, cable (max.) IEC 60529: degree of protection Operating temperature Short-term (15 min) Storage temperature Weight	10 cm 45 m 10 cm 30 m Clamp foot 3.7 ±0.4 mm 120 150 20 20 mm 600 N 60 N IP67 -25 to +80 °C -40 to +100 °C -40 to +80 °C 54 g/m
Electrical operating conditions	
Terminal resistance (±1%) Nominal output (max.) Resistance: sensor activated Number of /BK-type sensors Switching voltage (max.) Switching current (min. max.) Connection cable	8k2 250 mW < 400 ohms Max. 5 in series DC 24 V 1 10 mA Ø 3.7 mm TPE 2× 0.22 mm ²



Physical resistance

	TPE
IEC 60529: degree of protection	IP67
UV resistance	Yes
DIN 75200: burning rate	40 mm/min

Chemical resistance

Explanation of symbols:

+ = resistant

± = resistant to a certain extent

- = not resistant

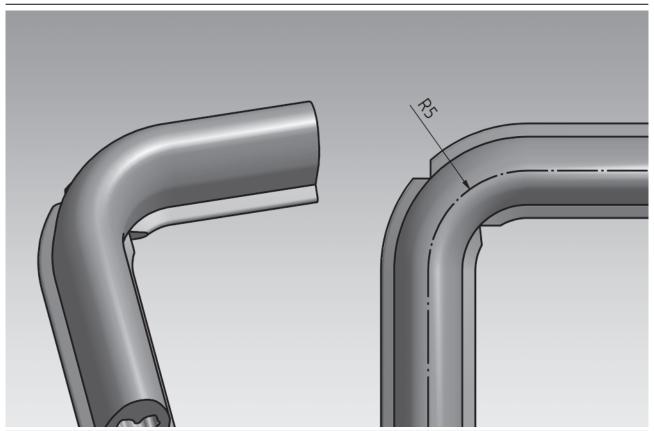
	TPE
Acetone	_
Formic acid	_
Armor All	+
Car shampoo	+
Petrol	_
Brake fluid	+
Buraton	+
Butanol	_
Sodium hypochlorite	_
Disinfectant 1%	+
Diesel	_
Acetic acid 10%	_
Ethanol	+
Ethyl acetate	_
Ethylene glycol	+
Greases	<u>±</u>
Anti-frost agent	+
Skin cream	+
Incidin	+
Incidin Plus	+
Cooling lubricant	_
Plastic cleaner	+
Lyso FD 10	+
Metal working oil	_
Microbac	+
Microbac forte	+
Minutil	+
Saline solution 5%	+
Spirit (ethyl alcohol)	+
Terralin	+
Centring oil	_

All tests were carried out at room temperature (+23 °C).





Product Information



Miniature Safety Edge EKS 038

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Important information

Read through the product information carefully. It contains important information on operation, safety and maintenance of the product. Retain the product information for later reference. Always observe the safety instructions on the following pages under **ATTENTION.** Only use the product for the purpose described in the product information.

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Definitions

Miniature Safety Edges are sensors for tactile protective devices. A suitable Control Unit is required for evaluation of the signals.

Intended use

A Miniature Safety Edge detects a person or part of the body when pressure is applied to the actuation area. It is part of a linear tripping device. The task of the protective device is to avoid potential hazardous situations for a person within a danger zone such as shearing or pinching edges.

Typical application areas are automatic windows, covers on machines, medical diagnostic equipment and height-adjustable furniture.

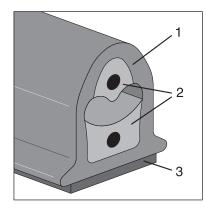
Safe operation of a Miniature Safety Edge depends entirely on

- the surface condition of the mounting surface,
- the correct selection of the size and resistance,
- correct installation as well as
- selection of the suitable Control Unit according to ISO 13849-1.

Limits

A maximum of 5 Miniature Safety Edges may be connected to one Control Unit.

Design



The Miniature Safety Edge EKS 038 consists of (1) insulating TPE-covering, (2) conductive contact layers with embedded wires and (3) self-adhesive acrylic foam on the base of profile.

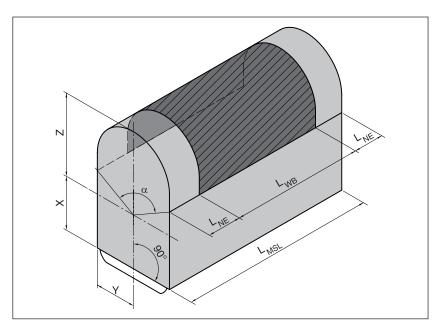


Effective actuation area

The parameters X, Y, Z, $\rm L_{NE}$ and angle α describe the effective actuation area.

For the effective actuation area, the following applies:

$$L_{WB} = L_{MSL} - 2 \times L_{NE}$$



MSL	EKS 038		
α	60°		
L _{NE}	10 mm		
Х	2 mm		
Y	2.65 mm		
Z	2.9 mm		

Parameters:

 L_{WB} = effective actuation length

L_{MSL} = overall length of the Miniature Safety Edge

 L_{NE} = non-sensitive length at the end

 α = effective actuation angle

Available lengths



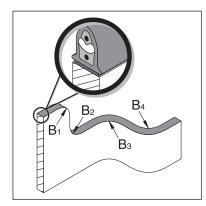


Bend angles and bend radii

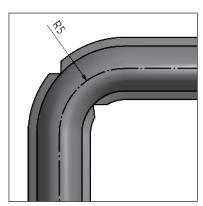
Bend angles

Bend angles are not possible on the Miniature Safety Edge.

Bend radius



Bend radius min.	s EKS 038	
B ₁	500 mm	
B ₂	300 mm	
B ₃	15 mm	
B4	15 mm	



Small 90° bends can also be implemented: Small bend radii up to 5 mm are possible for B_3 and B_4 with two opposite cuts in the protruding parts of the profile base.

Installation position

The installation position can be selected as required.

CAUTION

No pressure must be exerted on the Miniature Safety Edge in non-operative mode.



Connection

Cable exits

Tip

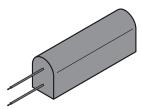
CAUTION

free of tension.

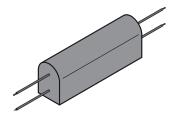
The cables must be laid

With more than one sensor connected one behind the other, we recommend the BK versions.

Axial exit







Version: EKS 038/BK

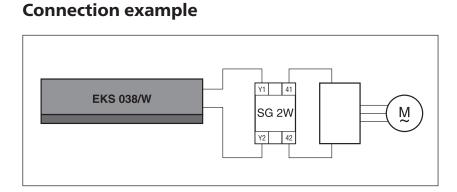
Cable connection

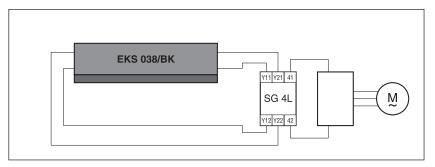
• Cable: 0.35 mm² per strand, Ø 1.4 mm, black

• Cable length: 2.0 m

Option: to max. 200 m
• Cable ends: strands stripped

Option: cable ends available with plug and coupling





Key:

SG 2W 2-wire-technology evaluationSG 4L 4-wire-technology evaluation

Y11, Y12 lower cables; Y21, Y22 upper cables



Profiles

Dimensions and operating paths

EKS 038	
4.0	
Actuation force: < 50 N Actuation distance: < 1.2 mm	

Physical resistance

Miniature Safety Edges EKS	TPE
Degree of protection (IEC 60529)	IP65
Hardness as per Shore A	50 ±5
Behaviour in fire	approx. 40
(DIN 75200)	mm/min



Chemical resistance

The Miniature Safety Edge is resistant against normal chemical influences such as diluted acids and alkalis as well as alcohol over an exposure period of 24 hrs.

The values in the table are results of tests carried out in our laboratory to the best of our knowledge and belief. The suitability of our products for your special area of application must always be verified with your own practical tests.

Explanation of symbols:

+ = resistant

± = resistant to a certain extent

- = not resistant

Miniature Safety Edge EKS	TPE
Acetone	-
Formic acid	-
Armor All	+
Car shampoo	+
Buraton	+
Butanol	-
Sodium hypochlorite	-
Disinfectant	+
Acetic acid 10 %	-
Ethanol	+
Ethyl acetate	-
Ethylene glycol	+
Window cleaner	
Alcohol-based	+
Alkaline cleaner	+
Neutral cleaner	+
Greases	±
Volatile softeners	-
Anti-frost agent	+
Skin cream	+
Icidine	+
Incidine	+
Incidine plus	+
Plastic cleaner	+
Lyso FD 10	+
Metal working oil	-
Microbac	+
Microbac forte	+
Minutil	+
Saline solution 5 %	+
Spirit (ethyl alcohol)	+
Terralin	+
UV-resistance	+
Centring oil	-

Note:

Tests are carried out at room temperature (+23 °C).

Attachment

Per acrylic-foam adhesive tape

Requirements

For ideal bonding, the bonding surface must be

- + clean
- + dry
- + smooth.

Avoid

- very uneven
- sharp-edged bonding surfaces.

Recommended working temperature: +15 to +25°C.

Note:

Check with adhesion tests before serial use whether bonding is possible on the selected installation surface.

Bonding with on	with Primer	without Primer
ABS	1	-
Aluminium: natural	1	+
Aluminium: anodised	1/3	-
Aluminium: powder-coated	1	-
CAB	-	-
Glass	4/5	-
Wood: natural	-	-
Wood: glazed, varnished	2	-
Wood: veneered, light weight building board	2	-
PA6, PA66	3	-
PE, HDPE	-	-
PMMA	1	-
PP	1	-
PS	-	-
PVC	2	-
SAN	1	-
Steel, stainless steel	1/3	-

Note:

Tests are carried out at room temperature (+23 °C).

Preparation

Only applies to bend radii < 15 mm.

- 1. Measure bend locations and mark on both sides.
- 2. Carefully cut into both profile sides at the markings, making sure you only cut the projecting part.

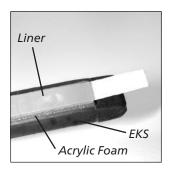
Explanation of symbols:

- + = suitable
- = not suitable
- 1 = Primer 4298UV
- 2 = Primer 4297
- 3 = Multiprimer
- 4 = Silan Primer
- 5 = Primer 4299

CAUTION

Damage to the rest of the TPE-covering renders the Miniature Safety Edge unusable. Dispose of faulty Miniature Safety Edge.





Bonding

- 1. Clean and degrease bonding surface (e.g. with isopropanol).
- 2. Apply primer as thinly as possible to complete bonding surface with brush.
- 3. Air dry primer for approx.10 minutes.
- 4. Remove 10 to 15 cm of liner from acrylic foam.
- 5. Place on bonding surface and press on firmly, without any tensile stress.
- 6. Repeat items 4. and 5. until EKS is completely bonded.
- 7. Maximum adhesion is achieved after 24 hrs.

Note:

If tensile stress is applied, the EKS can become several millimetres longer.

Tip:

For long straight sections, an extended try square may be useful for alignment.

Installation accessories

Part no.	Designation	Pack. unit
7500462	Primer 4298 type 3M, 125 ml, in can	1 pc.
7501995	Primer 4297 type 3M, 125 ml, in can	1 pc.
1003360	Multiprimer, 250 ml 24-P	1 pc.

ATTENTION

Smaller winding diameters cause separation of the liner and therefore damage to the selfadhesive acrylic foam.

Storage

Correct storage of the Miniature Safety Edge requires a winding diameter of at least 600 mm.



Miniature Safety Edge EKS 038 cut-to-size with resistor (type W) or without resistor (type BK).



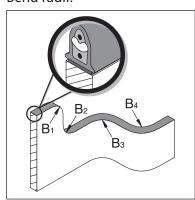
1:1

Switching characteristics at v _{test} = 5	0 mm/min		
Switching operations	> 1× 10 ⁵		
Actuating force	+23 °C	-25 °C	
Test piece (rod) Ø 4 mm	< 15 N	< 25 N	
Test piece (rod) Ø 200 mm	< 35 N	< 50 N	
Actuating distance			
Test piece (cylinder) Ø 80 mm	< 1.2 mm		
Actuation angle			
Test piece (cylinder) Ø 80 mm	± 30°		
Safety classifications			
B _{10d} as per ISO 13849-1	2× 10 ⁶		
Mechanical operating conditions			
Sensor length (min./max.)	70 mm / 150) m	
Cable length (min./max.)	2 / 200 m		
Attachment	Using acrylic-foam adhesive		
Peel force	15 N/cm		
Bend radii, minimum			
B ₁ / B ₂ / B ₃ / B ₄	500 / 300 / 15 / 15 mm		
IEC 60529: Degree of protection	IP65		
Operating temperature	-25 °C to +80 °C		
short-term (15 min)	-40 °C to +10	00 °C	
Electrical operating conditions			
Terminal resistance	1k2 ± 5%		
Output	max. 250 mV	V	
Contact transition resistance	< 400 Ohm (per sensor)		
More than one sensor	max. 5 in series		
Electrical rating			
Voltage	max. 24 V D0	2	
Current (min./max.)	1 mA / 10 mA		
Connection cable	Ø 1.4 mm pe	r strand	
	2× 0.35	mm ²	
Control Unit (recommendation)			
ISO 13849-1 Cat. 3	SG-EFS 104/2W (type W)		
ISO 13849-1 Cat. 3	SG-EFS 104/4	4L (type BK)	
Chemical resistance			
The Miniature Safety Edge is resistan			
fluences over a period of exposure of	24 hrs (see p. 8)		

ISO 3302 L2

ISO 3302 E2

Bend radii:



Length as per Profile section as per

Dimensional tolerances



From:			
		Fax:	
Company			+49 731 2061-222
Department			
Name, first name			
P. O. Box	Post code	City	
Street	Post code	City	
Phone	Fax	E-mail	
Area of application			
(e.g window construction, transport,) Mechanical condition	medical technology, machine	closing edges, public	
EKS	○ Type BK		
LK3		esistor kΩ	
Length: m	Packing unit:		
Attachment per:	O Bonding	units	
Attachment per.	O Snap-in foot		
☐ Angle piece	Shap in root		
construction:	× per EKS		
☐ Cable length:	m (standard	d: 2.0 m)	
☐ Number of monito	oring circuits:	□ SG	
Pinching and shearin	g edges to be protecte	ed:	
(Diagram incl. mounting po	ssibility and cable routing)		





DIY miniature safety edges



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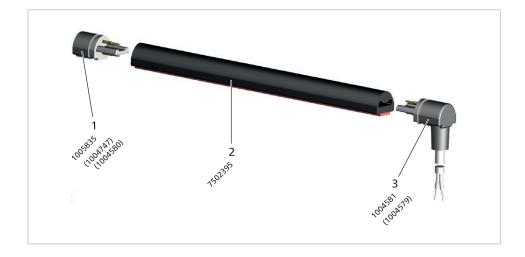
Overview

Contact profile – miniature safety edge

The semi-finished contact profile is cut to length and assembled with the other components to create the finished working product, which is called a miniature safety edge.

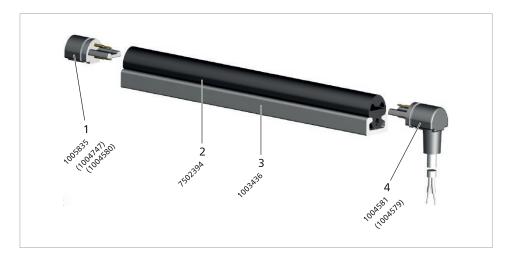
EKS 011 TPE

- 1 End piece with resistor
- 2 Contact profile
- 3 End piece with cable



EKS 014 TPE

- 1 End piece with resistor
- 2 Contact profile
- 3 Aluminium profile
- 4 End piece with cable



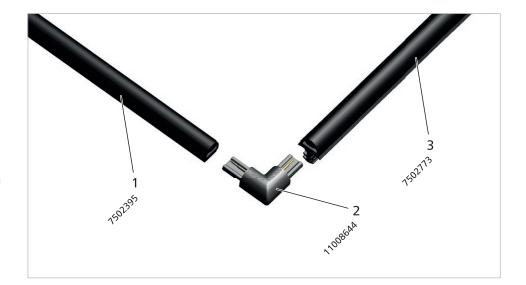
EKS 052 TPE

- 1 End piece with resistor
- 2 Contact profile
- 3 End piece with cable



Subject to technical modifications.





Example combination comprising:

- 1 Contact profile EKS 011
- 2 Connector
- 3 Contact profile EKS 052

Materials list

Part No.	Designation	PU
7502395	Contact profile EKS 011 TPE, self-adhesive	50 m
7502394	Contact profile EKS 014 TPE, with snap-in foot	50 m
7502773	Contact profile EKS 052 TPE, with clamp foot, black	45 m
7504150	Contact profile EKS 052 TPE, with clamp foot, window grey *	45 m
11011768	Contact profile EKS 052 TPE, with clamp foot, light grey *	45 m
1004580	End piece with resistor 1k2	50 pcs.
1004747	End piece with resistor 2k2	50 pcs.
11008731	End piece with resistor 5k6 *	50 pcs.
1005835	End piece with resistor 8k2	50 pcs.
1004579	End piece with PVC cable 2.5 m, axial	50 pcs.
1004581	End piece with PVC cable 2.5 m, angled 90°	50 pcs.
11008644	90° connector * incl. assembly aid SH4	50 pcs.
1007219	End piece without resistor *	50 pcs.
1003436	Aluminium profile C 10 for EKS 014 with snap-in foot	6 m
11002568	Scissors with stop	1 pc.
11012760	Assembly aid SH4	1 pc.
11013001	Installation instructions for DIY miniature safety edges	1 pc.

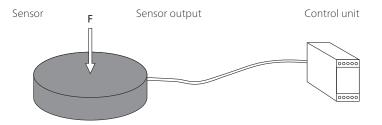
^{*} Not covered by UL certification



Definitions

Pressure-sensitive protective device

A pressure-sensitive protective device consists of one or more pressure-sensitive sensors, a signal processing unit, and one or more output signal switching devices. The control unit is made up of the signal processing unit and output signal switching device(s). The pressure-sensitive protective device is triggered when the sensor is activated.

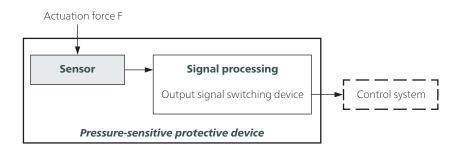


Sensor

The sensor is the part of the pressure-sensitive protective device that generates a signal when the actuation force F is applied. Mayser safety systems feature a sensor whose actuation area is deformed locally.

Signal processing

The signal processing unit is the part of the pressure-sensitive protective device that converts the output signal of the sensor and controls the status of the output signal switching device. The output signal switching device is the part of the signal processing unit which is connected to the downstream control system and which transmits safety output signals such as STOP.



Tip: Terms are defined in ISO 13856-2 Section 3.

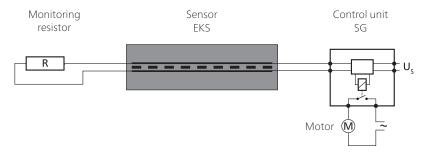
Tip: Safety-related terms are defined in ISO 13849-1 Section 3.



Criteria for selecting the sensor type

- Category according to ISO 13849-1
- Performance level (PL) of the pressure-sensitive protective device = at least PL,
- Temperature range
- Degree of protection according to IEC 60529:
 IP40 is the standard for DIY miniature safety edges.
 Higher degrees of protection are possible if special adhesive is used.
- Low actuation forces
- Minimum overall height
- Small bend radii; 90° angles possible with 90° connector (part no. 11008644)

Operation principle of 2-wire technology



The monitoring resistor must be compatible with the control unit. The standard type is 8k2.

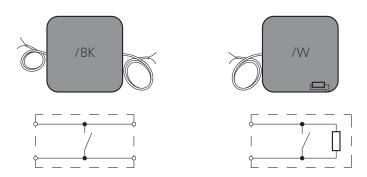
For your safety:

The sensor and connection cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on controlled bridging of the contact surfaces with a monitoring resistor (closed-circuit principle).

Types

/BK With cables on both sides for use as a through sensor or with an external monitoring resistor for use as an end sensor

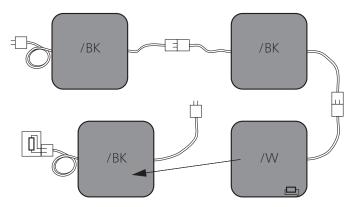
/W With an integrated monitoring resistor for use as an end sensor



Subject to technical modifications.



Sensor combination

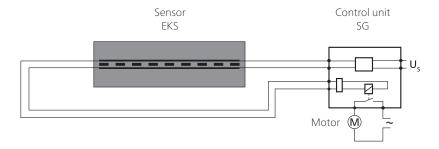


Version with external resistor, therefore no variety of models

Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety edges can be combined to achieve custom lengths and angles

Operation principle of 4-wire technology



The 4-wire technology can only be used together with control unit SG-EFS 104/4L.

For your safety:

The sensor and connection cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on signal transmission feedback – without a monitoring resistor.

Types

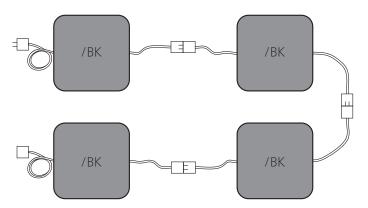
/BK With cables on both sides for use as a through sensor



Subject to technical modifications.



Sensor combination



Combination:

- Connection of more than one sensor
- Only one control unit required
- Safety edges can be combined to achieve custom lengths and angles

Safety

Intended use

A miniature safety edge detects a person or part of their body when pressure is applied to the actuation area. It is a linear tripping device. Its purpose is to prevent possible hazardous situations that could affect someone within a danger zone, such as shearing and pinching edges.

Typical areas of application are automated windows and façade systems, automation technology and moving units in medical technology.

Safe operation of a miniature safety edge depends entirely on

- the surface condition of the mounting surface,
- the correct choice of EKS profile and
- correct installation.

Due to the design, the actuation area is actually smaller than it looks because of the non-sensitive edges. Once these have been allowed for, what remains is the effective actuation area (see chapter *Effective actuation area*).



Limits

- No more than 3 /BK-type sensors can be connected to one control unit
- No more than 2 /BK-type sensors and 1 /W-type sensor can be connected to one control unit

If more sensors are required, please contact Mayser's service department.

Note: Two contact profiles connected via a 90° connector count as 2 sensors.

Exclusions

The sensors are **not** suitable for:

• Performing a sealing function. Constant actuation of sensors can result in permanent damage.

Other safety aspects

The following safety aspects relate to pressure-sensitive protective devices consisting of a sensor and a control unit.

Performance Level (PL)

Fault exclusion according to ISO 13849-2 Table D.8: Non-closing of contacts in the case of pressure-sensitive protective devices according to ISO 13856. In this case, the diagnostic coverage (DC) is not calculated or taken into account when determining the PL. Assuming a high $MTTF_D$ value for the control unit, a performance level of up to PL d can be achieved by the pressure-sensitive protective device.

Is the protective device suitable?

First, the integrator must decide what PL_r is required for the hazard. After that, they must select the protective device.

Finally, the integrator needs to check whether the category and PL of the selected protective device are appropriate.

Risk and safety assessment

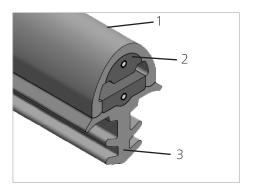
For the risk and safety assessment of your machine, we recommend ISO 12100 "Safety of machinery — General principles for design".

Without reset function

When a protective device without reset function is used (automatic reset), the reset function must be provided in some other way.



Design



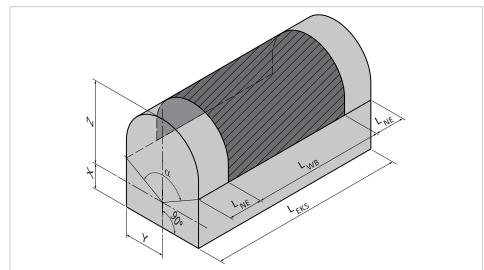
The miniature safety edge consists of a sensor (1 to 3)

- (1) EKS contact profile with
- (2) integrated NO switch element,
- (3) mounting element and an SG evaluating control unit.

Effective actuation area

The parameters X, Y, Z, L_{WB} and the angle α describe the effective actuation area. For the effective actuation area, the following applies:

$$L_{WB} = L_{EKS} - 2 \times L_{NE}$$



		EKS 011	EKS 014	EKS 052
α		80°	80°	80°
	End piece W	27 mm	27 mm	27 mm
	End piece with cable, axial	27 mm	27 mm	27 mm
L _{NE}	End piece with cable, angled 90°	28.5 mm	28.5 mm	28.5 mm
	90° connector	27 mm	27 mm	27 mm
Χ		2.05 mm	2.3 mm	2.1 mm
Υ		3.95 mm	3.9 mm	4.7 mm
Z		4.6 mm	4.5 mm	4.5 mm
X + Z		6.65 mm	6.8 mm	6.6 mm

Parameters:

 L_{WB} = effective actuation length

 L_{EKS} = overall length of the miniature safety edge

L_{NE} = non-sensitive length at the end of the miniature safety edge

 $\alpha = \text{effective actuation}$ angle

Subject to technical modifications.



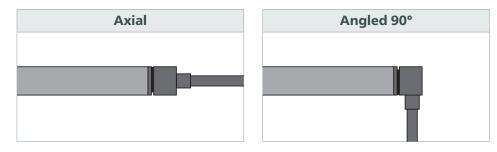
Installation position

The installation position can be selected as required, i.e. all installation positions from A to D as per ISO 13856-2 are possible.

Connection

Cable exits

Two cable exits are available: axial and angled 90°.



Cable connection

- Standard cable lengths
 L = 2.5 m
- Maximum total cable length to the control unit L_{max} = 100 m (minus the lengths of the sensors)

/W-type sensor with 1 line	/BK-type sensor with 2 lines	
 As an individual /W-type sensor or a /W-type end sensor Integrated resistor 1 two-wire cable 	As a /BK-type through sensorWithout resistor2 two-wire cables	
/W I	/BK	



Wire colours

Colour coding

BK Black RD Red

/W-type sensor with 1 line	/BK-type sensor with 2 lines	
RD I BK	RD ← − − → RD	

Connection examples

Key:

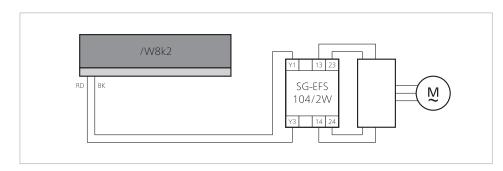
/W8k2 Sensor for 2-wire technology with resistor 8k2

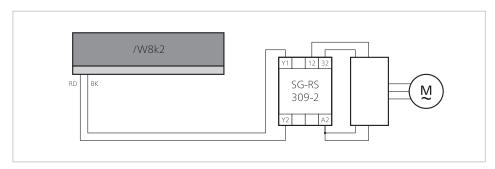
/BK Sensor for 4-wire technology

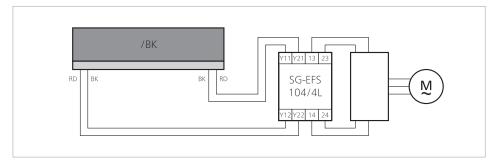
M Motor

Colour coding

BK Black RD Red

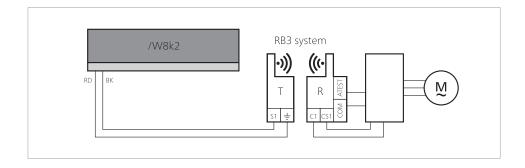






Subject to technical modifications.





Sensor surface

Resistance

The resistance ratings listed below (at a room temperature of 23 °C) depend on the sensor having an undamaged surface.

Physical resistance

Higher degree of protection

Higher degrees of protection up to IP64 are possible using special adhesive (part no. 1004987).

	TPE
IEC 60529: degree of protection	IP40
UV resistance	Yes

Chemical resistance

The sensor is resistant to a certain extent to normal chemical influences such as diluted acids and alkalis, as well as alcohol, over an exposure period of 24 hours.

The values in the table are the results of tests carried out in our laboratory. You must always conduct your own practical tests to verify that our products are suitable for your specific area of application.



Explanation of symbols:

- + = resistant
- ± = resistant to a certain extent
- = not resistant

	TPE
Acetone	_
Formic acid	_
Armor All	+
Car shampoo	+
Petrol	_
Brake fluid	+
Buraton	+
Butanol	_
Sodium hypochlorite	_
Disinfectant 1%	+
Diesel	_
Acetic acid 10%	_
Ethanol	+
Ethyl acetate	_
Ethylene glycol	+
Greases	<u>+</u>
Anti-frost agent	+
Skin cream	+
Incidin	+
Incidin Plus	+
Cooling lubricant	_
Plastic cleaner	+
Lyso FD 10	+
Metal working oil	_
Microbac	+
Microbac forte	+
Minutil	+
Saline solution 5%	+
Spirit (ethyl alcohol)	+
Terralin	+
Centring oil	_



Fixing

Three fixing methods are available:

- Using acrylic foam adhesive tape
- Using a snap-in foot
- Using a clamp foot

The fixing method depends on which contact profile is selected.

Fixing method	EKS 011	EKS 014	EKS 052
Acrylic foam adhesive tape	•	_	_
Snap-in foot	_	•	_
Clamp foot	_	_	•

Using acrylic foam adhesive tape

Double-sided foam adhesive tape is applied to the miniature safety edge. The double-sided foam adhesive tape (acrylic foam) is already affixed to the bottom side of the contact profile.

With primer

The clean, dry and smooth bonding surface must be treated with primer before sticking on the miniature safety edge.

Without primer

The only material that the acrylic foam will adhere to reliably without using primer is uncoated aluminium.

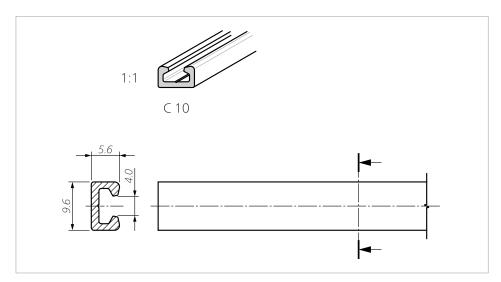
Not suitable

The following materials are not suitable for acrylic foam adhesive tape: CAB, glass, uncoated wood, PE, HDPE and PS.



Using a snap-in foot

The miniature safety edge is clipped into an aluminium profile.



Tolerances in accordance with EN 755-9

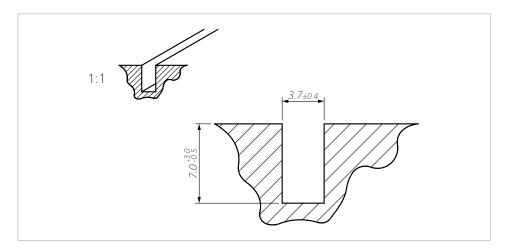
Aluminium profile C 10

Standard profile for EKS 014:

First the aluminium profile must be mounted onto the closing edge and then the miniature safety edge clipped into the aluminium profile.

Using a clamp foot

The miniature safety edge is pressed into a groove. A precise groove ensures an accurate and lasting fit.





Maintenance and cleaning

The sensors are virtually maintenance-free.

The control unit also monitors the sensor at the same time.

Regular inspection

Depending on the operational demands, the sensors must be inspected at regular intervals (at least monthly)

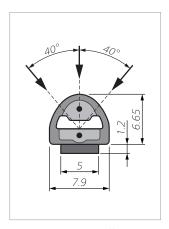
- for proper functioning,
- for damage and
- for correct fixing.

Cleaning

If the sensors become dirty, they can be cleaned with a mild cleaning product.

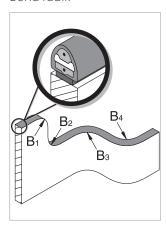


SK EKS 011 TPE



Dimensions in millimetres (mm) Dimensional tolerances according to ISO 3302 E2/L2

Bend radii:



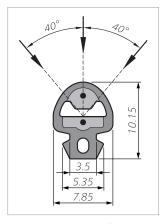
Higher degree of protection, higher tensile load

If special adhesive is used (e.g. Weicon VA 250 Black ID 10018873), higher degrees of protection of up to IP64 can be achieved and a tensile load of up to 60 N can be exerted on the cable.

Miniature safety edge (without control unit)	SK EKS/W 011 TPE or SK EKS/BK 011 TPE	
Testing basis Sensor colour	In accordance with ISO 13856-2 Black	
Switching characteristics at $v_{test} = 5$	0 mm/min	
Switching operations	10,000	
Actuation force	+23 °C -25 °C	
Test piece (rod) Ø 4 mm	< 15 N < 30 N	
Test piece (rod) Ø 200 mm	< 25 N < 50 N	
Actuation distance		
Test piece (cylinder) Ø 80 mm	< 2.0 mm	
Actuation angle		
Test piece (cylinder) Ø 80 mm	±40°	
Finger detection	Yes	
Safety classifications		
ISO 13849-1: B _{10D}	2× 10 ⁶	
Mechanical operating conditions		
Sensor length (min. max.)	10 cm 50 m	
Cable length	2.5 m	
Fixing method	Acrylic foam adhesive tape	
Peel force	15 N/cm	
Bend radii, minimum		
B ₁ B ₂ B ₃ B ₄	120 150 20 20 mm	
Max. load capacity (impulse)	600 N	
Tensile load, cable (max.)	20 N	
IEC 60529: degree of protection	IP40	
Operating temperature	-25 to +80 °C	
Short-term (15 min)	-40 to +100 °C	
Storage temperature Weight (with acrylic foam)	−40 to +80 °C 43 g/m	
,	45 g/111	
Electrical operating conditions	412 212 516 212	
Terminal resistance (±1%)	1k2, 2k2, 5k6 or 8k2	
Nominal output (max.)	250 mW	
Resistance: sensor activated	< 400 ohms	
Number of /BK-type sensors Switching voltage (max.)	Max. 3 in series	
SWITCHING VOILAGE (MAX.)	DC 24 V	
Switching current (min. max.)	1 10 mA	

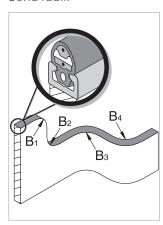


SK EKS 014 TPE



Dimensions in millimetres (mm) Dimensional tolerances according to ISO 3302 E2/L2

Bend radii:



Higher degree of protection, higher tensile load

If special adhesive is used (e.g. Weicon VA 250 Black to 60 N can be exerted on the cable.

Miniature safety edge (without control unit)	SK EKS/W 014 TPE or SK EKS/BK 014 TPE	
Testing basis Sensor colour	In accordance with ISO 13856-2 Black	
Switching characteristics at v _{test} = 50 mm/min		
Switching operations Actuation force Test piece (rod) Ø 4 mm Test piece (rod) Ø 200 mm Actuation distance Test piece (cylinder) Ø 80 mm Actuation angle Test piece (cylinder) Ø 80 mm Finger detection	10,000 +23 °C	
Safety classifications	1.03	
ISO 13849-1: B _{10D}	2× 10 ⁶	
Mechanical operating conditions		
Sensor length (min. max.) Cable length Fixing method Snap-in foot width Aluminium profile (recommended) Bend radii, minimum B1 B2 B3 B4 Max. load capacity (impulse) Tensile load, cable (max.) IEC 60529: degree of protection Operating temperature Short-term (15 min) Storage temperature Weight	10 cm 50 m 2.5 m Snap-in foot 3.5 mm C 10 120 150 20 20 mm 600 N 20 N IP40 -25 to +80 °C -40 to +100 °C -40 to +80 °C Without with aluminium profile (type) 49 g/m 125 g/m (C 10)	
Electrical operating conditions		
Terminal resistance (±1%) Nominal output (max.)	1k2, 2k2, 5k6 or 8k2 250 mW	

< 400 ohms

DC 24 V

1 | 10 mA

Max. 3 in series

 \emptyset 2.9 mm PVC 2 \times 0.25 mm²

ID 10018873), higher degrees of protection of up to IP64 can be achieved and a tensile load of up

Resistance: sensor activated

Number of /BK-type sensors

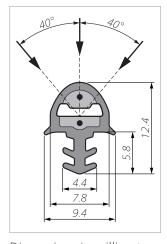
Switching current (min. | max.)

Switching voltage (max.)

Connection cable

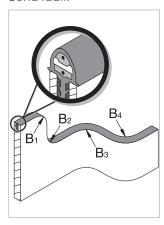


SK EKS 052 TPE



Dimensions in millimetres (mm) Dimensional tolerances according to ISO 3302 E2/L2

Bend radii:



Higher degree of protection, higher tensile load

If special adhesive is used (e.g. Weicon VA 250 Black ID 10018873), higher degrees of protection of up to IP64 can be achieved and a tensile load of up to 60 N can be exerted on the cable.

Miniature safety edge (without control unit)	SK EKS/W 052 TPE or SK EKS/BK 052 TPE
Testing basis Sensor colour	In accordance with ISO 13856-2 Black, window grey (RAL 7040) or light grey (RAL 7035)
Switching characteristics at $v_{test} = 5$	0 mm/min
Switching operations Actuation force Test piece (rod) Ø 4 mm Test piece (rod) Ø 200 mm Actuation distance Test piece (cylinder) Ø 80 mm Actuation angle Test piece (cylinder) Ø 80 mm Finger detection	10,000 +23 °C -25 °C < 25 N < 30 N < 40 N < 50 N < 2.0 mm ±40° Yes
<u>-</u>	res
Safety classifications ISO 13849-1: B _{10D}	2× 10 ⁶
Mechanical operating conditions	2.7.10
Sensor length (min. max.) Cable length Fixing method Groove width for clamp foot Bend radii, minimum B1 B2 B3 B4 Max. load capacity (impulse) Tensile load, cable (max.) IEC 60529: degree of protection Operating temperature Short-term (15 min) Storage temperature Weight	10 cm 45 m 2.5 m Clamp foot 3.7 ±0.4 mm 120 150 20 20 mm 600 N 20 N IP40 -25 to +80 °C -40 to +100 °C -40 to +80 °C 54 g/m
Electrical operating conditions	
Terminal resistance (±1%) Nominal output (max.) Resistance: sensor activated Number of /BK-type sensors Switching voltage (max.) Switching current (min. max.) Connection cable	1k2, 2k2, 5k6 or 8k2 250 mW < 400 ohms Max. 3 in series DC 24 V 1 10 mA Ø 2.9 mm PVC 2 × 0.25 mm²



Marking

If you combine sensors with control units and thereby place pressure-sensitive protective devices on the market, you should observe the basic requirements according to ISO 13856.

As well as meeting technical requirements, this also means – in particular – observing any that relate to marking and information for use.

UL certification

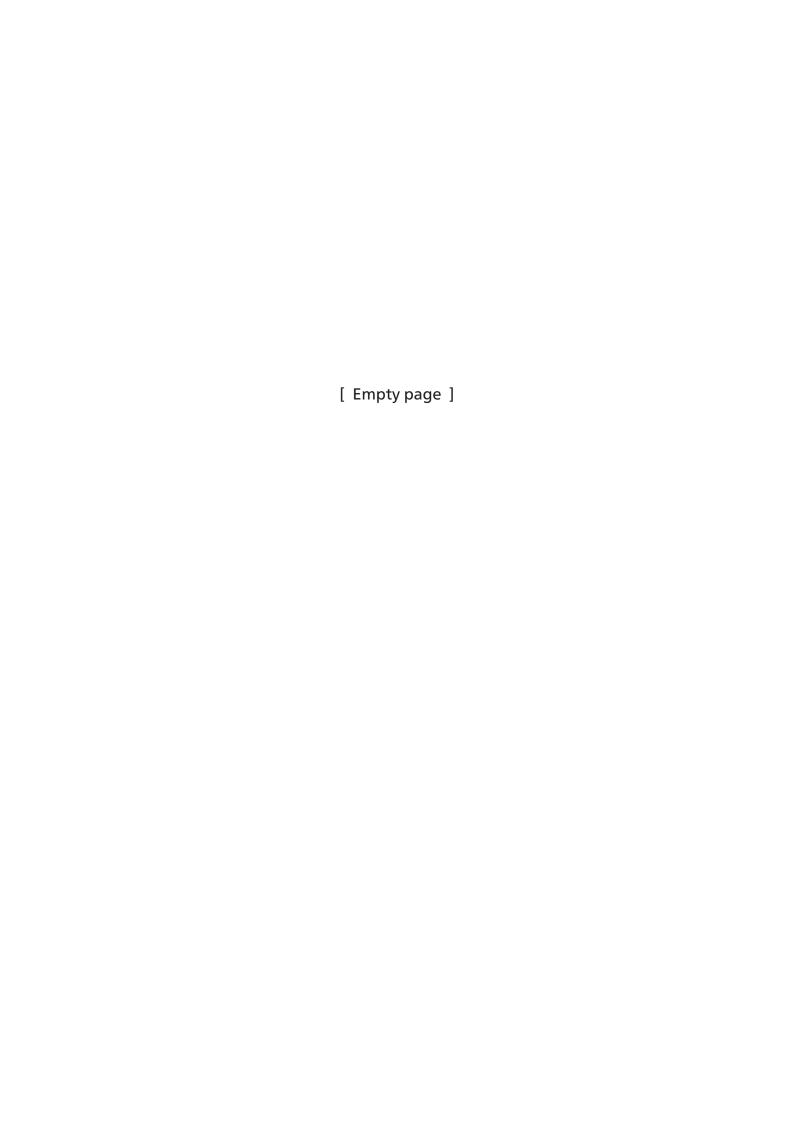


The design type of the product complies with the basic requirements of UL standard:

• UL 325

The same applies to all components listed in this document, with the exception of:

- 7504150 Contact profile EKS 052 TPE, window grey
- 11011768 Contact profile EKS 052 TPE, light grey
- 11008731 End piece with resistor 5k6
- 11008644 90° connector
- 1007219 End piece without resistor



MAYSER[®]



Safety bumpers SB



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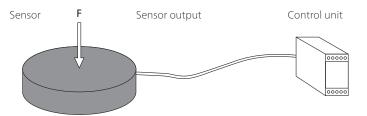
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Definitions

Pressure-sensitive protective device

A pressure-sensitive protective device consists of one or more pressure-sensitive sensors, a signal processing unit, and one or more output signal switching devices. The control unit is made up of the signal processing unit and output signal switching device(s). The pressure-sensitive protective device is triggered when the sensor is activated.

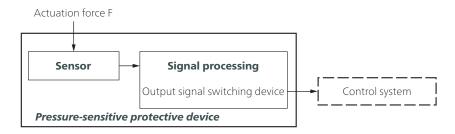


Sensor

The sensor is the part of the pressure-sensitive protective device that generates a signal when the actuation force F is applied. Mayser safety systems feature a sensor whose actuation area is deformed locally.

Signal processing

The signal processing unit is the part of the pressure-sensitive protective device that converts the output signal of the sensor and controls the status of the output signal switching device. The output signal switching device is the part of the signal processing unit which is connected to the downstream control system and which transmits safety output signals such as STOP.



Tip: Terms are defined in ISO 13856-3 Section 3.

Tip: Safety-related terms are defined in ISO 13849-1 Section 3.

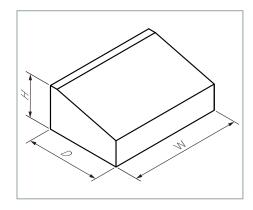


Dimensions

Width W (length) Height H Depth D

Technical data: Width \times height \times depth $(W \times H \times D)$

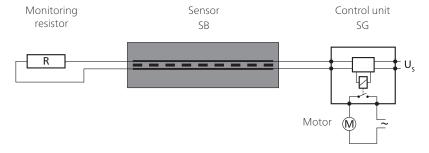
e.g. STB $1000 \times 100 \times 150$



Criteria for selecting the sensor type

- Category according to ISO 13849-1
- Performance level (PL) of the pressure-sensitive protective device = at least PL_r
- Temperature range
- Degree of protection in accordance with IEC 60529: IP54 is standard for safety bumpers (it is important to pay attention to the installation position).
 - Higher degrees of protection must be checked individually.
- Environmental influences such as swarf, oil, coolant, outdoor use...

Operation principle of 2-wire technology



The monitoring resistor must be compatible with the control unit. The standard type is 8k2.

For your safety:

The sensor and connection cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on controlled bridging of the contact surfaces with a monitoring resistor (closed-circuit principle).

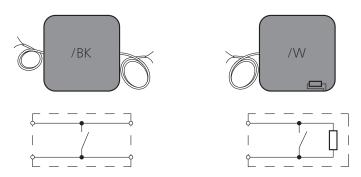
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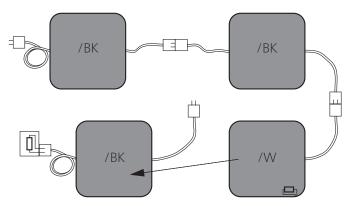
Types

/BK With cables on both sides for use as a through sensor or with an external monitoring resistor for use as an end sensor

/W With an integrated monitoring resistor for use as an end sensor



Sensor combination



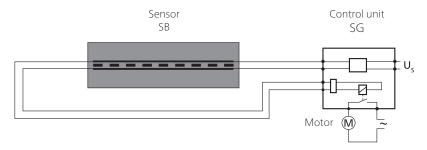
Version with external resistor, therefore no variety of models

Combination:

- Connection of more than one sensor
- Only one control unit required
- Bumper design can be customised in terms of depth and shape



Operation principle of 4-wire technology



The 4-wire technology can only be used together with control unit SG-EFS 104/4L.

For your safety:

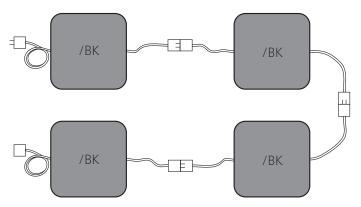
The sensor and connection cables are constantly monitored to ensure they are functioning correctly. Monitoring relies on signal transmission feedback – without a monitoring resistor.

Types

/BK With cables on both sides for use as a through sensor



Sensor combination



Combination:

- Connection of more than one sensor
- Only one control unit required
- Bumper design can be customised in terms of depth and shape



Safety

Intended use

A safety bumper detects a person or part of the body when pressure is applied to the effective actuation area. In most cases it is a linear tripping device and presence detector. Its purpose is to prevent possible hazardous situations that could affect someone within a danger zone, such as shearing and pinching edges. Typical areas of application are: AGV systems, hangar doors, aerial platforms and gantry cranes.

Safe operation of a safety bumper depends entirely on

- the surface condition of the mounting surface,
- the correct selection of the size and resistance rating as well as
- correct installation.

For additional application guidance, please refer to ISO 13856-3 Annex D.

Limits

- No more than 10 /BK-type sensors can be connected to one control unit
- No more than 9 /BK-type sensors and 1 /W-type sensor can be connected to one control unit

Exclusions

The sensors are **not** suitable for:

Detecting fingers



Other safety aspects

The following safety aspects relate to pressure-sensitive protective devices consisting of a sensor and a control unit.

Performance Level (PL)

The PL has been determined using the procedure defined by ISO 13849-1. Fault exclusion according to ISO 13849-2 Table D.8: Non-closing of contacts in the case of pressure-sensitive protective devices according to ISO 13856. In this case, the diagnostic coverage (DC) is not calculated or taken into account when determining the PL. Assuming a high MTTF $_{\rm D}$ value for the control unit, a performance level of up to PL d can be achieved by the pressure-sensitive protective device.

Is the protective device suitable?

First, the integrator must decide what PL_r is required for the hazard. After that, they must select the protective device.

Finally, the integrator needs to check whether the category and PL of the selected protective device are appropriate.

Risk and safety assessment

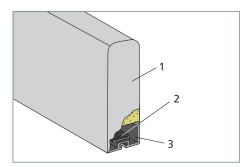
For the risk and safety assessment of your machine, we recommend ISO 12100 "Safety of machinery — General principles for design".

Without reset function

When a protective device without reset function is used (automatic reset), the reset function must be provided in some other way.



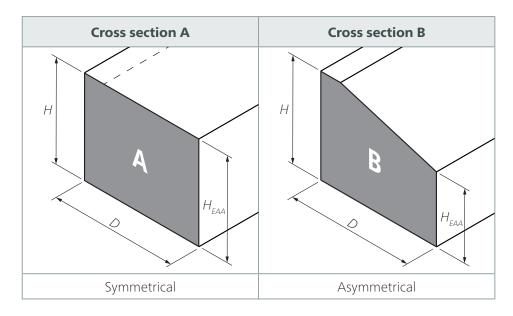
Design



The safety bumper consists of a sensor (1 to 3) –

- (1) foam with casing,
- (2) switch element,
- (3) aluminium mounting plate and an SG evaluating control unit.

Cross sections



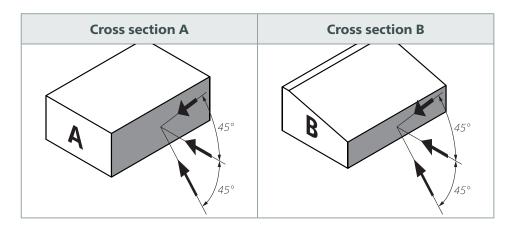
Cross section and aluminium mounting plate combinations

Cross section	Α	В	В
Aluminium mounting plate	C 40	C 100	C 150
Height H	40 mm	100 mm	150 mm
	Height of	effective actuation	area H_{EAA}
Depth D = 100 mm	40 mm	_	_
Depth D = 150 mm	_	78 mm	_
Depth D = 200 mm	_	70 mm	_
Depth D = 250 mm	_	61 mm	_
Depth D = 300 mm	_	_	102 mm
Depth D = 400 mm	_	_	84 mm

Subject to technical modifications.



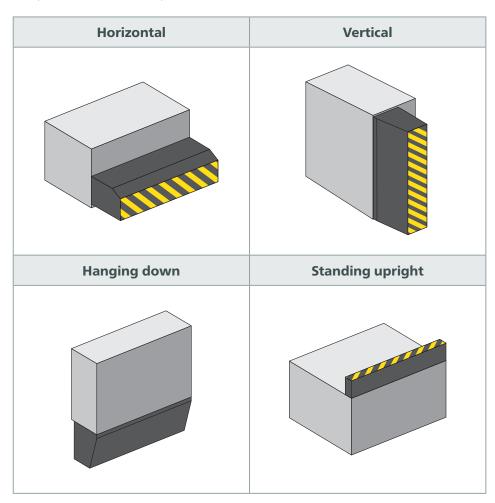
Effective actuation area



Installation position

The installation position can be selected as required, i.e. all installation positions necessitated by the application are possible.

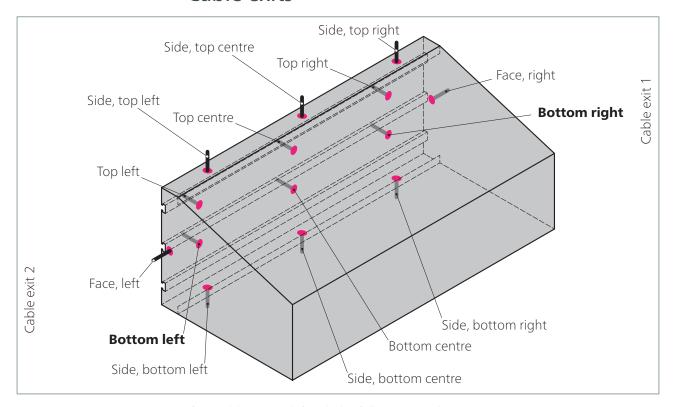
The preferred installation positions are:





Connection

Cable exits



If no cable exit is defined, the following applies:

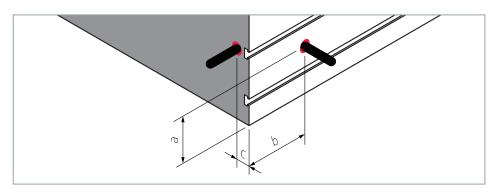
SB/W Cable exit 1: bottom right

Cable exit 2:-

SB/BK Cable exit 1: bottom right

Cable exit 2: bottom left

Position



Aluminium mounting plate	C 40	C 100	C 150
а	7 mm	40 mm	50 mm
b	50 mm	50 mm	50 mm
С	14 mm	14 mm	14 mm

Subject to technical modifications.



Cable connection

Standard cable lengths
 L = 2.0 m / 5.0 m / 10 m

• Maximum total cable length to the control unit $L_{max} = 100 \text{ m}$

• Cable ends: stripped wires
Optional: cable ends available with plug and coupling

/W-type sensor with 1 line	/BK-type sensor with 2 lines
 As an individual /W-type sensor or a /W-type end sensor Integrated resistor 1 two-wire cable 	 As a /BK-type through sensor Without resistor 2 two-wire cables
/W U	/BK

Wire colours

/W-type sensor with 1 line	/BK-type sensor with 2 lines
RD I BK	RD ← ← ← → RD I BK ← BK

Colour coding

BK Black RD Red



Connection examples

Key:

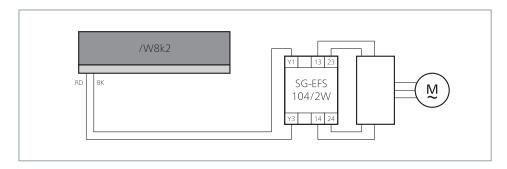
/W8k2 Sensor for 2-wire technology with resistor 8k2

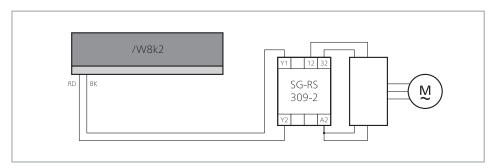
/BK Sensor for 4-wire technology

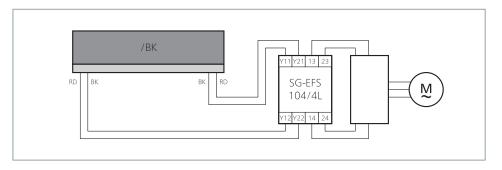
M Motor

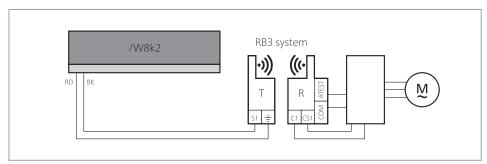
Colour coding

BK Black RD Red











Sensor surface

The sensor surface is a sleeve that mechanically protects the foam body and the internal parts. The sleeve also prevents dirt and moisture from penetrating the sensor (IP54).

PES (polyester sleeve)

Areas of application:

- Indoors
- Outdoors with additional sealing
- Heavy mechanical loads

Colour:

Standard:

- Plain yellow
- Plain black
- Black and yellow stripes

Optional:

• "No entry" symbol



PUR (skin)

Areas of application:

- For dry indoor environments
- Normal mechanical loads
- Tight-fitting skin around foam

Colour:

Standard:

- Plain yellow
- Plain black
- Black and yellow stripes

Optional:

• "No entry" symbol

Subject to technical modifications.





Synthetic leather

Areas of application:

• For environments with high aesthetic requirements

Colour:

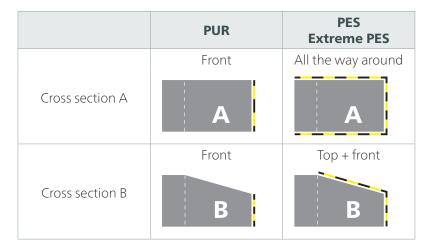
Standard:

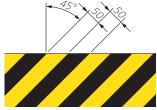
Plain black

Optional sleeves

- Extreme PES in yellow or black, or with black and yellow stripes (for use outdoors)
- Welding protection sleeve in silver (good resistance to flying sparks and hot swarf)
- Theatre fabric, black
- PUR in another RAL colour (on request)

Warning stripes





Subject to technical modifications.



Resistance

The resistance ratings listed below (at a room temperature of 23 °C) depend on the sensor having an undamaged surface.

Physical resistance

	PES	PUR
UV resistance	Yes	Yes
Impregnation (fluorocarbons)		
Water, oil and dirt-repellent	Yes	No

Chemical resistance

The sensor is resistant to a certain extent to normal chemical influences such as diluted acids and alkalis, as well as alcohol, over an exposure period of 24 hours.

The values in the table are the results of tests carried out in our laboratory. You must always conduct your own practical tests to verify that our products are suitable for your specific area of application.

Explanation of symbols:

+ = resistant

± = resistant to a certain extent

– = not resistant

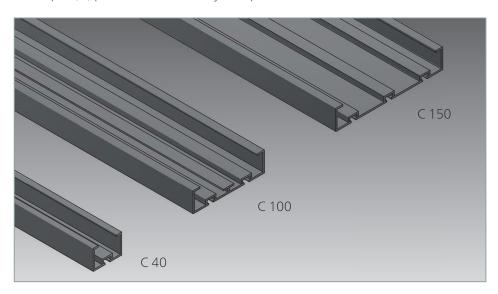
	PES	PUR	Syn- thetic leather	Ex- treme PES	Welding pro- tection sleeve
Acetone	±	_	_	±	+
Formic acid 10%	+	+	±	+	_
Petrol	+	+	_	_	+
Disinfectant	+	_	_	_	+
Diesel fuel	+	+	_	_	+
Acetic acid 10%	+	±	±	+	_
Ethanol 95%	+	_	_	_	+
Ethyl acetate	±	_	_	±	+
Gearbox oil	+	+	_	_	+
Hydraulic oil	+	+	±	+	+
Isopropanol	+	+	_	_	+
Cooling lubricant	+	+	_	+	+
Tap water	+	+	+	+	+
Engine oil	+	+	_	_	+
Sodium hydroxide 10%	_	_	_	_	_
Sulphuric acid 10%	+	+	±	+	_
Washing-up liquid	+	+	+	+	+



Fixing

Safety bumper SB products are mounted directly on the impact surfaces that pose a danger. Aluminium mounting plates are used to support them and fix them in place. The aluminium mounting plates can be fixed in place by using sliding blocks, hammer nuts or M6 hexagon bolts in conjunction with the integrated 6 mm groove.

The following rule applies: the higher the aluminium mounting plate, the greater the depth (D) possible for the safety bumper.



Material properties

- AlMgSi0.5 F22
- Wall thickness: at least 2.0 mm, extruded
- Hot hardened
- Tolerances in accordance with EN 755-9

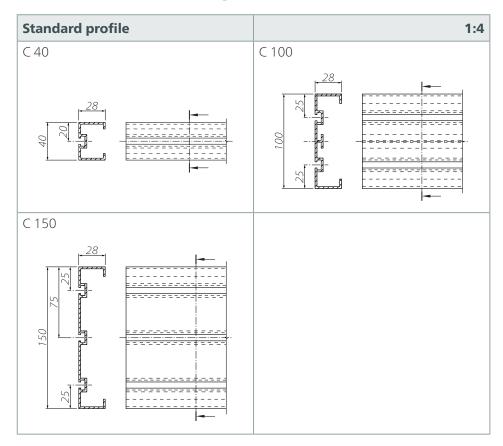
Aluminium mounting plates: Fixing types

Standard profile

C 40	C 100	C 150

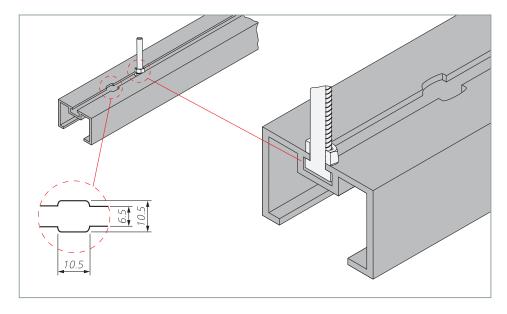


Aluminium mounting plates: Dimensions



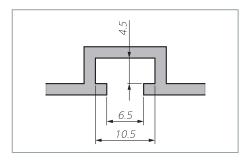
Fixing groove

The fixing grooves are only accessible through the groove openings. Access from the side is blocked by the sleeve.





Dimensions and quantities



	Quantity
C 40	1×
C 100	2×
C 150	3×

Standard: fixed using low-profile M5 sliding block for 6 mm groove, flat-head M6 hexagon bolt or M6 thin nut.



Calculation for selecting the safety bumper depth

The stopping distance of the dangerous movement is calculated according to the following formula:

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$

In accordance with ISO 13856-3, the minimum overtravel distance of the safety bumper is calculated according to the following formula:

$$s = s_1 \times C$$
 where: $C = 1.2$

A suitable safety bumper can now be selected based on the result. For details of the overtravel distances for safety bumpers, see chapter *Technical data*.

s₁ = Stopping distance of the dangerous movement [mm]

v = Velocity of the dangerous movement [mm/s]

T = Follow-through time of the complete system [s]

t₁ = Safety bumper response time

t₂ = Stopping time of the machine

s = Minimum overtravel distance of the safety bumper to ensure that the stipulated limit forces are not exceeded [mm]

C = Safety factor; if components susceptible to failures (braking system) exist in the system, a higher factor must be selected

Calculation examples

Calculation example 1

The dangerous movement on your machine with a width of 1.5 m has a velocity of v = 10 mm/s and can be brought to a standstill within $t_2 = 0.25$ s. The relatively low velocity suggests that a short overtravel distance is to be expected. Therefore, the safety bumper STB 1500 \times 40 \times 100 could be sufficient. The safety bumper response time (STB + control unit*) is $t_1 = 1180$ ms.

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$
 $s_1 = 1/2 \times 10 \text{ mm/s} \times (1.18 \text{ s} + 0.25 \text{ s})$
 $s_1 = 1/2 \times 10 \text{ mm/s} \times 1.43 \text{ s} = 7.2 \text{ mm}$

$$s = s_1 \times C$$
 where: $C = 1.2$

 $s = 7.2 \text{ mm} \times 1.2 = 9 \text{ mm}$

The safety bumper must have a minimum overtravel distance of s = 9 mm. The selected safety bumper STB $1500 \times 40 \times 100$ has an overtravel distance of at least 57.3 mm. This is more than the required 9 mm.

Result: The STB $1500 \times 40 \times 100$ mm is **suitable** for this case.

Subject to technical modifications.

^{*} Assumption: Typical reaction time of a control unit = 20 ms



Calculation example 2

The same conditions apply as in calculation example 1 with the exception of the velocity and the stopping time. Instead, these are now v = 200 m/s and $t_2 = 0.5$ s. The safety bumper response time (STB + control unit*) is $t_1 = 95$ ms.

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$
 $s_1 = 1/2 \times 200 \text{ mm/s} \times (0.095 \text{ s} + 0.5 \text{ s})$
 $s_1 = 1/2 \times 200 \text{ mm/s} \times 0.595 \text{ s} = 60 \text{ mm}$
 $s = s_1 \times C$ where: $C = 1.2$
 $s = 60 \text{ mm} \times 1.2 = 72 \text{ mm}$

The safety bumper must have a minimum overtravel distance of s = 72 mm. The selected safety bumper STB $1500 \times 40 \times 100$ has an overtravel distance of at least 57.3 mm. This is less than the required 72 mm.

Result: The STB $1500 \times 40 \times 100$ is **not suitable** for this case.

Calculation example 3

The same conditions apply as in calculation example 2. Instead of the safety bumper STB $1500 \times 40 \times 100$, a safety bumper STB $1500 \times 100 \times 200$ is selected. The safety bumper response time (STB + control unit*) is $t_1 = 108$ ms.

$$s_1 = 1/2 \times v \times T$$
 where: $T = t_1 + t_2$
 $s_1 = 1/2 \times 200 \text{ mm/s} \times (0.108 \text{ s} + 0.5 \text{ s})$
 $s_1 = 1/2 \times 200 \text{ mm/s} \times 0.608 \text{ s} = 61 \text{ mm}$
 $s = s_1 \times C$ where: $C = 1.2$
 $s = 61 \text{ mm} \times 1.2 = 74 \text{ mm}$

The safety bumper must have a minimum overtravel distance of s = 74 mm. The selected safety bumper STB $1500 \times 100 \times 200$ has an overtravel distance of at least 147 mm. This is more than the required 74 mm.

Result: The STB $1500 \times 100 \times 200$ is **suitable** for this case.

Subject to technical modifications.

^{*} Assumption: Typical reaction time of a control unit = 20 ms



Customised designs

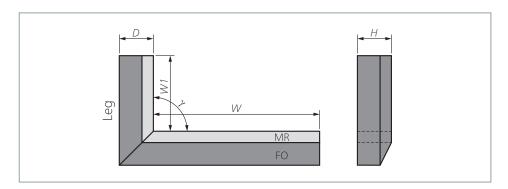
In addition to the standard range, special solutions are also possible, such as:

L shape

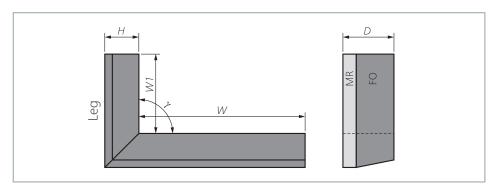
- Depth (D) is the same in the case of W and W1
- Leg angle $\gamma:90^{\circ}/120^{\circ}/135^{\circ}/150^{\circ}$

Horizontal

MR = mounting plate FO = foam



Vertical



Possible installation positions

	L shape
Horizontal	•
Vertical	•
Hanging down	•
Standing upright	•

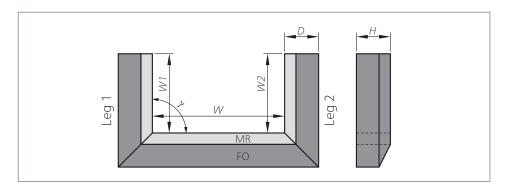


U shape

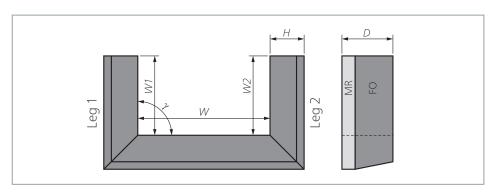
- Depth (D) is the same in the case of W, W1 and W2
- Leg angle $\gamma:90^{\circ}/120^{\circ}/135^{\circ}/150^{\circ}$

Horizontal

MR = mounting plateFO = foam



Vertical



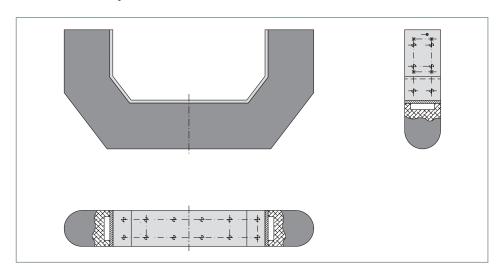
Possible installation positions

	U shape
Horizontal	•
Vertical	•
Hanging down	•
Standing upright	•

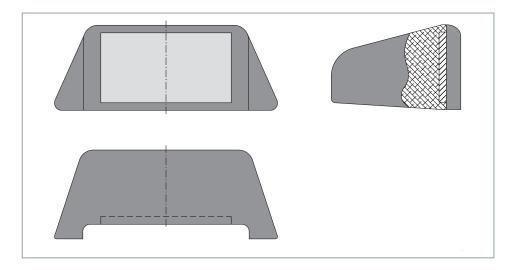


Additional options

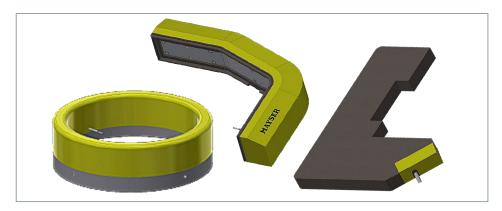
Extended U shape



Trapezium shape



Additional shapes



Subject to technical modifications.



Other mounting plates

Optional: Customer-specific mounting plates can be provided on request.

Maintenance and cleaning

The sensor is virtually maintenance-free.

The control unit also monitors the sensor at the same time.

Regular inspection

Depending on the operational demands, the sensors must be inspected at regular intervals (at least monthly)

- for proper functioning,
- for damage and
- for correct fixing.

Cleaning

If the sensors become dirty, they can be cleaned with a mild cleaning product.



Technical data

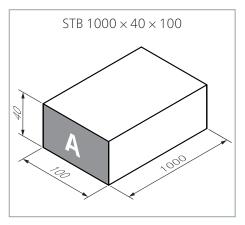
STB 1000 × 40 × 100 PES

Cross section A $1000 \times 40 \times 100 \text{ mm (W} \times \text{H} \times \text{D)}$ PES (polyester sleeve)	Safety bumper STB/W with SG-EFS 104/2W	Safety bumper STB/BK with SG-EFS 104/4L	Sensor* STB/W or STB/BK (without control unit)
Testing basis	EN 12978, ISO 13849	EN 12978, ISO 13849-1, ISO 13856-3	
Switching characteristics at v _{test} =	= 100 mm/s		
Switching operations	> 1× 10 ⁵	> 1× 10 ⁵	> 1× 10 ⁵
Actuation forces			
Test piece (rod) 🗖 45 mm	< 600 N	< 600 N	< 600 N
Test piece (cylinder) Ø 80 mm	< 150 N	< 150 N	< 150 N
Actuation angle	±45°	±45°	±45°
Response time	135 ms	150 ms	120 ms
Actuation distance	14 mm	15 mm	12 mm
Overtravel distance	54 mm	53 mm	56 mm
Safety classifications			
ISO 13856: reset function	With/without	With/without	_
ISO 13849-1:2023	Category 3 PL d	Category 3 PL d	Category 1
MTTF _D (pressure-sensitive			
protective device)	251 a	100 a	_
B _{10D} (sensor)	6× 10 ⁶	6× 10 ⁶	6× 10 ⁶
n _{op} (assumption)	52560/a	52560/a	_
Mechanical operating conditions	3		
Sensor width	200 to 3000 mm		200 to 3000 mm
Cable length (min./max.)	10 cm / 100 m		
Operating velocity			
(min. / max.)	10 mm/s / 200 mm/s		10 mm/s / 200 mm/s
Tensile load, cable (max.)	20 N		20 N
IEC 60529: degree of protection			
Sensor	IP54		IP54
Control unit	IP20		_
Operating temperature			
Individual sensor with			
PES or synthetic leather	−20 to +55 °C		−20 to +55 °C
PUR	+5 to +55 °C		+5 to +55 °C
Weight (incl. aluminium mounting	1		
plate)	0.99 kg/m (without control unit)		0.99 kg/m
Electrical operating conditions			
Terminal resistance (standard)	8k2 ±1%	_	/W: 8k2 ±1%; /BK:-
Nominal output (max.)	250 mW	_	/W: 250 mW; /BK:-
Resistance: sensor activated	< 400 ohms	< 400 ohms	< 400 ohms
Number of sensors	Max. 10 in series	Max. 10 in series	Max. 10 in series
	$(9 \times /BK + 1 \times /W)$	(10×/BK)	$(9 \times /BK + 1 \times /W)$
Sensor	24 V DC / max. 10 mA	24 V DC / max. 10 mA	24 V DC / max. 10 mA

^{*} See footnote on page 39.



Dimensions and distances



Dimensional tolerances in accordance with MWN003

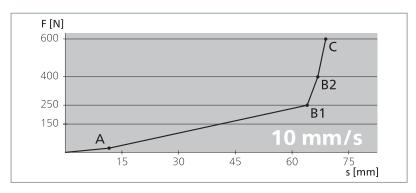
Test conditions

according to ISO 13856-3

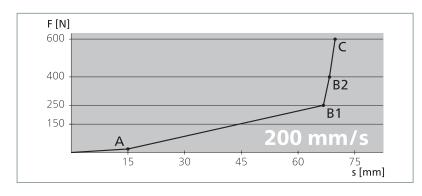
- Installation position C
- Temperature +20 °C
- Measurement point C3
- Test sample 1 with Ø 80 mm
- Without control unit

All data stated here is documented in EC type examination certificates.

Force-distance ratios



F [N]					
600				1	C
400					32
250					•
150				B1	
	A			100 m	m/s
	15	30	45	60	75 s [mm]



Test velocity	10 mm/s
Actuation force	22.5 N
Response time	1160 ms
Actuation distance (A)	11.6 mm
Overtravel distance	
up to 250 N (B1)	52.4 mm
up to 400 N (B2)	55.2 mm
up to 600 N (C)	57.3 mm
Total deformation	68.9 mm

Test velocity	100 mm/s
Actuation force	23.6 N
Response time	116 ms
Actuation distance (A)	11.6 mm
Overtravel distance	
up to 250 N (B1)	52.0 mm
up to 400 N (B2)	54.3 mm
up to 600 N (C)	56.0 mm
Total deformation	67.6 mm

Test velocity	200 mm/s
Actuation force	18.7 N
Response time	75 ms
Actuation distance (A)	15.0 mm
Overtravel distance	
up to 250 N (B1)	51.7 mm
up to 400 N (B2)	53.3 mm
up to 600 N (C)	54.8 mm
Total deformation	69.8 mm



Technical data

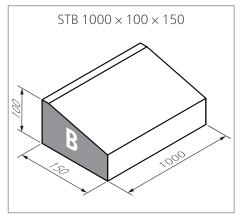
STB 1000 × 100 × 150 PES

Cross section B $1000 \times 100 \times 150 \text{ mm } (W \times H \times D)$ PES (polyester sleeve)	Safety bumper STB/W with SG-EFS 104/2W	Safety bumper STB/BK with SG-EFS 104/4L	Sensor* STB/W or STB/BK (without control unit)
Testing basis	EN 12978, ISO 13849	EN 12978, ISO 13849-1, ISO 13856-3	
Switching characteristics at v _{test} =	= 100 mm/s		
Switching operations Actuation forces	> 1× 10 ⁵	> 1× 10 ⁵	> 1× 10 ⁵
Test piece (rod) □ 45 mm	< 600 N	< 600 N	< 600 N
Test piece (cylinder) Ø 80 mm	< 150 N	< 150 N	< 150 N
Actuation angle	±45°	±45°	±45°
Response time	155 ms	170 ms	140 ms
Actuation distance	16 mm	17 mm	14 mm
Overtravel distance	98 mm	97 mm	100 mm
Safety classifications			
ISO 13856: reset function	With/without	With/without	_
ISO 13849-1:2023	Category 3 PL d	Category 3 PL d	Category 1
MTTF _D (pressure-sensitive			
protective device)	251 a	100 a	-
B _{10D} (sensor)	6× 10 ⁶	6× 10 ⁶	6× 10 ⁶
n _{op} (assumption)	52560/a	52560/a	-
Mechanical operating conditions	5		
Sensor width	200 to 3000 mm		200 to 3000 mm
Cable length (min./max.)	10 cm / 100 m		10 cm / 100 m
Operating velocity			
(min. / max.)	10 mm/s / 200 mm/s		10 mm/s / 200 mm/s
Tensile load, cable (max.)	20 N		20 N
IEC 60529: degree of protection			
Sensor	IP54		IP54
Control unit	IP20		-
Operating temperature			
Individual sensor with			
PES or synthetic leather	−20 to +55 °C		−20 to +55 °C
PUR	+5 to +55 °C		+5 to +55 °C
Weight (incl. aluminium mounting plate)	1.76 kg/m (without control unit)		1.76 kg/m
Electrical operating conditions			
Terminal resistance (standard)	8k2 ±1%	_	/W: 8k2 ±1%; /BK:-
Nominal output (max.)	250 mW	_	/W: 250 mW; /BK: –
Resistance: sensor activated	< 400 ohms	< 400 ohms	< 400 ohms
Number of sensors	Max. 10 in series $(9 \times /BK + 1 \times /W)$	Max. 10 in series (10× /BK)	Max. 10 in series $(9 \times /BK + 1 \times /W)$
Sensor	24 V DC / max. 10 mA	24 V DC / max. 10 mA	24 V DC / max. 10 mA

^{*} See footnote on page 39.



Dimensions and distances



Dimensional tolerances in accordance with MWN003

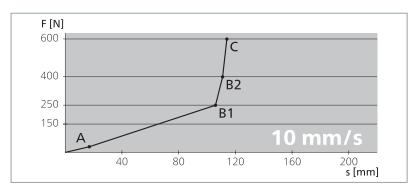
Test conditions

according to ISO 13856-3

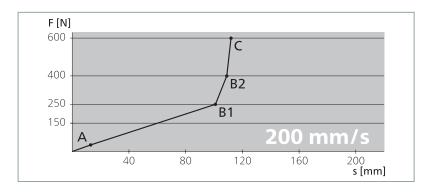
- Installation position C
- Temperature +20 °C
- Measurement point C3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.

Force-distance ratios



F [N]					
600 +			C		
400			/B2		
250			B1		
150 -	A	,		100 m	m/s
	40	80	120	160	200 s [mm]



Test velocity	10 mm/s
Actuation force	30 N
Response time	1700 ms
Actuation distance (A)	17 mm
Overtravel distance	
up to 250 N (B1)	89 mm
up to 400 N (B2)	94 mm
up to 600 N (C)	97 mm
Total deformation	114 mm

Test velocity	100 mm/s
Actuation force	38 N
Response time	140 ms
Actuation distance (A)	14 mm
Overtravel distance	
up to 250 N (B1)	88 mm
up to 400 N (B2)	96 mm
up to 600 N (C)	100 mm
Total deformation	114 mm

Test velocity	200 mm/s
Actuation force	35 N
Response time	65 ms
Actuation distance (A)	13 mm
Overtravel distance	
up to 250 N (B1)	88 mm
up to 400 N (B2)	96 mm
up to 600 N (C)	99 mm
Total deformation	112 mm



Technical data

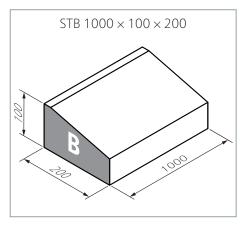
STB 1000 × 100 × 200 PES

Cross section B 1000 × 100 × 200 mm (W × H × D) PES (polyester sleeve)	Safety bumper STB/W with SG-EFS 104/2W	Safety bumper STB/BK with SG-EFS 104/4L	Sensor* STB/W or STB/BK (without control unit)
Testing basis	EN 12978, ISO 13849-1, ISO 13856-3		ISO 13856-3
Switching characteristics at v _{test} =	100 mm/s	,	
Switching operations	> 1× 10 ⁵	> 1× 10 ⁵	> 1× 10 ⁵
Actuation forces			
Test piece (rod) 🗖 45 mm	< 600 N	< 600 N	< 600 N
Test piece (cylinder) Ø 80 mm	< 150 N	< 150 N	< 150 N
Actuation angle	±45°	±45°	±45°
Response time	175 ms	190 ms	160 ms
Actuation distance	18 mm	19 mm	16 mm
Overtravel distance	140 mm	139 mm	142 mm
Safety classifications			
ISO 13856: reset function	With/without	With/without	_
ISO 13849-1:2023	Category 3 PL d	Category 3 PL d	Category 1
MTTF _D (pressure-sensitive			
protective device)	251 a	100 a	_
B _{10D} (sensor)	6× 10 ⁶	6× 10 ⁶	6× 10 ⁶
n _{op} (assumption)	52560/a	52560/a	_
Mechanical operating conditions			
Sensor width	200 to 3000 mm		200 to 3000 mm
Cable length (min./max.)	10 cm / 100 m		10 cm / 100 m
Operating velocity			
(min. / max.)	10 mm/s / 200 mm/s		10 mm/s / 200 mm/s
Tensile load, cable (max.)	20 N		20 N
IEC 60529: degree of protection			
Sensor	 IP54		 IP54
Control unit	IP20		
Operating temperature			
Individual sensor with			
PES or synthetic leather	−20 to +55 °C		−20 to +55 °C
PUR	+5 to +55 °C		+5 to +55 °C
Weight (incl. aluminium mounting	13 (0 133 C		13 (0 133 C
plate)	1.86 kg/m (without control unit)		1.86 kg/m
Electrical operating conditions		,	
Terminal resistance (standard)	8k2 ±1%	_	/W: 8k2 ±1%; /BK:-
Nominal output (max.)	250 mW	_	/W: 250 mW; /BK:-
Resistance: sensor activated	< 400 ohms	< 400 ohms	< 400 ohms
Number of sensors	Max. 10 in series (9×/BK + 1×/W)	Max. 10 in series (10×/BK)	Max. 10 in series (9×/BK + 1×/W)
	1 1 2 A / PIX I I A / V V /		

^{*} See footnote on page 39.



Dimensions and distances



Dimensional tolerances in accordance with MWN003

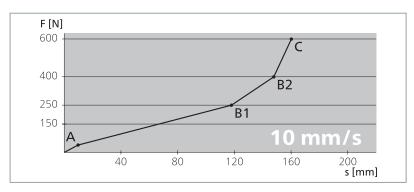
Test conditions

according to ISO 13856-3

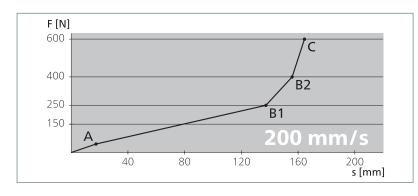
- Installation position C
- Temperature +20 °C
- Measurement point C3
- Test sample 1 with Ø 80 mm
- Without control unit

All data stated here is documented in EC type examination certificates.

Force-distance ratios



F [N]					
600				C	
400 - 250 -				B2	
150 -			B1	100	
	A			100 m	m/s
	40	80	120	160	200 s [mm]



Test velocity	10 mm/s
Actuation force	39.0 N
Response time	980 ms
Actuation distance (A)	9.8 mm
Overtravel distance	
up to 250 N (B1)	108.1 mm
up to 400 N (B2)	138.0 mm
up to 600 N (C)	150.4 mm
Total deformation	160.2 mm

Test velocity	100 mm/s
Actuation force	44.9 N
Response time	160 ms
Actuation distance (A)	16.0 mm
Overtravel distance	
up to 250 N (B1)	110.0 mm
up to 400 N (B2)	132.5 mm
up to 600 N (C)	142.0 mm
Total deformation	158.0 mm

Test velocity	200 mm/s
Actuation force	44.8 N
Response time	88 ms
Actuation distance (A)	17.5 mm
Overtravel distance	
up to 250 N (B1)	119.8 mm
up to 400 N (B2)	138.3 mm
up to 600 N (C)	147.0 mm
Total deformation	164.5 mm



Technical data

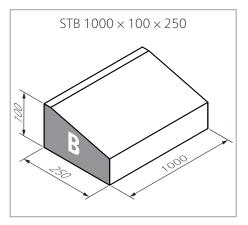
STB 1000 × 100 × 250 PES

Cross section B $1000 \times 100 \times 250 \text{ mm (W} \times H \times D)$ PES (polyester sleeve)	Safety bumper STB/W with SG-EFS 104/2W	Safety bumper STB/BK with SG-EFS 104/4L	Sensor* STB/W or STB/BK (without control unit)
Testing basis	EN 12978, ISO 13849	EN 12978, ISO 13849-1, ISO 13856-3	
Switching characteristics at v _{test} :	= 100 mm/s		
Switching operations	> 1× 10 ⁵	> 1× 10 ⁵	> 1× 10 ⁵
Actuation forces			
Test piece (rod) □ 45 mm	< 600 N	< 600 N	< 600 N
Test piece (cylinder) Ø 80 mm	< 150 N	< 150 N	< 150 N
Actuation angle	±45°	±45°	±45°
Response time	375 ms	390 ms	360 ms
Actuation distance	38 mm	39 mm	36 mm
Overtravel distance	169 mm	168 mm	171 mm
Safety classifications			
ISO 13856: reset function	With/without	With/without	_
ISO 13849-1:2023	Category 3 PL d	Category 3 PL d	Category 1
MTTF _D (pressure-sensitive			
protective device)	251 a	100 a	_
B _{10D} (sensor)	6× 10 ⁶	6× 10 ⁶	6× 10 ⁶
n _{op} (assumption)	52560/a	52560/a	_
Mechanical operating conditions	5		
Sensor width	200 to 3000 mm		200 to 3000 mm
Cable length (min./max.)	10 cm / 100 m	10 cm / 100 m	
Operating velocity			
(min. / max.)	10 mm/s / 200 mm/s		10 mm/s / 200 mm/s
Tensile load, cable (max.)	20 N		20 N
IEC 60529: degree of protection			
Sensor	IP54		IP54
Control unit	IP20		_
Operating temperature			
Individual sensor with			
PES or synthetic leather	−20 to +55 °C	−20 to +55 °C	
PUR	+5 to +55 °C		+5 to +55 °C
Weight (incl. aluminium mounting			
plate)	1.93 kg/m (without control unit)		1.93 kg/m
Electrical operating conditions			
Terminal resistance (standard)	8k2 ±1%	_	/W: 8k2 ±1%; /BK:-
Nominal output (max.)	250 mW	_	/W: 250 mW; /BK:-
Resistance: sensor activated	< 400 ohms	< 400 ohms	< 400 ohms
Number of sensors	Max. 10 in series	Max. 10 in series	Max. 10 in series
	$(9 \times /BK + 1 \times /W)$	(10×/BK)	$(9 \times /BK + 1 \times /W)$
Sensor	24 V DC / max. 10 mA	24 V DC / max. 10 mA	24 V DC / max. 10 mA

^{*} See footnote on page 39.



Dimensions and distances



Dimensional tolerances in accordance with MWN003

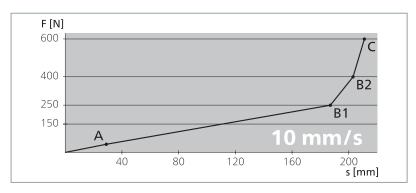
Test conditions

according to ISO 13856-3

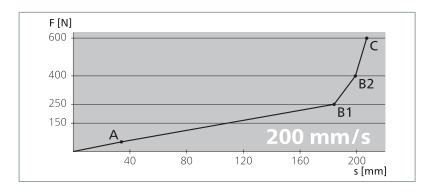
- Installation position C
- Temperature +20 °C
- Measurement point C3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.

Force-distance ratios



F [N]					
600					C
400					B2
					B1
150	A		1	100 m	m/s
_	40	80	120	160	200 s [mm]



Test velocity	10 mm/s
Actuation force	43 N
Response time	2900 ms
Actuation distance (A)	29 mm
Overtravel distance	
up to 250 N (B1)	158 mm
up to 400 N (B2)	174 mm
up to 600 N (C)	182 mm
Total deformation	211 mm

Test velocity	100 mm/s
Actuation force	48 N
Response time	360 ms
Actuation distance (A)	36 mm
Overtravel distance	
up to 250 N (B1)	152 mm
up to 400 N (B2)	165 mm
up to 600 N (C)	171 mm
Total deformation	207 mm

Test velocity	200 mm/s
Actuation force	51 N
Response time	170 ms
Actuation distance (A)	34 mm
Overtravel distance	
up to 250 N (B1)	150 mm
up to 400 N (B2)	165 mm
up to 600 N (C)	173 mm
Total deformation	207 mm



Technical data

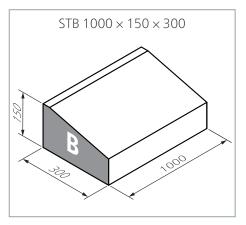
STB 1000 × 150 × 300 PES

Cross section B $1000 \times 150 \times 300 \text{ mm } (W \times H \times D)$ PES (polyester sleeve)	Safety bumper STB/W with SG-EFS 104/2W	Safety bumper STB/BK with SG-EFS 104/4L	Sensor* STB/W or STB/BK (without control unit)
Testing basis	EN 12978, ISO 13849	-1, ISO 13856-3	ISO 13856-3
Switching characteristics at v _{test} :	= 100 mm/s		
Switching operations Actuation forces	> 1× 10 ⁵	> 1× 10 ⁵	> 1× 10 ⁵
Test piece (rod) □ 45 mm	< 600 N	< 600 N	< 600 N
Test piece (cylinder) Ø 80 mm	< 150 N	< 150 N	< 150 N
Actuation angle	±45°	±45°	±45°
Response time	395 ms	410 ms	380 ms
Actuation distance	40 mm	41 mm	38 mm
Overtravel distance	199 mm	198 mm	201 mm
Safety classifications			
ISO 13856: reset function	With/without	With/without	_
ISO 13849-1:2023	Category 3 PL d	Category 3 PL d	Category 1
MTTF _D (pressure-sensitive			
protective device)	251 a	100 a	-
B _{10D} (sensor)	6× 10 ⁶	6× 10 ⁶	6× 10 ⁶
n _{op} (assumption)	52560/a	52560/a	_
Mechanical operating conditions	5		
Sensor width	200 to 3000 mm		200 to 3000 mm
Cable length (min./max.)	10 cm / 100 m		10 cm / 100 m
Operating velocity			
(min. / max.)	10 mm/s / 200 mm/s		10 mm/s / 200 mm/s
Tensile load, cable (max.)	20 N		20 N
IEC 60529: degree of protection			
Sensor	IP54	IP54	
Control unit	IP20		-
Operating temperature			
Individual sensor with			
PES or synthetic leather	−20 to +55 °C		−20 to +55 °C
PUR	+5 to +55 °C	+5 to +55 °C	
Weight (incl. aluminium mounting plate)	2.50 kg/m (without control unit)		2.50 kg/m
Electrical operating conditions			
Terminal resistance (standard)	8k2 ±1%	_	/W: 8k2 ±1%; /BK:-
Nominal output (max.)	250 mW	_	/W: 250 mW; /BK:-
Resistance: sensor activated	< 400 ohms	< 400 ohms	< 400 ohms
Number of sensors	Max. 10 in series $(9 \times /BK + 1 \times /W)$	Max. 10 in series (10× /BK)	Max. 10 in series $(9 \times /BK + 1 \times /W)$
Sensor	24 V DC / max. 10 mA	24 V DC / max. 10 mA	24 V DC / max. 10 mA

^{*} See footnote on page 39.



Dimensions and distances



Dimensional tolerances in accordance with MWN003

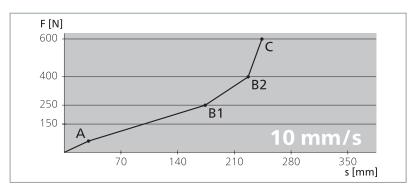
Test conditions

according to ISO 13856-3

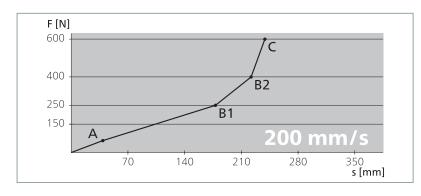
- Installation position C
- Temperature +20 °C
- Measurement point C3
- Test sample 1 with Ø 80 mm
- Without control unit

All the data given here has been verified by Mayser GmbH & Co. KG.

Force-distance ratios



F [N]					
600				С	
400 —			BZ	2	
150		/	B1		
	A			100 m	m/s
	70	140	210	280	350 s [mm]



Test velocity	10 mm/s
Actuation force	60 N
Response time	3000 ms
Actuation distance (A)	30 mm
Overtravel distance	
up to 250 N (B1)	144 mm
up to 400 N (B2)	197 mm
up to 600 N (C)	214 mm
Total deformation	244 mm

Test velocity	100 mm/s
Actuation force	61 N
Response time	380 ms
Actuation distance (A)	38 mm
Overtravel distance	
up to 250 N (B1)	144 mm
up to 400 N (B2)	186 mm
up to 600 N (C)	201 mm
Total deformation	239 mm

Test velocity	200 mm/s		
Actuation force	63 N		
Response time	195 ms		
Actuation distance (A)	39 mm		
Overtravel distance			
up to 250 N (B1)	139 mm		
up to 400 N (B2)	183 mm		
up to 600 N (C)	200 mm		
Total deformation	239 mm		



Technical data

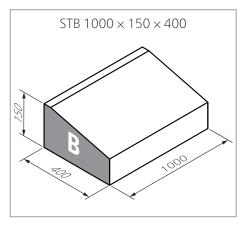
STB 1000 × 150 × 400 PES

Cross section B $1000 \times 150 \times 400 \text{ mm (W} \times H \times D)$ PES (polyester sleeve)	Safety bumper STB/W with SG-EFS 104/2W	Safety bumper STB/BK with SG-EFS 104/4L	Sensor* STB/W or STB/BK (without control unit)
Testing basis	EN 12978, ISO 13849	-1, ISO 13856-3	ISO 13856-3
Switching characteristics at v _{test} =	= 100 mm/s		
Switching operations	> 1× 10 ⁵	> 1× 10 ⁵	> 1× 10 ⁵
Actuation forces			
Test piece (rod) □ 45 mm	< 600 N	< 600 N	< 600 N
Test piece (cylinder) Ø 80 mm	< 150 N	< 150 N	< 150 N
Actuation angle	±45°	±45°	±45°
Response time	495 ms	510 ms	480 ms
Actuation distance	50 mm	51 mm	48 mm
Overtravel distance	295 mm	294 mm	297 mm
Safety classifications			
ISO 13856: reset function	With/without	With/without	_
ISO 13849-1:2023	Category 3 PL d	Category 3 PL d	Category 1
MTTF _D (pressure-sensitive			
protective device)	251 a	100 a	_
B_{10D} (sensor) 6×10^6 6×10^6		6× 10 ⁶	
n _{op} (assumption)	52560/a	52560/a	_
Mechanical operating conditions	3		
Sensor width	200 to 3000 mm	200 to 3000 mm	
Cable length (min./max.)	10 cm / 100 m		10 cm / 100 m
Operating velocity			
(min. / max.)	10 mm/s / 200 mm/s		10 mm/s / 200 mm/s
Tensile load, cable (max.)	20 N		20 N
IEC 60529: degree of protection		2014	
Sensor	IP54		IP54
Control unit	IP20		_
Operating temperature		11 20	
Individual sensor with			
PES or synthetic leather	−20 to +55 °C		−20 to +55 °C
PUR	+5 to +55 °C		+5 to +55 °C
Weight (incl. aluminium mounting	13 to 133 t	+3 t0 +33 C	
plate)	2.73 kg/m (without control unit)		2.73 kg/m
Electrical operating conditions	<u>'</u>	,	,
Terminal resistance (standard)	8k2 ±1%	_	/W: 8k2 ±1%; /BK:-
Nominal output (max.)	250 mW	_	/W: 250 mW; /BK: –
Resistance: sensor activated	< 400 ohms	< 400 ohms	< 400 ohms
Number of sensors	Max. 10 in series	Max. 10 in series	Max. 10 in series
	$(9 \times /BK + 1 \times /W)$	(10× /BK)	$(9 \times /BK + 1 \times /W)$
Sensor	24 V DC / max. 10 mA	24 V DC / max. 10 mA	24 V DC / max. 10 mA

^{*} See footnote on page 39.



Dimensions and distances



Dimensional tolerances in accordance with MWN003

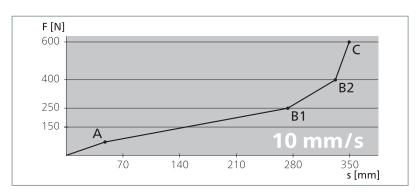
Test conditions

according to ISO 13856-3

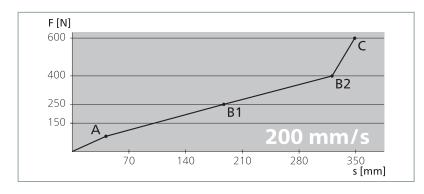
- Installation position C
- Temperature +20 °C
- Measurement point C3
- Test sample 1 with Ø 80 mm
- Without control unit

All data stated here is documented in EC type examination certificates.

Force-distance ratios



F [N]	
600	2 -
	′ C
400	.
B2	4
250	
150 B1	
	16
100 mm	/5
70 140 210 280	350
	s [mm]



Test velocity	10 mm/s			
Actuation force	71.0 N			
Response time	4790 ms			
Actuation distance (A)	47.9 mm			
Overtravel distance				
up to 250 N (B1)	225.6 mm			
up to 400 N (B2)	284.3 mm			
up to 600 N (C)	301.3 mm			
Total deformation	349.2 mm			

Test velocity	100 mm/s
Actuation force	81.9 N
Response time	472 ms
Actuation distance (A)	47.2 mm
Overtravel distance	
up to 250 N (B1)	197.1 mm
up to 400 N (B2)	273.5 mm
up to 600 N (C)	297.1 mm
Total deformation	344.3 mm

Test velocity	200 mm/s		
Actuation force	80.6 N		
Response time	208 ms		
Actuation distance (A)	41.6 mm		
Overtravel distance			
up to 250 N (B1)	145.5 mm		
up to 400 N (B2)	279.1 mm		
up to 600 N (C)	307.1 mm		
Total deformation	348.7 mm		



Conformity

Conformity



The CE symbol indicates that this Mayser product complies with the relevant EC directives and that the stipulated conformity assessments have been carried out.

The design type of the product complies with the basic requirements of the following directives:

- 2006/42/EC (Safety of Machinery)
- 2011/65/EU (RoHS)
- 2014/30/EU (EMC)

The Declaration of Conformity is available in the Downloads section of our website: www.mayser.com.

EC type examination

The product was tested by an independent institute.

There is an EC type examination certificate to confirm conformity.

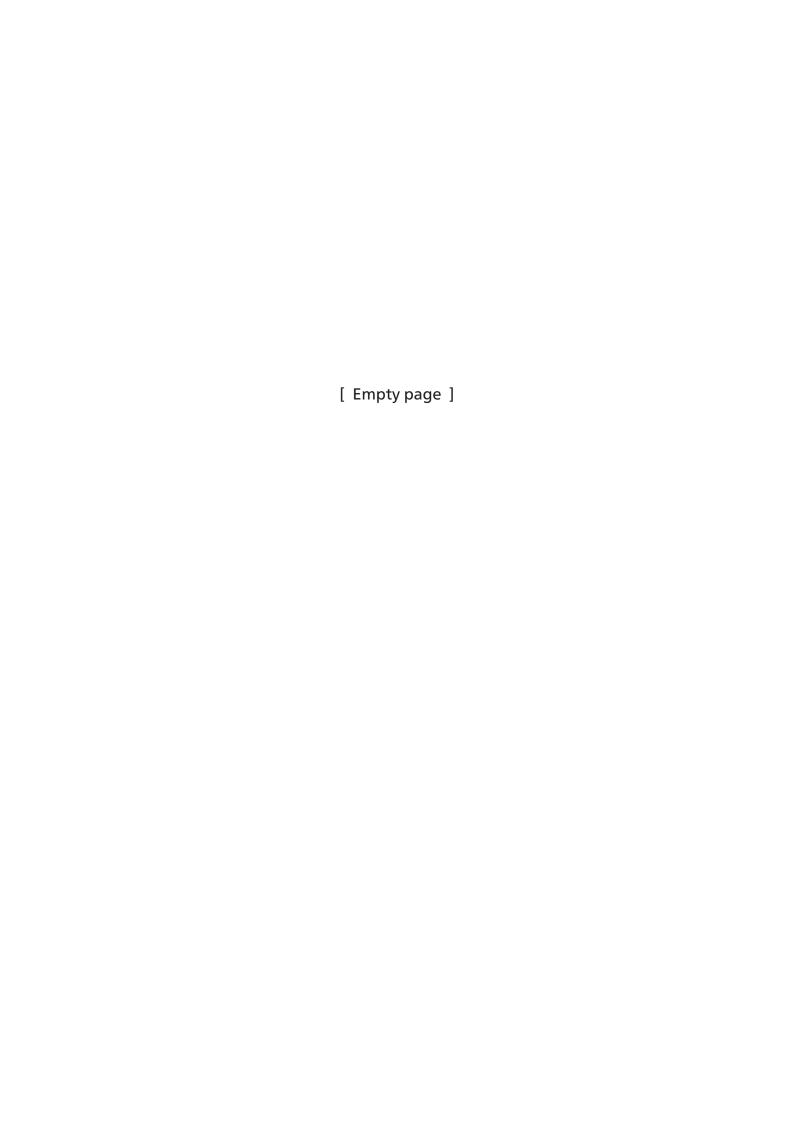
The EC type examination certificate is available in the Downloads section of our website: www.mayser.com.

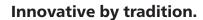
As well as meeting technical requirements, this also means – in particular – observing any that relate to marking and information for use.

Declarations of Conformity only apply to pressure-sensitive protective devices. In the case of sensors that are going to be used to make pressure-sensitive protective devices, Declarations of Incorporation are issued instead.

Subject to technical modifications.

^{*} If you combine sensors with control units and thereby place pressure-sensitive protective devices on the market, you should observe the basic requirements according to ISO 13856.









Control units SG



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Туре	SG-EFS 104/4L	SG-EFS 104/2W	SG-RS 309-2	RB3 system	
Safety classification ISO 13849-1:2015 ISO 13856: reset function MTTF _D DC _{avg} $B_{10D} [\times 10^6]$	Category 3 PL e With/without 100 a 90 % 0.4	Category 3 PL d With/without 257 a 60 % 1.8	Category 3 PL d With/without 937 a 92 % –	Category 2 PL d - 50 a 91 % 20	
Times					
Reaction time	DC: < 30 ms AC: < 50 ms	< 15 ms	< 15 ms	35 ms	
Restart time	< 500 ms	< 50 ms	< 150 ms	5 ms	
Control unit inputs					
Sensor types	SM, SP, SL, MSL, SB	SM, SP, SL, MSL, SB	SM, SP, SL, MSL, SB	SP, SL, MSL, SB	
Monitoring type	4-wire technology	1k2 or 8k2 monitoring resistor	8k2 or 10k monitoring resistor	8k2 monitoring resistor	
Monitoring circuits	1	1	2	1	
Other inputs				Test signal	
Control unit outputs Switching channels	1× 3-channel	1× 2-channel	2× 2-channel	2× 2-channel	
Switching current					
(min. / max.)	-/5A	-/4A	> 0 mA / 100 mA	- mA / 2 A	
Switching capacity (max.)	1150 VA / 120 W	1000 VA / 96 W 1 signal circuit,	3.6 W	120 VA / 24 W	
Other outputs	1 signal circuit	2 signal outputs	2 signal outputs	1 signal output	
Mechanical operating conditions					
Mounting	IEC 60715 mounting rail	IEC 60715 mounting rail	IEC 60715 mounting rail	Wall mounting	
IEC 60529: degree of protection	IP20	IP20	IP20	IP65	
Operating temperature	−25 to +55 °C	−25 to +55 °C	−40 to +70 °C	−20 to +55 °C	
Dimensions (W \times H \times D)	22.5 × 99 × 114.5 mm	22.5 × 99 × 114.5 mm	17.5 × 99 × 114.5 mm	82 × 190 × 40 mm 60 × 151 × 23 mm	
Variants Part number Connecting voltage U _s Power consumption P	SG-EFS 104/4L 1004128 24 V AC/DC < 5 VA / < 3 W	SG-EFS 104/2W 1005196 24 V AC/DC < 4 VA / < 3 W	SG-RS 309-2 1006747 24 to 36 V DC < 1.5 W	RB3 system 1007228 + 1007229 12 to 24 V AC/DC < 0.3 VA / < 0.4 W	





Signal transmission system WLS



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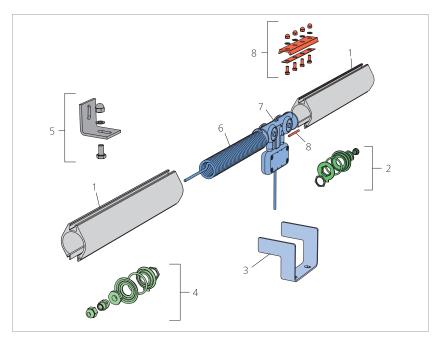
Areas of application

The WLS signal transmission system is used as a protective conduit for cables in doors and gates. When it comes to making danger areas safe, the system is especially suitable for safe transmission of signals between tactile sensors e.g. safety edges and the control module.

Examples:

- Vertical and horizontal gates
- Machine hoods and windows
- Conservatories
- Sun blinds
- Moulding and textile machines

System design



Pos.	Part No.	Designation	Comment		
1	10038-0609	Profile tube WLS	aluminium anodised; 2, 3, 4 and 6 m		
2	1003792	WLS-sealing cap	closed		
3	1003771	Carrying fork for WLS			
4	1003791	WLS-sealing cap	PG7		
6 + 7	75015-1324	Spiral cable with carriage	4× 0.14 mm ²		
8	1003802	Tube connector for WLS	stainless steel		

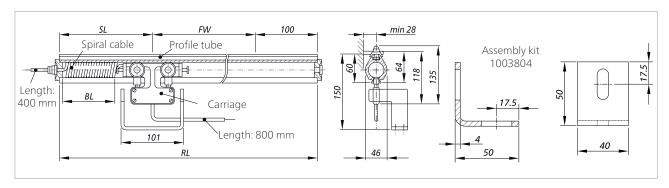
Accessories			
5	1003804	Fastening parts for WLS	incl. nuts and screws



Operation

The system consists of an aluminium profile tube and a specially designed, abrasion-resistant and extremely dimensionally stable spiral cable with carriage. When the carriage is put into motion the cable is stretched inside the profile tube and returns to its original position when the carriage goes back. The system components were designed to co-ordinate with each other and can be used in gates both indoors and outdoors. The WLS is suitable for gates in high-frequency operation.

Dimensions and part numbers



WLS complete	WLS-kit, no profile tube	Spiral cable with car-riage	Max. run- way	Profile tube length	Storage length	Block length
Part No.	Part No.	Part No.	FW [m]	RL [m]	SL [m]	BL [m]
7501482	7501501	7501513	1.5	2	0.3	0.12
7501483	7501502	7501514	1.6 2.5	3	0.4	0.29
7501484	7501502	7501514	2.6 3.5	4	0.4	0.29
7501485	7501503	7501515	3.6 4.3	5 = 2+3	0.6	0.46
7501486	7501503	7501515	4.4 5.3	6	0.6	0.46
7501487	7501504	7501516	5.4 6.1	7 = 3+4	0.8	0.63
7501488	7501504	7501516	6.2 7.1	8 = 4+4	0.8	0.63
7501489	7501505	7501517	7.2 8.0	9 = 3+6	0.9	0.80
7501490	7501505	7501517	8.1 9.0	10 = 4+6	0.9	0.80
7501491	7501506	7501518	9.1 9.8	11 = 3+4+4	1.05	0.96
7501492	7501506	7501518	9.9 10.8	12 = 6+6	1.05	0.96
7501493	7501506	7501518	10.9 11.8	13 = 3+4+6	1.05	0.96
7501494	7501507	7501519	11.9 12.6	14 = 2+6+6	1.25	1.13
7501495	7501507	7501519	12.7 13.6	15 = 3+6+6	1.25	1.13
7501496	7501508	7501520	13.7 15.3	17 = 2+3+6+6	1.60	1.48
7501497	7501509	7501521	15.4 17.1	19 = 3+4+6+6	1.80	1.65
7501498	7501510	7501522	17.2 19.0	21 = 3+6+6+6	1.90	1.78
7501499	7501511	7501523	19.1 20.9	23 = 2+3+6+6+6	2.00	1.85
7501500	7501512	7501524	21.0 23.5	26 = 2+6+6+6+6	2.40	2.28
Quantity buy	Quantity buyers and dealers: please send us your request for quotation.					



Technical data

Cable	special, wear-free, double insulated spiral cable
Number of wires/cross-section	4× 0.14 mm ²
Operating voltage	max. 48 V AC/DC
Max. load (at +25 °C)	max. 1.5 A eff.
Temperature range	-20 to +80 °C
Moving speed	40 m/min
Runway lengths	1.5 m to 23.5 m
System lengths	2.0 m to 26.0 m in fixed lengths: 2, 3, 4 and 6 m
Conduit rail	aluminium, anodized, warp resistant

At a glance

- Robust, simple, proven construction
- Quick and easy installation due to low number of components in modular form
- Maintenance-free
- Short envelope delay to meet the dynamic force and time parameters in accordance with EN 12453 and EN 12445